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Contest (1)

template.cpp101 lines

```
// #pragma comment(linker, "/stack:200000000")
// #pragma GCC optimize("Ofast")
// #pragma GCC optimize("O3,unroll-loops")
// #pragma GCC target("sse,sse2,sse3,ssse3,sse4")
// #pragma GCC target("avx2,bmi,bmi2,popcnt,lzcnt")

// #define _GLIBCXX_DEBUG
// #define _GLIBCXX_DEBUG_PEDANTIC

#include <cassert>
#include <iomanip>
#include <iostream>
#include <vector>
#include <algorithm>
#include <map>
#include <set>
#include <functional>
#include <array>
#include <numeric>
#include <queue>
#include <deque>
#include <cmath>
#include <climits>

using namespace std;

const int MOD = 998244353;
const long double PI = 3.141592653589793;
using ll = long long;
const ll INF = 1e18;

// #define int ll

// -----> sashko123's defines:

#define itn int //Vasya sorry :(
#define p_b push_back
#define fi first
#define se second
#define pii std::pair<int, int>
#define oo LLONG_MAX
```

```
#define big INT_MAX
#define elif else if

1 int input()
{
3     int x;
    cin>>x;
    return x;
4 }

// -----> end of sashko123's defines (thank you Vasya <3)

6 template<typename T>
using graph = vector<vector<T>>;

9 template<typename T>
istream& operator>>(istream& in, vector<T>& a) {
14     for (auto& i: a) {
        in >> i;
16     }
    return in;
17 }

ll fast_pow(ll a, ll b, ll mod) {
    if (b == 0)
        return 1;
    if (b % 2) {
        return (1ll * a * fast_pow(a, b - 1, mod)) % mod;
    }
    ll k = fast_pow(a, b / 2, mod);
    return (1ll * k * k) % mod;
}

ll fast_pow(ll a, ll b) {
    if (b == 0)
        return 1;
    if (b % 2) {
        return (1ll * a * fast_pow(a, b - 1));
    }
    ll k = fast_pow(a, b / 2);
    return (1ll * k * k);
}

void solve() {
}

int32_t main(int32_t argc, const char * argv[]) {
    cin.tie(0);
    cout.tie(0);
    ios_base::sync_with_stdio(0);
    // insert code here...
    int tt= 1;
    // std::cin >> tt;
    while (tt--) {
        solve();
    }
    return 0;
}
```

fast-input.h35 lines

```
double readNumber() {
    const int BSIZE = 4096;
    static char buffer[BSIZE];
    static char* bptr = buffer + BSIZE;
    auto getChar = []() {
        if (bptr == buffer + BSIZE) {
```

```
        memset(buffer, 0, BSIZE);
        cin.read(buffer, BSIZE);
        bptr = buffer;
    }
    return *bptr++;
};
char c = getChar();
while (c && (c < '0' || c > '9') && c != '-')
    c = getChar();
bool minus = false;
if (c == '-') minus = true, c = getChar();
double res = 0;

while (c >= '0' && c <= '9') {
    res = res * 10 + c - '0';
    c = getChar();
}

if (c == '.') {
    c = getChar();
    double cur = 0.1;
    while (c >= '0' && c <= '9') {
        res = res + (c - '0') * cur;
        c = getChar();
        cur /= 10.0;
    }
}
return minus ? -res : res;
}
```

.bashrc3 lines

```
alias c='g++ -Wall -Wconversion -Wfatal-errors -g -std=c++20 \
-fsanitize=undefined,address'
xmodmap -e 'clear lock' -e 'keycode 66=less greater' #caps = <
```

.vimrc6 lines

```
set cin aw ai is ts=4 sw=4 tm=50 nu noeb bg=dark ru cul
sy on | im jk <esc> | im kj <esc> | no ; :
" Select region and then type :Hash to hash your selection.
" Useful for verifying that there aren't mistypes.
ca Hash w !cpp -dD -P -fpreprocessed \ | tr -d '[:space:]' \
\ | md5sum \ | cut -c-6
```

hash.sh3 lines

```
# Hashes a file, ignoring all whitespace and comments. Use for
# verifying that code was correctly typed.
cpp -dD -P -fpreprocessed | tr -d '[:space:]' | md5sum |cut -c-6
```

