

Real Analysis
(Rudin, *Principles of Mathematical Analysis*)

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Contents

1 Real and Complex Number System

1.1 Ordered Sets

Definition 1.1 (Order, Ordered Set). An **order** on set S is a relation denoted by $<$, with the following two properties:

1. For all $x, y \in S$, one and only one of the statements $x < y, x = y, y < x$ is true.
2. For all $x, y, z \in S$, if $x < y, y < z$ then $x < z$.

$x \leq y$ indicates $x < y$ or $x = y$. Sometimes we write $y > x$ in place of $x < y$, write $y \geq x$ in place of $x \leq y$. With such an order, the set S is called an **ordered set**.

Definition 1.2 (Bound). Suppose S is an ordered set, and $E \subset S$. If there exists a $\beta \in S$ such that $x \leq \beta$ for every $x \in E$, then we say E is **bounded above**, and call β an **upper bound** of E .

Analogously, if there exists a $\alpha \in S$ such that $x \geq \alpha$ for every $x \in E$, then we say E is **bounded below**, and call α an **lower bound** of E .

Definition 1.3 (Supremum, Infimum). Suppose S is an ordered set, and $E \subset S$ is bounded above. Suppose there exists an $\alpha \in S$ with the following properties:

1. α is an upper bound of E ;
2. If $\gamma < \alpha$, then γ is not an upper bound of E .

Then α is called the **least upper bound (supremum)** of E , and we write $\alpha = \sup E$.

Analogously, suppose there exists an $\alpha \in S$ with the following properties:

1. α is a lower bound of E ;
2. If $\gamma > \alpha$, then γ is not a lower bound of E .

Then α is called the **greatest lower bound (infimum)** of E , and we write $\alpha = \inf E$.

Note that the definition above *supposes* but not *guarantees* that there exists supremum or infimum. The example below shows that even a bounded subset may not have supremum or infimum.

Example 1.1. Let $A = \{x \in \mathbb{Q} : x^2 < 2\}$, which is clearly bounded above. It could be shown that it has no supremum in \mathbb{Q} .

Definition 1.4 (Least-Upper-Bound Property). An ordered set S is said to have the **least-upper-bound property** (is **Dedekind complete**) if for all non-empty subset $E \subset S$, $\sup E$ exists in S whenever it is bounded above.

Theorem 1.1. Suppose S is an Dedekind complete ordered set, $B \subset S$ is non-empty and bounded below. Let L be the set of all lower bounds of B , then $\alpha = \sup L$ exists in S , and $\alpha = \inf B$.

Proof. First note that L is non-empty since B is bounded below. Since L consists of exactly those $y \in S$ which satisfy $y \leq x$ for every $x \in B$, we see that every $x \in B$ is an upper bound of L . Thus L is bounded above, and thus $\sup L$ exists since S is Dedekind complete. Let $\alpha = \sup L$. Now we only need to show that $\alpha = \inf B$.

If $\gamma < \alpha$, then γ is not an upper bound of L , hence $\gamma \notin B$. Then we have $\alpha \leq x$ for every $x \in B$, and thus $\alpha \in L$.

If $\alpha < \beta$, then $\beta \notin L$, since α is an upper bound of L . Hence, we have shown that α is a lower bound of B (since $\alpha \in L$), but β is not if $\beta > \alpha$. Therefore, $\alpha = \inf B$. \square

1.2 Fields and Real Field

Definition 1.5 (Field). A **field** is a set F with two operations, called **addition** and **multiplication**, which satisfy the following 'field axioms':

1. Axioms for addition:

- (a) If $x, y \in F$, then their sum $x + y \in F$;
- (b) Commutative law: $x + y = y + x$ for all $x, y \in F$;
- (c) Associative law: $(x + y) + z = x + (y + z)$ for all $x, y, z \in F$;
- (d) F contains element 0 such that $0 + x = x$ for every $x \in F$;
- (e) To every $x \in F$ corresponds an element $-x \in F$ such that $x + (-x) = 0$.

2. Axioms for multiplication:

- (a) If $x, y \in F$, then their product $xy \in F$;
 - (b) Commutative law: $xy = yx$ for all $x, y \in F$;
 - (c) Associative law: $(xy)z = x(yz)$ for all $x, y, z \in F$;
 - (d) F contains an element $1 \neq 0$ such that $1x = x$ for every $x \in F$;
 - (e) If $x \in F$ and $x \neq 0$, then there exists an element $1/x \in F$ such that $x \cdot (1/x) = 1$.
3. The distributive law: $x(y + z) = xy + xz$ for all $x, y, z \in F$.

Proposition 1.1. *The axioms for addition imply the following statements:*

- 1. Cancellation law: If $x + y = x + z$, then $y = z$;
- 2. Uniqueness of 0: If $x + y = x$, then $y = 0$;
- 3. Uniqueness of $-x$: If $x + y = 0$, then $y = -x$;
- 4. $-(-x) = x$.

Proof.

- 1. If $x + y = x + z$, then axioms for addition give

$$y = 0 + y = (-x + x) + y = -x + (x + y) = -x + (x + z) = (-x + x) + z = 0 + z = z.$$

- 2. It follows from (1) by taking $z = 0$.
- 3. It follows from (1) by taking $z = -x$.
- 4. It follows from (3) by replacing x by $-x$.

□

Proposition 1.2. *The axioms for multiplication imply the following statements:*

- 1. Cancellation law: If $x \neq 0$ and $xy = xz$, then $y = z$;
- 2. Uniqueness of 1: If $x \neq 0$ and $xy = x$, then $y = 1$;
- 3. Uniqueness of $1/x$: If $x \neq 0$ and $xy = 1$, then $y = 1/x$;
- 4. If $x \neq 0$, then $1/(1/x) = x$.

Proof. Analogous to the proof of Proposition 1.1.

□

Proposition 1.3. *The field axioms imply the following statements:*

- 1. $0x = 0$;
- 2. If $x \neq 0, y \neq 0$, then $xy \neq 0$;
- 3. $(-x)y = -(xy) = x(-y)$;
- 4. $(-x)(-y) = xy$.

Proof.

- 1. Note that $0x + 0x = (0 + 0)x = 0x$. Hence Proposition 1.1(2) implies that $0x = 0$.
- 2. Assume $x \neq 0, y \neq 0$ but $xy = 0$. Then (1) gives

$$1 = (1/y)(1/x)xy = (1/y)(1/x)0 = 0$$

where has a contradiction. Hence (2) holds.

- 3. The first equality comes from

$$(-x)y + xy = (-x + x)y = 0y = 0,$$

combined with Proposition 1.1(3). The second equality is proved in the same way.

- 4. By (3) and Proposition 1.1(4) we have

$$(-x)(-y) = -[x(-y)] = -[-(xy)] = xy.$$

□

Definition 1.6 (Ordered Field). *An **ordered field** is a field F which is also an ordered set such that*

- 1. $x + y < x + z$ if $x, y, z \in F$ and $y < z$;
- 2. $xy > 0$ if $x, y \in F$, and $x, y > 0$.

*We call x is **positive** if $x > 0$, or **negative** if $x < 0$.*

For example, \mathbb{Q} is an ordered field.

Proposition 1.4. *The following statements are true in every ordered field.*

1. If $x > 0$, then $-x < 0$, and vice versa;
2. If $x > 0$ and $y < z$, then $xy < xz$;
3. If $x < 0$ and $y < z$, then $xy > xz$;
4. If $x \neq 0$ then $x^2 > 0$. In particular, $1 = 1^2 > 0$;
5. If $0 < x < y$, then $0 < 1/y < 1/x$.

Proof.

1. If $x > 0$, then $0 = -x + x > -x + 0$, so that $-x < 0$. If $x < 0$, then $0 = -x + x < -x + 0$, so that $-x > 0$.
2. Since $z > y$, we have $z - y > y - y = 0$, hence $x(z - y) > 0$, and therefore

$$xz = x(z - y) + xy > 0 + xy = xy.$$

3. By (1)(2) and Proposition 1.3(3),

$$-[x(z - y)] = (-x)(z - y) > 0,$$

so that $x(z - y) < 0$, hence $xz < xy$.

4. If $x > 0$, by definition we have $x^2 > 0$; if $x < 0$, then $-x > 0$ and hence $(-x)^2 > 0$. By Proposition 1.3(4) we have $(-x)^2 = x^2$.
5. If $y > 0$ and $v \leq 0$, then $yv \leq 0$. But $y \cdot (1/y) = 1 > 0$. Hence, $1/y > 0$. Analogously, $1/x > 0$. By multiplying both sides of the inequality $x < y$ by $(1/x)(1/y)$, we obtain $1/y < 1/x$.

□

Theorem 1.2. *There exists an ordered field \mathbb{R} which has the least-upper-bound property. Moreover, \mathbb{R} contains \mathbb{Q} as a subfield.*

Proof. Omitted.

□

Theorem 1.3.

1. *Archimedean property:* If $x, y \in \mathbb{R}$, and $x > 0$, then there is a positive integer n such that $nx > y$.
2. *Density of \mathbb{Q} :* If $x, y \in \mathbb{R}$, and $x < y$, then there exists a $p \in \mathbb{Q}$ such that $x < p < y$.

Proof.

1. Let $A = \{nx : n \in \mathbb{N}^+\}$. If false, then y would be an upper bound of A . Then A has a least upper bound in \mathbb{R} , denote $\alpha = \sup A$. Since $x > 0$, $\alpha - x < \alpha$, and $\alpha - x$ is not an upper bound of A . Hence, $\alpha - x < mx$ for some $m \in \mathbb{N}^+$. But then $\alpha < (m + 1)x$, which contradicts the fact that α is an upper bound of A .
2. Since $x < y$, we have $y - x > 0$, and (1) guarantees a positive number n such that

$$n(y - x) > 1.$$

Apply (1) again and we obtain positive integers m_1 and m_2 such that $m_1 > nx, m_2 > -nx$. Then

$$-m_2 < nx < m_1.$$

Hence, there is an integer m (with $-m_2 \leq m \leq m_1$) such that

$$m - 1 \leq nx < m.$$

Combining these inequalities, we have

$$nx < m \leq nx + 1 < ny.$$

Since $n > 0$, it follows that

$$x < \frac{m}{n} < y$$

where $p = m/n \in \mathbb{Q}$.

□

Theorem 1.4. For every real number $x > 0$ and every integer $n > 0$, there is one and only one real number y such that $y^n = x$.

Proof. Omitted.

□

Definition 1.7 (Extended Real Number System). The **extended real number system** consists of the real field \mathbb{R} and two symbols $+\infty$ and $-\infty$. We preserve the original order in \mathbb{R} and define $-\infty < x < +\infty$ for every $x \in \mathbb{R}$.

The extended real number system is not a field, but it is customary to make the following conventions:

1. If x is real, then

$$x + \infty = +\infty, x - \infty = -\infty, \frac{x}{+\infty} = \frac{x}{-\infty} = 0.$$

2. If $x > 0$, then $x \cdot (+\infty) = +\infty, x \cdot (-\infty) = -\infty$;

3. If $x < 0$, then $x \cdot (+\infty) = -\infty, x \cdot (-\infty) = +\infty$.

1.3 Complex Field

Definition 1.8 (Complex Number). A **complex number** is an ordered pair (a, b) of real numbers. Here ‘ordered’ means that (a, b) and (b, a) are distinct if $a \neq b$.

Let $x = (a, b), y = (c, d)$. We define

$$x + y = (a + c, b + d),$$

$$xy = (ac - bd, ad + bc).$$

Theorem 1.5. These definitions of addition and multiplication turn the set of all complex numbers into a field, with $(0, 0)$ and $(1, 0)$ in the role of 0 and 1.

Proof. Let $x = (a, b), y = (c, d), z = (e, f)$ be any complex numbers. We verify axioms one by one.

1. Axioms for addition:

(a) Closure: trivial.

(b) Commutative law: $x + y = (a + c, b + d) = (c + a, d + b) = y + x$.

(c) Associative law: $(x + y) + z = (a + c, b + d) + (e, f) = (a + c + e, b + d + f) = (a, b) + (c + e, d + f) = x + (y + z)$.

(d) Zero element: $x + 0 = (a, b) + (0, 0) = (a, b) = x$.

(e) Inverse element: put $-x = (-a, -b)$. Then $x + (-x) = (0, 0) = 0$.

2. Axioms for multiplication:

(a) Closure: trivial.

(b) Commutative law: $xy = (ac - bd, ad + bc) = (ca - db, da + cb) = yx$.

(c) Associative law:

$$\begin{aligned} (xy)z &= (ac - bd, ad + bc)(e, f) \\ &= (ace - bde - adf - bcf, acf - bdf + ade + bce) \\ &= (a, b)(ce - df, cf + de) = x(yz). \end{aligned}$$

(d) Unit element: $1x = (1, 0)(a, b) = (a, b) = x$.

(e) Inverse element: If $x \neq 0$ then $(a, b) \neq (0, 0)$, which means at least one of the real numbers a, b is different from 0. Hence, $a^2 + b^2 > 0$ by Proposition 1.4(4). Define

$$\frac{1}{x} = \left(\frac{a}{a^2 + b^2}, \frac{-b}{a^2 + b^2} \right).$$

Then

$$x \cdot \frac{1}{x} = (a, b) \left(\frac{a}{a^2 + b^2}, \frac{-b}{a^2 + b^2} \right) = (1, 0) = 1.$$

3. Distributive law:

$$\begin{aligned} x(y + z) &= (a, b)(c + e, d + f) \\ &= (ac + ae - bd - bf, ad + af + bc + be) \\ &= (ac - bd, ad + bc) + (ae - bf, af + be) \\ &= xy + xz. \end{aligned}$$

□

Theorem 1.6. For any real numbers a and b , we have

$$(a, 0) + (b, 0) = (a + b, 0), (a, 0)(b, 0) = (ab, 0).$$

Proof. Trivial. □

Definition 1.9. $i = (0, 1)$.

Theorem 1.7. $i^2 = -1$.

Proof. $i^2 = (0, 1)(0, 1) = (-1, 0) = -1$. □

Theorem 1.8. If a, b are real, then $(a, b) = a + bi$.

Proof. $a + bi = (a, 0) + (b, 0)(0, 1) = (a, 0) + (0, b) = (a, b)$. □

Definition 1.10 (Conjugate, Real Part, Imaginary Part). If a, b are real and $z = a + bi$, then the complex number $\bar{z} = a - bi$ is called the **conjugate** of z . The numbers a and b are the **real part** and the **imaginary part** of z , respectively. We write $a = \text{Re}(z), b = \text{Im}(z)$.

Theorem 1.9. If z and w are complex, then

1. $\overline{z + w} = \bar{z} + \bar{w}$;
2. $\overline{z\bar{w}} = \bar{z} \cdot \bar{\bar{w}}$;
3. $z + \bar{z} = 2\text{Re}(z), z - \bar{z} = 2i\text{Im}(z)$;
4. $z\bar{z}$ is real and positive (except when $z = 0$).

Proof. Trivial. □

Definition 1.11 (Absolute Value). If z is a complex number, its absolute value $|z|$ is the non-negative square root of $z\bar{z}$, that is, $|z| = (z\bar{z})^{1/2}$.

Theorem 1.10. Let z and w be complex numbers. Then

1. $|z| > 0$ unless $z = 0$. $|0| = 0$;
2. $|\bar{z}| = |z|$;
3. $|zw| = |z||w|$;
4. $|\text{Re}(z)| \leq |z|$;
5. $|z + w| \leq |z| + |w|$.

Proof.

1. Trivial.
2. Trivial.
3. Let $z = a + bi, w = c + di$ with a, b, c, d real. Then

$$|zw|^2 = (ac - bd)^2 + (ad + bc)^2 = (a^2 + b^2)(c^2 + d^2) = |z|^2|w|^2$$

which means $|zw|^2 = (|z||w|)^2$. Then (3) follows from the uniqueness assertion of Theorem 1.4.

4. Trivial.
5. Note that $\bar{z}w$ is the conjugate of $z\bar{w}$, so that $\bar{z}w + z\bar{w} = 2\text{Re}(z\bar{w})$. Hence

$$\begin{aligned} |z + w|^2 &= (z + w)(\bar{z} + \bar{w}) = z\bar{z} + z\bar{w} + \bar{z}w + \bar{w}w \\ &= |z|^2 + 2\text{Re}(z\bar{w}) + |w|^2 \\ &\leq |z|^2 + 2|z\bar{w}| + |w|^2 \\ &= |z|^2 + 2|z||w| + |w|^2 = (|z| + |w|)^2. \end{aligned}$$

□

Theorem 1.11 (Cauchy-Schwarz Inequality). *If a_1, \dots, a_n and b_1, \dots, b_n are complex numbers, then*

$$\left| \sum_{j=1}^n a_j \bar{b}_j \right|^2 \leq \sum_{j=1}^n |a_j|^2 \sum_{j=1}^n |b_j|^2.$$

Proof. Let $A = \sum |a_j|^2, B = \sum |b_j|^2, C = \sum a_j \bar{b}_j$. If $B = 0$, then $b_1 = \dots = b_n = 0$ and the proof is trivial. Assume $B > 0$. By Theorem 1.9 we have

$$\begin{aligned} \sum |Ba_j - Cb_j|^2 &= \sum (Ba_j - Cb_j)(B\bar{a}_j - \bar{C}\bar{b}_j) \\ &= B^2 \sum |a_j|^2 - B\bar{C} \sum a_j \bar{b}_j - BC \sum \bar{a}_j b_j + |C|^2 \sum |b_j|^2 \\ &= B^2 A - B|C|^2 = B(AB - |C|^2). \end{aligned}$$

Since each term in the first sum is non-negative, we have

$$B(AB - |C|^2) \geq 0.$$

Since $B > 0$, it follows that $AB - |C|^2 \geq 0$ and we complete the proof. □

1.4 Euclidean Spaces

Definition 1.12 (Euclidean Space). *For each positive integer k , let \mathbb{R}^k be the set of all ordered k -tuples*

$$x = (x_1, x_2, \dots, x_k),$$

where x_1, \dots, x_k are real numbers, called the **coordinates** of x . The elements of \mathbb{R}^k are called *points* or *vectors* (especially when $k > 1$). If $y = (y_1, \dots, y_n)$ and α is a real number, put

$$x + y = (x_1 + y_1, \dots, x_k + y_k),$$

$$\alpha x = (\alpha x_1, \dots, \alpha x_k)$$

so that $x + y, \alpha x \in \mathbb{R}^k$. This defines addition of vectors, and multiplication of a vector by a real number (scalar). These two operations satisfy the commutative, associative, and distributive laws, and make \mathbb{R}^k into a **vector space over the real field**. The zero element of \mathbb{R}^k is the point 0 , all of whose coordinates are 0 .

We also define the **inner product** of x and y by

$$x \cdot y = \sum_{i=1}^k x_i y_i,$$

and the norm of x by

$$|x| = (x \cdot x)^{1/2} = \left(\sum_{i=1}^k x_i^2 \right)^{1/2}.$$

The structure now defined is called **Euclidean k -space**.

Theorem 1.12. *Suppose $x, y, z \in \mathbb{R}^k$, and α is real. Then*

1. $|x| \geq 0$;
2. $|x| = 0$ if and only if $x = 0$;
3. $|\alpha x| = |\alpha| |x|$;
4. $|x \cdot y| \leq |x| |y|$;
5. $|x + y| \leq |x| + |y|$;
6. $|x - z| \leq |x - y| + |y - z|$.

Note that (1)(2)(6) allow us to regard \mathbb{R}^k as a metric space.

Proof.

1. Obvious.
2. Obvious.
3. Obvious.
4. It follows from Cauchy-Schwarz inequality (Theorem 1.11).
5. By (4) we have

$$\begin{aligned}|x + y|^2 &= (x + y) \cdot (x + y) \\ &= x \cdot x + 2x \cdot y + y \cdot y \\ &\leq |x|^2 + 2|x||y| + |y|^2 \\ &= (|x| + |y|)^2.\end{aligned}$$

6. It follows from (5) by replacing x by $x - y$, and y by $y - z$.

□

2 Basic Topology

2.1 Metric Spaces

Definition 2.1 (Metric Spaces). A set X whose elements is called **points**, is said to be a **metric space** if with any two points p, q of X , there is associated a real number $d(p, q)$ called the **distance** from p to q , such that

1. $d(p, q) > 0$ if $p \neq q$; $d(p, p) = 0$;
2. $d(p, q) = d(q, p)$;
3. $d(p, q) \leq d(p, r) + d(r, q)$ for any $r \in X$.

Any function d with these three properties is called a **distance function** or **metric**.

In Euclidean spaces \mathbb{R}^k we use Euclidean distance defined by

$$d(x, y) = |x - y| = \sqrt{\sum_{i=1}^k |x_i - y_i|^2}.$$

Definition 2.2 (Segments, Intervals, k -Cells). By the segment (a, b) we mean the set of all real numbers x such that $a < x < b$; by the interval $[a, b]$ we mean the set of all real numbers x such that $a \leq x \leq b$. Generally, if $a_i < b_i$ for $i = 1, \dots, k$, the set $\{x = (x_1, \dots, x_k) \in \mathbb{R}^k : a_i \leq x_i \leq b_i, i = 1, \dots, k\}$ is called a **k -cell**. Thus a 1-cell is an interval, 2-cell is a rectangle, etc.

Definition 2.3 (Ball, Neighborhood). If $x \in X$ and $r > 0$, the **(open) ball** B with center at x and radius r is defined as

$$B_r(x) = \{y \in X : d(x, y) < r\}.$$

Typically we also refer a ball of x as a **neighborhood** of x .

Definition 2.4 (Interior, Boundary, Open Set, Bounded Set). Let X be a metric space

1. A point $x \in X$ is an **interior point** of $E \subseteq X$ if there is a neighborhood $N \subseteq X$ of x such that $N \subseteq E$. The set of all interior points of E is denoted E° .
2. A point $x \in X$ is a **boundary point** of $E \subseteq X$ if every its neighborhood contains point(s) of both E and E^c . The set of all boundary points of E is denoted ∂E .
3. $E \subseteq X$ is **open** if every point of E is an interior point of E ; that is, for every point of E it has a neighborhood $N \subseteq X$ such that $N \subseteq E$.
4. $E \subseteq X$ is **bounded** if there is a real number $R > 0$ and a point $x \in X$ such that $d(x, y) < R$ for all $y \in E$; that is, $E \subseteq B_R(x)$.

Theorem 2.1. Every neighborhood is an open set.

Proof. Consider a neighborhood $E = B_r(p)$ and let q be any point of E . Then there is a positive number h such that $d(p, q) = r - h$. To show that $B_q(h) \subseteq E$, note that for all $s \in B_q(h)$, we have $d(p, s) \leq d(p, q) + d(q, s) < r - h + h = r$, and thus $s \in E$. Therefore, q is an interior point of E , and hence E is open. \square

Theorem 2.2. If $E \subseteq X$ is open, then there exists a family of open balls $\{B_\alpha\}$ such that $E = \cup_\alpha B_\alpha$.

Proof. For any $x \in E$, since E is open, there exists $r > 0$ such that $B_r(x) \subseteq E$. Let the family of open balls be $\{B_x = B_r(x)\}_{x \in X}$. Clearly, $\cup_x B_x \subseteq E$ since each $B_x \subseteq E$, and also $E \subseteq \cup_x B_x$ since all $y \in E$ is contained in B_y . \square

Proposition 2.1. $E \subseteq X$ is open if and only if $E = E^\circ$.

Proof. Clearly $E^\circ \subseteq E$. To show that $E \subseteq E^\circ$, if $x \in E$ and E is open, then x is an interior point of E , and hence $x \in E^\circ$. \square

Definition 2.5 (Limit Point, Isolated Point). A point p is a **limit point** of the set E if every neighborhood of p contains a point $q \neq p$ such that $q \in E$. The set of all limit points of E is denoted E' .

If $p \in E$ but p is not a limit point of E ($p \notin E'$), then p is called an **isolated point** of E .

Theorem 2.3. *If p is a limit point of a set E , then every neighborhood of p contains infinitely many points of E .*

Proof. Suppose not, then there is a neighborhood N of p which contains only a finite number of points of E . Let q_1, \dots, q_n be those distinct points of $N \cap E$, and put

$$r = \min_{1 \leq m \leq n} d(p, q_m).$$

Then we have $r > 0$, and the neighborhood $B_r(p)$ contains no point q of E (such that $q \neq p$), and hence p is not a limit point of E , which has a contradiction. \square

Corollary 2.1. *A finite point set has no limit points.*

Definition 2.6 (Closure). *The **closure** of $E \subseteq X$, denoted by \bar{E} , is the set of all points $x \in X$ such that every its neighborhood intersects E ; that is, for all $r > 0$ we have $B_r(x) \cap E \neq \emptyset$.*

Proposition 2.2. *For any $E \subseteq X$, we have $E' \subseteq \bar{E}$, $\partial E \subseteq \bar{E}$ and $E \subseteq \bar{E}$.*

Proof. It immediately follows from definition of limit points, boundary points and closure. \square

Proposition 2.3. $\bar{E} = E \cup E' = E \cup \partial E$. Hence, we have $\partial E = \bar{E} \setminus E^\circ$.

Proof. By proposition above we have $E \cup E' \subseteq \bar{E}$ and $E \cup \partial E \subseteq \bar{E}$. Suppose $x \in \bar{E}$ but $x \notin E$. Since $x \in \bar{E}$, every neighborhood of x contains a point of E , and it cannot be $x \notin E$, so that $x \in E'$. Since every neighborhood of x also contains $x \in E^c$, so that $x \in \partial E$. \square

Definition 2.7 (Closed Set). *The set $E \subseteq X$ is **closed** if one the following equivalent conditions hold:*

1. $E = \bar{E}$;
2. $E' \subseteq E$;
3. $\partial E \subseteq E$;
4. E^c is open.

Proof. The proposition above has shown the equivalence among (1)(2)(3). Then we only need to show

- (1) \Rightarrow (4): For any $x \in E^c$, we have $x \notin E$ and thus $x \notin \bar{E}$. It means there exists a neighborhood N of x which doesn't intersect E , i.e. $N \subseteq E^c$. Therefore, E^c is open.
- (4) \Rightarrow (1): Clearly $E \subseteq \bar{E}$. To show $\bar{E} \subseteq E$, if $x \notin E$, then $x \in E^c$ which is open. So there exists $r > 0$ such that $B_r(x) \subseteq E^c$, that is, $B_r(x) \cap E = \emptyset$. Hence, $x \notin \bar{E}$ and thus $\bar{E} \subseteq E$.

\square

Example 2.1. *Consider the following subsets of \mathbb{C} (or equivalently, \mathbb{R}^2):*

1. $\{z : |z| < 1\}$ is open, not closed, bounded;
2. $\{z : |z| \leq 1\}$ is not open, closed, bounded;
3. a finite set is not open, closed, bounded;
4. the set of all integers is not open, closed, not bounded;
5. $\{z : z = 1/n, n \in \mathbb{N}^+\}$ is not open, not closed, bounded;
6. The whole set \mathbb{C} is open, closed, not bounded;
7. The segment (a, b) is not open, not closed, bounded.

Theorem 2.4. *Let $\{E_\alpha\}$ be a (finite or infinite) collection of sets. Then*

$$\left(\bigcup_{\alpha} E_{\alpha} \right)^c = \bigcap_{\alpha} E_{\alpha}^c.$$

Proof. Let A and B be the LHS and RHS. If $x \in A$, then $x \notin E_\alpha$ for any α , which means $x \in E_\alpha^c$ for every α , so that $x \in \cap_\alpha E_\alpha^c = B$. Thus $A \subseteq B$.

If $x \in B$, then $x \in E_\alpha^c$ for every α , which means $x \notin E_\alpha$ for any α , so that $x \notin \cup_\alpha E_\alpha$ and hence $x \in (\cup_\alpha E_\alpha)^c = A$. Thus $B \subseteq A$. Therefore, $A = B$. \square

Theorem 2.5.

1. For any collection $\{G_\alpha\}$ of open sets, $\cup_\alpha G_\alpha$ is open;
2. For any collection $\{F_\alpha\}$ of closed sets, $\cap_\alpha F_\alpha$ is closed;
3. For any finite collection G_1, \dots, G_n of open sets, $\cap_{i=1}^n G_i$ is open;
4. For any finite collection F_1, \dots, F_n of closed sets, $\cup_{i=1}^n F_i$ is closed.

