#### **CPE301 – SPRING 2019**

# Design Assignment 5

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Primary Github address: <a href="https://github.com/Vasty1995/submission\_da">https://github.com/Vasty1995/submission\_da</a>

Directory: DA5

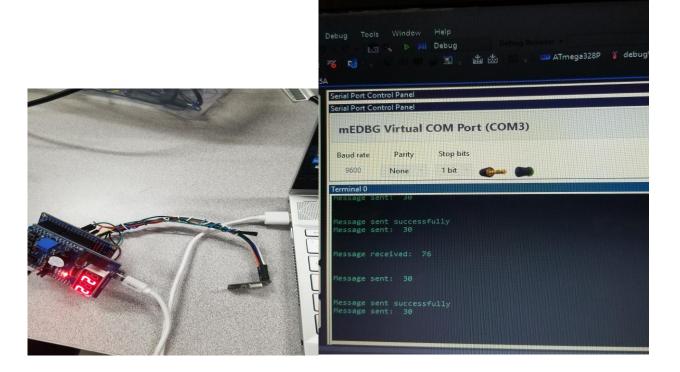
### 1. INITIAL/MODIFIED/DEVELOPED CODE

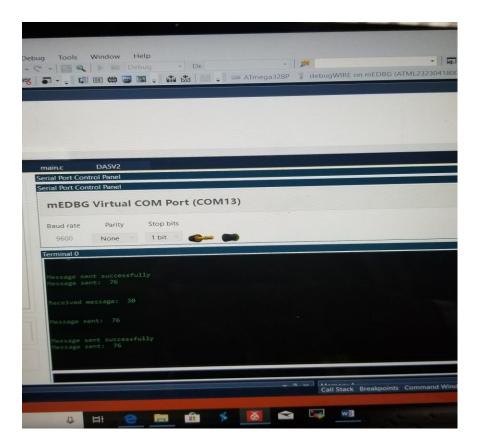
```
#ifndef F CPU
#define F_CPU 16000000UL
#endif
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>
#include <stdbool.h>
#include <stdio.h>
#include <string.h>
      Set up UART for printf();
#ifndef BAUD
#define BAUD 9600
#endif
#include "inc/STDIO_UART.h"
      Include nRF24L01+ library
#include "inc/nrf24l01.h"
#include "inc/nrf24l01-mnemonics.h"
#include "inc/spi.h"
void print_config(void);
                           // Function Declarations
void read adc(void);
void adc init(void);
volatile unsigned int adc_temp;
char outs[20];
//
      Used in IRQ ISR
volatile bool message_received = false;
volatile bool status = false;
int main(void)
{
             Set cliche message to send (message cannot exceed 32 characters)
                                         // Define string array
       char tx_message[32];
      strcpy(tx_message, "hello i am cody"); // Copy string into array
             Initialize UART
      uart_init();
      adc_init();
             Initialize nRF24L01+ and print configuration info
       nrf24_init();
```

```
print_config();
             Start listening to incoming messages
      nrf24_start_listening();
      while (1)
              read_adc();
              adc_temp = (adc_temp*500)/1023 + 20;
             snprintf(outs, sizeof(outs), "%3d\r\n", adc_temp); // print it
             strcpy(tx_message,outs);
                                        // Copy string into array
             nrf24_send_message(tx_message);
             _delay_ms(1500);
             if (message received)
             {
                           Message received, print it
                    message received = false;
                    printf("Received message: %s\n",nrf24_read_message());
                           Send message as response
                    //
                    _delay_ms(500);
                    status = nrf24 send message(tx message);
                    if (status == true) printf("Message sent successfully\n");
             }
      }
}
//
      Interrupt on IRQ pin
ISR(INT0_vect)
{
      message_received = true;
}
void print_config(void)
      uint8_t data;
      printf("Startup successful\n\n nRF24L01+ configured as:\n");
      printf("-----
      nrf24_read(CONFIG,&data,1);
      printf("CONFIG
                                  0x%02X\n",data);
      nrf24_read(EN_AA,&data,1);
      printf("EN_AA
                                  0x%02X\n",data);
      nrf24_read(EN_RXADDR,&data,1);
      printf("EN_RXADDR
                                  0x%02X\n",data);
      nrf24_read(SETUP_RETR,&data,1);
      printf("SETUP RETR
                                  0x%02X\n",data);
      nrf24_read(RF_CH,&data,1);
      printf("RF_CH
                                  0x%02X\n",data);
      nrf24_read(RF_SETUP,&data,1);
      printf("RF_SETUP
                                  0x%02X\n",data);
      nrf24_read(STATUS,&data,1);
      printf("STATUS
                                  0x%02X\n",data);
      nrf24_read(FEATURE,&data,1);
      printf("FEATURE
                                  0x%02X\n",data);
      printf("-----
}
/* INIT ADC */
void adc_init(void)
```

```
{
       /** Setup and enable ADC **/
       ADMUX = (0 < < REFS1)
                             // Reference Selection Bits
       (1<<REFS0)
                      // AVcc - external cap at AREF
                      // ADC Left Adjust Result
       (0<<ADLAR)
                      // Analog Channel Selection Bits
       (1<<MUX2)
                      // ADC4 (PC4 PIN27)
       (0<<MUX1)
       (0<<MUX0);
       ADCSRA = (1 < < ADEN)
                              // ADC ENable
                      // ADC Start Conversion
       (0<<ADSC)
                      // ADC Auto Trigger Enable
       (0<<ADATE)
                      // ADC Interrupt Flag
       (0<<ADIF)
                      // ADC Interrupt Enable
       (0<<ADIE)
       (1<<ADPS2)
                      // ADC Prescaler Select Bits
       (0<<ADPS1)
       (1<<ADPS0);
/* READ ADC PINS */
void read_adc(void)
       unsigned char i = 4;
       adc_temp = 0;
       while (i--)
       {
              ADCSRA |= (1<<ADSC);
              while(ADCSRA & (1<<ADSC));</pre>
              adc temp+= ADC;
              _delay_ms(50);
       adc_temp = adc_temp / 4; // Average a few samples
}
```

2. SCREENSHOT OF EACH DEMO (BOARD SETUP)





# 3. VIDEO LINKS OF EACH DEMO

https://youtu.be/liTHcic-boU

# **Student Academic Misconduct Policy**

http://studentconduct.unlv.edu/misconduct/policy.html

"This assignment submission is my own, original work".

Yannick Gael Kengne Tatcha