Mathematics (2)

2.1 Equations

$$ax^2 + bx + c = 0 \Rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

The extremum is given by $x = -b/2a$.

$$\begin{aligned} ax + by &= e & \Rightarrow & \begin{aligned} x &= \frac{ed - bf}{ad - bc} \\ y &= \frac{af - ec}{ad - bc} \end{aligned} \end{aligned}$$

In general, given an equation $Ax = b$, the solution to a variable x_i is given by

$$x_i = \frac{\det A'_i}{\det A}$$

where A'_i is A with the i 'th column replaced by b .

2.2 Recurrences

If $a_n = c_1a_{n-1} + \dots + c_ka_{n-k}$, and r_1, \dots, r_k are distinct roots of $x^k - c_1x^{k-1} - \dots - c_k$, there are d_1, \dots, d_k s.t.

$$a_n = d_1r_1^n + \dots + d_kr_k^n.$$

Non-distinct roots r become polynomial factors, e.g. $a_n = (d_1n + d_2)r^n$.

2.3 Trigonometry

$$\begin{aligned}\sin(v+w) &= \sin v \cos w + \cos v \sin w \\ \cos(v+w) &= \cos v \cos w - \sin v \sin w\end{aligned}$$

$$\begin{aligned}\tan(v+w) &= \frac{\tan v + \tan w}{1 - \tan v \tan w} \\ \sin v + \sin w &= 2 \sin \frac{v+w}{2} \cos \frac{v-w}{2} \\ \cos v + \cos w &= 2 \cos \frac{v+w}{2} \cos \frac{v-w}{2}\end{aligned}$$

$$(V+W)\tan(v-w)/2 = (V-W)\tan(v+w)/2$$

where V, W are lengths of sides opposite angles v, w .

$$\begin{aligned}a \cos x + b \sin x &= r \cos(x - \phi) \\ a \sin x + b \cos x &= r \sin(x + \phi)\end{aligned}$$

where $r = \sqrt{a^2 + b^2}, \phi = \text{atan2}(b, a)$.

2.4 Geometry

2.4.1 Triangles

Side lengths: a, b, c

Semiperimeter: $p = \frac{a+b+c}{2}$

Area: $A = \sqrt{p(p-a)(p-b)(p-c)}$

Circumradius: $R = \frac{abc}{4A}$

Inradius: $r = \frac{A}{p}$

Length of median (divides triangle into two equal-area triangles): $m_a = \frac{1}{2}\sqrt{2b^2 + 2c^2 - a^2}$

Length of bisector (divides angles in two):

$$s_a = \sqrt{bc \left[1 - \left(\frac{a}{b+c} \right)^2 \right]}$$

Law of sines: $\frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c} = \frac{1}{2R}$

Law of cosines: $a^2 = b^2 + c^2 - 2bc \cos \alpha$

Law of tangents: $\frac{a+b}{a-b} = \frac{\tan \frac{\alpha+\beta}{2}}{\tan \frac{\alpha-\beta}{2}}$

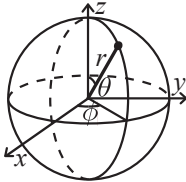
2.4.2 Quadrilaterals

With side lengths a, b, c, d , diagonals e, f , diagonals angle θ , area A and magic flux $F = b^2 + d^2 - a^2 - c^2$:

$$4A = 2ef \cdot \sin \theta = F \tan \theta = \sqrt{4e^2f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is 180° , $ef = ac + bd$, and $A = \sqrt{(p-a)(p-b)(p-c)(p-d)}$.