Proof.

1. If $x \in \cup_\alpha G_\alpha$, there are some α such that $x \in G_\alpha$. Since G_α is open, there exists a neighborhood N of x such that $N \subseteq G_\alpha$, and thus $N \subseteq \cup_\alpha G_\alpha$. Therefore, $\cup_\alpha G_\alpha$ is open.
2. It comes from (1) by replacing G_α with F_α^c , and using the conclusion of Theorem 2.4.
3. If $x \in \cap_{i=1}^n G_i$, then $x \in G_i$ for every i . Since G_i is open, there exists $r_i > 0$ such that $B_{r_i}(x) \subseteq G_i$. Let $r = \min_{i=1, \dots, n} r_i$ and $r > 0$, we have $B_r(x) \subseteq G_i$ for all i and hence $B_r(x) \subseteq \cap_{i=1}^n G_i$. Therefore, $\cap_{i=1}^n G_i$ is open.
4. It comes from (3) by replacing G_i with F_i^c and using the conclusion of Theorem 2.4. \square

Example 2.2. The following examples show why finiteness in Theorem 2.5(3)(4) is necessary.

1. Suppose $G_n = (-1/n, 1/n)$ for $n = 1, 2, \dots$ which are open subsets of \mathbb{R} . Then $\cap_{i=1}^n G_i = (-1/n, 1/n)$ is open for every n , while $\cap_{i=1}^\infty G_i = \{0\}$ is closed.
2. Suppose $F_n = [-1 + 1/n, 1 - 1/n]$ for $n = 1, 2, \dots$ which are closed subsets of \mathbb{R} . Then $\cup_{i=1}^n F_i = [-1 + 1/n, 1 - 1/n]$ is closed for every n , while $\cap_{i=1}^\infty F_i = (-1, 1)$ is open.

Theorem 2.6. If X is a metric space and $E \subseteq X$, then

1. \bar{E} is closed;
2. If $E \subseteq F$ and F is closed, then $\bar{E} \subseteq F$;
3. $\bar{E} = \cap_{E \subseteq F, F \text{ closed}} F$; that is, \bar{E} is the smallest closed set in X containing E .

Proof.

1. If $x \notin \bar{E}$, then there exists a neighborhood N of x such that $N \cap E = \emptyset$. It means \bar{E}^c is open and hence \bar{E} is closed.
2. For any $x \in \bar{E}$ and any its neighborhood B , B contains point in E , and thus also contains point in F . Hence, $x \in \bar{F} = F$.
3. From (2) we have $\bar{E} \subseteq \cap F$. On the other hand, \bar{E} itself is closed and $E \subseteq \bar{E}$, so that $\cap F \subseteq \bar{E}$. \square

Definition 2.8 (Relative Open/Closed). Suppose (X, d) is a metric space and $Y \subseteq X$. $E \subseteq Y$ is **open/closed relative to Y** if E is open/closed in the metric space (Y, d) .

Theorem 2.7. Suppose $Y \subseteq X$. A subset E of Y is open relative to Y if and only if $E = Y \cap G$ for some open subset G of X .

Proof. If E is open relative to Y , then for all $x \in E$, there exists $r > 0$ such that $d(x, y) < r, y \in Y$ implies $y \in E$, which means $[B_r(x)]_Y \equiv \{y \in Y : d(x, y) < r\} \subseteq E$. Let $G = \cup_{x \in E} B_r(x)$, then G is open in X and we have $G \cap Y = E$ since $[B_r(x)]_Y = B_r(x) \cap Y$ for all $x \in E$.

Suppose $E = Y \cap G$ where $G \subseteq X$ is open. Then for all $x \in E$, there exists $r > 0$ such that $B_r(x) \subseteq G$, so that $[B_r(x)]_Y = B_r(x) \cap Y \subseteq G \cap Y = E$. Therefore, E is open relative to Y . \square

Corollary 2.2. Suppose $Y \subseteq X$. A subset E of Y is closed relative to Y if and only if $E = Y \cap F$ for some closed subset F of X .

Corollary 2.3. If $E \subseteq Y \subseteq X$ is closed relative to Y , then E is closed relative to X if and only if $\bar{E} \subseteq Y$.

Theorem 2.8. Let E be a non-empty set of real numbers which is bounded above. Let $y = \sup E$. Then $y \in \bar{E}$. Hence, $y \in E$ if E is closed.

Proof. (CONTINUE) \square

2.2 Connected Sets

Definition 2.9 (Separate Sets, Connected Sets). Two subsets A, B of a metric space X are **separated** if both $A \cap \bar{B}$ and $\bar{A} \cap B$ are empty, that is, if no point of A lies in the closure of B , and no point of B lies in the closure of A .

A set $E \subseteq X$ is **connected** if E is not a union of two non-empty separated sets.

Proposition 2.4. If $A \subseteq X$ is both closed and open, and $A \neq \emptyset, X$, then X is disconnected.

Proof. It is because $X = A \cup A^c$, and $\bar{A} = A, \bar{A}^c = A^c$, and the fact that $A \cap A^c = \emptyset$. Note that A^c is non-empty since $A \neq X$. \square

Lemma 2.1. If A, B are separated, and $E \subseteq A \cup B$ is connected, then we have either $E \subseteq A$ or $E \subseteq B$ (but not both).

Proof. Note that $E = (E \cap A) \cup (E \cap B)$, and $E \cap A$ and $E \cap B$ are separated. If both $E \cap A$ and $E \cap B$ are non-empty, then E is disconnected, where has a contradiction. \square

Proposition 2.5. If E, F are connected and $E \cap F \neq \emptyset$, then $E \cup F$ is connected.

Proof. Suppose $E \cup F$ is disconnected, then we have $E \cup F = A \cup B$ where A, B are non-empty and separated. By lemma above, we have either $E \subseteq A$ or $E \subseteq B$, and either $F \subseteq A$ or $F \subseteq B$. If E, F are both subsets of A or B , then B or A will be empty and has a contradiction; if E and F belong to A and B respectively, then we have $E \cap F \subseteq A \cap B = \emptyset$ where also has a contradiction. \square

Definition 2.10 (Connected Component). A **connected component** A of metric space X is a maximal connected subset of X such that (1) A is connected; (2) If $A \subseteq B \subseteq X$ and B is connected, then $A = B$.

Proposition 2.6. Connected components of X partition X ; that is, they are pairwise disjoint, and their union is X .

Proof. (CONTINUE) \square

2.3 Compact Sets

Definition 2.11 (Open Cover). An **open cover** of a set E in a metric space X is a collection $\{G_\alpha\}$ of open subsets of X such that $E \subseteq \cup_\alpha G_\alpha$.

Definition 2.12 (Compact Sets). A subset K of a metric space X is **compact** if every open cover of K contains a finite subcover. That is, for any open cover $\{G_\alpha\}$ of K , there are finitely many indices $\alpha_1, \dots, \alpha_n$ such that $K \subseteq G_{\alpha_1} \cup \dots \cup G_{\alpha_n}$.

Theorem 2.9. A compact set K in a metric space X is closed and bounded.

Proof. To show that K is closed, we only need to show that K^c is open. If $x \notin K$, then for any $y \in K$, suppose $d(x, y) = r_y > 0$. By triangle inequality we have $B_{r_y/3}(x) \cap B_{r_y/3}(y) = \emptyset$. Then we can construct an open cover of K by $\{B_{r_y/3}(y)\}_{y \in K}$. Since K is compact, it has finite subcover $\{B_{r_{y_n}/3}(y_n)\}_{n=1}^N$. Let $r = \min_{1 \leq n \leq N} r_{y_n} > 0$, then we have $B_r(x) \subseteq K^c$. Therefore, K^c is open.

To show that K is bounded, choose any $x \in X$ and construct an open cover of K by $\{B_r(x)\}_{r>0}$. Since K is compact, it has a finite subcover $\{B_{r_n}(x)\}_{n=1}^N$. Let $R = \max_{1 \leq n \leq N} r_n$ and we have $K \subseteq B_R(x)$. \square

Theorem 2.10. Let $K \subseteq X$ be compact and $E \subseteq K$ be infinite. Then E has limit point in K .

Proof. Suppose E has no limit point in K , then every $x \in K$ has a neighborhood B_x such that $B_x \cap E$ has at most one point. The collection $\{B_x\}_{x \in K}$ is an open cover of K , and by the compactness of K , it has a finite subcover of K (and also of E), but they only contain finite points of E , where has a contradiction. \square

Theorem 2.11. Suppose $K \subseteq Y \subseteq X$. Then K is compact relative to X if and only if K is compact relative to Y .

Proof. If K is compact relative to Y , let $\{V_\alpha\}_{\alpha \in A}$ be an open cover of K and let $U_\alpha = V_\alpha \cap Y$ for every $\alpha \in A$. Then $\{U_\alpha\}_{\alpha \in A}$ is also an open cover of K , and by compactness of K (relative to Y) it has a finite subcover $\{U_i\}_{i=1}^n$. Since $K \subseteq \bigcup_{i=1}^n U_i \subseteq \bigcup_{i=1}^n V_i$, $\{V_i\}_{i=1}^n$ is also a finite subcover of K , and thus K is compact relative to X . \square

Theorem 2.12. *If $E \subseteq K$ is closed and K is compact, then E is compact.*

Proof. Let $\{G_\alpha\}_{\alpha \in A}$ be an open cover of E , then $\{G_\alpha\}_{\alpha \in A} \cup \{E^c\}$ is an open cover of K . By the compactness of K , it has a finite subcover $\{G_i\}_{i=1}^n \cup \{E^c\}$. Hence, $\{G_i\}_{i=1}^n$ is a finite subcover of $\{G_\alpha\}_{\alpha \in A}$ containing E . Therefore, E is compact. \square

Definition 2.13 (Finite Intersection Property). *A family of subsets $\{E_\alpha\}_{\alpha \in A}$ of X has **finite intersection property (FIP)** if the intersection of any of its finite subcover $\{E_i\}_{i=1}^n$ is non-empty.*

Theorem 2.13. *K is compact if and only if for all families of closed sets $\{E_\alpha \subseteq K\}_{\alpha \in A}$ with FIP, their intersection $\bigcap_{\alpha \in A} E_\alpha$ is non-empty.*

Proof. Suppose K is compact, and there exists $\{E_\alpha\}_{\alpha \in A}$ which are closed sets of K with FIP, and $\bigcap_{\alpha \in A} E_\alpha = \emptyset$. Then take $G_\alpha = E_\alpha^c$, and $\{G_\alpha\}_{\alpha \in A}$ becomes an open cover of K since $\bigcup_{\alpha \in A} G_\alpha \supseteq K$ (which follows $\bigcap_{\alpha \in A} E_\alpha = \emptyset$). However, $\{E_\alpha\}_{\alpha \in A}$ has FIP implies $\bigcap_{\alpha \in B} E_\alpha$ is non-empty for any finite subset $B \subseteq A$, that is, $\bigcup_{\alpha \in B} G_\alpha$ cannot cover K for any finite subset $B \subseteq A$, so that $\{G_\alpha\}_{\alpha \in A}$ has no finite subcover, where has a contradiction.

Suppose for all families of closed subsets $\{E_\alpha\}_{\alpha \in A}$ of K with FIP, their intersection is non-empty. If K is not compact, there exists an open cover $\{G_\alpha\}_{\alpha \in A}$ with no finite subcover. Take $E_\alpha = K \setminus G_\alpha$, then $\{E_\alpha\}_{\alpha \in A}$ are closed subsets of K with FIP and non-empty intersection.

(CONTINUE) \square

Corollary 2.4. *If $\{K_\alpha\}_{\alpha \in A}$ is a family of compact subsets of X , and it has FIP, then their intersection $\bigcap_{\alpha \in A} K_\alpha$ is non-empty.*

Proof. Choose a member K_0 from $\{K_\alpha\}_{\alpha \in A}$ and let $G_\alpha = K_\alpha^c$. If there is no point of K_0 belongs to every K_α , then the sets $\{G_\alpha\}_{\alpha \in A}$ is an open cover of K_0 . By the compactness of K_0 , it has a finite subcover $\{G_i\}_{i=1}^n$ such that $K_0 \subseteq \bigcup_{i=1}^n G_i$. However, it implies that $K_0 \cap (\bigcap_{i=1}^n K_i) = K_0 \cap (\bigcup_{i=1}^n G_i)^c$ is empty, which contradicts the FIP. \square

Corollary 2.5. *If $\{K_n\}$ is a sequence of non-empty compact sets such that $K_n \supset K_{n+1}$, then $\bigcap_{n=1}^\infty K_n$ is not empty.*

Theorem 2.14. *Suppose $a < b$ are real numbers. Then the interval $[a, b] \subseteq \mathbb{R}$ is compact.*

Proof. Suppose not, then there is an open cover $\{G_\alpha\}_{\alpha \in A}$ of $[a, b]$ with no finite subcover. Take $c = (a + b)/2$ be the center point, then either $[a, c]$ or $[c, b]$ has no finite subcover and denote it $[a_1, b_1]$. Repeating this procedure we could define a sequence of intervals $\{[a_n, b_n]\}_{n=1}^\infty$ such that

1. $[a_n, b_n] \supseteq [a_{n+1}, b_{n+1}]$;
2. $|b_n - a_n| = 2^{-n}|b - a|$;
3. $[a_n, b_n]$ cannot be covered by any finite elements of $\{G_\alpha\}_{\alpha \in A}$.

Let $x = \sup_n a_n$; it exists since $a_n \leq x \leq b$ for all n . Then we have $[a_n, b_n] \subseteq B_{2^{1-n}|b-a|}(x)$ for all n . Since open sets $\{G_\alpha\}_{\alpha \in A}$ covers x , there exists $r > 0$ such that $B_r(x) \subseteq G_\alpha$ for some $\alpha \in A$. Hence, when n is great enough such that $2^{1-n}|b - a| < r$, we have $[a_n, b_n] \subseteq B_{2^{1-n}|b-a|}(x) \subseteq B_r(x) \subseteq G_\alpha$, where has a contradiction. \square

Theorem 2.15. *Every k -cell $\{(x_1, \dots, x_k) : a_i \leq x_i \leq b_i, i = 1, \dots, k\} \subseteq \mathbb{R}^k$ is compact.*

Proof. Omitted. \square

Theorem 2.16. *For a set $E \subseteq \mathbb{R}^k$ the following three properties are equivalent:*

1. E is closed and bounded;
2. E is compact;

3. Every infinite subset of E has a limit point in E .

The equivalence of (1)(2) is known as the **Heine-Borel Theorem**.

Proof. Theorem 2.9 has shown that (2) \Rightarrow (1), and Theorem 2.10 has shown that (2) \Rightarrow (3). Then we only need to show

1. (1) \Rightarrow (2): Since E is bounded, then it is a subset of k -cell $\{(x_1, \dots, x_k) \in \mathbb{R}^k : -R \leq x_i \leq R, i = 1, \dots, k\}$ for some $R > 0$, which is compact (by Theorem 2.15). Thus E is compact since it is a closed subset of a compact set (Theorem 2.12).
2. (3) \Rightarrow (1): (CONTINUE)

□

Theorem 2.17 (Weierstrass). *Every bounded infinite subset of \mathbb{R}^k has a limit point in \mathbb{R}^k .*

Proof. Since it is bounded, it is a subset of $\{(x_1, \dots, x_k) \in \mathbb{R}^k : -R \leq x_i \leq R, i = 1, \dots, k\}$ for some $R > 0$, which is compact. Then, it has a limit point since it is an infinite subset of a compact set (Theorem 2.10). □

Definition 2.14 (Dense). *In metric space (X, d) , $E \subseteq X$ is **dense** in X if $\bar{E} = X$.*

For example, \mathbb{Q} is dense in \mathbb{R} .

3 Numerical Sequences and Series

3.1 Convergence

Definition 3.1 (Sequence). A **sequence** in X is a mapping $p : \mathbb{N} \rightarrow X$, denoted by (p_n) or (p_0, p_1, \dots) .

Definition 3.2 (Convergence). The sequence (p_n) in metric space (X, d) **converges** to $p \in X$, if for all $\varepsilon > 0$, there exists N such that for all $n \geq N$, we have $d(p_n, p) < \varepsilon$. We write $p_n \rightarrow p$ or $\lim_{n \rightarrow \infty} p_n = p$.

Sequence (p_n) is **divergent** if it is not convergent.

Note that the convergence of a sequence may depend on the space it belongs to. For example, the sequence $(1, 1.4, 1.41, 1.414, \dots)$ (the first decimals of $\sqrt{2}$) converges to $\sqrt{2}$ in \mathbb{R} , but divergent in \mathbb{Q} .

Proposition 3.1. $x_n \rightarrow x$ if and only if every neighborhood of x contains all but finitely many x_n .

Theorem 3.1. If $E \subseteq X$ and p is a limit point of E , then there is a sequence (p_n) in E such that $p_n \rightarrow p$.

Proof. Since p is a limit point of E , for all $n = 1, 2, \dots$ there exists a point $p_n \in E$ such that $d(p_n, p) < 1/n$. Then it could be shown that such sequence (p_n) converges to p : for all $\varepsilon > 0$, choose N so that $N\varepsilon > 1$, then $d(p_n, p) < \varepsilon$ for all $n \geq N$. \square

Theorem 3.2. $E \subseteq X$ is closed if and only if for every sequence (x_n) in E such that $x_n \rightarrow x$, we have $x \in E$.

Proof. If (x_n) in E converges to $x \in E$, then every neighborhood of x contains some x_n , which means $x \in \bar{E}$. Since E is closed, we have $x \in E = \bar{E}$.

Conversely, for all $x \in \bar{E}$, choose $x_n \in B_{1/n}(x) \cap E$ for all $n = 1, 2, \dots$ (such x_n exists since x is a limit point of E) and we have $x_n \rightarrow x$. By $x \in E$ we have $\bar{E} \subseteq E$, which means $E = \bar{E}$ and thus E is closed. \square

Theorem 3.3. The limit of a sequence is unique (if exists).

Proof. Suppose $x_n \rightarrow p$ and $x_n \rightarrow q$; we only need to show that $d(p, q) = 0$. The convergence means that for all $\varepsilon > 0$, there exists N, M such that for all $n \geq N$ we have $d(x_n, p) < \varepsilon/2$, and for all $n \geq M$ we have $d(x_n, q) < \varepsilon/2$. Hence, for all $n \geq \max\{N, M\}$, we have $d(p, q) \leq d(x_n, p) + d(x_n, q) < \varepsilon$. Since $\varepsilon > 0$ is arbitrary, we must have $d(p, q) = 0$. \square

Definition 3.3 (Boundedness). A sequence (x_n) is **bounded** if its range $\{x_n : n \in \mathbb{N}\}$ is bounded.

Theorem 3.4. Any convergent sequence is bounded.

Proof. Suppose $x_n \rightarrow x$, then there exists N such that for all $n \geq N$ we have $d(x_n, x) < 1$. Hence,

$$\sup d(x_n, x) \leq \sup\{d(x_0, x), d(x_1, x), \dots, d(x_N, x), 1\} < \infty$$

since the set in the equation above is finite. \square

Proposition 3.2. If $(a_n), (b_n)$ are sequences such that (1) $a_n = b_n$ for all but finitely many n , or (2) $(b_n) = (a_N, a_{N+1}, \dots)$ for some N , then either they both diverge, or they have the same limit.

3.2 Cauchy Convergence

Definition 3.4 (Cauchy Convergence). The sequence (x_n) is **Cauchy** if for all $\varepsilon > 0$, there exists N such that for all $n, m > N$, we have $d(x_n, x_m) < \varepsilon$.

Theorem 3.5. Every convergent sequence is Cauchy.

Definition 3.5 (Cauchy Completeness). A space (X, d) is **Cauchy complete** if every Cauchy sequence in X converges in X .

Theorem 3.6. Compact sets are Cauchy complete.

Proof. Suppose (x_n) is Cauchy in a compact set K . If there exists $y \in K$ such that $x_n = y$ for infinitely many n , then $x_n \rightarrow y$ since (x_n) is Cauchy.

If not, let $E_N = \{x_n : n \geq N\}$ for $N = 1, 2, \dots$. Then we know that every E_N is infinite, $\bar{E}_N \subseteq K$ (closed set of compact set is also compact), and clearly has FIP. Hence there exists $x \in \bigcap_N \bar{E}_N$.

To show that $x_n \rightarrow x$, for all $\varepsilon > 0$, choose M such that for all $n, m > M$ we have $d(x_n, x_m) < \varepsilon/2$. Meanwhile, $x \in \bar{E}_M$ implies that the neighborhood $B_{\varepsilon/2}(x)$ contains some x_n . Hence, $d(x, x_m) < \varepsilon$ for all $m > M$ and thus $x_n \rightarrow x$. \square

Corollary 3.1. \mathbb{R}^n is complete.

Proof. (CONTINUE) \square

Definition 3.6 (Cauchy Completion). If $X \subseteq Y$ where X is a metric space, Y is Cauchy complete, and X is dense in Y , then we call Y the **Cauchy completion** of X .

Theorem 3.7. For metric space (X, d) , its Cauchy completion always exists and unique up to isomorphism.

3.3 Subsequence

Definition 3.7 (Subsequence). Let (x_n) be a sequence in metric space (X, d) , and (n_k) be a strictly increasing sequence in \mathbb{N} . Then $(x_{n_k})_{k \in \mathbb{N}}$ is a **subsequence** of (x_n) . If $x_{n_k} \rightarrow y$ as $k \rightarrow \infty$, then we call y a **subsequential limit** of (x_n) .

Proposition 3.3. $x_n \rightarrow x$ if and only if every subsequence of (x_n) converges to x .

Proof. Since $n_k \rightarrow \infty$ as $k \rightarrow \infty$, we have $x_n \rightarrow x \Rightarrow x_{n_k} \rightarrow x$; If $x_n \nrightarrow x$, then for some $\varepsilon > 0$, we can construct a subsequence (x_{n_k}) by letting $k \in A = \{n \in \mathbb{N} : x_n \notin B_\varepsilon(x)\}$ which is infinite, and then $x_{n_k} \nrightarrow x$. \square

Proposition 3.4. If (x_n) is Cauchy, and some subsequences (x_{n_k}) converge to x , then $x_n \rightarrow x$.

Proof. For any $\varepsilon > 0$, since (x_n) is Cauchy, there exists N such that for all $n, m > N$, we have $d(x_n, x_m) < \varepsilon/2$. Take $n_k > N$ such that $d(x_{n_k}, x) < \varepsilon/2$, then for all $m > N$, we have $d(x, x_m) < d(x_{n_k}, x_m) + d(x_{n_k}, x) < \varepsilon/2 + \varepsilon/2 = \varepsilon$. \square

Theorem 3.8. If x is a limit point of the range of (x_n) , then x is also a subsequential limit of (x_n) .

Proof. We can construct such a subsequence by taking $x_{n_k} \in B_{1/k}(x)$ for every $k = 1, 2, \dots$, while making sure that $n_k > n_{k-1}$. Such subsequence exists since every neighborhood of x contains some points in (x_n) . \square

However, the converse doesn't hold. A counter-example is $(1, 1/2, 1, 1/3, 1, 1/4, \dots)$ which has no limit, 2 subsequential limits (0 and 1), but only 1 limit point (0).

Corollary 3.2. If (x_n) is a sequence in a compact space K , then (x_k) has a convergent subsequence.

Proof. If the range of (x_n) is finite, then clearly it has convergent (and indeed constant) subsequence and thus subsequential limit. If the range is infinite, we can show it by the fact that an infinite subset of a compact set has limit point (Theorem 2.10), and thus has subsequential limit by the theorem above. \square

Theorem 3.9 (Bolzano-Weierstrass). Any bounded sequence in \mathbb{R}^n has convergent subsequences.

Proof. It follows from the corollary above, and the fact that a bounded subset in \mathbb{R}^n lies in a compact subset of \mathbb{R}^n (Heine-Borel, Theorem 2.16). \square

Theorem 3.10. For any sequence (x_n) , the set of all subsequential limits is closed.

Proof. Suppose (x_n) is a sequence, $\{x_{n_k^l} = (x_{n_0^l}, x_{n_1^l}, x_{n_2^l}, \dots)\}_{l \in \mathbb{N}}$ is an infinite set of subsequences of (x_n) , where $x_{n_k^l} \rightarrow y_l (k \rightarrow \infty)$ and $y_l \rightarrow y (l \rightarrow \infty)$. Then we only need to show that y is also a sequential limit of (x_n) .

Choose $n_0 = n_0^0$; given n_{l-1} , take $n_l \in \{n_k^l\}_{k \in \mathbb{N}}$ such that $n_l > n_{l-1}$, and $d(x_{n_l}, y_l) < 2^{-l}$. By triangle inequality, we have

$$d(x_{n_l}, y) \leq d(x_{n_l}, y_l) + d(y_l, y) < 2^{-l} + d(y_l, y).$$

For all $\varepsilon > 0$, there exists N such that $2^{-N} < \varepsilon/2$ and $d(y_l, y) < \varepsilon/2$ for all $l > N$, hence $d(x_{n_l}, y) < \varepsilon$ for all $l > N$. Therefore, $x_{n_l} \rightarrow y$ as $l \rightarrow \infty$ and y is a sequential limit of (x_n) . \square

Definition 3.8 (Monotonicity). Let (a_n) be a sequence in \mathbb{R} . If $a_n \leq a_{n+1}$ for all n , we call (a_n) **(monotone) increasing**; if $a_n \geq a_{n+1}$ for all n , we call (a_n) **(monotone) decreasing**. (a_n) is **monotone** if it is either increasing or decreasing.

Theorem 3.11. A monotone sequence has a limit if and only if it is bounded.

Proof. Suppose (a_n) is increasing and bounded. Let $\alpha = \sup \text{range}(a_n) \in \mathbb{R}$. For all $\varepsilon > 0$, there exists N such that $a_N > \alpha - \varepsilon$, and $\alpha - \varepsilon < a_n \leq \alpha$ for all $n > N$, hence $a_n \rightarrow \alpha$. The case of decreasing bounded sequences is analogous. The converse is shown in Theorem 3.4. \square

Definition 3.9 (Tend to Infinity). For a sequence (x_n) in \mathbb{R} , we say $x_n \rightarrow \infty$ if for all R , there exists N such that for all $n > N$, we have $x_n \geq R$; we say $x_n \rightarrow -\infty$ if $x_n \leq -R$.

Note that a sequence is not bounded if and only if it has some subsequence that tends to infinity.

3.4 Limit Superior and Inferior

Definition 3.10 (Limit Superior/Inferior). For a sequence (x_n) in \mathbb{R} , define its **limit superior** and **limit inferior** as

$$\begin{aligned} \limsup x_n &= \lim_{n \rightarrow \infty} \sup E_n \\ \liminf x_n &= \lim_{n \rightarrow \infty} \inf E_n \end{aligned}$$

where $E_N = \{x_n : n \geq N\}$ is the range of (x_n) excluding first N terms.

Usually we say $\limsup x_n = \infty$ or $\liminf x_n = -\infty$ if (x_n) is not bounded above or below.

Note that

1. the sequence $(\sup E_n)$ is decreasing, while $(\inf E_n)$ is increasing. Since the values are extended to extended reals $\mathbb{R} \cup \{\pm\infty\}$, the limit superior and inferior always exist.
2. if (x_n) converges, then we have $\limsup x_n = \liminf x_n = \lim x_n$.

Proposition 3.5. $\limsup x_n$ (if finite) is the least number α such that for all $\varepsilon > 0$, there exists N such that for all $n > N$, we have $x_n < \alpha + \varepsilon$.

Theorem 3.12. Let (x_n) be a sequence and y a subsequential limit of (x_n) . Then we have

$$\liminf x_n \leq y \leq \limsup x_n.$$

Proof. Suppose $y \leq \limsup x_n$ doesn't hold, so that $y - \limsup x_n = \varepsilon > 0$. Since $\limsup x_n = \lim_{N \rightarrow \infty} \sup\{x_n : n > N\}$, there exists N such that $\sup\{x_n : n > N\} < \limsup x_n + \varepsilon/2 = y - \varepsilon/2$. Hence, $B_{\varepsilon/2}(y)$ doesn't contain any x_n such that $n > N$, which means y cannot be a subsequential limit. Analogously we can show that $y \geq \liminf x_n$. \square

Corollary 3.3. For any sequence (x_n) , we have $\liminf x_n \leq \limsup x_n$.