2.4.3 Spherical coordinates



$$\begin{aligned}x &= r \sin \theta \cos \phi & r &= \sqrt{x^2 + y^2 + z^2} \\ y &= r \sin \theta \sin \phi & \theta &= \arccos(z / \sqrt{x^2 + y^2 + z^2}) \\ z &= r \cos \theta & \phi &= \text{atan2}(y, x)\end{aligned}$$

2.5 Derivatives/Integrals

$$\begin{aligned}\frac{d}{dx} \arcsin x &= \frac{1}{\sqrt{1-x^2}} & \frac{d}{dx} \arccos x &= -\frac{1}{\sqrt{1-x^2}} \\ \frac{d}{dx} \tan x &= 1 + \tan^2 x & \frac{d}{dx} \arctan x &= \frac{1}{1+x^2} \\ \int \tan ax &= -\frac{\ln |\cos ax|}{a} & \int x \sin ax &= \frac{\sin ax - ax \cos ax}{a^2} \\ \int e^{-x^2} &= \frac{\sqrt{\pi}}{2} \text{erf}(x) & \int x e^{ax} dx &= \frac{e^{ax}}{a^2} (ax - 1)\end{aligned}$$

Integration by parts:

$$\int_a^b f(x)g(x)dx = [F(x)g(x)]_a^b - \int_a^b F(x)g'(x)dx$$

2.6 Sums

$$c^a + c^{a+1} + \dots + c^b = \frac{c^{b+1} - c^a}{c - 1}, c \neq 1$$

$$\begin{aligned}1 + 2 + 3 + \dots + n &= \frac{n(n+1)}{2} \\ 1^2 + 2^2 + 3^2 + \dots + n^2 &= \frac{n(2n+1)(n+1)}{6} \\ 1^3 + 2^3 + 3^3 + \dots + n^3 &= \frac{n^2(n+1)^2}{4} \\ 1^4 + 2^4 + 3^4 + \dots + n^4 &= \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}\end{aligned}$$

2.7 Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots, (-\infty < x < \infty)$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots, (-1 < x \leq 1)$$

$$\sqrt{1+x} = 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{2x^3}{32} - \frac{5x^4}{128} + \dots, (-1 \leq x \leq 1)$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots, (-\infty < x < \infty)$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots, (-\infty < x < \infty)$$

2.8 Probability theory

Let X be a discrete random variable with probability $p_X(x)$ of assuming the value x . It will then have an expected value (mean) $\mu = \mathbb{E}(X) = \sum_x x p_X(x)$ and variance $\sigma^2 = V(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \sum_x (x - \mathbb{E}(X))^2 p_X(x)$ where σ is the standard deviation. If X is instead continuous it will have a probability density function $f_X(x)$ and the sums above will instead be integrals with $p_X(x)$ replaced by $f_X(x)$.

Expectation is linear:

$$\mathbb{E}(aX + bY) = a\mathbb{E}(X) + b\mathbb{E}(Y)$$

For independent X and Y ,

$$V(aX + bY) = a^2V(X) + b^2V(Y).$$

2.8.1 Discrete distributions

Binomial distribution

The number of successes in n independent yes/no experiments, each which yields success with probability p is $\text{Bin}(n, p)$, $n = 1, 2, \dots$, $0 \leq p \leq 1$.

$$p(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

$$\mu = np, \sigma^2 = np(1-p)$$

$\text{Bin}(n, p)$ is approximately $\text{Po}(np)$ for small p .

First success distribution

The number of trials needed to get the first success in independent yes/no experiments, each which yields success with probability p is $Fs(p)$, $0 \leq p \leq 1$.

$$p(k) = p(1 - p)^{k-1}, \, k = 1, 2, \dots$$

$$\mu = \frac{1}{p}, \, \sigma^2 = \frac{1 - p}{p^2}$$

Poisson distribution

The number of events occurring in a fixed period of time t if these events occur with a known average rate κ and independently of the time since the last event is $Po(\lambda)$, $\lambda = t\kappa$.

$$p(k) = e^{-\lambda} \frac{\lambda^k}{k!}, \, k = 0, 1, 2, \dots$$

$$\mu = \lambda, \, \sigma^2 = \lambda$$

2.8.2 Continuous distributions

Uniform distribution

If the probability density function is constant between a and b and 0 elsewhere it is $U(a, b)$, $a < b$.

$$f(x) = \begin{cases} \frac{1}{b-a} & a < x < b \\ 0 & \text{otherwise} \end{cases}$$

$$\mu = \frac{a + b}{2}, \, \sigma^2 = \frac{(b - a)^2}{12}$$

Exponential distribution

The time between events in a Poisson process is $Exp(\lambda)$, $\lambda > 0$.

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & x < 0 \end{cases}$$

$$\mu = \frac{1}{\lambda}, \, \sigma^2 = \frac{1}{\lambda^2}$$

Normal distribution

Most real random values with mean μ and variance σ^2 are well described by $\mathcal{N}(\mu, \sigma^2)$, $\sigma > 0$.

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

If $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$ and $X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$ then

$$aX_1 + bX_2 + c \sim \mathcal{N}(\mu_1 + \mu_2 + c, a^2\sigma_1^2 + b^2\sigma_2^2)$$

2.9 Markov chains

A *Markov chain* is a discrete random process with the property that the next state depends only on the current state. Let X_1, X_2, \dots be a sequence of random variables generated by the Markov process. Then there is a transition matrix $\mathbf{P} = (p_{ij})$, with $p_{ij} = \Pr(X_n = i | X_{n-1} = j)$, and $\mathbf{p}^{(n)} = \mathbf{P}^n \mathbf{p}^{(0)}$ is the probability distribution for X_n (i.e., $p_i^{(n)} = \Pr(X_n = i)$), where $\mathbf{p}^{(0)}$ is the initial distribution.

π is a stationary distribution if $\pi = \pi \mathbf{P}$. If the Markov chain is *irreducible* (it is possible to get to any state from any state), then $\pi_i = \frac{1}{\mathbb{E}(T_i)}$ where $\mathbb{E}(T_i)$ is the expected time between two visits in state i . π_j / π_i is the expected number of visits in state j between two visits in state i .

For a connected, undirected and non-bipartite graph, where the transition probability is uniform among all neighbors, π_i is proportional to node i 's degree.

A Markov chain is *ergodic* if the asymptotic distribution is independent of the initial distribution. A finite Markov chain is ergodic iff it is irreducible and *aperiodic* (i.e., the gcd of cycle lengths is 1). $\lim_{k \rightarrow \infty} \mathbf{P}^k = \mathbf{1}\pi$.

A Markov chain is an A-chain if the states can be partitioned into two sets **A** and **G**, such that all states in **A** are absorbing ($p_{ii} = 1$), and all states in **G** leads to an absorbing state in **A**. The probability for absorption in state $i \in \mathbf{A}$, when the initial state is j , is $a_{ij} = p_{ij} + \sum_{k \in \mathbf{G}} a_{ik} p_{kj}$. The expected time until absorption, when the initial state is i , is $t_i = 1 + \sum_{k \in \mathbf{G}} p_{ki} t_k$.

Algebra (3)

```
xor-basis.h
Description: Xor basis, all elements in the main set can be constructed using xor operation and elements in the basis
Time: insert per element -  $\mathcal{O}(\log(A_{max}))$ 
<vector> hash46 lines
template<typename T = int, int max_bit = 31>
struct xor_basis
{
    std::vector<T> basis; // basis[i] -> element with smallest
                           set bit equal to i
    int sz; // Current size of the basis

    xor_basis() {
        basis.assign(max_bit);
    }

    bool insert(T val) {
        for (int i = 0; i < max_bit; i++) {
            if (((val >> i)&1) == 0)
                continue;
            if (!basis[i]) {
                basis[i] = val;
                sz++;
                return true;
            }
        }
    }
}
```

```
        val ^= basis[i];
    }
    return false;
}

bool contains(T val) {
    for (int i = 0; i < max_bit; i++) {
        if (((val >> i)&1) == 0)
            continue;
        if (!basis[i]) {
            return false;
        }
        val ^= basis[i];
    }
    return true;
}

T max_element() { // not-sure
    T val = 0;
    for (int i = max_bit - 1; i >= 0; i--) {
        if (basis[i] && !((val>>i)&1)) {
            val ^= basis[i];
        }
    }
    return val;
}
};

fft.h
Description: FFT implementation
Time: (n + m) * log(n + m) hash56 lines
<vector>, <complex>
using cd = std::complex<double>;

void fft(std::vector<cd> &a, bool invert) {
    int n = a.size();

    for (int i = 1, j = 0; i < n; i++) {
        int bit = n >> 1;
        for (; j & bit; bit >>= 1)
            j ^= bit;
        j ^= bit;

        if (i < j)
            swap(a[i], a[j]);
    }

    for (int len = 2; len <= n; len <= 1) {
        double ang = 2 * PI / len * (invert ? -1 : 1);
        cd wlen(cos(ang), sin(ang));
        for (int i = 0; i < n; i += len) {
            cd w(1);
            for (int j = 0; j < len / 2; j++) {
                cd u = a[i+j], v = a[i+j+len/2] * w;
                a[i+j] = u + v;
                a[i+j+len/2] = u - v;
                w *= wlen;
            }
        }
    }

    if (invert) {
        for (cd &x : a)
            x /= n;
    }
}

template<typename T>
```

```
std::vector<T> multiply(const std::vector<T>& a, const std::vector<T>& b) {
    std::vector<cd> fa(a.begin(), a.end()), fb(b.begin(), b.end());
    while (n < a.size() + b.size())
        n <= 1;
    fa.resize(n);
    fb.resize(n);

    fft(fa, false);
    fft(fb, false);
    for (int i = 0; i < n; i++)
        fa[i] *= fb[i];
    fft(fa, true);

    std::vector<T> result(n);
    for (int i = 0; i < n; i++)
        result[i] = round(fa[i].real());
    result.resize(a.size() + b.size() - 1);
    return result;
}
```