Proof. If (x_n) is bounded, then by Bolzano-Weierstrass theorem, it has subsequential limit y , then by theorem above we complete the proof. If (x_n) is not bounded above(below), then there exists some subsequence tends to $+\infty(-\infty)$, so that $\limsup x_n = +\infty(\liminf x_n = -\infty)$ and we complete the proof. \square

3.5 Series

Definition 3.11 (Series). Given sequence (x_n) in \mathbb{R}^d , for $N \leq M \in \mathbb{N}$, denote

$$\sum_{n=N}^M x_n = x_N + x_{N+1} + \dots + x_M.$$

We call $S_N = \sum_{n=0}^N x_n$ the **partial sum** of (x_n) , and we associate a sequence (S_n) with (x_n) .

We call $\sum_{n=0}^{\infty} x_n$ a **series**; we say $\sum_{n=0}^{\infty} x_n = \lim_{n \rightarrow \infty} S_n$ if (S_n) converges; call $\sum_{n=0}^{\infty} x_n$ diverges if (S_n) diverges.

Recall that \mathbb{R}^d is Cauchy complete; so that $\sum_{n=0}^{\infty} x_n$ converges if and only if (S_n) is Cauchy.

Theorem 3.13. If the series $\sum x_n$ converges, then $x_n \rightarrow 0$.

Proof. Since (s_n) is Cauchy, for all $\varepsilon > 0$ there exists N such that for all $n > N$, we have

$$|x_{n+1}| = |S_{n+1} - S_n| \leq \varepsilon$$

so that $x_n \rightarrow 0$. □

Note that the converse does not hold. A typical counter-example is that the harmonic series $1 + 1/2 + 1/3 + \dots$ diverges.

Theorem 3.14 (Comparison Test).

1. If $|a_n| \leq c_n$ for all $n \geq N_0$, and $\sum c_n$ converges, then $\sum a_n$ converges.
2. If $a_n \geq d_n \geq 0$ for all $n \geq N_0$, and $\sum d_n$ diverges, then $\sum a_n$ diverges.

Proof. Suppose $\sum c_n$ converges, so that for all $\varepsilon > 0$, there exists $N \geq N_0$ such that for all $m \geq n \geq N$ we have $\sum_{k=n}^m c_k \leq \varepsilon$ by Cauchy criterion. Then (1) follows from

$$\left| \sum_{k=n}^m a_k \right| \leq \sum_{k=n}^m |a_k| \leq \sum_{k=n}^m c_k \leq \varepsilon.$$

(2) follows from (1), for if $\sum a_n$ converges, $\sum d_n$ must converge. □

Theorem 3.15 (Root Test). Given series $\sum a_n$, let $\alpha = \limsup \sqrt[n]{|a_n|}$. Then

1. If $\alpha < 1$, $\sum a_n$ converges;
2. If $\alpha > 1$, $\sum a_n$ diverges;
3. If $\alpha = 1$, this test cannot tell if $\sum a_n$ converges or diverges.

Proof.

1. If $\alpha < 1$, there exists N such that for all $n > N$, we have $\sqrt[n]{|a_n|} < \beta$, where $\alpha < \beta < 1$. Then we have $|a_n| < \beta^n$ for all $n > N$. The series $\sum \beta^n$ converges since $0 < \beta < 1$. Hence, $\sum a_n$ converges by the comparison test.
2. If $\alpha > 1$, there is a sequence (n_k) such that $\sqrt[n_k]{|a_{n_k}|} \rightarrow \alpha$. Hence, $|a_n| > 1$ for infinitely many n , so that $a_n \not\rightarrow 0$ and thus $\sum a_n$ diverges.
3. Consider two series $\sum 1/n$ and $\sum 1/n^2$; for each of them $\alpha = 1$, but the first diverges, the second converges. □

Theorem 3.16 (Ratio Test). Given series $\sum a_n$, it

1. converges if $\limsup |a_{n+1}/a_n| < 1$;
2. diverges if $|a_{n+1}/a_n| \geq 1$ for all $n \geq n_0$.

Proof.

1. If $\limsup |a_{n+1}/a_n| < 1$, then there exists N such that for all $n > N$, we have $|a_{n+1}/a_n| < \beta$ where $\beta < 1$. So that

$$|a_{N+p}| < \beta |a_{N+p-1}| < \dots < \beta^p |a_N|, \forall p = 1, 2, \dots$$

which implies

$$|a_n| < (|a_N|\beta^{-N})\beta^n$$

for all $n > N$. Hence, $\sum a_n$ converges by the comparison test.

2. If $|a_{n+1}| \geq |a_n|$ for all $n \geq n_0$, we have $a_n \not\rightarrow 0$ and thus $\sum a_n$ diverges. □

Theorem 3.17 (Comparison of Root and Ratio Tests). *If the series $\sum_{n=1}^{\infty} a_n$ passes ratio test, then it will also pass root test. Hence, the root test is always better to detect convergent series.*

Proof. Suppose the ratio test shows convergence of $\sum_{n=1}^{\infty} a_n$, that is, $\limsup a_{n+1}/a_n = \lambda < 1$. Then for all $\varepsilon > 0$, there exists N such that for all $n = 1, 2, \dots$, we have $a_{N+n} \leq (\lambda + \varepsilon)^n a_N$. Hence

$$\limsup \sqrt[n]{a_n} \leq \lim_{m \rightarrow \infty} [(\lambda + \varepsilon)^m a_N]^{1/(N+m)} = \lambda + \varepsilon.$$

Therefore, $\limsup \sqrt[n]{a_n} \leq \limsup a_{n+1}/a_n$, and the inequality holds in some cases (shown below). □

Example 3.1. Consider the series $1/2 + 1/3 + 1/2^2 + 1/3^2 + 1/2^3 + 1/3^3 + \dots$. Note that

1. $a_{n+1}/a_n = (2/3)^k$ or $(1/2)(3/2)^k$, so that $\limsup a_{n+1}/a_n = \infty$;
2. $\sqrt[n]{a_n} \approx 1/\sqrt{3}$ or $1/\sqrt{2}$.

Hence, this series fails to pass the ratio test, while passes the root test (and thus convergent).

Definition 3.12 (Absolute Convergence). *The series $\sum a_n$ **converges absolutely** if the series $\sum |a_n|$ converges.*

Theorem 3.18. *If $\sum a_n$ converges absolutely, then $\sum a_n$ converges.*

Note that the converse does not hold. For example, the series $\sum (-1)^n/n$ converges while the harmonic series $\sum 1/n$ diverges.

Theorem 3.19. *If $\sum a_n = A, \sum b_n = B$, then $\sum (a_n + \lambda b_n) = A + \lambda B$ for any fixed λ .*

Proof. It is because the partial sums satisfy

$$\sum_{n=0}^k (a_n + \lambda b_n) = \sum_{n=0}^k a_n + \lambda \sum_{n=0}^k b_n$$

By letting $k \rightarrow \infty$ we complete the proof. □

Definition 3.13 (Product of Series). *Given two series $\sum a_n, \sum b_n$, we put*

$$c_n = \sum_{k=0}^n a_k b_{n-k}$$

*and call $\sum c_n$ the **product** of the two given series.*

Theorem 3.20. *Suppose $\sum a_n$ converges absolutely, $\sum a_n = A, \sum b_n = B$, and $c_n = \sum_{k=0}^n a_k b_{n-k}$, then $\sum c_n = AB$.*

Proof. Put

$$A_n = \sum_{k=0}^n a_k, \quad B_n = \sum_{k=0}^n b_k, \quad C_n = \sum_{k=0}^n c_k, \quad \beta_n = B_n - B.$$

Then we have

$$\begin{aligned} C_n &= a_0 b_0 + (a_0 b_1 + a_1 b_0) + \dots + (a_0 b_n + a_1 b_{n-1} + \dots + a_n b_0) \\ &= a_0 B_n + a_1 B_{n-1} + \dots + a_n B_0 \\ &= a_0 (B + \beta_n) + a_1 (B + \beta_{n-1}) + \dots + a_n (B + \beta_0) \\ &= A_n B + a_0 \beta_n + a_1 \beta_{n-1} + \dots + a_n \beta_0. \end{aligned}$$

Put $\gamma_n = \alpha_0\beta_n + \dots + \alpha_n\beta_0$. Since $A_nB \rightarrow AB$, then we only need to show that $\gamma_n \rightarrow 0$.

Put $\alpha = \sum_{n=0}^{\infty} |a_n|$ (recall that $\sum a_n$ converges absolutely). Since $B_n \rightarrow B$, for all $\varepsilon > 0$, there exists N such that for all $n \geq N$, we have $|\beta_n| = |B_n - B| \leq \varepsilon$. Then for $n \geq N$, we have

$$\begin{aligned} |\gamma_n| &\leq |\beta_0 a_n + \dots + \beta_N a_{n-N}| + |\beta_{N+1} a_{n-(N+1)} + \dots + \beta_n a_0| \\ &\leq |\beta_0 a_n + \dots + \beta_N a_{n-N}| + \varepsilon \alpha. \end{aligned}$$

Keeping N fixed, by letting $n \rightarrow \infty$, we get

$$\limsup |\gamma_n| \leq \varepsilon \alpha$$

since $a_k \rightarrow 0$ as $k \rightarrow \infty$. Since $\varepsilon > 0$ is arbitrary, we have $\gamma_n \rightarrow 0$. \square

Theorem 3.21. *If the series $\sum a_n, \sum b_n, \sum c_n$ converge to A, B, C , and $c_n = a_0 b_n + \dots + a_n b_0$, then $C = AB$.*

Theorem 3.22 (Alternating Series Test). *Suppose (a_n) is a non-negative monotone decreasing sequence such that $a_1 \geq a_2 \geq \dots$ and $\lim a_n = 0$. Then $\sum_{n=1}^{\infty} (-1)^{n+1} a_n = a_1 - a_2 + a_3 - a_4 + \dots$ converges.*

Proof. The partial sum of even number of terms is

$$S_{2N} = (a_1 - a_2) + (a_3 - a_4) + \dots$$

in which every term is non-negative (since (a_n) is decreasing), so that the sequence $(S_{2N})_N$ is non-negative and increasing. On the other hand, the partial sum of odd number of terms is

$$S_{2N+1} = a_1 - (a_2 - a_3) - (a_4 - a_5) - \dots$$

in which every term (except for a_1) is non-positive, so that the sequence $(S_{2N+1})_N$ is decreasing. Also, for all N we have

$$0 \leq S_{2N} \leq S_{2N+1} \leq a_1$$

so that both sequences converges. Moreover, since

$$\lim_{N \rightarrow \infty} |S_{2N+1} - S_{2N}| = \lim_{N \rightarrow \infty} a_{2N+1} = 0,$$

so that both sequences have the same limit $\lim_{N \rightarrow \infty} S_N$. Therefore, the series $\sum_{n=1}^{\infty} (-1)^{n+1} a_n$ converges. \square

Definition 3.14 (Rearrangement of Series). *Suppose $k : \mathbb{N}^+ \rightarrow \mathbb{N}^+$ is a bijection. Then we say that $\sum a'_n = \sum a_{k(n)}$ is a **rearrangement** of $\sum a_n$.*

Theorem 3.23 (Riemann Rearrangement). *Suppose $\sum a_n$ is a series of real numbers which converges but not absolutely. Suppose $-\infty \leq \alpha \leq \beta \leq +\infty$. Then there exists a rearrangement $\sum a'_n = \sum a_{k(n)}$ with partial sums s'_n such that*

$$\liminf s'_n = \alpha, \quad \limsup s'_n = \beta.$$

Proof. Let

$$p_n = \frac{|a_n| + a_n}{2}, \quad q_n = \frac{|a_n| - a_n}{2}$$

so that $p_n - q_n = a_n, p_n + q_n = |a_n|$ and $p_n, q_n \geq 0$ for all n . The series $\sum p_n, \sum q_n$ must both diverge: they cannot both be convergent since $\sum (p_n + q_n) = \sum |a_n|$ diverges; if one of them converges while the other diverges, $\sum (p_n - q_n) = \sum a_n$ will diverge and bring contradiction.

Let P_1, P_2, P_3, \dots denote the non-negative terms of $\sum a_n$ (in the order in which they occur), and Q_1, Q_2, Q_3 be the absolute values of negative terms of $\sum a_n$ (also in their original order). The series $\sum P_n, \sum Q_n$ differ from $\sum p_n, \sum q_n$ only by zero terms, and are therefore divergent.

Now we manage to construct sequences $(m_n), (k_n)$ such that the series

$$P_1 + \dots + P_{m_1} - Q_1 - \dots - Q_{k_1} + P_{m_1+1} + \dots + P_{m_2} - Q_{k_1+1} - \dots - Q_{k_2} + \dots$$

which clearly is a rearrangement of $\sum a_n$, satisfies $\liminf s'_n = \alpha, \limsup s'_n = \beta$.

To construct such rearrangement, choose real-valued sequences $(\alpha_n), (\beta_n)$ such that $\alpha_n \rightarrow \alpha, \beta_n \rightarrow \beta$, $\alpha < \beta$ and $\beta_1 > 0$. The construction takes following steps:

1. Let m_1 be the smallest integer such that $P_1 + \dots + P_{m_1} > \beta_1$;
2. Let k_1 be the smallest integer such that $P_1 + \dots + P_{m_1} - Q_1 - \dots - Q_{k_1} < \alpha_1$;
3. Let m_2 be the smallest integer such that $P_1 + \dots + P_{m_1} - Q_1 - \dots - Q_{k_1} + P_{m_1+1} + \dots + P_{m_2} > \beta_2$;
4. Let k_2 be the smallest integer such that $P_1 + \dots + P_{m_1} - Q_1 - \dots - Q_{k_1} + P_{m_1+1} + \dots + P_{m_2} - Q_{k_1+1} - \dots - Q_{k_2} < \alpha_2$;
5. Repeat previous steps to find m_3, k_3, \dots .

Such integers $m_1, k_1, m_2, k_2, \dots$ could be found since $\sum P_n$ and $\sum Q_n$ diverges.

If x_n, y_n denote the partial sums of rearrangement whose last terms are $P_{m_n}, -Q_{k_n}$, then we have

$$|x_n - \beta_n| \leq P_{m_n}, \quad |y_n - \alpha_n| \leq Q_{k_n}.$$

Since $P_n \rightarrow 0, Q_n \rightarrow 0$ as $n \rightarrow \infty$ (as $\sum a_n$ converges), we have $x_n \rightarrow \beta, y_n \rightarrow \alpha$.

Finally, it is clear that no number less than α or greater than β can be a sequential limit of the partial sums of the rearrangement. \square

Theorem 3.24. *If $\sum a_n$ is a series of complex numbers which converges absolutely, then every rearrangement of $\sum a_n$ converges, and they all converge to the same sum.*

Proof. Let $\sum a_{k(n)} = \sum a'_n$ be a rearrangement with partial sums s'_n . Since $\sum |a_n|$ converges, for all $\varepsilon > 0$, there exists N such that for all $m \geq n \geq N$, we have $\sum_{i=n}^m |a_i| \leq \varepsilon$.

Choose p such that integers $1, 2, \dots, N$ are all contained in the set $k(1), \dots, k(p)$. Then for all $n > p$, we have $|s_n - s'_n| \leq \varepsilon$ since a_1, \dots, a_N are contained in both s_n and s'_n . Therefore, (s'_n) converges to the same sum as (s_n) . \square

3.6 Some Important Series

Theorem 3.25. *For $r \in \mathbb{R}$, the series $\sum_{n=0}^{\infty} r^n = 1/(1-r)$ if $|r| < 1$, diverges if $|r| \geq 1$.*

Proof. The partial sum is given by

$$S_n = 1 + r + \dots + r^n = \frac{1 - r^{n+1}}{1 - r}.$$

If $|r| \geq 1$, then $|r^n| \geq 1$ for all n , so that (S_n) diverges; if $|r| < 1$, then $r^{n+1} \rightarrow 0$, so that $S_n \rightarrow 1/(1-r)$. \square

Theorem 3.26. *For $p \in \mathbb{R}$, the series $\sum_{n=1}^{\infty} 1/n^p$ converges if $p > 1$, diverges if $p \leq 1$.*

Proof. Suppose $p > 1$. Then the partial sum satisfies

$$\sum_{n=1}^{2^{N+1}} \frac{1}{n^p} \leq 1 + \frac{1}{2^p} + \frac{1}{2^p} + \frac{1}{4^p} + \frac{1}{4^p} + \frac{1}{4^p} + \frac{1}{4^p} + \dots = \sum_{n=0}^N \left(\frac{2}{2^p}\right)^n$$

which converges.

Suppose $p = 1$. Then the partial sum satisfies

$$\sum_{n=1}^{2^N-1} \frac{1}{n} \geq \frac{1}{2} + \frac{1}{4} + \frac{1}{4} + \frac{1}{8} + \frac{1}{8} + \frac{1}{8} + \frac{1}{8} + \dots = \frac{N}{2}$$

which clearly diverges, so that the harmonic series diverges.

Suppose $p < 1$, then the series clearly diverges since $1/n^p \geq 1/n$ for all n . \square

Theorem 3.27. *Suppose (a_n) is monotone decreasing and $a_n \geq 0$ for all n . Then the series $\sum a_n$ converges if and only if the series*

$$\sum_{k=0}^{\infty} 2^k a_{2^k} = a_1 + 2a_2 + 4a_4 + 8a_8 + \dots$$

converges.

Proof. We only need to show that the partial sums are bounded. Let the partial sums be $s_n = a_1 + \dots + a_n$ and $t_k = a_1 + 2a_2 + \dots + 2^k a_{2^k}$.

For $n < 2^k$, we have

$$\begin{aligned} s_n &\leq a_1 + (a_2 + a_3) + \dots + (a_{2^k} + \dots + a_{2^{k+1}-1}) \\ &\leq a_1 + 2a_2 + \dots + 2^k a_{2^k} = t_k \end{aligned}$$

so that $s_n \leq t_k$. On the other hand, for $n > 2^k$, we have

$$\begin{aligned} s_n &\geq a_1 + a_2 + (a_3 + a_4) + \dots + (a_{2^{k-1}+1} + \dots + a_{2^k}) \\ &\geq \frac{1}{2}a_1 + a_2 + 2a_4 + \dots + 2^{k-1}a_{2^k} = \frac{1}{2}t_k \end{aligned}$$

so that $2s_n \geq t_k$. Hence, the sequences (s_n) and (t_k) are either both bounded or both unbounded. Therefore we complete the proof. \square

Theorem 3.28. *If $p > 1$, the series $\sum_{n=2}^{\infty} \frac{1}{n(\log n)^p}$ converges; if $p \leq 1$, this series diverges.*

Proof. Note that the sequence $(1/n \log n)$ decreases. Then by theorem above, it leads us to the series

$$\sum_{k=1}^{\infty} 2^k \frac{1}{2^k (\log 2^k)^p} = \sum_{k=1}^{\infty} \frac{1}{(k \log 2)^p} = \frac{1}{(\log 2)^p} \sum_{k=1}^{\infty} \frac{1}{k^p}$$

which converges if and only if $p > 1$, diverges if and only if $p \leq 1$. \square

Definition 3.15 (e). $e = \sum_{n=0}^{\infty} 1/n!$ (here $0! = 1$).

Note that such series converges, since the sequence of partial sums $(s_n = \sum_{k=0}^n 1/k!)$ is monotone increasing, and it is bounded:

$$\begin{aligned} s_n &= 1 + 1 + \frac{1}{1 \times 2} + \frac{1}{1 \times 2 \times 3} + \dots + \frac{1}{1 \times 2 \times \dots \times n} \\ &< 1 + 1 + \frac{1}{2} + \frac{1}{2^2} + \dots + \frac{1}{2^{n-1}} < 3. \end{aligned}$$

Theorem 3.29. $\lim_{n \rightarrow \infty} (1 + 1/n)^n = e$.

Proof. Let $s_n = \sum_{k=0}^n 1/k!$ and $t_n = (1 + 1/n)^n$. By binomial theorem,

$$\begin{aligned} t_n &= 1 + \frac{n!}{(n-1)!1!} \frac{1}{n} + \frac{n!}{(n-2)!2!} \frac{1}{n^2} + \dots + \frac{n!}{1!(n-1)!} \frac{1}{n^n} \\ &= 1 + 1 + \frac{1}{2!} \left(1 - \frac{1}{n}\right) + \frac{1}{3!} \left(1 - \frac{2}{n}\right) + \dots + \frac{1}{n!} \left(1 - \frac{1}{n}\right) \left(1 - \frac{2}{n}\right) \dots \left(1 - \frac{n-1}{n}\right). \end{aligned}$$

Hence $t_n \leq s_n$, so that $\limsup t_n \leq e$.

Next, if $n \geq m$,

$$t_n \geq 1 + 1 + \frac{1}{2!} \left(1 - \frac{1}{n}\right) + \dots + \frac{1}{m!} \left(1 - \frac{1}{n}\right) \left(1 - \frac{2}{n}\right) \dots \left(1 - \frac{m-1}{n}\right).$$

Keeping m fixed, by letting $n \rightarrow \infty$, we have

$$\liminf t_n \geq 1 + 1 + \frac{1}{2!} + \dots + \frac{1}{m!}$$

so that $s_m \leq \liminf t_n$. Letting $m \rightarrow \infty$ we obtain $e \leq \liminf t_n$. Therefore, $\lim_{n \rightarrow \infty} t_n = e$. \square

Theorem 3.30. e is irrational.

Proof. Since $e = \sum_{n=0}^{\infty} 1/n!$, let the partial sums be $s_n = \sum_{k=0}^n 1/k!$, then we have

$$\begin{aligned} e - s_n &= \frac{1}{(n+1)!} + \frac{1}{(n+2)!} + \dots \\ &< \frac{1}{(n+1)!} \left[1 + \frac{1}{n+1} + \frac{1}{(n+1)^2} + \dots \right] = \frac{1}{n!n}. \end{aligned}$$

So that

$$0 < e - s_n < \frac{1}{n!n}.$$

Suppose e is rational, then $e = p/q$ where p, q are positive integers. Then we have

$$0 < q!(e - s_q) < \frac{1}{q}.$$

Since

$$q!s_q = q! \left(1 + 1 + \frac{1}{2!} + \dots + \frac{1}{q!} \right)$$

is an integer, $q!(e - s_q)$ is also an integer. However, $1/q \in (0, 1]$ since $q \geq 1$, where has a contradiction. \square

Definition 3.16 (Power Series). *Given a sequence (c_n) of complex numbers, the series $\sum_{n=0}^{\infty} c_n z^n$ is called a **power series**, where z is a complex number.*

Theorem 3.31. *Given the power series $\sum c_n z^n$, put*

$$\alpha = \limsup \sqrt[n]{|c_n|}, \quad R = \frac{1}{\alpha}$$

(If $\alpha = 0$, $R = +\infty$; if $\alpha = +\infty$, $R = 0$). Then $\sum c_n z^n$ converges absolutely if $|z| < R$, diverges if $|z| > R$. R is called the radius of convergence of $\sum c_n z^n$.

Proof. Put $a_n = c_n z^n$ and apply the root test:

$$\limsup \sqrt[n]{|a_n|} = |z| \limsup \sqrt[n]{|c_n|} = \frac{|z|}{R}.$$

\square

However, at the boundary $|z| = R$ one cannot simply assert the convergence or divergence of the power series. Indeed, any situation may be the case at the boundary.

Example 3.2.

1. The power series $\sum z^n$ has radius $R = 1$ and diverges whenever $|z| = 1$.
2. The power series $\sum z^n/n^2$ has radius $R = 1$ and converges whenever $|z| = 1$.
3. The power series $\sum z^n/n$ has radius $R = 1$, diverges when $z = 1$, but converges conditionally for other $|z| = 1$.

3.7 p -Norm, \mathbb{R}^N and \mathbb{R}^∞

Definition 3.17 (p -Norm). *For $p \in [1, \infty)$, the **p -norm** on \mathbb{R}^n is given by*

$$\|x\|_p = \left(\sum_{i=1}^n |x_i|^p \right)^{1/p}$$

It also defines a metric on \mathbb{R}^n by $d(x, y) = \|x - y\|_p$. When $p = \infty$ define the ∞ -norm as

$$\|x\|_\infty = \lim_{p \rightarrow \infty} \|x\|_p = \max_{1 \leq i \leq n} |x_i|.$$

Theorem 3.32. For any $x \in \mathbb{R}^d$ and $1 \leq p \leq q \leq \infty$,

$$\|x\|_q \leq \|x\|_p \leq d^{\frac{1}{p} - \frac{1}{q}} \|x\|_q.$$

This means that in finite dimensional vector space \mathbb{R}^d , all p -norms share the identical topological structure with typical 2-norm.

Definition 3.18 ($\mathbb{R}^\mathbb{N}$). $\cup_{n=1}^\infty \mathbb{R}^n = \mathbb{R}^\mathbb{N}$.

Note that infinite sequences are NOT contained in $\mathbb{R}^\mathbb{N}$; all elements in $\mathbb{R}^\mathbb{N}$ are of finite dimension.

Now consider $(\mathbb{R}^\mathbb{N}, p)$, the space $\mathbb{R}^\mathbb{N}$ with p -norm. The following proposition shows that different p -norms have different topological structure in $\mathbb{R}^\mathbb{N}$.

Proposition 3.6. Let $p \in [1, \infty], q \in \mathbb{R}$. Then in $(\mathbb{R}^\mathbb{N}, p)$ the sequence $(a_n) = ((1, 1/2^q, \dots, 1/n^q))_{n \in \mathbb{N}}$ is (1) Cauchy if $pq > 1$; (2) unbounded if $pq \leq 1$; (3) bounded but not Cauchy if $pq = \infty \cdot 0$.

Proof. For $p \in [1, \infty)$ we have

$$\|a_n\|_p = \left(\sum_{k=1}^n \frac{1}{k^{pq}} \right)^{1/q}$$

so that for $m > n$,

$$\|a_m - a_n\|_p = \left(\sum_{k=n+1}^m \frac{1}{k^{pq}} \right)^{1/q}.$$

Hence, (a_n) is Cauchy if and only if the sequence $(1/n^{pq})$ converges, that is, if and only if $pq > 1$.

For $p = \infty$ we have

$$\|a_n\|_\infty = \begin{cases} 1 & q \geq 0 \\ n^{-q} & q < 0 \end{cases}$$

so that (a_n) is bounded if and only if $q \geq 0$. Also, for $m > n$,

$$\|a_m - a_n\|_\infty = \max \left\{ \frac{1}{n^p}, \frac{1}{m^p} \right\}.$$

Hence, (a_n) is Cauchy if and only if $1/n^p \rightarrow 0$, that is, if and only if $p > 0$. □

Theorem 3.33. For $p \in [1, \infty]$, the space $(\mathbb{R}^\mathbb{N}, p)$ is not Cauchy complete.

Example 3.3. Let $p = 2, a_n = (1, 1/2, \dots, 1/n)$. Consider whether the Cauchy sequence (a_n) is convergent in $\mathbb{R}^\mathbb{N}$: for any $x \in \mathbb{R}^d \subseteq \mathbb{R}^\mathbb{N}$ and $m > d$, we have

$$\|x - a_m\|_2^2 = \|x - a_d\|_2^2 + \frac{1}{(d+1)^2} + \dots + \frac{1}{m^2}.$$

So that $x \notin B_\varepsilon(a_m)$ for all $\varepsilon < 1/(d+1)^2$. Hence, $a_n \not\rightarrow x$ and (a_n) diverges.

Definition 3.19 (Sequence Space). The **sequence space** \mathbb{R}^∞ is the set of all (infinite) sequences in \mathbb{R} .

We claim that $\mathbb{R}^\mathbb{N} \subseteq \mathbb{R}^\infty$, by identifying $(x^1, \dots, x^d) \in \mathbb{R}^\mathbb{N}$ with $(x^1, \dots, x^d, 0, 0, \dots) \in \mathbb{R}^\infty$.

Definition 3.20 (ℓ^p Space). For $p \in [1, \infty]$ and $a = (a^1, a^2, \dots) \in \mathbb{R}^\infty$, define its p -norm as

$$\|a\|_p = \left(\sum_{n=1}^\infty (a^n)^p \right)^{1/p}, \quad 1 \leq p < \infty$$

and

$$\|a\|_\infty = \sup_n |a^n|.$$

Define ℓ^p **space** as

$$\ell^p = \{a \in \mathbb{R}^\infty : \|a\|_p < \infty\}$$

and it is also a metric space with $d(x, y) = \|x - y\|_p$.