nnt.h

Description: NNT implementation by modulo 998244353

Time: $(n + m) \cdot \log(n + m)$

`<vector>`

hash68 lines

```
const int root = 31; // primitive root of module
const int root_1 = fast_pow(root, MOD - 2, MOD); // (primitive root) ^ -1
const int root_pw = 1 << 23; // max power of 2 in MOD - 1
```

```
inline int inverse(int n, int mod) {
    return fast_pow(n, mod - 2, mod);
}

void nnt(std::vector<int> &a, bool invert, int mod) {
    int n = a.size();

    for (int i = 1, j = 0; i < n; i++) {
        int bit = n >> 1;
        for (; j & bit; bit >>= 1)
            j ^= bit;
        j ^= bit;

        if (i < j)
            std::swap(a[i], a[j]);
    }

    for (int len = 2; len <= n; len <= 1) {
        int wlen = invert ? root_1 : root;
        for (int i = len; i < root_pw; i <= 1)
            wlen = (int)(1LL * wlen * wlen % mod);

        for (int i = 0; i < n; i += len) {
            int w = 1;
            for (int j = 0; j < len / 2; j++) {
                int u = a[i+j], v = (int)(1LL * a[i+j+len/2] * w % mod);
                a[i+j] = u + v < mod ? u + v : u + v - mod;
                a[i+j+len/2] = u - v >= 0 ? u - v : u - v + mod;
                w = (1ll * w * wlen % mod);
            }
        }
    }

    if (invert) {
        int n_1 = inverse(n, mod);
```

```
        for (int& x : a)
            x = (1ll * x * n_1 % mod);
    }
}

std::vector<int> multiply(const std::vector<int>& a, const std::vector<int>& b, int mod) {
    int n = a.size(), m = b.size();
    int k = n + m - 1;
    int l = 1;
    while (l < k)
        l <= 1;

    std::vector<int> A(l), B(l);
    for (int i = 0; i < n; i++) {
        A[i] = a[i];
    }
    for (int i = 0; i < m; i++) {
        B[i] = b[i];
    }

    nnt(A, false, mod);
    nnt(B, false, mod);
    for (int i = 0; i < B.size(); i++) {
        A[i] = (1ll * A[i] * B[i]) % mod;
    }
    nnt(A, true, mod);
    A.resize(k);
    return A;
}
```

floor-sum.h

Description:

$$\sum_{i=0}^{n-1} ((a \cdot i + b) / m)$$

Time: $\log(n)$

`<utility>`

hash24 lines

```
using ull = unsigned long long;

ull floor_sum_unsigned(ull n, ull m, ull a, ull b) {
    ull ans = 0;
    while (true) {
        if (a >= m) {
            ans += n * (n - 1) / 2 * (a / m);
            a %= m;
        }
        if (b >= m) {
            ans += n * (b / m);
            b %= m;
        }

        ull y_max = a * n + b;
        if (y_max < m) break;
        // y_max < m * (n + 1)
        // floor(y_max / m) <= n
        n = (ull)(y_max / m);
        b = (ull)(y_max % m);
        std::swap(m, a);
    }
    return ans;
}
```

```
ull floor_sum_unsigned(ull n, ull m, ull a, ull b) {
    ull ans = 0;
    while (true) {
        if (a >= m) {
            ans += n * (n - 1) / 2 * (a / m);
            a %= m;
        }
        if (b >= m) {
            ans += n * (b / m);
            b %= m;
        }

        ull y_max = a * n + b;
        if (y_max < m) break;
        // y_max < m * (n + 1)
        // floor(y_max / m) <= n
        n = (ull)(y_max / m);
        b = (ull)(y_max % m);
        std::swap(m, a);
    }
    return ans;
}
```

berlekamp-massey.h

Description: For given n first elements of sequence a, return array c, $a[i] = \sum_{j=1 \dots i} a[i-j] \cdot c[j]$

Time: $\mathcal{O}(n^2)$

`template<typename T>`

hash45 lines

```
vector<T> berlekamp_massey(const vector<T> &s) {
    vector<T> c;
    vector<T> oldC;
    int f = -1;
    for (int i=0; i<(int)s.size(); i++) {
        T delta = s[i];
        for (int j=1; j<=(int)c.size(); j++)
            delta -= c[j-1] * s[i-j];
        if (delta == 0)
            continue;
        if (f == -1) {
            c.resize(i + 1);
            mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
            for (T &x : c)
                x = rng();
            f = i;
        } else {
            vector<T> d = oldC;
            for (T &x : d)
                x = -x;
            d.insert(d.begin(), 1);
            T df1 = 0;
            for (int j=1; j<=(int)d.size(); j++)
                df1 += d[j-1] * s[f+1-j];
            assert(df1 != 0);
            T coef = delta / df1;
            for (T &x : d)
                x *= coef;
            vector<T> zeros(i - f - 1);
            zeros.insert(zeros.end(), d.begin(), d.end());
            d = zeros;
            vector<T> temp = c;
            c.resize(max(c.size(), d.size()));
            for (int j=0; j<(int)d.size(); j++)
                c[j] += d[j];
            if ((int) temp.size() > f - (int) oldC.size()) {
                oldC = temp;
                f = i;
            }
        }
    }
    return c;
}
```

Numeric (4)

primitive-root.h

Description: Primitive root of n

`constexpr long long safe_mod(long long x, long long m)`

hash54 lines

```
constexpr long long safe_mod(long long x, long long m) {
    x %= m;
    if (x < 0) x += m;
    return x;
}

long long pow_mod(long long x, long long n, int m) {
    if (m == 1) return 0;
    unsigned int _m = (unsigned int)(m);
    unsigned long long r = 1;
    unsigned long long y = safe_mod(x, m);
    while (n) {
        if (n & 1) r = (r * y) % _m;
        y = (y * y) % _m;
        n >>= 1;
    }
}
```

```
    return r;
}

int primitive_root(int m) {
    if (m == 2) return 1;
    if (m == 167772161) return 3;
    if (m == 469762049) return 3;
    if (m == 754974721) return 11;
    if (m == 998244353) return 3;
    int divs[20] = {};
    divs[0] = 2;
    int cnt = 1;
    int x = (m - 1) / 2;
    while (x % 2 == 0) x /= 2;
    for (int i = 3; (long long)(i)*i <= x; i += 2) {
        if (x % i == 0) {
            divs[cnt++] = i;
            while (x % i == 0) {
                x /= i;
            }
        }
    }
    if (x > 1) {
        divs[cnt++] = x;
    }
    for (int g = 2;; g++) {
        bool ok = true;
        for (int i = 0; i < cnt; i++) {
            if (pow_mod(g, (m - 1) / divs[i], m) == 1) {
                ok = false;
                break;
            }
        }
        if (ok) return g;
    }
}

template <int m> constexpr int primitive_root = primitive_root(
    m);
```