Example 3.4. For any $a = (a^n) \in \mathbb{R}^\infty$,

1. $\|a\|_1 = \sum_{n=1}^{\infty} |a^n|$, so that ℓ^1 is the set of all absolute convergent sequences.
2. $\|a\|_\infty = \sup_n |a^n|$, so that ℓ^∞ is the set of all bounded sequences.

Proposition 3.7. For any $p \in [1, \infty]$, $\mathbb{R}^\mathbb{N} \subseteq \ell^p \subseteq \mathbb{R}^\infty$.

Proposition 3.8. For any $p \in [1, \infty)$ and $a = (a^n) \in \mathbb{R}^\infty$, define $a_n = (a^1, \dots, a^n, 0, \dots) \in \mathbb{R}^\mathbb{N} \subseteq \mathbb{R}^\infty$, then $a \in \ell^p$ if and only if $a_n \rightarrow a$ in ℓ^p .

Proof. It is because

$$a \in \ell^p \Leftrightarrow \sum |a^n|^p \text{ converges} \Leftrightarrow \sum_{n=N}^{\infty} |a^n|^p \rightarrow 0 (N \rightarrow \infty) \Leftrightarrow a_n \rightarrow a.$$

□

Theorem 3.34. For $p \in [1, \infty)$, ℓ^p is the Cauchy completion of $\mathbb{R}^\mathbb{N}$ with respect to the p -norm.

Proof. By proposition above we know that $\mathbb{R}^\mathbb{N}$ is dense in ℓ^p . Then we only need to show that ℓ^p is Cauchy complete. Here we only prove the ℓ^1 case.

Suppose $(a_n) = ((a_n^1, a_n^2, \dots))_n$ is Cauchy in ℓ^1 . First we show that the sequences of each fixed component $(a_n^k \in \mathbb{R})_n$ is convergent, since it is Cauchy:

$$|a_n^k - a_m^k| \leq \sum_{k=1}^{\infty} |a_n^k - a_m^k| = \|a_n - a_m\|_1 \rightarrow 0 (n, m \rightarrow \infty)$$

and \mathbb{R} is Cauchy complete. Hence, we denote $a^k = \lim_{n \rightarrow \infty} a_n^k$ and $a = (a^1, a^2, \dots)$.

To ensure that $a \in \ell^1$, since (a_n) is Cauchy, there exists R such that $\|a_n\|_1 = \sum_k |a_n^k| \leq R$ for all n . Hence, for all K we have

$$\sum_{k=1}^K |a^k| = \sum_{k=1}^K \left| \lim_{n \rightarrow \infty} a_n^k \right| = \lim_{n \rightarrow \infty} \sum_{k=1}^K |a_n^k| \leq R$$

and by letting $K \rightarrow \infty$ we have $\sum_k |a^k| \leq R$. Therefore, $a \in \ell^1$.

Finally, we show that $a_n \rightarrow a$. Since (a_n) is Cauchy, for all $\varepsilon > 0$, there exists N such that for all $n, m > N$ we have

$$\|a_n - a_m\|_1 = \sum_{k=1}^{\infty} |a_n^k - a_m^k| < \varepsilon.$$

Thus, for all K we also have $\sum_{k=1}^K |a_n^k - a_m^k| < \varepsilon$. By letting $m \rightarrow \infty$ we have

$$\sum_{k=1}^K |a_n^k - a^k| \leq \varepsilon.$$

Therefore,

$$\|a_n - a\|_1 = \sum_{k=1}^{\infty} |a_n^k - a^k| = \sup_K \sum_{k=1}^K |a_n^k - a^k| \leq \varepsilon$$

and $a_n \rightarrow a$.

□

4 Continuous Function

Definition 4.1 (Basic Concepts of Functions). Let $f : X \rightarrow Y$ be a **function**. We call X the **domain** of f , and Y the **codomain** of f .

For $E \subseteq X$, call $f(E) = \{f(x) : x \in E\}$ the **image** of E under f . $f(X)$ is called the **image** of f .

For $F \subseteq Y$, call $f^{-1}(F) = \{x \in X : f(x) \in F\}$ the **pre-image (inverse image)** of F .

Example 4.1.

1. Identity mapping $\text{id} : X \rightarrow X, x \mapsto x$;
2. Constant mapping $c : X \rightarrow Y, x \mapsto c \in Y$;
3. Quadratic functions $f : \mathbb{R} \rightarrow \mathbb{R}, f(x) = x^2$, $g : \mathbb{Q} \rightarrow \mathbb{Q}, g(x) = x^2$, and $h : \mathbb{Q} \rightarrow \mathbb{R}, h(x) = x^2$. We also write $h = f|_{\mathbb{Q}}$ as the **restriction** of f to \mathbb{Q} .

Definition 4.2 (Limit in Function). Let X, Y be metric spaces, $f : X \rightarrow Y$, $E \subseteq X$ and $p \in E'$. We say

$$\lim_{x \rightarrow p} f(x) = y$$

if for all $\varepsilon > 0$, there exists $\delta > 0$ such that for all $x \in E$ and $x \neq p$, we have

$$d_X(x, p) < \delta \Rightarrow d_Y(f(x), y) < \varepsilon.$$

Note that the limit cannot be well-defined for $p \notin E'$.

Proposition 4.1. Suppose $f : E \rightarrow Y$ where $E \subseteq X, p \in E'$. Then $\lim_{x \rightarrow p} f(x) = y$ if and only if for all sequences (x_n) in E (and $x_n \neq p$ for any n) such that $\lim_{n \rightarrow \infty} x_n = p$, we have $\lim_{n \rightarrow \infty} f(x_n) = y$.

Proof.

- \Rightarrow Take $\varepsilon > 0$; since $\lim_{x \rightarrow p} f(x) = y$, there exists $\delta > 0$ such that $d_X(x, p) < \delta \Rightarrow d_Y(f(x), y) < \varepsilon$. Moreover, since $x_n \rightarrow p$, there exists $N > 0$ such that for all $n > N$, we have $d_X(x_n, p) < \delta$, and thus $d_Y(f(x_n), y) < \varepsilon$ for all $n > N$. Therefore, $f(x_n) \rightarrow y$.
- \Leftarrow Suppose $\lim_{x \rightarrow p} f(x) \neq y$, then there exists $\varepsilon > 0$ such that for all δ , there exists $x \in B_\delta(p), x \neq p$ such that $d_Y(f(x), y) \geq \varepsilon$. Then for all $n \in \mathbb{N}_+$, we can choose $x_n \in B_{1/n}(p), x_n \neq p$ such that $d_Y(f(x_n), y) \geq \varepsilon$, so that $f(x_n) \not\rightarrow y$ where has a contradiction. □

Corollary 4.1. The limit in function is unique; if $\lim_{x \rightarrow p} f(x) = a$ and $\lim_{x \rightarrow p} f(x) = b$, then $a = b$.

To incorporate the concept of infinite limits and limits at infinity, we can extend the concept of limit in function. Here we define that for any $c \in \mathbb{R}$, the set $(c, +\infty)$ is a neighborhood of $+\infty$, and $(-\infty, c)$ is a neighborhood of $-\infty$.

Definition 4.3 (Limit in Function). Let f be a real function defined on E . We say that $f(t) \rightarrow A$ as $t \rightarrow x$ where $A, x \in \mathbb{R} \cup \{\pm\infty\}$, if for every neighborhood U of A , there exists a neighborhood V of x such that $f(t) \in U$ for all $t \in V \cap E, t \neq x$ (and $V \cap E$ is non-empty).

4.1 Continuous Function

Definition 4.4 (Continuous Function). Let X, Y be metric spaces, $f : X \rightarrow Y, E \subseteq X$ and $p \in E$. We say that the function f is **continuous** at point p if for all $\varepsilon > 0$, there exists $\delta > 0$ such that for all $x \in X$, we have $d_X(x, p) < \delta \Rightarrow d_Y(f(x), f(p)) < \varepsilon$.

If f is **continuous** at any point $p \in E$, we say that f is **continuous on E** ; f is **continuous** if it is continuous on X .

Proposition 4.2. If p is an isolated point of X , then f is continuous at p .

Proposition 4.3. $f : X \rightarrow Y$ is continuous at p if and only if for all sequences (x_n) in X such that $x_n \rightarrow p$, we have $f(x_n) \rightarrow f(p)$.

Theorem 4.1. $f : X \rightarrow Y$ is continuous if and only if for all open subsets $U \subseteq Y$, its inverse $f^{-1}(U) \subseteq X$ is also open in X .

Proof.

\Leftarrow : For all $p \in X, \varepsilon > 0$, define $A = f^{-1}(B_\varepsilon(f(p))) \subseteq X$. If property holds, then $A \subseteq X$ is open and $p \in A$, so that there exists $\delta > 0$ such that $B_\delta(p) \subseteq A$; that is, $d_X(x, p) < \delta \Rightarrow d_Y(f(x), f(p)) < \varepsilon$, so that f is continuous at p .

\Rightarrow : Consider a open subset $U \subseteq Y$ and any $p \in f^{-1}(U)$: since U is open, there exists $\varepsilon > 0$ such that $B_\varepsilon(f(p)) \subseteq U$. Since f is continuous, there exists $\delta > 0$ such that $d_X(x, p) < \delta \Rightarrow d_Y(f(x), f(p)) < \varepsilon$. Hence, $f(B_\delta(p)) \subseteq B_\varepsilon(f(p)) \subseteq U$ and $B_\delta(p) \subseteq f^{-1}(U)$. Since $p \in f^{-1}(U)$ is arbitrary, $f^{-1}(U)$ is open. \square

Corollary 4.2. $f : X \rightarrow Y$ is continuous if and only if the pre-images of all closed subsets of Y are closed.

Theorem 4.2. Composition of continuous functions is also continuous. Suppose $f : X \rightarrow Y, g : Y \rightarrow Z$ are continuous, then $g \circ f : X \rightarrow Z$ is also continuous.

Proof. It could be proved in three ways using different definitions of continuity which are actually equivalent.

1. For all $\varepsilon > 0, p \in X$, since g is continuous, there exists $\eta > 0$ such that

$$d_Y(f(p), y) < \eta \Rightarrow d_Z(g \circ f(p), g(y)) < \varepsilon.$$

Moreover, since f is continuous, there exists $\delta > 0$ such that

$$d_X(p, x) < \delta \Rightarrow d_Y(f(p), y) < \eta \Rightarrow d_Z(g \circ f(p), g \circ f(x)) < \varepsilon.$$

2. Let $x_n \rightarrow p \in X$, then $f(x_n) \rightarrow f(p) \in Y$ since f is continuous, and $g \circ f(x_n) \rightarrow g \circ f(p) \in Z$ since g is continuous.

3. Let $U \subseteq Z$ be open, then $g^{-1}(U) \subseteq Y$ is open since g is continuous, and $f^{-1}(g^{-1}(U)) = (g \circ f)^{-1}(U) \subseteq X$ is open since f is continuous. \square

Proposition 4.4. If $\lim_{x \rightarrow p} f(x) = y$ for $f : E \rightarrow Y$ and $p \in E'$, and $g : Y \rightarrow Z$ is continuous, then $\lim_{x \rightarrow p} g \circ f(x) = g(y)$.

Theorem 4.3. $+: \mathbb{R}^2 \rightarrow \mathbb{R}$ is continuous.

Proof. Take a sequence $((x_n, y_n))_n$ in \mathbb{R} such that $(x_n, y_n) \rightarrow (x, y)$, then

$$+((x_n, y_n)) = x_n + y_n \rightarrow x + y = +((x, y)).$$

\square

Lemma 4.1. Let $f, g : E \rightarrow \mathbb{R}, E \subseteq X$ and $p \in E'$. Let $(f, g) : E \rightarrow \mathbb{R}^2, x \mapsto (f(x), g(x))$, then

$$\lim_{x \rightarrow p} (f, g)(x) = \left(\lim_{x \rightarrow p} f(x), \lim_{x \rightarrow p} g(x) \right).$$

Also, (f, g) is continuous if and only if f, g are both continuous.

Theorem 4.4. For $f, g : X \rightarrow \mathbb{R}$ and $p \in X'$, we have

$$\lim_{x \rightarrow p} f(x) + g(x) = \lim_{x \rightarrow p} f(x) + \lim_{x \rightarrow p} g(x).$$

Proof. It is because

$$\begin{aligned} \lim_{x \rightarrow p} f(x) + g(x) &= \lim_{x \rightarrow p} +((f, g)(x)) = + \left(\lim_{x \rightarrow p} (f, g)(x) \right) \\ &= + \left(\left(\lim_{x \rightarrow p} f(x), \lim_{x \rightarrow p} g(x) \right) \right) = \lim_{x \rightarrow p} f(x) + \lim_{x \rightarrow p} g(x). \end{aligned}$$

□

Proposition 4.5. In \mathbb{R}^n , the addition, scalar multiplication, and dot product are continuous; in \mathbb{C} and \mathbb{R} , the multiplication is continuous, and division is continuous if the denominator is non-zero.

Consequently, the properties (continuity, limit, etc.) of $f, g : X \rightarrow \mathbb{R}$ can be inherited to $f + g, f \cdot g, f/g$.

4.2 Continuity and Compactness

Definition 4.5 (Boundedness). A function is **bounded** if its image is bounded.

Theorem 4.5. If function $f : K \rightarrow Y$ is continuous and K is compact, the image $f(K)$ is also compact in Y .

Proof. Let $\{G_\alpha\}_\alpha$ be an open cover of $f(K)$. First we show that $\{f^{-1}(G_\alpha)\}_\alpha$ is also an open cover of K : (1) Each $f^{-1}(G_\alpha)$ is open since f is continuous; (2) For any $x \in K$, $f(x) \in f(K)$ so that $f(x) \in f(G_\alpha)$ for some α , so that $x \in f^{-1}(G_\alpha)$.

Since K is compact, $\{f^{-1}(G_\alpha)\}_\alpha$ has finite subcover $\{f^{-1}(G_n)\}_{n=1}^N$. For any $y \in f(K)$, we have $y = f(x)$ for some $x \in K$, and $x \in f^{-1}(G_n)$ for some n , so that $y \in G_n$ and thus $\{G_n\}_{n=1}^N$ is a finite subcover of K . □

Corollary 4.3. If function $f : K \rightarrow \mathbb{R}$ is continuous and K is compact,

1. $f(K)$ is bounded;
2. there exists $a, b \in K$ such that $f(a) = \inf_{x \in K} f(x)$, $f(b) = \sup_{x \in K} f(x)$;
3. if $f(x) > 0$ for all $x \in K$, then $\inf_{x \in K} f(x) > 0$.

Consider a continuous function $f : K \rightarrow Y$ with compact domain K ; if $E \subseteq K$ is closed, it is also compact, so that $f(E) \subseteq Y$ is compact, which implies $f(E)$ is closed in Y . However, it does not necessarily hold for open sets.

Proposition 4.6. Let $f : X \rightarrow Y$ be surjective and K be compact. If $U \subseteq K$ is open, then $f(U)$ is also open; if f is bijective, then $f^{-1} : Y \rightarrow K$ is also continuous.

4.3 Uniform Continuity

Definition 4.6 (Uniform Continuity). A function $f : X \rightarrow Y$ is **uniformly continuous** if for all $\varepsilon > 0$, there exists $\delta > 0$ such that $d_X(x, y) < \delta \Rightarrow d_Y(f(x), f(y)) < \varepsilon$.

Recall that the definition of continuity only requires that $f : X \rightarrow Y$ is continuous at all $x \in X$, so that for a fixed $\varepsilon > 0$, the chosen δ may vary with $x \in X$; however, δ must also be fixed for all $x \in X$ by definition of uniform continuity.

Theorem 4.6. Let $f : X \rightarrow Y$ be uniformly continuous, and (x_n) be Cauchy in X , then $(f(x_n))$ is also Cauchy in Y .

Proof. By definition of uniform continuity, for all $\varepsilon > 0$, there exists $\delta > 0$ such that $d_X(a, b) < \delta \Rightarrow d_Y(f(a), f(b)) < \varepsilon$. Since (x_n) is Cauchy, there exists N such that $d_X(x_n, x_m) < \delta \Rightarrow d_Y(f(x_n), f(x_m)) < \varepsilon$ for all $m, n > N$, so that $(f(x_n))$ is also Cauchy. □

Example 4.2. To show that the uniform continuity matters, suppose $f(x) = 1/x$ and $(x_n) = (1/n)$ which is Cauchy, then $(f(x_n)) = (n)$ which is not Cauchy.

Theorem 4.7. If $f : K \rightarrow Y$ is continuous and K is compact, then f is uniformly continuous.

Proof. For all $\varepsilon > 0$ and all $x \in K$, we define r_x such that

$$B_{r_x}(x) \subseteq f^{-1}(B_{\varepsilon/2}(f(x))).$$

Since $\{B_{r_x/2}(x)\}_{x \in K}$ is an open cover of K , it has finite subcover $\{B_{r_{x_n}/2}(x_n)\}_{n=1}^N$. Take $\delta = \min_n r_{x_n}/2$; if $d_X(x, y) < \delta$, there exists some x_n such that $d_X(x_n, y) \leq d_X(x_n, x) + d_X(x, y) < r_{x_n}$. Hence,

$$d_Y(f(x), f(y)) \leq d_Y(f(x), f(x_n)) + d_Y(f(x_n), f(y)) < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon.$$

□

Theorem 4.8. Suppose $f : E \rightarrow Y$ where $E \subseteq X$ and $p \in E'$. If f is uniformly continuous and Y is complete, then $\lim_{x \rightarrow p} f(x)$ exists.

Proof. Suppose the sequence (a_n) in E converges to p and $a_n \neq p$ for all n . Then (a_n) is Cauchy and so is $(f(a_n))$, so that $f(a_n) \rightarrow y \in Y$ since Y is complete. To show that y does not depend on the choice of sequence (a_n) , suppose another sequence (b_n) in E converges to p and $b_n \neq p$ for all n . Then the mixed sequence $(a_0, b_0, a_1, b_1, \dots)$ is also Cauchy, and so is $(f(a_0), f(b_0), f(a_1), f(b_1), \dots)$. Hence, there must be $f(b_n) \rightarrow y$ as well. \square

Theorem 4.9. Let $E \subseteq X$, $f : E \rightarrow Y$ be uniformly continuous, and Y is complete. Then there exists an extension $\bar{f} : \bar{E} \rightarrow Y$ which is continuous.

Proof. For $p \in \bar{E} \setminus E$, define $\bar{f}(p) = \lim_{x \rightarrow p} f(x)$ (the existence of limit is shown in theorem above). Now we only to show the continuity of \bar{f} at $p \in \bar{E} \setminus E$, that is, for all $\varepsilon > 0$, there exists $\delta > 0$ such that $d(x, y) < \delta \Rightarrow d(\bar{f}(x), \bar{f}(y)) < \varepsilon$ for any $x, y \in \bar{E} \setminus E$.

Take two sequences $(x_n), (y_n)$ in E such that $x_n \rightarrow x, y_n \rightarrow y$, then by definition we have $f(x_n) \rightarrow \bar{f}(x), f(y_n) \rightarrow \bar{f}(y)$. Since f is uniformly continuous, for all $\varepsilon > 0$, there exists $\delta > 0$ such that $d(x_n, y_n) < 3\delta \Rightarrow d(f(x_n), f(y_n)) < \varepsilon/3$.

Suppose $d(x, y) < \delta$; we only need to show that $d(\bar{f}(x), \bar{f}(y)) < \varepsilon$. Since $x_n \rightarrow x, y_n \rightarrow y$, there exists N such that for all $n > N$, we have $d(x_n, x) < \delta, d(y_n, y) < \delta$, then by triangle inequality,

$$d(x_n, y_n) < d(x_n, x) + d(x, y) + d(y, y_n) < 3\delta$$

so that $d(f(x_n), f(y_n)) < \varepsilon/3$.

Since $f(x_n) \rightarrow \bar{f}(x), f(y_n) \rightarrow \bar{f}(y)$, there exists $M > N$ such that for all $n > M$, we have $d(f(x_n), \bar{f}(x)) < \varepsilon/3, d(f(y_n), \bar{f}(y)) < \varepsilon/3$. Hence, by triangle inequality,

$$d(\bar{f}(x), \bar{f}(y)) < d(\bar{f}(x), f(x_n)) + d(f(x_n), f(y_n)) + d(f(y_n), \bar{f}(y)) < \varepsilon$$

and we complete the proof. \square

4.4 Continuity and Connectedness

Theorem 4.10. If $f : X \rightarrow Y$ is continuous and X is connected, then the image $f(X) \subseteq Y$ is also connected.

Proof. Suppose $f(X)$ is disconnected, so that $f(X) = A \cup B \subseteq Y$, where $A, B \subseteq Y$ are non-empty and separated (i.e. $\bar{A} \cap B = A \cap \bar{B} = \emptyset$). Then $X \subseteq f^{-1}(A) \cup f^{-1}(B)$.

It could be shown that $f^{-1}(A), f^{-1}(B)$ are separated: since $f^{-1}(A) \subseteq f^{-1}(\bar{A})$ which is closed due to the continuity of f , we have $\overline{f^{-1}(A)} \subseteq f^{-1}(\bar{A})$, then

$$\overline{f^{-1}(A)} \cap f^{-1}(B) \subseteq f^{-1}(\bar{A}) \cap f^{-1}(B) = \emptyset$$

since $\bar{A} \cap B = \emptyset$. Analogously, $f^{-1}(A) \cap \overline{f^{-1}(B)} = \emptyset$.

However, since $X \subseteq f^{-1}(A) \cup f^{-1}(B)$ is connected, there must be either $X \subseteq f^{-1}(A)$ or $X \subseteq f^{-1}(B)$, which implies $f(X) \subseteq A$ or $f(X) \subseteq B$, and contradicts the non-emptiness of B or A . Therefore, $f(X)$ is connected. \square

Corollary 4.4 (Intermediate Value Theorem). If $f : X \rightarrow Y$ is continuous and X is connected, and there exist $a, b \in X$ such that $f(a) < r < f(b)$, then there exists $x \in X$ such that $f(x) = r$.

However, IVT (and connected domain) cannot imply continuity. An example is

$$f(x) = \begin{cases} \sin(1/x) & x > 0 \\ 0 & x = 0 \end{cases}$$

It satisfies IVT but is not continuous at $x = 0$.

Theorem 4.11. E is connected if and only if any function $f : E \rightarrow \{0, 1\}$ (with discrete metric) which is continuous, we have $f(E) = \{0\}$ or $\{1\}$.

Proof. If E is connected and f is continuous, by IVT $f(E)$ is connected, so that $f(E) = \{0\}$ or $\{1\}$.

To show the converse, suppose E is disconnected and $E = A \cup B$ which are disjoint, closed and non-empty. Take

$$f(x) = \begin{cases} 0 & x \in A \\ 1 & x \in B \end{cases}$$

Since f is continuous and $\{0, 1\}$ has four open subsets $\emptyset, \{0\}, \{1\}, \{0, 1\}$, we have $f^{-1}(\{0\}) = A, f^{-1}(\{1\}) = B$ must be open, where has a contradiction. Therefore, E is connected. \square

A more common notion of connectedness is to use the idea of **paths**.

Definition 4.7 (Path Connectedness). A path in X is a continuous function $f : [0, 1] \rightarrow X$, from point $f(0) = a$ to point $f(1) = b$. A set E is **path connected** if for all $a, b \in E$, there exists a path $f : [0, 1] \rightarrow E$ such that $f(0) = a, f(1) = b$.

With the theorem above, now we can show that path connectedness implies connectedness.

Theorem 4.12. Path connectedness implies connectedness.

Proof. If E is disconnected, we have $E = A \cup B$ where A, B are separated. Then pick $a \in A, b \in B$. If f is a path from a to b , since A, B are open and f is continuous, $f^{-1}(A), f^{-1}(B) \subseteq [0, 1]$ are non-empty and open. However, $[0, 1]$ is impossible to separate into two (non-empty) open subsets. \square

However, the converse does not hold. A well-known example is given below.

Example 4.3 (Topologists' sine curve). Consider the set

$$\{(x, y) : y = \sin(1/x), x > 0\} \cup \{(0, y) : -1 \leq y \leq 1\}.$$

It could be shown that such set is connected but not path connected.

4.5 Discontinuities

Definition 4.8 (Limit from Above/Below). For function $f : \mathbb{R} \rightarrow \mathbb{R}$ and $p \in \mathbb{R}$, take $g = f|_{(-\infty, p)}, h = f|_{(p, +\infty)}$, define the **limit from above/below** by

$$\lim_{x \rightarrow p^+} f(x) = \lim_{x \rightarrow p} h(x), \quad \lim_{x \rightarrow p^-} f(x) = \lim_{x \rightarrow p} g(x).$$

Note that f is continuous at p if and only if

$$\lim_{x \rightarrow p^+} f(x) = \lim_{x \rightarrow p^-} f(x) = f(p).$$

Usually we categorize three kinds of continuities:

1. Removable discontinuity: $\lim_{x \rightarrow p^+} f(x) = \lim_{x \rightarrow p^-} f(x) \neq f(p)$. A simple example is

$$f(x) = \begin{cases} x^2 & x \neq 0 \\ 1 & x = 0 \end{cases}$$

2. Jump discontinuity: $\lim_{x \rightarrow p^+} f(x) \neq \lim_{x \rightarrow p^-} f(x)$. A simple example is $\text{sgn}(x)$ at $x = 0$.
3. Essential discontinuity: cases other than (1)(2); that is, at least one of $\lim_{x \rightarrow p^+} f(x)$ and $\lim_{x \rightarrow p^-} f(x)$ does not exist. A simple example is $f(x) = 1/x$ at $x = 0$.

The following examples show that the number of discontinuities is not limited.

Example 4.4.

1. Suppose $f(x)$ is discontinuous at $x = 0$, then the function $g(x) = f(x - a) + f(x - b) + f(x - c)$ is discontinuous at $x = a, b, c$. This means we can construct functions with finitely many discontinuities.

2. The well-known **Dirichlet function** is given by

$$1_{\mathbb{Q}} = \begin{cases} 1 & x \in \mathbb{Q} \\ 0 & x \notin \mathbb{Q} \end{cases}$$

Since \mathbb{Q} is dense in \mathbb{R} , the Dirichlet function is discontinuous everywhere.

3. We can construct function $f(x) = 1_{\mathbb{Q}}(x) \sin(nx)$ so that it is continuous only at $x \in \mathbb{Z}$. That is, we can construct functions which is discontinuous everywhere except some countably many points.
4. The well-known **Thomae's function** is given by

$$f(x) = \begin{cases} 1/q & x = p/q \in \mathbb{Q}, p, q \in \mathbb{Z} \\ 0 & x \notin \mathbb{Q} \end{cases}$$

where p/q is the most reduced form of $x \in \mathbb{Q}$. It could be shown that f is continuous at irrational points but discontinuous at rational points. That is, we can construct functions with countably many discontinuities.

5. The **Conway Base-13 Function** is discontinuous everywhere but still satisfies IVT. It is defined as follows: for every $x \in \mathbb{R}$, write it in base 13 using the alphabet $\{0, 1, \dots, 9, +, -, .\}$. If from some point onwards, the expansion is of form $+x_1x_2\dots x_n.y_1y_2\dots$ or $-x_1x_2\dots x_n.y_1y_2\dots$, then $f(x) = x_1\dots x_n.y_1y_2\dots$ or $-x_1x_2\dots x_n.y_1y_2\dots$; else $f(x) = 0$.

Definition 4.9 (Monotonicity). For ordered sets X, Y , the function $f : X \rightarrow Y$ is **monotone increasing/decreasing** if $a \geq b$ implies $f(a) \geq / \leq f(b)$. In both cases f is **monotone**.

Here we only focus on $f : \mathbb{R} \rightarrow \mathbb{R}$.

Theorem 4.13. Monotone functions can only have jump discontinuities (or no discontinuity).

Proof. For any p , consider the sequences $\{f(p - 1/n)\}_n$ and $\{f(p + 1/n)\}_n$; they are both monotone bounded by $f(p)$, so that they are both convergent. Denote $f(p - 1/n) \rightarrow f(p^-)$ and $f(p + 1/n) \rightarrow f(p^+)$.