pollard-rho.h
Description: Finds divider of N.
Time: $\mathcal{O}\left(N^{1/4} * \log(N)\right)$

```
<numeric> hash20 lines

long long mult(long long a, long long b, long long mod) {
    return (__int128)a * b % mod;
}

long long f(long long x, long long c, long long mod) {
    return (mult(x, x, mod) + c) % mod;
}

long long rho(long long n, long long x0=2, long long c=1) {
    long long x = x0;
    long long y = x0;
    long long g = 1;
    while (g == 1) {
        x = f(x, c, n);
        y = f(y, c, n);
        y = f(y, c, n);
        g = std::gcd(abs(x - y), n);
    }
    return g;
}
```

```
miller-rabin.h
Description: checks whether given number (up to 1e18) is prime
Time: +-  $\mathcal{O}(\log^3(n))$  hash43 lines

using ul28 = __uint128_t;

ll fast_pow(ll a, ll b, ll mod) {
    if (b == 0)
        return 1;
    if (b % 2) {
        return ((ul28) a * fast_pow(a, b - 1, mod)) % mod;
    }
    ll k = fast_pow(a, b / 2, mod);
    return ((ul28) k * k) % mod;
}

bool check_composite(ll n, ll a, ll d, int s) {
    ll x = fast_pow(a, d, n);
    if (x == 1 || x == n - 1)
        return false;
    for (int r = 1; r < s; r++) {
        x = (ul28)x * x % n;
        if (x == n - 1)
            return false;
    }
    return true;
};

bool miller_rabin(ll n) {
    if (n < 2)
        return false;

    int r = 0;
    ll d = n - 1;
    while ((d & 1) == 0) {
        d >>= 1;
        r++;
    }

    for (int a : {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37}) {
        if (n == a)
            return true;
        if (check_composite(n, a, d, r))
            return false;
    }
    return true;
}
```

```
euclidean-algorithm.h
Description: Find x and y, s.t. x*a + y*b = gcd(a, b) // extended Euclidean algorithm
Time:  $\mathcal{O}(\logmin(a,b))$ 
<tuple> hash12 lines

template<typename T>
std::pair<T, T> euclidean_algorithm(T a, T b) {
    T x = 1, y = 0;
    T x1 = 0, y1 = 1, a1 = a, b1 = b;
    while (b1) {
        T q = a1 / b1;
        std::tie(x, x1) = std::make_tuple(x1, x - q * x1);
        std::tie(y, y1) = std::make_tuple(y1, y - q * y1);
        std::tie(a1, b1) = std::make_tuple(b1, a1 - q * b1);
    }
    return {x, y};
}
```

```
chinese-remainder-theorem.h
Description: Solves chinese remainder theorem.
Time:  $\mathcal{O}(n)$ , n - number of equations. hash19 lines

struct Congruence {
    long long a, m;
};

long long chinese_remainder_theorem(vector<Congruence> const& congruences) {
    long long M = 1;
    for (auto const& congruence : congruences) {
        M *= congruence.m;
    }

    long long solution = 0;
    for (auto const& congruence : congruences) {
        long long a_i = congruence.a;
        long long M_i = M / congruence.m;
        long long N_i = mod_inv(M_i, congruence.m);
        solution = (solution + a_i * M_i % M * N_i) % M;
    }
    return solution;
}
```

```
mod-sqrt.h
Description: for given n finds all a, s.t. a*a = n (mod p)
Time:  $\mathcal{O}(\log^2)$  hash45 lines

unsigned xrand() {
    static unsigned x = 314159265, y = 358979323, z = 846264338,
        w = 327950288;
    unsigned t = x ^ x << 11; x = y; y = z; z = w; return w = w ^
        w >> 19 ^ t ^ t >> 8;
}

int jacobi(ll a, ll m) {
    int s = 1;
    if (a < 0) a = a % m + m;
    for (; m > 1; ) {
        a %= m;
        if (a == 0) return 0;
        const int r = __builtin_ctz(a);
        if ((r & 1) && ((m + 2) & 4)) s = -s;
        a >>= r;
        if (a & m & 2) s = -s;
        std::swap(a, m);
    }
    return s;
}
```

```
vector<ll> mod_sqrt(ll a, ll p) {
    if (p == 2) return {a & 1};
    const int j = jacobi(a, p);
    if (j == 0) return {0};
    if (j == -1) return {};
    ll b, d;
    for (; ) {
        b = xrand() % p;
        d = (b * b - a) % p;
        if (d < 0) d += p;
        if (jacobi(d, p) == -1) break;
    }
    ll f0 = b, f1 = 1, g0 = 1, g1 = 0, tmp;
    for (ll e = (p + 1) >> 1; e; e >>= 1) {
        if (e & 1) {
            tmp = (g0 * f0 + d * ((g1 * f1) % p)) % p;
            g1 = (g0 * f1 + g1 * f0) % p;
            g0 = tmp;
        }
    }
}
```

```
    tmp = (f0 * f0 + d * ((f1 * f1) % p)) % p;
    f1 = (2 * f0 * f1) % p;
    f0 = tmp;
}
return (g0 < p - g0) ? vector<ll>{g0, p - g0} : vector<ll>{p
    - g0, g0};
}
```