To show that $\lim_{x \rightarrow p^-} f(x) = f(p^-)$, since $f(p - 1/n) \rightarrow f(p^-)$, for all ε there exists N such that $|f(p - 1/n) - f(p^-)| < \varepsilon$ for all $n > N$, so take $\delta = 1/(N + 1)$ and we have $|x - p| < \delta \Rightarrow |f(x) - f(p^-)| < \varepsilon$. Analogously, $\lim_{x \rightarrow p^+} f(x) = f(p^+)$.

Finally, to show that $f(p^-), f(p), f(p^+)$ are ordered, it follows from the fact that $f(p - 1/n), f(p), f(p + 1/n)$ are ordered for all n . \square

Theorem 4.14. Monotone functions can be discontinuous only at countably many points.

Proof. Suppose f is monotone increasing and E is the set of jump discontinuous points. For $p \in E$, define

$$I_p = \left(\lim_{x \rightarrow p^-} f(x), \lim_{x \rightarrow p^+} f(x) \right)$$

as the jump interval. Clearly each I_p is non-empty open interval, and I_p, I_q are disjoint if $p \neq q$. However, \mathbb{R} cannot contain uncountably many non-empty disjoint open intervals, since each of the intervals contains at least one rational number. \square

Except for the restriction given by the theorem above, the discontinuities of monotone functions can be arbitrary.

Example 4.5. Let $\sum a_n$ be a convergent series, and $\{p_n\}$ be a countable collection of points in \mathbb{R} (suppose $p_1 < p_2 < \dots$). Then define $f(x) = \sum_{n: p_n < x} a_n$. It is an increasing function, but discontinuous at each p_n :

$$\lim_{x \rightarrow p_n} f(x) = \sum_{k=1}^{n-1} a_k, \quad \lim_{x \rightarrow p_n^+} f(x) = \sum_{k=1}^n a_k.$$

5 Differentiation

5.1 Derivative of Real Function

Definition 5.1 (Derivative). For function $f : \mathbb{R} \rightarrow \mathbb{R}$ and $x \in [a, b]$, define (provided this limit exists)

$$f'(x) = \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

where $t \neq x, h \neq 0$.

Thus, we associate with the function f a function f' whose domain is the set of points x at which the limit exists. f' is called the **derivative** of f .

If f' is defined at the point x , we say that f is **differentiable** at x ; if f' is defined at every point of a set $E \subseteq \mathbb{R}$, we say that f is differentiable on E .

Example 5.1.

1. Suppose

$$f(x) = \begin{cases} x^2 & x \in \mathbb{Q} \\ -x^2 & x \notin \mathbb{Q} \end{cases}$$

then

$$\frac{f(0+h) - f(0)}{h} = \begin{cases} h & h \in \mathbb{Q} \\ -h & h \notin \mathbb{Q} \end{cases}$$

so that $f'(0) = 0$.

2. The well-known Cantor staircase function is continuous and has derivative 0 (except for the Cantor set), but not constant.

Theorem 5.1. Let f be defined on $[a, b]$. If f is differentiable at a point $x \in [a, b]$, then f is continuous at x .

Proof. It is because as $t \rightarrow x$,

$$f(t) - f(x) = \frac{f(t) - f(x)}{t - x}(t - x) \rightarrow f'(x) \cdot 0 = 0.$$

□

Theorem 5.2. Suppose f, g are defined on $[a, b]$ and are differentiable at a point $x \in [a, b]$. Then $f+g, fg, f/g$ (if $g(x) \neq 0$) are differentiable at x , and

1. $(f+g)'(x) = f'(x) + g'(x)$;
2. $(fg)'(x) = f'(x)g(x) + f(x)g'(x)$;
3. $\left(\frac{f}{g}\right)'(x) = \frac{f'(x)g(x) - f(x)g'(x)}{[g(x)]^2}$.

Proof.

1.

$$\begin{aligned} (f+g)'(x) &= \lim_{h \rightarrow 0} \frac{[f(x+h) + g(x+h)] - [f(x) + g(x)]}{h} \\ &= \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} + \frac{g(x+h) - g(x)}{h} = f'(x) + g'(x). \end{aligned}$$

2.

$$\begin{aligned} (fg)'(x) &= \lim_{h \rightarrow 0} \frac{f(x+h)g(x+h) - f(x)g(x)}{h} \\ &= \lim_{h \rightarrow 0} \frac{f(x+h)g(x+h) - f(x)g(x+h)}{h} + \frac{f(x)g(x+h) - f(x)g(x)}{h} \\ &= \lim_{h \rightarrow 0} f'(x)g(x+h) + f(x)g'(x) = f'(x)g(x) + f(x)g'(x). \end{aligned}$$

3.

$$\begin{aligned}\left(\frac{f}{g}\right)'(x) &= \lim_{h \rightarrow 0} \frac{\frac{f(x+h)}{g(x+h)} - \frac{f(x)}{g(x)}}{h} \\ &= \lim_{h \rightarrow 0} \frac{1}{g(x+h)g(x)} \frac{f(x+h)g(x) - f(x)g(x+h)}{h} \\ &= \frac{1}{[g(x)]^2} [f'(x)g(x) - f(x)g'(x)].\end{aligned}$$

□

Theorem 5.3 (Chain Rule). Suppose f is continuous on $[a, b]$, $f'(x)$ exists at some point $x \in [a, b]$, g is defined on an interval I which contains the range of f , and g is differentiable at the point $f(x)$. Then $h = f \circ g$ is differentiable at x , and

$$h'(x) = g'(f(x))f'(x).$$

Proof. Let $y = f(x)$. By the definition of the derivative, we have

$$f(t) - f(x) = (t - x)[f'(x) + u(t)]$$

$$g(s) - g(y) = (s - y)[g'(y) + v(s)]$$

where $t \in [a, b]$, $s \in I$, and $u(t) \rightarrow 0, v(s) \rightarrow 0$ as $t \rightarrow x, s \rightarrow y$. Let $s = f(t)$. Then we obtain

$$\begin{aligned}h(t) - h(x) &= g(f(t)) - g(f(x)) = [f(t) - f(x)][g'(y) + v(s)] \\ &= (t - x)[f'(x) + u(t)][g'(y) + v(s)]\end{aligned}$$

so that when $t \neq x$,

$$\frac{h(t) - h(x)}{t - x} = [g'(y) + v(s)][f'(x) + u(t)]$$

As $t \rightarrow x$, we have $s \rightarrow y$; by the continuity of f , the RHS tends to $g'(y)f'(x)$. □

Example 5.2. Consider the function

$$f(x) = \begin{cases} x \sin(1/x) & x \neq 0 \\ 0 & x = 0 \end{cases}$$

Using the chain rule we have

$$f'(x) = \sin(1/x) + x \cos(1/x)(-1/x^2) = \sin(1/x) - \cos(1/x)/x$$

which does not have limit at $x = 0$, so that $f'(0)$ does not exist.

However, consider the function

$$g(x) = \begin{cases} x^2 \sin(1/x) & x \neq 0 \\ 0 & x = 0 \end{cases}$$

Using the chain rule we have

$$g'(x) = 2x \sin(1/x) + x^2 \cos(1/x)(-1/x^2) = 2x \sin(1/x) - \cos(1/x)$$

which does not have limit at $x = 0$, but by definition it could be shown that $g'(0) = 0$.

5.2 Mean Value Theorems

Theorem 5.4. Let $f : U \rightarrow \mathbb{R}$ be monotone increasing(decreasing), and differentiable at $p \in U$. Then $f'(p) \geq (\leq) 0$.

Proof. Since f is monotone increasing, we have $f(p+h) \geq f(p)$ when $h > 0$, and $f(p+h) \leq f(p)$ when $h < 0$. Hence, $\frac{f(p+h)-f(p)}{h} \geq 0$ for all $h \neq 0$ and $f'(p) \geq 0$. □

Definition 5.2 (Local Maximum/Minimum). Let f be a real function defined on a metric space X . We say that f has a **local maximum (minimum)** at a point $p \in X$ if there exists $\delta > 0$ such that for all $q \in X$, we have $d(p, q) < \delta \Rightarrow f(q) \leq (\geq) f(p)$.

Theorem 5.5. Let f be defined on $[a, b]$; if f has a local maximum at a point $x \in (a, b)$, and $f'(x)$ exists, then $f'(x) = 0$.

Proof. Since f has a local maximum at $x \in (a, b)$, choose δ so that $d(x, t) < \delta \Rightarrow f(t) \leq f(x)$, and $a < x - \delta < x < x + \delta < b$. If $x - \delta < t < x$, we have

$$\frac{f(x) - f(t)}{x - t} \geq 0.$$

Letting $t \rightarrow x$, we have $f'(x) \geq 0$. If $x < t < x + \delta$, we have

$$\frac{f(x) - f(t)}{x - t} \leq 0.$$

Letting $t \rightarrow x$, we have $f'(x) \leq 0$. Hence, $f'(x) = 0$. □

Theorem 5.6 (Rolle's Theorem). If $f : [a, b] \rightarrow \mathbb{R}$ is continuous and differentiable on (a, b) , and $f(a) = f(b)$, then there is a point $x \in (a, b)$ such that $f'(x) = 0$.

Proof. Since $[a, b]$ is compact, there exist $x \in [a, b]$ at which f attains its maximum, and also one of its local maximum; and $y \in [a, b]$ at which f attains its minimum, and also one of its local minimum. If x or $y \in (a, b)$, by Theorem 5.5 we have $f'(x) = 0$ or $f'(y) = 0$.

If x, y are both endpoints, we have $f(a) = f(b) = \sup_{x \in [a, b]} f(x) = \inf_{x \in [a, b]} f(x)$, so that f is constant and $f'(x) = 0$ for all $x \in (a, b)$. □

Corollary 5.1 (Mean Value Theorem). If f is a real continuous real function on $[a, b]$ which is differentiable on (a, b) , then there is a point $x \in (a, b)$ such that

$$f(b) - f(a) = (b - a)f'(x).$$

Proof. Let $g(x) = f(x) - \frac{f(b) - f(a)}{b - a}(x - a)$, then it follows from applying Rolle's theorem to g . □

Corollary 5.2. Suppose f is differentiable on (a, b) , then

1. f is monotone increasing if and only if $f'(x) \geq 0$ for all $x \in (a, b)$.
2. f is constant if and only if $f'(x) = 0$ for all $x \in (a, b)$.
3. f is monotone decreasing if and only if $f'(x) \leq 0$ for all $x \in (a, b)$.

5.3 Lipschitz Function

Definition 5.3 (Lipschitz Function). A function $f : X \rightarrow Y$ is **Lipschitz** if there exists $M \geq 0$ such that for all $x, y \in X$, we have

$$d_Y(f(x), f(y)) \leq M d_X(x, y).$$

We call M the **Lipschitz constant** for f .

Note that Lipschitz function is uniformly continuous: for all $\varepsilon > 0$, take $\delta = \varepsilon/M$ so that $d_X(x, y) < \delta \Rightarrow d_Y(f(x), f(y)) < \delta M = \varepsilon$.

Theorem 5.7. Suppose $f : U \rightarrow \mathbb{R}$ is differentiable on a connected set U . If there exists $M \geq 0$ such that $|f'(x)| \leq M$ for all $x \in U$, then f is a Lipschitz function with constant M .

Note that the converse does not hold; a counter-example is $f(x) = |x|$, which is Lipschitz with constant 1, but not differentiable at $x = 0$.

Proof. For all $a, b \in U$ (suppose $a < b$), since $-M \leq f'(x) \leq M$ for all $x \in (a, b)$, by MVT we have

$$\frac{f(b) - f(a)}{b - a} \leq M \Rightarrow f(b) - f(a) \leq M(b - a)$$

and

$$\frac{f(b) - f(a)}{b - a} \geq -M \Rightarrow f(b) - f(a) \geq -M(b - a).$$

Hence, $|f(b) - f(a)| \leq M|b - a|$ and f is Lipschitz with constant M . □

Theorem 5.8. *If f is differentiable at p , then there exists $M \geq 0, r > 0$ such that*

$$|f(x) - f(p)| \leq M|x - p|, \quad \forall x \in B_r(p).$$

We can say that f is ‘locally Lipschitz’ at p .

Note that the converse does not hold; the counter-example still can be $f(x) = |x|$ at $x = 0$.

Proof. Since f is differentiable at p , $\frac{f(x) - f(p)}{x - p} \rightarrow f'(p)$ as $x \rightarrow p$. Take $r > 0$ such that

$$|x - p| < r \Rightarrow \left| \frac{f(x) - f(p)}{x - p} - f'(p) \right| < 1.$$

Then we have

$$\frac{|f(x) - f(p)|}{|x - p|} \leq |f'(p)| + 1.$$

Hence,

$$|f(x) - f(p)| \leq (|f'(p)| + 1)|x - p|$$

and the Lipschitz constant is given by $M = |f'(p)| + 1$. □

Definition 5.4 (Best Linear Approximation). $a + b(x - p)$ is called the **best linear approximation** of $f(x)$ at p if

$$\lim_{x \rightarrow p} \frac{f(x) - [a + b(x - p)]}{x - p} = 0.$$

Equivalently,

$$f(x) = a + b(x - p) + o(x - p).$$

Theorem 5.9. *Suppose $f : U \rightarrow \mathbb{R}$ is continuous and $p \in U$. Then $a + b(x - p)$ is the best linear approximation of f at p if and only if f is differentiable at p , and*

$$a = f(p), \quad b = f'(p).$$

5.4 Higher Derivatives and Taylor’s Theorem

Definition 5.5 (Higher Derivatives).

$$f^{(n)}(x) = \frac{d}{dx} f^{(n-1)}(x) = \frac{d^n}{dx^n} f(x).$$

Definition 5.6 (Taylor Polynomial). *Suppose $f : U \rightarrow \mathbb{R}$ is n -times differentiable at $p \in U$, then the n -degree **Taylor polynomial** for f at p is a degree- n polynomial*

$$T_p^n(f)(x) = f(p) + f'(p)(x - p) + \dots + \frac{f^{(n)}(p)}{n!}(x - p)^n.$$

Lemma 5.1. *Suppose $f : [a, b] \rightarrow \mathbb{R}$ is n -times differentiable on $[a, b]$, and $f^{(i)}$ is continuous on $[a, b]$ for all $i = 0, 1, \dots, n - 1$. Suppose $f(b) = 0, f(a) = f'(a) = \dots = f^{(n-1)}(a) = 0$. Then there exists $c \in (a, b)$ such that $f^{(n)}(c) = 0$.*

Proof. It could be shown by iterating Rolle’s theorem. By $f(a) = f(b) = 0$, there is some $c_1 \in (a, b)$ such that $f'(c_1) = 0$; by $f'(a) = f'(c_1) = 0$, there is some $c_2 \in (a, c_1)$ such that $f''(c_2) = 0$; ... By iterating this process, we finally find some $c_n \in (a, c_{n-1}) \subset (a, b)$ such that $f^{(n)}(c_n) = 0$. □

Theorem 5.10 (Taylor's Theorem). Suppose $f : [a, b] \rightarrow \mathbb{R}$ is n -times differentiable on $[a, b]$, and suppose $a < \alpha < \beta < b$. Then there exists $z \in (\alpha, \beta)$ such that

$$f(\beta) = T_{\alpha}^{n-1}(f)(\beta) + \frac{f^{(n)}(z)}{n!}(\beta - \alpha)^n.$$

Proof. Let

$$g(x) = f(x) - T_{\alpha}^{(n-1)}(f)(x) - M(x - \alpha)^n.$$

Then $g^{(i)}$ is continuous on $[\alpha, \beta]$ for all $i = 0, 1, \dots, n-1$, and $g(\alpha) = g'(\alpha) = \dots = g^{(n-1)}(\alpha) = 0$, and $g(\beta) = 0$ for some M .

To find M , by the lemma above, there exists $z \in (\alpha, \beta)$ such that

$$g^{(n)}(z) = f^{(n)}(z) - Mn! = 0.$$

Hence, we have $M = f^{(n)}(z)/n!$ and therefore

$$g(\beta) = f(\beta) - T_{\alpha}^{(n-1)}(f)(\beta) - \frac{f^{(n)}(z)}{n!}(\beta - \alpha)^n = 0.$$

□

Corollary 5.3.

1. If $f'' \geq 0$ on $[a, b]$, then $f(x) \geq f(p) + f'(p)(x - p)$ for all $x, p \in [a, b]$;
2. If $|f^{(n+1)}| \leq C$ on $[a, b]$, then $|f(x) - T_p^n(f)(x)| \leq C|x - p|^{n+1}$.

Theorem 5.11. Suppose $f : U \rightarrow \mathbb{R}$ is n -times differentiable at $p \in U$, and $Q : \mathbb{R} \rightarrow \mathbb{R}$ is an n -degree polynomial. Then

$$\lim_{x \rightarrow p} \left| \frac{f(x) - Q(x)}{(x - p)^n} \right| = 0$$

if and only if $Q = T_p^n(f)$. Therefore,

$$f(x) = f(p) + f'(p)(x - p) + \frac{f''(p)}{2}(x - p)^2 + \dots + \frac{f^{(n)}(p)}{n!}(x - p)^n + o(|x - p|^n).$$

Proof. Suppose $Q = T_p^n(f)$. By L'Hospital's rule we have

$$\lim_{x \rightarrow p} \frac{f(x) - T_p^n(f)(x)}{(x - p)^n} = \lim_{x \rightarrow p} \frac{f'(x) - T_p^{n-1}(f')(x)}{n(x - p)^{n-1}} = \dots = \lim_{x \rightarrow p} \frac{f^{(n-1)}(x) - f^{(n-1)}(p) - f^{(n)}(p)(x - p)}{n!(x - p)} = 0$$

since $f^{(n-1)}$ is differentiable at p . Note that

$$\frac{f(x) - Q(x)}{(x - p)^n} = \frac{f(x) - T_p^n(f)(x)}{(x - p)^n} + \frac{T_p^n(f)(x) - Q(x)}{(x - p)^n}.$$

We have shown that the first term on RHS converges to zero. So that it converges to zero if and only if the second term on RHS converges to zero, and

$$\frac{T_p^n(f)(x) - Q(x)}{(x - p)^n} = \frac{a_0 + a_1(x - p) + \dots + a_n(x - p)^n}{(x - p)^n} \rightarrow 0 \text{ as } x \rightarrow p$$

if and only if $a_0 = a_1 = \dots = a_n = 0$. Therefore, $Q = T_p^n(f)$. □

Corollary 5.4 (L'Hospital's Rule). If f, g are 2-times differentiable and $f(p) = g(p) = 0$, $g'(x) \neq 0$ for all x close to p , then

$$\lim_{x \rightarrow p} \frac{f(x)}{g(x)} = \lim_{x \rightarrow p} \frac{f'(x)}{g'(x)}.$$

Proof. By theorem above we have

$$\lim_{x \rightarrow p} \frac{f(x)}{g(x)} = \lim_{x \rightarrow p} \frac{f(p) + f'(p)(x-p) + o(|x-p|)}{g(p) + g'(p)(x-p) + o(|x-p|)} = \lim_{x \rightarrow p} \frac{f'(p)(x-p) + o(|x-p|)}{g'(p)(x-p) + o(|x-p|)} = \lim_{x \rightarrow p} \frac{f'(p)}{g'(p)}.$$

□

Definition 5.7 (Taylor Series). The **Taylor series** for infinite-time differentiable function f at p is the power series

$$T_p(f)(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(p)}{n!} (x-p)^n.$$

Definition 5.8 (Analytic Function). For infinite-time differentiable function f and point p , if there exists $R > 0$ such that

$$T_p(f)(x) = f(x), \quad \forall x \in B_R(p),$$

then we say that f is **analytic** at p .

By the definition, an analytic function is infinite-time differentiable, but the converse does not hold.

Example 5.3. Consider

$$f(x) = \begin{cases} e^{-1/x} & x > 0 \\ 0 & x \leq 0 \end{cases}$$

It could be shown that $f^{(n)}(0) = 0$ for all $n = 0, 1, \dots$ (so that f is infinite-time differentiable), and the Taylor series of f at 0 is $T_0(f) = 0$. However, $f(x) \neq 0$ for any $x > 0$, so that f is not analytic at 0.

5.5 Vector-Valued Function

A vector-valued function $f : \mathbb{R} \rightarrow \mathbb{R}^n$ can be represented by functions mapping to each component: $f(x) = (f_1(x), f_2(x), \dots, f_n(x))'$. Then clearly $f'(x) = (f'_1(x), f'_2(x), \dots, f'_n(x))'$ (if exists).

The MVT does not hold for vector-valued function; a counter-example is to consider $f(x) = (\cos x, \sin x)'$, we have $f(0) = f(2\pi) = 0$ but $f'(x) \neq 0$ for all $x \in \mathbb{R}$.

The relationship between bounded derivative and Lipschitz property still holds.

Theorem 5.12. Suppose $f : [a, b] \rightarrow \mathbb{R}^n$ is continuously differentiable on $[a, b]$, and $\|f'\| \leq M$, then

$$\|f(b) - f(a)\| \leq M|b - a|.$$

Proof. We cannot use MVT directly to f because it does not hold for vector-valued functions. To apply MVT, let $v \in \mathbb{R}^n$ and consider $v \cdot f : [a, b] \rightarrow \mathbb{R}$; we have $(v \cdot f)' = v \cdot f'$. Then by MVT we have

$$\left| \frac{v \cdot (f(b) - f(a))}{b - a} \right| \leq \sup_{x \in [a, b]} (v \cdot f')(x) \leq \|v\| M$$

so that

$$\frac{v}{\|v\|} (f(b) - f(a)) \leq M(b - a).$$

Take $v = f(b) - f(a)$ and we complete the proof. □

The relationship between derivative and best linear approximation still holds. Indeed, if we extend the domain so that $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$, we can define the derivative f' by the best linear approximation: For matrix $A \in \mathbb{R}^{m \times n}$, we call $A = f'(x)$ if

$$f(x) - f(p) - A(x - p) = o(\|x - p\|).$$

6 Integrals

6.1 Darboux Integral and Riemann-Stieltjes Integral

Definition 6.1 (Partition). A **partition** of an interval $[a, b]$ is a finite subset $P \subseteq [a, b]$ with $a, b \in P$. We write

$$P = \{a = x_0 \leq x_1 \leq x_2 \leq \dots \leq x_n = b\}.$$

We denote $\Delta_i = x_i - x_{i-1}$ so that $b - a = \Delta_1 + \Delta_2 + \dots + \Delta_n$. For $t_i \in [x_{i-1}, x_i]$, $i = 1, 2, \dots$, we say that P with $\{t_i\}_{i=1}^n$ is a **tagged partition** of $[a, b]$.

Given function $f : [a, b] \rightarrow \mathbb{R}$ and a partition $P = \{x_0, x_1, \dots, x_n\}$, now we denote

$$m_i = \inf_{x \in [x_{i-1}, x_i]} f(x), \quad M_i = \sup_{x \in [x_{i-1}, x_i]} f(x).$$

So that for all tags $\{t_i\}_{i=1}^n$ we have

$$\sum_{i=1}^n m_i \Delta_i \leq \sum_{i=1}^n f(t_i) \Delta_i \leq \sum_{i=1}^n M_i \Delta_i$$

Definition 6.2 (Darboux Integral). For $f : [a, b] \rightarrow \mathbb{R}$ and partition of $[a, b]$, the **upper/lower Darboux sums** are defined as

$$U(f, p) = \sum_{i=1}^n M_i \Delta_i, \quad L(f, p) = \sum_{i=1}^n m_i \Delta_i.$$

The **upper/lower Darboux integrals** are defined as

$$\overline{\int_a^b} f = \inf_P U(f, p), \quad \underline{\int_a^b} f = \sup_P L(f, p).$$

If the upper and lower Darboux integral are equal (to C), we say that f is integrable (written $f \in \mathcal{R}$) and denote $\int_a^b f = C$.

Definition 6.3 (Riemann-Stieltjes Integral). Given a monotone function $\alpha : [a, b] \rightarrow \mathbb{R}$, for function $f : [a, b] \rightarrow \mathbb{R}$ and partition P , denote $\alpha_i = \alpha(x_i)$, $\forall x_i \in P$ and define

$$U(f, p, \alpha) = \sum_{i=1}^n M_i (\alpha_i - \alpha_{i-1}), \quad L(f, p, \alpha) = \sum_{i=1}^n m_i (\alpha_i - \alpha_{i-1}).$$

Then the **upper/lower Stieltjes integrals** are defined as

$$\overline{\int_a^b} f d\alpha = \inf_P U(f, p, \alpha), \quad \underline{\int_a^b} f d\alpha = \sup_P L(f, p, \alpha).$$

If the upper and lower Stieltjes integral are equal (to C), we say that $f \in \mathcal{R}(\alpha)$ and call $\int_a^b f = C$ the **Riemann-Stieltjes integral**.

Proposition 6.1. Suppose $f : [a, b] \rightarrow \mathbb{R}$ is bounded, α is increasing, P, Q are two partitions of $[a, b]$ such that $P \subseteq Q$ (Q is 'finer' than P), then we have

$$U(f, P, \alpha) \geq U(f, Q, \alpha), \quad L(f, P, \alpha) \leq L(f, Q, \alpha).$$

Proof. Essentially, it is because $A \subseteq B$ can imply $\inf B \leq \inf A$ and $\sup B \geq \sup A$. Then for any $x_{i-2} < x_{i-1} < x_i$ in the interval $[a, b]$, we have

$$\inf_{x \in [x_{i-2}, x_i]} f(x) \leq \inf_{x \in [x_{i-2}, x_{i-1}]} f(x), \quad \inf_{x \in [x_{i-1}, x_i]} f(x);$$

$$\sup_{x \in [x_{i-2}, x_i]} f(x) \geq \sup_{x \in [x_{i-2}, x_{i-1}]} f(x), \quad \sup_{x \in [x_{i-1}, x_i]} f(x).$$

□

Corollary 6.1. Suppose $f : [a, b] \rightarrow \mathbb{R}$ is bounded, α is increasing, P, Q are any two partitions of $[a, b]$, then

$$L(f, P, \alpha) \leq U(f, Q, \alpha).$$

Proof. If $P = Q$, then it is trivial; if not, we can use their common refinement $P \cup Q$ so that

$$L(f, P, \alpha) \leq L(f, P \cup Q, \alpha) \leq U(f, P \cup Q, \alpha) \leq U(f, Q, \alpha).$$

□

Proposition 6.2. Suppose $f : [a, b] \rightarrow \mathbb{R}$ is bounded, α is increasing, then

1. $\int_a^b f d\alpha \leq \int_a^b f d\alpha$.
2. $f \in \mathcal{R}(\alpha)$ if and only if for all $\varepsilon > 0$, there exists a partition P such that

$$U(f, P, \alpha) - L(f, P, \alpha) = \sum_{i=1}^n (M_i - m_i)(\alpha_i - \alpha_{i-1}) < \varepsilon.$$

Proof.

1. By Corollary 6.1 we know that $L(f, P, \alpha) \leq U(f, Q, \alpha)$ for all partitions P, Q . Hence,

$$\int_a^b f d\alpha = \sup_P L(f, P, \alpha) \leq \inf_Q U(f, Q, \alpha) = \int_a^b f d\alpha.$$

2. Denote $U = \{U(f, P, \alpha)\}, L = \{L(f, P, \alpha)\} \subseteq \mathbb{R}$; by Corollary 6.1 we have $l \leq u$ for any $l \in L, u \in U$. Hence, $\inf U(f, P, \alpha) \geq \sup L(f, P, \alpha)$.

If this inequality hold, there must be $\inf_P U(f, P, \alpha) = \sup_P L(f, P, \alpha)$; if not, take $\varepsilon < \inf_P U(f, P, \alpha) - \sup_P L(f, P, \alpha)$ and then there is contradiction. Hence, $\inf_P U(f, P, \alpha) = \sup_P L(f, P, \alpha)$ and $f \in \mathcal{R}(\alpha)$. If $f \in \mathcal{R}$, we have $\int f d\alpha = \inf_P U(f, P, \alpha) = \sup_P L(f, P, \alpha)$. For all $\varepsilon > 0$, take partition P such that $U(f, P, \alpha) < \int f d\alpha + \varepsilon/2$, and partition Q such that $L(f, Q, \alpha) > \int f d\alpha - \varepsilon/2$. Then consider their common partition $P \cup Q$: by Proposition 6.1 we have

$$\begin{aligned} U(f, P \cup Q, \alpha) - L(f, P \cup Q, \alpha) &= \left| U(f, P \cup Q, \alpha) - \int f d\alpha \right| + \left| L(f, P \cup Q, \alpha) - \int f d\alpha \right| \\ &< \left| U(f, P, \alpha) - \int f d\alpha \right| + \left| L(f, Q, \alpha) - \int f d\alpha \right| \\ &< \varepsilon/2 + \varepsilon/2 = \varepsilon. \end{aligned}$$

□

Theorem 6.1. Suppose $f : [a, b] \rightarrow \mathbb{R}$ is continuous, then $f \in \mathcal{R}(\alpha)$.

Proof. Let $L = \alpha(b) - \alpha(a)$. Since f is uniformly continuous (note that $[a, b] \subseteq \mathbb{R}$ is compact), for all $\varepsilon > 0$, there exists $\delta > 0$ such that

$$|x - y| < \delta \quad \Rightarrow \quad |f(x) - f(y)| < \frac{\varepsilon}{L}.$$

Then we consider a partition P such that each $\Delta_i < \delta$, so that

$$U(f, P, \alpha) - L(f, P, \alpha) \leq \sum_{i=1}^n \frac{\varepsilon}{L} (\alpha_i - \alpha_{i-1}) = \frac{\varepsilon}{L} L = \varepsilon$$

and $f \in \mathcal{R}(\alpha)$.

□

Example 6.1. *The topologist's sine curve*

$$f(x) = \begin{cases} \sin(1/x) & x > 0 \\ 0 & x = 0 \end{cases}$$

is integrable on $[0, 1]$ even though it is not continuous at 0. To show this, first note that it is integrable on $[\varepsilon, 1]$ for all $\varepsilon \in (0, 1]$ (due to the continuity). By Proposition 6.2(2), take partition $P = \{0, \varepsilon, x_2, \dots, x_n = 1\}$ such that

$$U(f, \{\varepsilon, x_2, \dots, x_n\}) - \int_{\varepsilon}^1 f \leq \varepsilon,$$

$$\int_{\varepsilon}^1 f - L(f, \{\varepsilon, x_2, \dots, x_n\}) \leq \varepsilon.$$

Note that the additional Riemann sum on interval $[0, \varepsilon]$ can be between $-\varepsilon$ and ε . Hence,

$$U(f, P) \leq \int_{\varepsilon}^1 f + 2\varepsilon, \quad L(f, P) \geq \int_{\varepsilon}^1 f - 2\varepsilon$$

so that

$$U(f, P) - L(f, P) \leq 4\varepsilon.$$

Since $\varepsilon > 0$ is arbitrary, f is integrable on $[0, 1]$.

6.2 Properties of Integral

Proposition 6.3. $\int_a^b f d\alpha$ is linear in f and linear in α . That is,

1. If $f, g \in \mathcal{R}(\alpha)$ and $\lambda \in \mathbb{R}$, then $f + \lambda g \in \mathcal{R}(\alpha)$.
2. If $f \in \mathcal{R}(\alpha), \mathcal{R}(\beta)$ and $\lambda > 0$, then $f \in \mathcal{R}(\alpha + \lambda\beta)$.
3. $\int_a^c f d\alpha = \int_a^b f d\alpha + \int_b^c f d\alpha$ (if any two exist).

Theorem 6.2. Let $g : [a, b] \rightarrow \mathbb{R}$ be bounded, $f : \mathbb{R} \rightarrow \mathbb{R}$ be continuous, and α be increasing. If $g \in \mathcal{R}(\alpha)$, then $f \circ g \in \mathcal{R}(\alpha)$.

Proof. Suppose f is uniformly continuous (since g is bounded). Take ε, δ such that

$$\sup_{x, y \in [x_{i-1}, x_i]} g(x) - g(y) < \delta \quad \Rightarrow \quad \sup_{x, y \in [x_{i-1}, x_i]} f \circ g(x) - f \circ g(y) < \varepsilon.$$

Note that

$$U(g, P, \alpha) - L(g, P, \alpha) \geq \sum_{i: M_i - m_i > \delta} \delta(\alpha_i - \alpha_{i-1})$$

so that (where $K = \sup_{x \in [a, b]} f \circ g(x) - \inf_{x \in [a, b]} f \circ g(x)$)

$$\begin{aligned} U(f \circ g, P, \alpha) - L(f \circ g, P, \alpha) &\leq \varepsilon[\alpha(b) - \alpha(a)] + \sum_{i: M_i - m_i > \delta} K(\alpha_i - \alpha_{i-1}) \\ &\leq \varepsilon[\alpha(b) - \alpha(a)] + \frac{K}{\delta}[U(g, P, \alpha) - L(g, P, \alpha)] \end{aligned}$$

holds for all partitions P . Hence, take P to make the second term on RHS sufficiently small, such that

$$U(f \circ g, P, \alpha) - L(f \circ g, P, \alpha) \leq \varepsilon[\alpha(b) - \alpha(a) + 1]$$

and we complete the proof. □

Corollary 6.2. If $f, g \in \mathcal{R}(\alpha)$, then $f^2, g^2, f \pm g, fg \in \mathcal{R}(\alpha)$. (Note that $fg = (1/4)[(f + g)^2 - (f - g)^2]$.)

Theorem 6.3 (Monotonicity of Integral). *If α is increasing, $f, g \in \mathcal{R}(\alpha)$ and $f \leq g$, then*

$$\int f d\alpha \leq \int g d\alpha.$$

Proof. Essentially, it is because for any interval of any partition,

$$\sup_{x \in [x_{i-1}, x_i]} f(x) \leq \sup_{x \in [x_{i-1}, x_i]} g(x), \quad \inf_{x \in [x_{i-1}, x_i]} f(x) \leq \inf_{x \in [x_{i-1}, x_i]} g(x).$$

□

Proposition 6.4. *Suppose $f, g \in \mathcal{R}(\alpha)$ where α is increasing, then*

1. $|\int f d\alpha| \leq \int |f| d\alpha$;
2. $\int f g d\alpha \leq (\int f^2 d\alpha \int g^2 d\alpha)^{1/2}$.

Proof.

1. Since $-|f| \leq f \leq |f|$, we have $-\int |f| d\alpha \leq \int f d\alpha \leq \int |f| d\alpha$. Note that $|f|$ is integrable because $|\cdot|$ is continuous.
2. Note that $f g \in \mathcal{R}(\alpha)$. By Cauchy-Schwarz we have

$$f g = (\lambda f)(g/\lambda) \leq \frac{\lambda^2 f^2}{2} + \frac{g^2}{2\lambda^2}, \quad \forall \lambda > 0$$

so that

$$\int f g d\alpha \leq \inf_{\lambda > 0} \left[\frac{\lambda^2}{2} \int f^2 d\alpha + \frac{1}{2\lambda^2} \int g^2 d\alpha \right] = \sqrt{\int f^2 d\alpha \int g^2 d\alpha}$$

□

Theorem 6.4 (Change of Variables). *Suppose $\phi : \mathbb{R} \rightarrow \mathbb{R}$ is continuous and strictly increasing, $f, \alpha : [\phi(a), \phi(b)] \rightarrow \mathbb{R}$, $f \in \mathcal{R}(\alpha)$. Suppose $g = f \circ \phi$, $\beta = \alpha \circ \phi$, then $g \in \mathcal{R}(\beta)$ and*

$$\int_a^b g d\beta = \int_{\phi(a)}^{\phi(b)} f d\alpha.$$

Proof. For any partition $P = \{a, x_1, \dots, x_{n-1}, b\}$ of $[a, b]$, define $\phi(P) = \{\phi(a), \phi(x_1), \dots, \phi(x_{n-1}), \phi(b)\}$ as a partition of $[\phi(a), \phi(b)]$. ϕ is an one-to-one mapping from partitions of $[a, b]$ to partitions of $[\phi(a), \phi(b)]$, since ϕ is continuous and strictly increasing. Hence,

$$U(f, \phi(P), \alpha) = U(g, P, \beta), \quad L(f, \phi(P), \alpha) = L(g, P, \beta).$$

□

Theorem 6.5. *Suppose $f, \alpha : [a, b] \rightarrow \mathbb{R}$, $\alpha' : (a, b) \rightarrow \mathbb{R}$ is continuous. Then $f \in \mathcal{R}(\alpha)$ if and only if $f \alpha' \in \mathcal{R}$ and*

$$\int f d\alpha = \int f \alpha'.$$

Proof. For all $\varepsilon > 0$, take partition $P = \{x_0, x_1, \dots, x_n\}$ such that $U(f, P, \alpha') - L(f, P, \alpha') < \varepsilon$. The MVT implies that for each interval $[x_{i-1}, x_i]$, there is some $t_i \in [x_{i-1}, x_i]$ such that

$$\alpha_i - \alpha_{i-1} = \alpha'(t_i) \Delta_i.$$

Also for all $s_i \in [x_{i-1}, x_i]$, we have

$$\sum_{i=1}^n |\alpha'(s_i) - \alpha'(t_i)| \Delta_i < \varepsilon.$$

Let $M = \sup |f(x)|$, then by inequality above,

$$\left| \sum_{i=1}^n f(s_i)(\alpha_i - \alpha_{i-1}) - \sum_{i=1}^n f(s_i)\alpha'(s_i)\Delta_i \right| \leq M\varepsilon.$$

On one hand, taking supremum over s_i on the second term on LHS gives

$$\sum_{i=1}^n f(s_i)(\alpha_i - \alpha_{i-1}) \leq U(f\alpha', P) + M\varepsilon.$$

Then by taking supremum over s_i on LHS, we have

$$U(f, P, \alpha) \leq U(f\alpha', P) + M\varepsilon.$$

On the other hand, taking supremum on the first term on LHS and then the other gives

$$U(f\alpha', P) \leq U(f, P, \alpha) + M\varepsilon.$$

Thus,

$$|U(f, P, \alpha) - U(f\alpha', P)| < M\varepsilon.$$

Since it also holds for any refinement of P , we conclude that

$$\left| \int_a^b f d\alpha - \int_a^b f \alpha' \right| < M\varepsilon.$$

Note that $\varepsilon > 0$ is arbitrary. Hence

$$\int_a^b f d\alpha = \int_a^b f \alpha'.$$

The equality of the lower integrals follows from the same way. \square

Theorem 6.6.

1. Let $\alpha(x) = 1_{x>p}$. If f is continuous at p , then $f \in \mathcal{R}(\alpha)$ and $\int f d\alpha = f(p)$.
2. Suppose $c_n \geq 0$ for $n = 1, 2, \dots$ and $\sum c_n$ converges, $\{s_n\}$ is a sequence of distinct points in (a, b) , and $\alpha(x) = \sum_{n=1}^{\infty} c_n 1_{x>s_n}$, and f is continuous. Then

$$\int_a^b f d\alpha = \sum_{n=1}^{\infty} c_n f(s_n).$$

Proof.

1. Consider the partition $P = \{x_0, x_1, x_2, x_3\}$ where $a = x_0 < x_1 = p < x_2 < x_3 = b$. Then clearly we have

$$U(f, P, \alpha) = \sup_{x \in [x_1, x_2]} f(x), \quad L(f, P, \alpha) = \inf_{x \in [x_1, x_2]} f(x).$$

Hence, by letting $x_2 \rightarrow x_1 = p$ we have $U(f, P, \alpha), L(f, P, \alpha) \rightarrow f(p)$.

2. For all $\varepsilon > 0$, take N such that $\sum_{n=N+1}^{\infty} c_n < \varepsilon$. Decompose α into $\alpha = \alpha_1 + \alpha_2$, where

$$\alpha_1(x) = \sum_{n=1}^N c_n 1_{x>s_n}, \quad \alpha_2(x) = \sum_{n=N+1}^{\infty} c_n 1_{x>s_n}.$$

Then by (1) we have

$$\int_a^b f d\alpha_1 = \sum_{n=1}^N c_n f(s_n), \quad \left| \int_a^b f d\alpha_2 \right| \leq M\varepsilon$$

where $M = \sup |f(x)|$. Hence,

$$\left| \int_a^b f d\alpha - \sum_{n=1}^N c_n f(s_n) \right| \leq M\varepsilon.$$

By letting $N \rightarrow \infty$ we complete the proof. □

6.3 Bounded Variation

Definition 6.4 (Total Variation). For function $f : [a, b] \rightarrow \mathbb{R}$ and partition P of $[a, b]$, the **variation** of f over P is

$$V(f, P) = \sum_{i=1}^n |f(x_i) - f(x_{i-1})|.$$

The **total variation** of f is $TV(f) = \sup_P V(f, P)$. If $TV(f)$ is finite, f has **bounded variation** (f is BV).

Theorem 6.7 (Jordan Decomposition). A function f is BV if and only if it can be decomposed into the sum of increasing and decreasing functions.

Proof. First note that if $f : [a, b] \rightarrow \mathbb{R}$ is monotone, then clearly $TV(f) = |f(a) - f(b)|$. Hence, if $f = f_1 + \dots + f_n$ where f_1, \dots, f_n are monotone (and BV), we have $TV(f) \leq TV(f_1) + \dots + TV(f_n)$ so that f is BV.

Suppose f is BV, consider $f_x = f|_{[a, x]}$, $x \in [a, b]$; then $TV(f_x)$ is increasing in x . Then given $\alpha < \beta$, choose any partition P and we have

$$f(\beta) - f(\alpha) = \sum [f(x_i) - f(x_{i-1})] \leq \sum |f(x_i) - f(x_{i-1})| = TV(f_\beta) - TV(f_\alpha).$$

Rearranging terms gives

$$f(\beta) - TV(f_\beta) \leq f(\alpha) - TV(f_\alpha)$$

so that $f(x) - TV(f_x)$ is decreasing. Hence, f can be decomposed into

$$f(x) = TV(f_x) + [f(x) - TV(f_x)]$$

in which the first term on RHS is increasing, and the second term is decreasing. □

Proposition 6.5. Suppose α is BV, $f \in \mathcal{R}(\alpha)$. Then for all $\varepsilon > 0$, there exist some tagged partition P such that

$$\left| \int f d\alpha - \sum f(t_i)(\alpha_i - \alpha_{i-1}) \right| < \varepsilon.$$

Proof. By Jordan decomposition, $\alpha = \alpha^+ - \alpha^-$ which are both increasing. By linearity of integral we have $\int f d\alpha = \int f d\alpha^+ - \int f d\alpha^-$ and $\mathcal{R}(\alpha) = \mathcal{R}(\alpha^+) \cap \mathcal{R}(\alpha^-)$. Hence,

$$\left| \int f d\alpha - \sum f(t_i)(\alpha_i - \alpha_{i-1}) \right| \leq \left| \int f d\alpha^+ - \sum f(t_i)(\alpha_i^+ - \alpha_{i-1}^+) \right| + \left| \int f d\alpha^- - \sum f(t_i)(\alpha_i^- - \alpha_{i-1}^-) \right|.$$

Since α^+, α^- are increasing, there exists partition P such that both two terms on RHS are smaller than $\varepsilon/3$. □

6.4 Fundamental Theorem of Calculus

Theorem 6.8 (FToC, Version 1). If $f \in \mathcal{R}$ on $[a, b]$, and let $F(x) = \int_a^x f$, $x \in [a, b]$, then F is continuous. Further, if f is continuous at $p \in [a, b]$, then $F'(p) = f(p)$.

Note that the continuity of f is necessary; for example, consider $f(x) = \text{sgn}(x)$ and thus $F(x) = |x|$; F is not differentiable at 0 since f is discontinuous at 0.

Proof. Since f is bounded (as $f \in \mathcal{R}$), $|f(x)| \leq M$ for some $M > 0$. Then

$$|F(x) - F(y)| = \left| \int_a^x f - \int_a^y f \right| = \left| \int_y^x f \right| \leq M|x - y|$$

and F is Lipschitz (thus continuous). Moreover, we can obtain a linear approximation equation

$$F(x) - F(p) = \int_p^x f = \int_p^x f(p) + \int_p^x [f - f(p)] = f(p)(x - p) + E$$

Hence, we only need to show that if f is continuous at p , then $E = o(|x - p|)$.

Since f is continuous, for all $\varepsilon > 0$, there exists $\delta > 0$ such that

$$|x - p| < \delta \quad \Rightarrow \quad |f(x) - f(p)| < \varepsilon$$

so that $|E| \leq \varepsilon|x - p|$. Since ε can be arbitrarily small, we complete the proof. \square

Theorem 6.9 (FToC, Version 2). *If $f \in \mathcal{R}$ and $f' \in \mathcal{R}$ on $[a, b]$, then*

$$f(b) = f(a) + \int_a^b f'.$$

Proof. For any partition P of $[a, b]$, by MVT there exist tags $\{t_i\}$ such that

$$\sum f'(t_i)\Delta_i = \sum f(x_i) - f(x_{i-1}) = f(b) - f(a).$$

Hence, $L(f', P) \leq f(b) - f(a) \leq U(f', P)$ for any partition P . Since f' is integrable, we must have $\int_a^b f' = f(b) - f(a)$. \square

6.5 Integration by Parts

Theorem 6.10 (Integration by Parts). *If $f, g : [a, b] \rightarrow \mathbb{R}$ and $f', g' : [a, b] \rightarrow \mathbb{R}$ are integrable, then*

$$\int_a^b fg' = fg|_a^b - \int_a^b f'g.$$

Proof. It follows from the product rule and FToC:

$$fg|_a^b = \int_a^b (fg)' = \int_a^b f'g + \int_a^b fg'.$$

\square

Theorem 6.11 (Generalized Integration by Parts). *Suppose $f : [a, b] \rightarrow \mathbb{R}$ is differentiable and α is BV. If $f \in \mathcal{R}(\alpha)$ and $\alpha f' \in \mathcal{R}$, then*

$$\int_a^b f d\alpha = f\alpha|_a^b - \int_a^b \alpha f'.$$

Proof. If α is increasing, for any partition we have (denote $f_i = f(x_i)$)

$$\begin{aligned} f\alpha|_a^b &= \sum_i (f_i\alpha_i - f_{i-1}\alpha_{i-1}) \\ &= \sum_i f_i(\alpha_i - \alpha_{i-1}) + \sum_i (f_i - f_{i-1})\alpha_{i-1} \\ &= \sum_i f_i(\alpha_i - \alpha_{i-1}) + \sum_i \alpha_{i-1}f'(t_i)\Delta_i \end{aligned}$$

in which the last equality follows from MVT, where $t_i \in [x_{i-1}, x_i]$. By definition of integrals, we have

$$f\alpha|_a^b = \sum_i f_i(\alpha_i - \alpha_{i-1}) + \sum_i \alpha_{i-1}f'(t_i)\Delta_i \rightarrow \int_a^b f d\alpha + \int_a^b \alpha f'$$

as partition P becomes finer.

For the general α , decompose it into $\alpha = \alpha^+ - \alpha^-$ and similar result follows from applying the argument to them respectively. \square

Indeed, the generalized integration by parts can include the special case of FToC: let $\alpha = 1_{[l,r]}$ where $[l, r] \subseteq [a, b]$; if f is integrable, we have

$$\int_a^b f d\alpha = f\alpha|_a^b - \int_a^b \alpha f' = - \int_l^r f'$$

Meanwhile, we know that $\int_a^b f d\alpha = f(l) - f(r)$, so that

$$\int_l^r f' = - \int_a^b f d\alpha = f(r) - f(l)$$

which exactly refers to the FToC (Version 2; Theorem 6.9).

7 Sequence of Functions

7.1 Pointwise Convergence

Definition 7.1 (Function Space). For metric spaces X, Y , denote $\mathcal{F}(X, Y)$ the set of all functions $f : X \rightarrow Y$. If Y is a vector space, then $\mathcal{F}(X, Y)$ is also a vector space. Denote $\mathcal{F}(X) = \mathcal{F}(X, \mathbb{R})$.

Definition 7.2 (Pointwise Convergence). For a sequence (f_n) of functions in $\mathcal{F}(X, Y)$, it **converges (pointwisely)** to $f : X \rightarrow Y$ if $\lim_{n \rightarrow \infty} f_n(x) = f(x)$ for all $x \in X$. We denote it by $f_n \rightarrow f$.

Note that a sequence (x_n) of (real) numbers can be viewed as a function $f : \mathbb{N} \rightarrow \mathbb{R}$, so that $\mathbb{R}^\infty = \mathcal{F}(\mathbb{N}, \mathbb{R})$. Here pointwise convergence $a_n \rightarrow a$ means $a_n^k \rightarrow a^k (n \rightarrow \infty)$ for all $k = 0, 1, 2, \dots$.

Example 7.1 (Problems of Pointwise Convergence, in $\mathcal{F}(\mathbb{N}, \mathbb{R})$).

1. Let $a_n = (1, \dots, 1, 0, 0, \dots)$ with first n arguments being 1, others being 0. Then $a_n \rightarrow a = (1, 1, \dots)$ since $\lim_{n \rightarrow \infty} a_n^k = 1$ for all k . However,

$$\lim_{k \rightarrow \infty} a_n^k = 0, \forall n \quad \lim_{k \rightarrow \infty} a^k = 1 \quad \Rightarrow \quad \lim_{n \rightarrow \infty} \lim_{k \rightarrow \infty} a_n^k \neq \lim_{k \rightarrow \infty} \lim_{n \rightarrow \infty} a_n^k$$

2. Let $e_n = (0, \dots, 0, 1, 0, \dots)$ with the n -th argument being 1, others being 0. Then $e_n \rightarrow e = 0$ since $\lim_{n \rightarrow \infty} e_n^k = 0$ for all k . However,

$$\sum_k e_n^k = 1, \forall n \quad \sum_k e^k = 0 \quad \Rightarrow \quad \lim_{n \rightarrow \infty} \sum_k e_n^k \neq \sum_k \lim_{n \rightarrow \infty} e_n^k$$

$$\|e_n\|_p = 1, \forall n \quad \|e\|_p = 0 \quad \Rightarrow \quad \lim_{n \rightarrow \infty} \|e_n\|_p \neq \left\| \lim_{n \rightarrow \infty} e_n \right\|_p$$

These examples show that pointwise convergence does not preserve limits, sums and ℓ^p norms.

Example 7.2 (Problems of Pointwise Convergence, in $\mathcal{F}(\mathbb{R}, \mathbb{R})$).

1. Let

$$f_n(x) = \frac{1}{(1+x^2)^n}, n = 1, 2, \dots$$

They are all uniformly continuous (continuous, Lipschitz, and differentiable) since $|f'_n| \leq n$. However, this sequence pointwisely converges to

$$f_n(x) \rightarrow f(x) = \begin{cases} 1 & x = 0 \\ 0 & x \neq 0 \end{cases}$$

which is discontinuous (not Lipschitz, and not differentiable).

2. Let

$$f_n(x) = \frac{1}{n} \sin(nx), n = 1, 2, \dots$$

whose graph oscillates between $[-1/n, 1/n]$ with wavelength $2\pi/n$, so that $f'_n \approx (2/n)/(\pi/n) = 2/\pi$ which does not depend on n . However, $f_n \rightarrow f = 0$ and $f' = 0$.

3. Let

$$f_n(x) = \begin{cases} 2^n & 2^{-n} \leq x \leq 2 \times 2^{-n} \\ 0 & \text{otherwise} \end{cases}, n = 1, 2, \dots$$

so that $\int_0^1 f_n = 1$ for all n . However, $f_n \rightarrow f = 0$ and $\int_0^1 f = 0$.

4. Let

$$f_n(x) = \begin{cases} 1 & x = p/q \in \mathbb{Q}, q \leq n \\ 0 & \text{otherwise} \end{cases}, n = 1, 2, \dots$$

so that $f_n(x) = 1$ for finitely many $x \in [0, 1]$ and $f_n \in \mathcal{R}$ for all n . However, $f_n \rightarrow 1_{\mathbb{Q}} \notin \mathcal{R}$.

These examples show that pointwise convergence does not preserve continuity, differentiability (and derivatives) and integrability (and integrals).

7.2 Uniform Convergence

Definition 7.3 (Uniform Convergence). For a sequence (f_n) of functions in $\mathcal{F}(X, Y)$, it **uniformly converges** to f (denoted $f_n \rightrightarrows f$) if for all $\varepsilon > 0$, there exists N such that for all $n \geq N$,

$$d(f_n(x), f(x)) < \varepsilon, \quad \forall x \in X.$$

Note that the difference from pointwise convergence is that ε does not depend on x .

Proposition 7.1. $f_n \rightrightarrows f$ if and only if

$$\sup_{x \in X} d(f_n(x), f(x)) \rightarrow 0 \quad (n \rightarrow \infty)$$

Similar with Cauchy property, define the ‘uniformly Cauchy’ property in sequence of functions as follows: for all $\varepsilon > 0$, there exists N such that

$$d(f_n, f_m) = \sup_{x \in X} d_Y(f_n(x), f_m(x)) < \varepsilon, \quad \forall n, m > N.$$

Theorem 7.1 (Cauchy Criterion). Suppose Y is Cauchy complete, (f_n) is ‘uniformly Cauchy’ in $\mathcal{F}(X, Y)$. Then $f_n \rightrightarrows f$ for some $f \in \mathcal{F}(X, Y)$.

Proof. For any fixed $x \in X$, the sequence $(f_n(x))_n$ is Cauchy since $d(f_n(x), f_m(x)) \leq \sup_{x \in X} d(f_n(x), f_m(x))$ for all n, m and $x \in X$. Since Y is Cauchy complete, the limit of $(f_n(x))$ exists and let $f(x) \equiv \lim_{n \rightarrow \infty} f_n(x)$. Now we only need to show that $f_n \rightrightarrows f$.

For all $\varepsilon > 0$, there exists N such that $\sup_{x \in X} d(f_n(x), f_m(x)) < \varepsilon$ for all $n, m > N$. Then

$$d(f_n(x), f(x)) = \lim_{m \rightarrow \infty} d(f_n(x), f_m(x)) \leq \varepsilon, \quad \forall x \in X, \forall n > N.$$

Therefore, $f_n \rightrightarrows f$ as $\varepsilon > 0$ is arbitrarily small. □

Corollary 7.1 (Weierstrass M-Test). Suppose (f_n) is a sequence in $\mathcal{F}(X)$ such that $\sup_{x \in X} |f_n(x)| \leq M_n$ and $\sum_n M_n < \infty$. Then $\sum_n f_n$ converges uniformly.

Proof. Note that

$$\left| \left(\sum_{k=1}^m f_k \right)(x) - \left(\sum_{k=1}^n f_k \right)(x) \right| = |f_{n+1}(x) + \dots + f_m(x)| \leq M_{n+1} + \dots + M_m$$

so that (M_n) is Cauchy implies that (f_n) is ‘uniformly Cauchy’. □

Theorem 7.2. Suppose $E \subseteq X$, $f_n, f : E \rightarrow Y$ and $p \in E'$. If $f_n \rightrightarrows f$ and $\lim_{x \rightarrow p} f_n(x) = L_n \in Y$ for every n , then (L_n) is Cauchy and

$$\lim_{n \rightarrow \infty} L_n = \lim_{x \rightarrow p} f(x)$$

if the limit of (L_n) exists. In other words, we have

$$\lim_{n \rightarrow \infty} \lim_{x \rightarrow p} f_n(x) = \lim_{x \rightarrow p} \lim_{n \rightarrow \infty} f_n(x).$$

Proof. To show that (L_n) is Cauchy, note that

$$d(L_n, L_m) \leq d(L_n, f_n(x)) + \sup_{x \in E} d(f_n(x), f_m(x)) + d(L_m, f_m(x)).$$

For the second term on RHS, since (f_n) converges uniformly, for all $\varepsilon > 0$, pick N such that $\sup_{x \in E} d(f_n(x), f_m(x)) < \varepsilon/3$ for all $n, m > N$. For the first and third term on RHS, there exists $x \in E$ such that $d(L_n, f_n(x)), d(L_m, f_m(x)) < \varepsilon/3$. Hence,

$$d(L_n, L_m) < \varepsilon, \quad \forall n, m \geq N$$

and (L_n) is Cauchy.

Denote $\lim_{n \rightarrow \infty} L_n = L$. To show that $f(x) \rightarrow L$ as $x \rightarrow p$, note that

$$d(f(x), L) \leq \sup_{x \in E} d(f(x), f_n(x)) + d(f_n(x), L_n) + d(L_n, L), \quad \forall n.$$

Taking $n \rightarrow \infty$, the first and third term on RHS converge to zero; then by taking $x \rightarrow p$, the second term on RHS converge to zero (note that the first and third term on RHS do not depend on x). Therefore, $f(x) = L = \lim_{n \rightarrow \infty} L_n$. \square

Corollary 7.2. *Suppose $f_n : X \rightarrow Y$ are continuous, $f_n \rightrightarrows f$, then f is also continuous.*

Definition 7.4. *Suppose X, Y are metric spaces and Y is complete. Denote $C^0(X, Y)$ the set of bounded continuous functions $f : X \rightarrow Y$ with metric (called ‘uniform distance’)*

$$d_0(f, g) = \sup_{x \in X} d_Y(f(x), g(x)).$$

Note that

1. Convergence in C^0 is equivalent with uniform convergence.
2. $C^0 \subseteq \mathcal{R}$.
3. C^0 is a complete metric space. The completeness can help to show the existence of some continuous functions.

Example 7.3 (Peano Curve). *Peano curve is a surjective continuous function $f : [0, 1] \rightarrow [0, 1] \times [0, 1]$ defined by the limit of sequence (f_n) . Details are omitted.*

By construction, (f_n) is Cauchy since

$$|f_n(x) - f_{n-1}(x)| \leq 2\sqrt{2} \cdot 3^{-n}$$

so that

$$d_0(f_n, f_m) \leq \sum_{i=n+1}^m 2\sqrt{2} \cdot 3^{-i} \rightarrow 0 \quad (n, m \rightarrow \infty).$$

Hence, $f_n \rightrightarrows f$ and f is continuous. It is surjective because (1) its image is closed since the domain is compact; (2) its image is dense in $[0, 1] \times [0, 1]$. Therefore, its image is exactly $[0, 1] \times [0, 1]$.

Proposition 7.2. *Integration $C^0([a, b]) \rightarrow \mathbb{R}$ is continuous.*

Proof. Notice that $C^0 \subseteq \mathcal{R}$, so we only need to show that $f_n \rightrightarrows f$ (in $C^0([a, b])$) implies $\int f_n \rightarrow \int f$. It is because

$$\left| \int f_n - \int f \right| = \left| \int_a^b (f_n - f) \right| \leq \sup_{x \in [a, b]} (f_n(x) - f(x))(b - a) \rightarrow 0 \quad (n \rightarrow \infty).$$

\square

Theorem 7.3. *Suppose α is BV, $f_n \rightrightarrows f$ and $f_n \in \mathcal{R}(\alpha)$ for all n . Then $f \in \mathcal{R}(\alpha)$ and $\int f_n d\alpha \rightarrow \int f d\alpha$.*

Proof. Without loss of generality, suppose α is monotone increasing. For all $\varepsilon > 0$, there exists n such that $\sup_{x \in [a, b]} |f_n(x) - f(x)| < \varepsilon$. Then take partition P such that $U(f_n, P, \alpha) - L(f_n, P, \alpha) < \varepsilon$ (since $f_n \in \mathcal{R}(\alpha)$). Then we have

$$\sup_{x \in [x_{i-1}, x_i]} f(x) < \sup_{x \in [x_{i-1}, x_i]} f_n(x) + \varepsilon, \quad \inf_{x \in [x_{i-1}, x_i]} f(x) > \inf_{x \in [x_{i-1}, x_i]} f_n(x) - \varepsilon.$$

Hence, $(M_i^n \equiv \sup_{x \in [x_{i-1}, x_i]} f_n(x), m_i^n \equiv \inf_{x \in [x_{i-1}, x_i]} f_n(x))$

$$\begin{aligned} U(f, P, \alpha) - L(f, P, \alpha) &= \sum_i (M_i - m_i)(\alpha_i - \alpha_{i-1}) \\ &\leq \sum_i (M_i^n - m_i^n + 2\varepsilon)(\alpha_i - \alpha_{i-1}) \\ &= U(f_n, P, \alpha) - L(f_n, P, \alpha) + 2\varepsilon(\alpha(b) - \alpha(a)) \\ &\leq \varepsilon + 2\varepsilon(\alpha(b) - \alpha(a)) \end{aligned}$$

and f is thus integrable. □

Example 7.4 (Integrability of Thomae's Function). *Recall the Thomae's function*

$$f(x) = \begin{cases} 1/q & x = p/q \in \mathbb{Q}, p, q \in \mathbb{Z} \\ 0 & x \notin \mathbb{Q} \end{cases}$$

Indeed, it is the limit of sequence (f_n) given by

$$f_n(x) = \begin{cases} 1/q & x = p/q \in \mathbb{Q}, p, q \in \mathbb{Z}, q \leq n \\ 0 & x \notin \mathbb{Q} \end{cases}$$

and the convergence is uniform as $\sup_{x \in [0,1]} |f_n(x) - f(x)| = 1/n \rightarrow 0 (n \rightarrow \infty)$.

Since each f_n is integrable and $\int f_n = 0$, the Thomae's function f is also integrable and $\int f = 0$.

However, even uniform convergence cannot preserve differentiability.

Example 7.5. Recall Example 7.2(2); let $f_n(x) = \frac{1}{n} \sin(nx)$ and $f'_n(x) = \cos(nx)$. It could be shown that $f_n \rightrightarrows f = 0$, but $\{f'_n(x)\}$ does not converge.

Lemma 7.1. Suppose f_n are differentiable, $f_n \rightarrow f$ pointwise, and $f'_n \rightrightarrows f'$. Then for all p ,

$$\Phi_n(x) = \frac{f_n(x) - f_n(p)}{x - p} \rightrightarrows \Phi(x) = \frac{f(x) - f(p)}{x - p}.$$

Proof. Note that for all x ,

$$\Phi_n(x) - \Phi_m(x) = \frac{(f_n - f_m)(x) - (f_n - f_m)(p)}{x - p} = (f_n - f_m)'(\alpha)$$

for some α . Since (f'_n) is Cauchy, $(f_n - f_m)'(\alpha) \rightarrow 0$ as $n, m \rightarrow \infty$, and (Φ_n) is also Cauchy. Then taking $m \rightarrow \infty$ gives for all x ,

$$|\Phi_n(x) - \Phi(x)| \leq \sup_x \lim_{m \rightarrow \infty} |\Phi_n(x) - \Phi_m(x)| \rightarrow 0 \quad (n \rightarrow \infty).$$

□

Theorem 7.4. Suppose $f_n : [a, b] \rightarrow \mathbb{R}$ are differentiable, $f_n \rightarrow f$ pointwise, and $f'_n \rightrightarrows g$, then $f' = g$ (if f' exists).

Proof. Define Φ_n, Φ as the lemma above; we only need to show that $\Phi(x) \rightarrow g(p)$ as $x \rightarrow p$ (for all p). Note that

$$|\Phi(x) - g(p)| \leq |\Phi(x) - \Phi_n(x)| + |\Phi_n(x) - f'_n(p)| + |f'_n(p) - g(p)|, \quad \forall n, \forall x.$$

Since $\Phi_n(x) \rightrightarrows \Phi(x)$ (by lemma above), the first term on RHS converges to 0 as $n \rightarrow \infty$ (regardless of x); since $f'_n \rightrightarrows g$, the third term on RHS also converges to 0 as $n \rightarrow \infty$ (regardless of p); the second term on RHS converges to 0 as $x \rightarrow p$. □

Finally, the following example shows that the limit of 'uniformly Cauchy' sequence of differentiable functions may be nowhere differentiable.

Example 7.6 (Weierstrass function). *The Weierstrass function can be constructed as follows:*

1. *Pick a bounded, oscillating and periodic function, such as $T(x) = \sin x$.*
2. *Let $f_n(x) = \alpha^n T(\beta^n x)$, where $\alpha < 1, \beta > 1$ and $\alpha\beta \geq 1$. Note that $\sup |f_n(x)| = \alpha^n \rightarrow 0$ but $\sup |f'_n(x)| = (\alpha\beta)^n \rightarrow \infty$ (if $\alpha\beta > 1$) as $n \rightarrow \infty$.*
3. *Take $f(x) = \sum_{n=1}^{\infty} f_n(x)$. It converges uniformly (by Weierstrass M-test) but $\sum_{n=1}^{\infty} f'_n(x)$ diverges for all x .*

7.3 Equicontinuity

Definition 7.5 (Modulus of Continuity). A **modulus of continuity** is a function $\omega : (0, \infty) \rightarrow [0, \infty]$ such that $\lim_{x \rightarrow 0} \omega(x) = 0$. Function f has modulus of continuity at p if there exists ω_p such that

$$d_X(x, p) < \delta \Rightarrow d_Y(f(x), f(p)) < \omega_p(\delta), \quad \forall p > 0.$$

Proposition 7.3. *f is continuous at p if and only if it has a modulus of continuity at p .*

By definition of modulus of continuity, it is easy to see that

1. *f is uniformly continuous if and only if its modulus of continuity is independent of p ; that is, f has a modulus of continuity ω at all p .*
2. *f is Lipschitz with constant L if and only if it has a modulus of continuity $\omega(\delta) = L\delta$ at all p .*

Definition 7.6 (Equicontinuity). A collection of functions $F \subseteq \mathcal{F}(X, Y)$ is **equicontinuous** if for all $p \in X$, there exists ω_p such that for all $f \in F$, ω_p is a modulus of continuity of f at p .

In other words, for all $\varepsilon > 0$, there exists $\delta > 0$ such that for all $x, p \in X$, we have $d_X(x, p) < \delta \Rightarrow d_Y(f(x), f(p)) < \varepsilon$ for all $f \in F$.

Theorem 7.5. *If $f_n \rightarrow f$ pointwise, and (f_n) is equicontinuous, then f is continuous.*

Proof. Suppose ω_p is a common modulus of continuity of (f_n) at p . Then if $|x - p| < \delta$, we have

$$|f(x) - f(p)| \leq |f(x) - f_n(x)| + |f_n(x) - f_n(p)| + |f_n(p) - f(p)| \leq |f(x) - f_n(x)| + \omega_p(\delta) + |f_n(p) - f(p)|, \quad \forall n.$$

For all $\varepsilon > 0$, since $\omega_p(\delta) \rightarrow 0$ as $\delta \rightarrow 0$, there exists $\delta_0 > 0$ such that $\omega_p(\delta) < \varepsilon/3$ for all $\delta < \delta_0$; since $f_n \rightarrow f$ pointwise, there exists N such that $|f(x) - f_n(x)|, |f(p) - f_n(p)| < \varepsilon/3$ for all $n > N$. Hence,

$$|x - p| < \delta_0 \quad \Rightarrow \quad |f(x) - f(p)| < \varepsilon/3 + \varepsilon/3 + \varepsilon/3 = \varepsilon$$

and f is continuous. □

7.4 Bounded Continuous Function Space C^0

Consider the compactness in function space C^0 .

Example 7.7. *Compact set in C^0 must be closed and bounded, but the converse may not hold. To see this, take $f(x) : [0, +\infty) \rightarrow \mathbb{R}$ such that (1) $f(0) = 0$, (2) $f(1) = 1$ which is the global maximum of f , and (3) $\lim_{x \rightarrow \infty} f(x) = 0$. Then let $f_n(x) = f(nx)$ (so that the global maximum of f_n is at $1/n$ and $f_n(1/n) = 1$).*

Clearly, $f_n \in C^0$ for all n , and $f_n \rightarrow 0$ pointwise, so that $(f_n) \subseteq \overline{B_1(0)}$. However, the convergence is not uniform, and any subsequence of (f_n) cannot be uniformly convergent. Therefore, $\overline{B_1(0)}$ is not compact. (Recall Corollary 3.2: any sequence of a compact set has convergent subsequence.)

Proposition 7.4. *If $f_n \rightrightarrows f$ in $C^0(X, Y)$, then for all $p \in X$, there exists a modulus of continuity ω_p such that f and all f_n have ω_p at p . That is, $(f_n) \cup \{f\}$ is equicontinuous.*

Proof. For any given $p \in X$, pick a modulus of continuity $\omega_{p,n}$ at p for each f_n , and ω_p at p for f . Then define

$$\bar{\omega}_p(r) = \sup\{\omega_p(r), \omega_{p,n}(r)\}_{n \in \mathbb{N}}, \quad \forall r.$$

Then for any function $g \in (f_n) \cup \{f\}$, we have

$$d(x, p) < \delta \quad \Rightarrow \quad d(g(x), g(p)) < \bar{\omega}_p(\delta).$$

That is, $\bar{\omega}_p(r)$ is a common modulus of continuity for all f_n and f if it can be legitimated.

To show that $\bar{\omega}_p(r)$ is a legitimate modulus of continuity, we only need to show that $\bar{\omega}_p(r) \rightarrow 0$ as $r \rightarrow 0$. For all $\varepsilon > 0$, since $f_n \rightrightarrows f$, there exists N such that for all $n > N$,

$$d(f_n(x), f_n(p)) < d(f(x), f(p)) + \varepsilon.$$

So by selecting $\omega_{p,n}(r) \leq \omega_p(r) + \varepsilon, \forall r$ for all $n > N$, we have

$$\bar{\omega}_p(r) \leq \max\{\omega_{p,0}(r), \dots, \omega_{p,n}(r), \omega_p(r) + \varepsilon\}$$

so that $\lim_{r \rightarrow 0} \bar{\omega}_p(r) \leq \varepsilon$. Therefore, $\lim_{r \rightarrow 0} \bar{\omega}_p(r) = 0$ as $\varepsilon > 0$ can be arbitrarily small. \square

Theorem 7.6. *If $F \subseteq C^0$ is compact, then*

1. *F is uniformly bounded; that is, there exists $M > 0$ such that $|f(x)| \leq M$ for all $x \in X$ and all $f \in F$.*
2. *F is equicontinuous.*

Proof. (1) follows from the boundedness of F . To show (2), take a modulus of continuity $\omega_{p,f}$ of each $f \in F$ and $p \in X$. Then define

$$\omega_p(r) = \sup_{f \in F} \omega_{p,f}(r), \quad \forall p, r.$$

Clearly, if $\omega_p(r)$ is a modulus of continuity, it is a common modulus of continuity for all $f \in F$.

Now we only need to show that $\omega_p(r)$ is a legitimate modulus of continuity, that is, $\omega_p(r) \rightarrow 0$ as $r \rightarrow 0$. If not, then there exists $(f_n) \subseteq F$ such that $\liminf \omega_{p,f_n}(1/n) = \alpha > 0$. However, by proposition above, (f_n) will have no convergent subsequence (CONTINUE), which contradicts the compactness of F . Therefore, $\omega_p(r)$ is a modulus of continuity. \square

Theorem 7.7 (Arzela-Ascoli). *Suppose K is compact, $F \subseteq C^0(K, \mathbb{R})$. If*

1. *F is bounded in C^0 ;*
2. *F is equicontinuous,*

then any sequence in F has a convergent subsequence in C^0 . Hence, if F is also closed, the limit of convergent subsequence is in F , so that F is compact.

Proof. Let $(f_k)_{k \in \mathbb{N}}$ be a sequence in F . Since F is equicontinuous, we can find a common modulus of continuity ω_p for F at any $p \in K$. Since K is compact (any open cover of K has finite subcover), for all $k \in \mathbb{N}$, there exists a finite collection $\{p_{i,k}, \delta_{i,k}\}_{i=1}^{n_k}$ such that

$$\omega_{p_{i,k}}(\delta_{i,k}) < \frac{1}{k}, \forall i = 1, \dots, n_k \quad \text{and} \quad K \subseteq \bigcup_{i=1}^{n_k} B_{\delta_{i,k}}(p_{i,k}).$$

Take $E_k = \{p_{i,k}\}_{i=1}^{n_k}$. Since E_k is finite and $\bigcup_{k=1}^{\infty} E_k$ is countable, there exists $A \subseteq \mathbb{N}$ such that $(f_k(p))_{k \in A}$ converges for all $p \in \bigcup_{k=1}^{\infty} E_k$. (CONTINUE)

Finally, we only need to show that $(f_k)_{k \in A}$ (as a subsequence of $(f_k)_{k \in \mathbb{N}}$) is uniformly convergent (so that it is convergent in C^0). For all $\varepsilon > 0$, for sufficiently large k such that $1/k < \varepsilon$, so that $\omega_p(\delta_p) \leq \varepsilon$ for all $p \in E_k$. By construction above, for all $x \in K$ there exists $p \in E$ such that $x \in B_{\delta_p}(p)$. Hence, for sufficiently large $m, n \in A$, we have

$$|f_n(x) - f_m(x)| \leq |f_n(p) - f_m(p)| + |f_n(x) - f_n(p)| + |f_m(x) - f_m(p)| \leq 3\varepsilon$$

since (1) $x \in B_{\delta_p}(p), \omega_p(\delta_p) \leq \varepsilon$ implies

$$|f_n(x) - f_n(p)| \leq \omega_p(|x - p|) \leq \omega_p(\delta_p) \leq \varepsilon$$

and (2) the convergence of $(f_k(p))_{k \in A}$ implies $|f_n(p) - f_m(p)| \leq \varepsilon$ for sufficiently large $n, m \in A$.

Therefore, $(f_k)_{k \in A}$ is convergent as $\varepsilon > 0$ can be arbitrarily small. \square

Theorem 7.8 (Stone-Weierstrass). *Suppose $f : [a, b] \rightarrow \mathbb{R}$ is continuous. Then there exists a sequence of polynomials (P_n) such that $P_n \rightrightarrows f$.*

Hence, the set of all polynomials on $[a, b]$ is dense in $C^0([a, b])$.

Note that (1) comparing to Taylor series, the function f needs not be differentiable; (2) the coefficients of P_n may vary with n .

Definition 7.7 (Algebra). In function space $\mathcal{F}(X, \mathbb{R})$, an **algebra** $A \subseteq \mathcal{F}(X, \mathbb{R})$ is a collection of functions such that for all $f, g \in A$ and $\lambda \in \mathbb{R}$, we have $f + g, fg, \lambda f \in A$; moreover, any constant function $C \in A$.

A collection $F \subseteq \mathcal{F}(X, \mathbb{R})$ of functions **separates points** if for any two distinct points $x, y \in X$, there exists $f \in F$ such that $f(x) \neq f(y)$.

Lemma 7.2. For any $N > 0$, there exists a sequence of polynomials (P_n) that uniformly converge to $|x|$ on $[-N, N]$.

Theorem 7.9 (Generalized Stone-Weierstrass). Suppose K is compact in a metric space, $A \subseteq C^0(K)$ is an algebra which separate points, then A is dense in $C^0(K)$.

Proof. Pick two distinct points $x, y \in K$, then there exists $g \in A$ such that $g(x) \neq g(y)$. Let $\bar{g} = \frac{g - g(y)}{g(x) - g(y)} \in A$, so that $\bar{g}(x) = 1, \bar{g}(y) = 0$. Then consider $f\bar{g} + f(1 - \bar{g}) \in A$; we have $f\bar{g} + f(1 - \bar{g}) = f$ at $x, y \in X$.

For any $x \in K$ and $\varepsilon > 0$, for all $y \in K$, there exists $g_y \in A$ such that (1) $g_y(x) = f(x), g_y(y) = f(y)$ (see above); (2) g_y is continuous, so that there exists δ_y such that $|f(z) - g_y(z)| < \varepsilon$ for all $z \in B_{\delta_y}(y)$.

Since K is compact, there exists $\{y_i, \delta_i\}_{i=1}^n$ such that $K \subseteq \cup_{i=1}^n B_{\delta_i}(y_i)$. Consider the corresponding $\{g_{y_i}\}_{i=1}^n$; there exists $\bar{g}_x \in A$ such that $\bar{g}_x \in B_\varepsilon(\max_{1 \leq i \leq n} g_{y_i})$, so that $\bar{g}_x(x) \in B_\varepsilon(f(x))$ and $\bar{g}_x(z) > f(z) - 2\varepsilon$ for all $z \in K$.

Moreover, we can find $\{\xi_i\}_{i=1}^m$ such that $f(z) + 2\varepsilon > \min_{1 \leq i \leq m} \bar{g}_{\xi_i}(z)$ for all $z \in K$. Hence, we finally take $g \in A$ such that $g \in B_\varepsilon(\min_{1 \leq i \leq m} \bar{g}_{\xi_i})$, so that $g \in B_{3\varepsilon}(f)$ and we complete the proof. \square

8 Functions of Several Variables

8.1 Linear Transformations

Definition 8.1 (Vector Space). A non-empty set $X \subset \mathbb{R}^n$ is a **vector space** if $x + y \in X$ and $cx \in X$ for all $x, y \in X$ and scalars c .

If $x_1, \dots, x_k \in \mathbb{R}^n$ and c_1, \dots, c_k are scalars, the vector $c_1x_1 + \dots + c_kx_k$ is called a **linear combination** of x_1, \dots, x_k . If $S \subset \mathbb{R}^n$ and E is the set of all linear combinations of elements of S , we say that S **spans** E , or that E is the **span** of S , denoted $E = \text{span}(S)$.

A set consisting of vectors x_1, \dots, x_k is **independent** if the relation $c_1x_1 + \dots + c_kx_k = 0$ implies $c_1 = \dots = c_k = 0$. Otherwise, $\{x_1, \dots, x_k\}$ is **dependent**.

If a vector space X contains an independent set of r vectors but contains no independent set of $r+1$ vectors, we say that X has **dimension** r , denoted $\dim(X) = r$. The set consisting of 0 alone is a vector space. Its dimension is defined to be 0.

An independent subset of a vector space X which spans X is called a **basis** of X . If $B = \{x_1, \dots, x_r\}$ is a basis of X , then every $x \in X$ has a unique representation of the form $x = \sum_j c_j x_j$. The numbers c_1, \dots, c_r are called the **coordinates** of x with respect to the basis B . The **standard basis** of \mathbb{R}^n is $\{e_1, \dots, e_n\}$, where e_j is the vector in \mathbb{R}^n whose j -th coordinate is 1 and other coordinates are all 0.

Theorem 8.1. Let $r \in \mathbb{N}_+$. If a vector space X is spanned by a set of r vectors, then $\dim(X) \leq r$.

Proof. If not, there is a vector space X which contains an independent set $Q = \{y_1, \dots, y_{r+1}\}$ and which is spanned by a set S_0 consisting of r vectors.

Now we construct S_1, \dots, S_n by induction. Suppose a set S_i ($i = 0, \dots, r-1$) has been constructed which spans X and which consists of y_1, \dots, y_i and a certain collection of $r-i$ members of S_0 , say x_1, \dots, x_{r-i} . Since S_i spans X , y_{i+1} is in the span of S_i , and there are scalars $a_1, \dots, a_{i+1}, b_1, \dots, b_{r-i}$ with $a_{i+1} = 1$ such that

$$\sum_{j=1}^{i+1} a_j y_j + \sum_{k=1}^{r-i} b_k x_k = 0.$$

If all b_k 's were 0, the independence of $Q = \{y_1, \dots, y_{r+1}\}$ implies all a_j 's will be 0, a contradiction. Hence, some $x_k \in S_i$ is a linear combination of the other members of $T_i = S_i \cup \{y_{i+1}\}$. Remove this x_k from T_i and call the remaining set S_{i+1} . Then S_{i+1} spans the same set as T_i , namely X . In this way we guarantee that S_{i+1} satisfies the hypothesis above.

Starting with S_0 , we thus construct sets S_1, \dots, S_r . Finally $S_r = \{y_1, \dots, y_r\}$ and it spans X . However, Q is independent, and hence y_{r+1} is not in the span of S_r . This contradiction completes the proof. \square

Corollary 8.1. $\dim(\mathbb{R}^n) = n$.

Proof. Since $\{e_1, \dots, e_n\}$ spans \mathbb{R}^n , the theorem above shows $\dim(\mathbb{R}^n) \leq n$. Since $\{e_1, \dots, e_n\}$ is independent, $\dim(\mathbb{R}^n) \geq n$. \square

Theorem 8.2. Suppose X is a vector space with $\dim(X) = n$.

1. A set E of n vectors in X spans X if and only if E is independent.
2. X has a basis, and every basis consists of n vectors.
3. If $1 \leq r \leq n$ and $\{y_1, \dots, y_r\}$ is an independent set in X , then X has a basis containing $\{y_1, \dots, y_r\}$.

Proof.

1. Suppose $E = \{x_1, \dots, x_n\}$. Since $\dim(X) = n$, the set $\{x_1, \dots, x_n, y\}$ is dependent for every $y \in X$. If E is independent, it follows that y is in $\text{span}(E)$ and hence $\text{span}(E) = X$. If E is dependent, one of its members can be removed without changing the $\text{span}(E)$, and hence $\text{span}(E) \neq X$.
2. Since $\dim(X) = n$, X contains an independent set of n vectors, and (1) shows that every such set is a basis of X . The second statement then follows from Theorem 8.1.
3. Let $\{x_1, \dots, x_n\}$ be a basis of X . The set

$$S = \{y_1, \dots, y_r, x_1, \dots, x_n\}$$

spans X and is dependent, since it has more than n vectors. The proof of Theorem 8.1 shows that one of the x_i 's is a linear combination of the other members of S . If this x_i is removed from S , the remaining

set still spans X . This process can be repeated r times and leads to a basis of X containing $\{y_1, \dots, y_r\}$ by (1). □

Definition 8.2 (Linear Transformation). *A mapping A of a vector space X into a vector space Y is a **linear transformation** if*

$$A(x_1 + x_2) = Ax_1 + Ax_2, \quad A(cx) = cAx$$

for all $x, x_1, x_2 \in X$ and scalars c .

Linear transformations of X into X are often called **linear operators** on X .

Definition 8.3 (Inverse of Linear Operator). *If A is a linear operator on X which (i) is one-to-one (injective), and (ii) maps X onto X , we say that A is **invertible**, and we can define an operator A^{-1} on X by requiring that $A^{-1}(Ax) = x$ for all $x \in X$.*

It is easy to see that $A(A^{-1}x) = x$ for all $x \in X$, and A^{-1} is also linear. The following theorem shows that condition (i) and (ii) are equivalent in finite-dimensional vector spaces.

Theorem 8.3. *A linear operator A on a finite-dimensional vector space X is one-to-one if and only if the range of A is all of X .*

Proof. Let $\{x_1, \dots, x_n\}$ be a basis of X . The linearity of A shows that its range $\mathcal{R}(A)$ is the span of the set $Q = \{Ax_1, \dots, Ax_n\}$. It follows from Theorem 8.2(1) that $\mathcal{R}(A) = X$ if and only if Q is independent. Therefore, we only need to prove it is true if and only if A is one-to-one.

Suppose A is one-to-one and $\sum_i c_i Ax_i = 0$. Then $A(\sum_i c_i x_i) = 0$ and hence $\sum_i c_i x_i = 0$, and hence $c_1 = \dots = c_n = 0$. Therefore, Q is independent.

Conversely, suppose Q is independent and $A(\sum_i c_i x_i) = 0$. Then $\sum_i c_i Ax_i = 0$ and hence $c_1 = \dots = c_n = 0$. Thus, $Ax = 0$ if and only if $x = 0$. As a result, $Ax = Ay$ implies $A(x - y) = 0$ and $x - y = 0$. It means A is one-to-one. □

Definition 8.4 (Sum and Product of Linear Transformations). *Let $L(X, Y)$ be the set of all linear transformations of the vector space X into the vector space Y . We write $L(X)$ instead of $L(X, X)$.*

If $A_1, A_2 \in L(X, Y)$ and if c_1, c_2 are scalars, define $c_1 A_1 + c_2 A_2$ by

$$(c_1 A_1 + c_2 A_2)x = c_1 A_1 x + c_2 A_2 x, \quad x \in X.$$

It is then clear that $c_1 A_1 + c_2 A_2 \in L(X, Y)$.

If X, Y, Z are vector spaces, $A \in L(X, Y)$ and $B \in L(Y, Z)$, we define their product BA to be the composition of A and B :

$$(BA)x = B(Ax), \quad x \in X.$$

Then $BA \in L(X, Z)$.

Definition 8.5 (Norm). *For $A \in L(\mathbb{R}^n, \mathbb{R}^m)$, define the **norm** $\|A\|$ of A to be the supremum of all numbers $|Ax|$, where x ranges over all vectors in \mathbb{R}^n with $|x| \leq 1$.*

Theorem 8.4.

1. *If $A \in L(\mathbb{R}^n, \mathbb{R}^m)$, then $\|A\| < \infty$ and A is a uniformly continuous mapping of \mathbb{R}^n into \mathbb{R}^m .*
2. *If $A, B \in L(\mathbb{R}^n, \mathbb{R}^m)$ and c is a scalar, then*

$$\|A + B\| \leq \|A\| + \|B\|, \quad \|cA\| = |c|\|A\|.$$

With the distance between A and B defined as $\|A - B\|$, $L(\mathbb{R}^n, \mathbb{R}^m)$ is a metric space.

3. *If $A \in L(\mathbb{R}^n, \mathbb{R}^m)$ and $B \in L(\mathbb{R}^m, \mathbb{R}^k)$, then*

$$\|BA\| \leq \|B\|\|A\|.$$

Proof.

1. Let $\{e_1, \dots, e_n\}$ be a standard basis in \mathbb{R}^n and suppose $x = \sum_i c_i e_i$, $|x| \leq 1$, so $|c_i| \leq 1$ for every $i = 1, \dots, n$. Then

$$|Ax| = \left| \sum_i c_i e_i \right| \leq \sum_i |c_i| |Ae_i| \leq \sum_i |Ae_i|,$$

so that

$$\|A\| \leq \sum_i |Ae_i| < \infty.$$

Next, since $|Ax - Ay| \leq \|A\||x - y|$ for $x, y \in \mathbb{R}^n$, A is uniformly continuous.

2. The first inequality follows from

$$|(A + B)x| = |Ax + Bx| \leq |Ax| + |Bx| \leq (\|A\| + \|B\|)|x|,$$

and the second inequality is proved analogously. The triangle inequality follows from

$$\|A - C\| = \|(A - B) + (B - C)\| \leq \|A - B\| + \|B - C\|.$$

3. It follows from

$$|(BA)x| = |B(Ax)| \leq \|B\||Ax| \leq \|B\|\|A\||x|.$$

□

Theorem 8.5. *Let Ω be the set of all invertible linear operators in \mathbb{R}^n .*

1. *If $A \in \Omega$, $B \in L(\mathbb{R}^n)$, and*

$$\|B - A\|\|A^{-1}\| < 1,$$

then $B \in \Omega$.

2. *Ω is an open subset of $L(\mathbb{R}^n)$, and the mapping $A \mapsto A^{-1}$ is continuous on Ω .*

Proof. Put $\|A^{-1}\| = 1/\alpha$ and $\|B - A\| = \beta$, then $\beta < \alpha$. For every $x \in \mathbb{R}^n$,

$$\alpha|x| = \alpha|A^{-1}Ax| \leq \alpha\|A^{-1}\||Ax| = |Ax| \leq |(A - B)x| + |Bx| \leq \beta|x| + |Bx|,$$

so that

$$(\alpha - \beta)|x| \leq |Bx|, \quad \forall x \in \mathbb{R}^n.$$

Since $\alpha - \beta > 0$, it shows that $Bx \neq 0$ if $x \neq 0$, and hence B is one-to-one (injective), and by Theorem 8.3 B is also surjective, and hence B is invertible.

Replacing x with $B^{-1}y$, then the resulting inequality

$$(\alpha - \beta)|B^{-1}y| \leq |BB^{-1}y| = |y|$$

shows that $\|B^{-1}\| \leq (\alpha - \beta)^{-1}$. Therefore, the identity

$$B^{-1} - A^{-1} = B^{-1}(A - B)A^{-1},$$

combined with Theorem 8.4(3) implies that

$$\|B^{-1} - A^{-1}\| \leq \|B^{-1}\| \|A - B\| \|A^{-1}\| \leq \frac{\beta}{\alpha(\alpha - \beta)} \rightarrow 0, \quad \beta \rightarrow 0.$$

This establishes the continuity since $\beta \rightarrow 0$ as $B \rightarrow A$.

□

Definition 8.6 (Matrix). *Suppose $\{x_1, \dots, x_n\}$ and $\{y_1, \dots, y_m\}$ are bases of vector spaces X and Y , respectively. Then every $A \in L(X, Y)$ determines a set of numbers $\{a_{ij}\}_{1 \leq i \leq m, 1 \leq j \leq n}$ such that*

$$Ax_j = \sum_{i=1}^m a_{ij} y_i, \quad j = 1, \dots, n.$$

We visualize these numbers in a rectangular array of m rows and n columns, called an $m \times n$ **matrix**:

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}.$$

Sometimes we write

$$A = [Ax_1, \dots, Ax_n],$$

since the coordinates a_{ij} of the vector $Ax_j = [a_{1j}, \dots, a_{mj}]^\top$ appear in the j -th column of A . The vectors Ax_j are therefore called the **column vectors** of A .

8.2 Differentiation

Definition 8.7. Suppose E is an open set in \mathbb{R}^n , f maps E into \mathbb{R}^m , and $x \in E$. If there exists a linear transformation A of \mathbb{R}^n into \mathbb{R}^m such that

$$\lim_{h \rightarrow 0} \frac{f(x+h) - f(x) - Ah}{|h|} = 0,$$

then we say that f is **differentiable** at x , and we write $f'(x) = A$.

If f is differentiable at every $x \in E$, we say that f is **differentiable** in E .

Theorem 8.6 (Uniqueness of Derivative). Suppose E and f are as in Definition 8.7, $x \in E$, and the limit holds with $A = A_1$ and with $A = A_2$, then $A_1 = A_2$.

Proof. Let $B = A_1 - A_2$, then the inequality

$$|Bh| \leq |f(x+h) - f(x) - A_1h| + |f(x+h) - f(x) - A_2h|$$

shows that $|Bh|/|h| \rightarrow 0$ as $h \rightarrow 0$. For fixed $h \neq 0$, it follows that

$$\frac{|B(th)|}{|th|} \rightarrow 0, \quad t \rightarrow 0.$$

The linearity of B shows that the result is independent of t , thus $Bh = 0$ for every $h \in \mathbb{R}^n$. Hence $B = 0$. \square

Theorem 8.7 (Chain Rule). Suppose E is an open set in \mathbb{R}^n , f maps E into \mathbb{R}^m , f is differentiable at $x_0 \in E$, g maps an open set containing $f(E)$ into \mathbb{R}^k , and g is differentiable at $f(x_0)$. Then the mapping $g \circ f$ of E into \mathbb{R}^k is differentiable at x_0 , and

$$(g \circ f)'(x_0) = g'(f(x_0))f'(x_0).$$

Proof. Put $y_0 = f(x_0)$, $A = f'(x_0)$, $B = g'(y_0)$, and define

$$u(h) = f(x_0 + h) - f(x_0) - Ah,$$

$$v(k) = g(y_0 + k) - g(y_0) - Bk,$$

for all $h \in \mathbb{R}^n$ and $k \in \mathbb{R}^m$ for which $f(x_0 + h)$ and $g(y_0 + k)$ are defined. Then by the definition of derivatives,

$$|u(h)| = \varepsilon(h)|h|, \quad |v(k)| = \eta(k)|k|,$$

where $\varepsilon(h) \rightarrow 0$ as $h \rightarrow 0$ and $\eta(k) \rightarrow 0$ as $k \rightarrow 0$.

Given h , put $k = f(x_0 + h) - f(x_0)$. Then

$$(g \circ f)(x_0 + h) - (g \circ f)(x_0) - BAh = g(y_0 + k) - g(y_0) - BAh = B(k - Ah) + v(k) = Buh(H) + v(k).$$

Hence, for $h \neq 0$ we have

$$\frac{|(g \circ f)(x_0 + h) - (g \circ f)(x_0) - BAh|}{|h|} \leq \|B\|\varepsilon(h) + [\|A\| + \varepsilon(h)]\eta(k).$$

Let $h \rightarrow 0$, then $\varepsilon(h) \rightarrow 0$. Also, then $k \rightarrow 0$ and thus $\eta(k) \rightarrow 0$. Therefore, $(g \circ f)'(x_0) = BA$. \square

Definition 8.8 (Partial Derivatives). Suppose f maps an open set $E \subset \mathbb{R}^n$ into \mathbb{R}^m . Let $\{e_1, \dots, e_n\}$ and $\{u_1, \dots, u_m\}$ be the standard bases of \mathbb{R}^n and \mathbb{R}^m . The **components** of f are real functions f_1, \dots, f_m defined by

$$f(x) = \sum_{i=1}^m f_i(x)u_i, \quad x \in E.$$

For $x \in E, i = 1, \dots, m, j = 1, \dots, n$, we define

$$(D_j f_i)(x) = \lim_{t \rightarrow 0} \frac{f_i(x + te_j) - f_i(x)}{t}.$$

provided the limit exists. The notation $\frac{\partial f_i}{\partial x_j}$ is often used in place of $D_j f_i$, and it is called a **partial derivative**.

Theorem 8.8. Suppose f maps an open set $E \subset \mathbb{R}^n$ into \mathbb{R}^m , and f is differentiable at a point $x \in E$. Then the partial derivatives $(D_j f_i)(x)$ exist, and

$$f'(x)e_j = \sum_{i=1}^m (D_j f_i)(x)u_i, \quad j = 1, \dots, n.$$

Proof. Fix j . Since f is differentiable at x ,

$$f(x + te_j) - f(x) = f'(x)(te_j) + r(te_j)$$

where $|r(te_j)|/t \rightarrow 0$ as $t \rightarrow 0$. The linearity of $f'(x)$ shows that

$$\lim_{t \rightarrow 0} \frac{f(x + te_j) - f(x)}{t} = f'(x)e_j.$$

If we represent f in terms of its components, then it becomes

$$\lim_{t \rightarrow 0} \sum_{i=1}^m \frac{f_i(x + te_j) - f_i(x)}{t} u_i = f'(x)e_j.$$

It follows that each quotient in this sum has a limit as $t \rightarrow 0$, so that each $(D_j f_i)(x)$ exists and the equation follows from the definition of partial derivatives. \square

Definition 8.9 (Gradient, Directional Derivative). Let f be a real-valued differentiable function with an open domain $E \subset \mathbb{R}^n$. Associated with each $x \in E$, the **gradient** of f at x is defined by

$$(\nabla f)(x) = \sum_{i=1}^n (D_i f)(x)e_i.$$

Fix $x \in E$ and let $u \in \mathbb{R}^n$ be a unit vector. The limit

$$(D_u f)(x) = \lim_{t \rightarrow 0} \frac{f(x + tu) - f(x)}{t} = (\nabla f)(x) \cdot u$$

is called the **directional derivative** of f at x in the direction of the unit vector u .

Theorem 8.9. Suppose f maps a convex open set $E \subset \mathbb{R}^n$ into \mathbb{R}^m , f is differentiable in E , and there is a real number M such that

$$\|f'(x)\| \leq M, \quad \forall x \in E.$$

Then

$$|f(b) - f(a)| \leq M|b - a|, \quad \forall a, b \in E.$$

Proof. Fix $a, b \in E$. Define

$$\gamma(t) = (1-t)a + tb, \quad t \in \mathbb{R}$$

provided that $\gamma(t) \in E$. Since E is convex, $\gamma(t) \in E$ for $t \in [0, 1]$. Put

$$g(t) = f(\gamma(t)).$$

Then using the chain's rule,

$$g'(t) = f'(\gamma(t))\gamma'(t) = f'(\gamma(t))(b-a),$$

so that

$$|g'(t)| \leq \|f'(\gamma(t))\| |b-a| \leq M|b-a|, \quad \forall t \in [0, 1].$$

Hence,

$$|f(b) - f(a)| = |g(1) - g(0)| \leq M|b-a|.$$

□

Corollary 8.2. *If, in addition, $f'(x) = 0$ for all $x \in E$, then f is constant.*

Definition 8.10 (Continuous Differentiability). *A differentiable mapping f of an open set $E \subset \mathbb{R}^n$ into \mathbb{R}^m is **continuously differentiable** in E if f' is a continuous mapping of E into $L(\mathbb{R}^n, \mathbb{R}^m)$.*

More explicitly, for every $x \in E$ and $\varepsilon > 0$ there exists a $\delta > 0$ such that for all $y \in E$,

$$|x - y| < \delta \quad \Rightarrow \quad \|f'(y) - f'(x)\| < \varepsilon.$$

If this is so, we also say that f is a \mathcal{C}' -mapping, denoted $f \in \mathcal{C}'(E)$.

Theorem 8.10. *Suppose f maps an open set $E \subset \mathbb{R}^n$ into \mathbb{R}^m . Then $f \in \mathcal{C}'(E)$ if and only if the partial derivatives $D_j f_i$ exist and are continuous on E for $i = 1, \dots, m, j = 1, \dots, n$.*

Proof. Suppose $f \in \mathcal{C}'(E)$, then f' is continuous. By the definition of partial derivatives,

$$(D_j f_i)(x) = (f'(x)e_j) \cdot u_i, \quad \forall i, j, \forall x \in E.$$

Hence,

$$(D_j f_i)(y) - (D_j f_i)(x) = [(f'(y) - f'(x))e_j] \cdot u_i.$$

Since $|u_i| = |e_j| = 1$, it follows that

$$|(D_j f_i)(y) - (D_j f_i)(x)| \leq |(f'(y) - f'(x))e_j| \leq \|f'(y) - f'(x)\|.$$

Hence, $D_j f_i$ is continuous.

Conversely, it suffices to consider the case $m = 1$. Fix $x \in E$ and $\varepsilon > 0$. Since E is open, there is an open ball $S \subset E$ centered at x with radius r , and the continuity of functions $D_j f$ shows that r can be chosen so that

$$|(D_j f)(y) - (D_j f)(x)| < \frac{\varepsilon}{n}, \quad \forall y \in S, \forall j = 1, \dots, n.$$

Suppose $h = \sum h_j e_j$ and $|h| < r$. Let $v_0 = 0$ and $v_k = h_1 e_1 + \dots + h_k e_k$ for $k = 1, \dots, n$. Then

$$f(x+h) - f(x) = \sum_{j=1}^n [f(x+v_j) - f(x+v_{j-1})].$$

Since $|v_k| < r$ for every k and S is convex, $x + v_{j-1}, x + v_j \in S$. Since $v_j = v_{j-1} + h_j e_j$, the mean value theorem shows that

$$f(x+v_j) - f(x+v_{j-1}) = h_j (D_j f)(x+v_{j-1} + \theta_j h_j e_j)$$

for some $\theta_j \in (0, 1)$, and it differs from $h_j (D_j f)(x)$ by less than $|h_j| \varepsilon / n$. It follows that

$$\left| f(x+h) - f(x) - \sum_{j=1}^n h_j (D_j f)(x) \right| \leq \frac{1}{n} \sum_{j=1}^n |h_j| \varepsilon \leq |h| \varepsilon$$

for all h such that $|h| < r$.

This says that f is differentiable at x , and $f'(x)$ is the linear function which assigns the number $\sum h_j (D_j f)(x)$ to the vector $h = \sum h_j e_j$. Hence, the matrix $f'(x)$ consists of the row $(D_1 f)(x), \dots, (D_n f)(x)$. Since $D_1 f, \dots, D_n f$ are continuous functions on E , $f \in \mathcal{C}'(E)$. \square

8.3 Inverse Function and Implicit Function Theorem

Definition 8.11 (Contraction). *Let X be a metric space with metric d . If φ maps X into X and if there is a number $c < 1$ such that*

$$d(\varphi(x), \varphi(y)) \leq cd(x, y), \quad \forall x, y \in X,$$

*then φ is a **contraction** of X into X .*

Theorem 8.11 (Contraction Principle). *If X is a complete metric space, and φ is a contraction of X into X , then there exists a unique $x \in X$ such that $\varphi(x) = x$.*

Proof. Pick $x_0 \in X$ arbitrarily, and define $\{x_n\}$ recursively by setting

$$x_{n+1} = \varphi(x_n), \quad n = 0, 1, 2, \dots$$

Then for $n \geq 1$ we have

$$d(x_{n+1}, x_n) = d(\varphi(x_n), \varphi(x_{n-1})) \leq cd(x_n, x_{n-1}).$$

Hence, induction gives

$$d(x_{n+1}, x_n) \leq c^n d(x_1, x_0), \quad n = 0, 1, 2, \dots$$

For $n < m$, it follows that

$$d(x_n, x_m) \leq \sum_{i=n+1}^m d(x_i, x_{i-1}) \leq (c^n + \dots + c^{m-1})d(x_1, x_0) \leq \frac{c^n}{1-c} d(x_1, x_0) \rightarrow 0, \quad n \rightarrow \infty.$$

Thus, $\{x_n\}$ is Cauchy. Since X is complete, $x_n \rightarrow x$ for some $x \in X$.

Finally, since φ is a contraction, φ is continuous on X and

$$\varphi(x) = \lim_{n \rightarrow \infty} \varphi(x_n) = \lim_{n \rightarrow \infty} x_{n+1} = x.$$

\square

Theorem 8.12 (Inverse Function). *Suppose f is a \mathcal{C}' -mapping of an open set $E \subset \mathbb{R}^n$ into \mathbb{R}^n , $f'(a)$ is invertible for some $a \in E$, and $b = f(a)$. Then*

1. *There exists open sets U and V in \mathbb{R}^n such that $a \in U, b \in V$, f is one-to-one on U , and $f(U) = V$.*
2. *If g is the inverse of f , defined in V by*

$$g(f(x)) = x, \quad x \in U,$$

then $g \in \mathcal{C}'(V)$.

Proof.

1. Put $f'(a) = A$ and choose λ so that

$$\lambda \|A^{-1}\| = 1/2.$$

Since f' is continuous at a , there is an open ball $U \subset E$ centered at a such that

$$\|f'(x) - A\| < \lambda, \quad \forall x \in U.$$

We associate to each $y \in \mathbb{R}^n$ a function φ defined by

$$\varphi(x) = x + A^{-1}(y - f(x)), \quad x \in E.$$

Note that $f(x) = y$ if and only if x is a fixed point of φ .
 Since $\varphi'(x) = I - A^{-1}f'(x) = A^{-1}(A - f'(x))$, by above we have

$$\|\varphi'(x)\| < \|A^{-1}\|\lambda = 1/2, \quad \forall x \in U.$$

Hence, by Theorem 8.9 we have

$$|\varphi(x_1) - \varphi(x_2)| \leq \frac{1}{2}|x_1 - x_2|, \quad \forall x_1, x_2 \in U$$

It follows that φ has at most one fixed point in U , so that $f(x) = y$ for at most one $x \in U$. Therefore, f is one-to-one (injective) in U .

Next, put $V = f(U)$ and pick $y_0 \in V$. Then $y_0 = f(x_0)$ for some $x_0 \in U$. Let B be an open ball centered at x_0 with radius $r > 0$, so that its closure $\bar{B} \subset U$. Now we show that $y \in V$ whenever $|y - y_0| < \lambda r$, which proves that V is open.

Fix y with $|y - y_0| < \lambda r$. By the definition of φ ,

$$|\varphi(x_0) - x_0| \leq |A^{-1}(y - y_0)| < \|A^{-1}\|\lambda r = \frac{r}{2}.$$

Given this, it could be shown that φ is a contraction of \bar{B} into itself: if $x \in \bar{B}$, then

$$|\varphi(x) - x_0| \leq |\varphi(x) - \varphi(x_0)| + |\varphi(x_0) - x_0| < \frac{1}{2}|x - x_0| + \frac{r}{2} \leq r,$$

so that $\varphi(x) \in B$. Since \bar{B} is complete as a closed subset of \mathbb{R}^n , by the contraction principle φ has a fixed point $x \in \bar{B}$, and $f(x) = y$. Thus, $y \in f(\bar{B}) \subset f(U) = V$.

2. Pick $y \in V$ and $y + k \in V$, then there exist $x \in U$ and $x + h \in U$ such that $y = f(x)$, $y + k = f(x + h)$. By the definition of φ ,

$$\varphi(x + h) - \varphi(x) = h + A^{-1}[f(x) - f(x + h)] = h - A^{-1}k.$$

By the contraction inequality above, $|h - A^{-1}k| \leq (1/2)|h|$. Hence, $|A^{-1}k| \geq (1/2)|h|$, and

$$|h| \leq 2\|A^{-1}\||k| = \lambda^{-1}|k|.$$

By Theorem 8.5, $f'(x)$ has an inverse denoted by T . Since

$$g(y + k) - g(y) - Tk = h - Tk = -T[f(x + h) - f(x) - f'(x)h],$$

the inequality above implies

$$\frac{|g(y + k) - g(y) - Tk|}{|k|} \leq \frac{\|T\|}{\lambda} \frac{|f(x + h) - f(x) - f'(x)h|}{|h|}$$

As $k \rightarrow 0$, $h \rightarrow 0$ and RHS $\rightarrow 0$. Hence, $g'(y) = T$, and

$$g'(y) = [f'(g(y))]^{-1}.$$

Finally, note that g is a continuous mapping of V onto U , f' is a continuous mapping of U into the set Ω of all invertible elements of $L(\mathbb{R}^n)$, and inversion is a continuous mapping of Ω onto Ω by Theorem 8.5. Combining these results gives $g \in \mathcal{C}'(V)$. □

Theorem 8.13. *If f is a \mathcal{C}' -mapping of an open set $E \subset \mathbb{R}^n$ into \mathbb{R}^n and $f'(x)$ is invertible for every $x \in E$, then $f(W)$ is an open subset of \mathbb{R}^n for every open set $W \subset E$. In other words, f is an open mapping of E into \mathbb{R}^n .*

If $x = (x_1, \dots, x_n) \in \mathbb{R}^n$ and $y = (y_1, \dots, y_m) \in \mathbb{R}^m$, write

$$(x, y) = (x_1, \dots, x_n, y_1, \dots, y_m) \in \mathbb{R}^{n+m}.$$

Every $A \in L(\mathbb{R}^{n+m}, \mathbb{R}^n)$ can be split into two linear transformations A_x and A_y defined by

$$A_x h = A(h, 0), \quad A_y k = A(0, k)$$

for $h \in \mathbb{R}^n, k \in \mathbb{R}^m$. Then $A_x \in L(\mathbb{R}^n, \mathbb{R}^n)$, $A_y \in L(\mathbb{R}^m, \mathbb{R}^n)$, and

$$A(h, k) = A_x h + A_y k.$$

Theorem 8.14 (Implicit Function, Linear). *Let $A \in L(\mathbb{R}^{n+m}, \mathbb{R}^n)$ and if A_x is invertible, then there corresponds to every $k \in \mathbb{R}^m$ a unique $h \in \mathbb{R}^n$ such that $A(h, k) = 0$. This h can be computed from k by the formula*

$$h = -(A_x)^{-1} A_y k.$$

Theorem 8.15 (Implicit Function). *Let f be a \mathcal{C}' -mapping of an open set $E \subset \mathbb{R}^{n+m}$ into \mathbb{R}^n , such that $f(a, b) = 0$ for some point $(a, b) \in E$. Put $A = f'(a, b)$ and assume that A_x is invertible. Then there exist open sets $U \subset \mathbb{R}^{n+m}$ and $W \subset \mathbb{R}^m$ with $(a, b) \in U$ and $b \in W$, such that every $y \in W$ correspond a unique x such that*

$$(x, y) \in U, \quad f(x, y) = 0.$$

If this x is defined to be $g(y)$, then g is a \mathcal{C}' -mapping of W into \mathbb{R}^n , $g(b) = a$, $f(g(y), y) = 0$ for all $y \in W$, and

$$g'(b) = -(A_x)^{-1} A_y.$$

Proof. □

8.4 Derivatives of Higher Order

Definition 8.12 (Second-Order Partial Derivatives). *Suppose f is a real function defined in an open set $E \subset \mathbb{R}^n$, with partial derivatives $D_1 f, \dots, D_n f$. If the functions $D_i f$ are themselves differentiable, then the **second-order partial derivatives** of f are defined by*

$$D_{ij} f = D_i D_j f, \quad i, j = 1, \dots, n.$$

If all these functions $D_{ij} f$ are continuous in E , we say that f is of class \mathcal{C}'' in E , written $f \in \mathcal{C}''(E)$.

The following two theorems are stated for real functions of two variables.

Theorem 8.16. *Suppose f is defined in an open set $E \subset \mathbb{R}^2$, and $D_1 f, D_2 f$ exist at every point of E . Suppose $Q \subset E$ is a closed rectangle with sides parallel to the coordinate axes, having (a, b) and $(a+h, b+k)$ as opposite vertices. Put*

$$\Delta(f, Q) = f(a+h, b+k) - f(a+h, b) - f(a, b+k) + f(a, b).$$

Then there is a point (x, y) in the interior of Q such that

$$\Delta(f, Q) = hk(D_{21} f)(x, y).$$

Proof. It follows from applying mean value theorem twice. Put $u(t) = f(t, b+k) - f(t, b)$. Then there is an $x \in (a, a+h)$ and a $y \in (b, b+k)$ such that

$$\Delta(f, Q) = u(a+h) - u(a) = hu'(x) = h[(D_1 f)(x, b+k) - (D_1 f)(x, b)] = hk(D_{21} f)(x, y).$$

□

Theorem 8.17 (Young). *Suppose f is defined in an open set $E \subset \mathbb{R}^2$, $D_1 f, D_{21} f, D_{22} f$ exist at every point of E , and $D_{21} f$ is continuous at some point $(a, b) \in E$. Then $D_{12} f$ exists at (a, b) and*

$$(D_{12} f)(a, b) = (D_{21} f)(a, b).$$

Proof. Put $A = (D_{21} f)(a, b)$. Choose $\varepsilon > 0$. Since $D_{21} f$ is continuous at (a, b) , if Q is a rectangle in Theorem 8.16, and if h and k are sufficiently small, we have

$$|A - (D_{21} f)(x, y)| < \varepsilon, \quad \forall (x, y) \in Q.$$

Thus,

$$\left| \frac{\Delta(f, Q)}{hk} - A \right| < \varepsilon.$$

Fix h and let $k \rightarrow 0$. Since D_2f exists in E , this inequality implies that

$$\left| \frac{(D_2f)(a+h, b) - (D_2f)(a, b)}{h} - A \right| \leq \varepsilon.$$

Since $\varepsilon > 0$ was arbitrary, and this inequality holds for all sufficiently small $h \neq 0$, it follows that $(D_{12}f)(a, b) = A$. \square

Corollary 8.3. $D_{21}f = D_{12}f$ if $f \in \mathcal{C}''(E)$.

8.5 Differentiation of Integrals

This subsection is about the condition under which the integral and differentiation of a function of two variables can be interchanged, that is,

$$\frac{d}{dt} \int_a^b \varphi(x, t) dx = \int_a^b \frac{\partial \varphi}{\partial t}(x, t) dx.$$

Theorem 8.18. Suppose $\varphi(x, t)$ is defined for $x \in [a, b], t \in [c, d]$. Suppose α is an increasing function on $[a, b]$. Suppose

1. $\varphi \in \mathcal{R}(\alpha)$ as a function of x for every $t \in [c, d]$.
2. φ_2 is continuous in t on (c, d) uniformly with respect to x , that is, for every $s \in (c, d)$, for any $\varepsilon > 0$ there is a $\delta > 0$ such that

$$|\varphi_2(x, t) - \varphi_2(x, s)| < \varepsilon, \quad \forall x \in [a, b], \forall t \in (s - \delta, s + \delta).$$

Define

$$f(t) = \int_a^b \varphi(x, t) d\alpha(x).$$

Then $\varphi_t \in \mathcal{R}(\alpha)$ as a function of x , $f'(s)$ exists, and

$$f'(s) = \int_a^b \varphi_t(x, s) d\alpha(x).$$

Proof. Consider the difference quotients

$$\psi(x, t) = \frac{\varphi(x, t) - \varphi(x, s)}{t - s}$$

for $0 < |t - s| < \delta$. By mean value theorem for each (x, t) there is a number u between s and t such that

$$\psi(x, t) = \varphi_2(x, u).$$

Hence, condition (2) implies that

$$|\psi(x, t) - \varphi_2(x, s)| < \varepsilon, \quad \forall x \in [a, b], 0 < |t - s| < \delta.$$

which implies $\psi \Rightarrow \varphi_2(x, s)$ (as functions of x) on $[a, b]$. Note that

$$\frac{f(t) - f(s)}{t - s} = \int_a^b \psi(x, t) d\alpha(x).$$

Since $\varphi \in \mathcal{R}(\alpha)$ as a function of x for every t , the conclusion follows from the fact that uniform convergence preserves integral (Theorem 7.3). \square