Data structures (5)

fenwick-tree.h
Description: Fenwick Tree, update(+=) at element, sum at segment. R is excluded.

Time: update - $\mathcal{O}(\log N)$, get - $\mathcal{O}(\log N)$

<cassert>, <vector>hash32 lines

```
template <class T> struct fenwick_tree {
public:
    fenwick_tree() : _n(0) {}
    fenwick_tree(int n) : _n(n), data(n) {}

    void add(int p, T x) {
        assert(0 <= p && p < _n);
        p++;
        while (p <= _n) {
            data[p - 1] += T(x);
            p += p & -p;
        }
    }

    T sum(int l, int r) {
        assert(0 <= l && l <= r && r <= _n);
        return sum(r) - sum(l);
    }

private:
    int _n;
    std::vector<T> data;

    T sum(int r) {
        T s = 0;
        while (r > 0) {
            s += data[r - 1];
            r -= r & -r;
        }
        return s;
    }
};
```

fenwick-tree-2d.h
Description: 2d fenwick tree, update(+=) at element, sum at 2d segment. R is excluded.

Time: update - $\mathcal{O}(\log N * \log M)$, get - $\mathcal{O}(\log N * \log M)$

hash53 lines

```
template <class T> struct fenwick_tree_2d{
    struct fenwick_tree {
        int n;
        unordered_map<int, T> data;
        fenwick_tree(): n(0) {};;
        fenwick_tree(int n): n(n) {};;

        void add(int p, T x) {
            assert(0 <= p && p < n);
            p++;
            while (p <= n) {
                data[p - 1] += T(x);
                p += p & -p;
            }
        }
    }
};
```

```
    T pref_sum(int r){
        T s = 0;
        while (r > 0) {
            s += data[r - 1];
            r -= r & -r;
        }
        return s;
    }
};

int n, m;
std::vector<fenwick_tree> data;

fenwick_tree_2d(int n,int m): n(n), m(m), data(n,
    fenwick_tree(m)) {};;

void add(int x, int y, T val) {
    assert(0 <= x && x < n);
    x++;
    while (x <= n) {
        data[x - 1].add(y, val);
        x += x & -x;
    }
}

T pref_sum(int xr, int yr){
    T s = 0;
    while (xr > 0) {
        s += data[xr - 1].pref_sum(yr);
        xr -= xr & -xr;
    }
    return s;
}

T sum(int x1, int y1, int xr, int yr) {
    return pref_sum(xr, yr) - pref_sum(xr, y1) - pref_sum(
        x1, yr) + pref_sum(x1, y1);
}
};
```

segment-tree.h
Description: Segment tree, update(+=) at element, sum at segment. R is excluded.

Time: update - $\mathcal{O}(\log N)$, get - $\mathcal{O}(\log N)$

<array>hash38 lines

```
template<typename T, int N = (1 << 18)> struct segment_tree {
    std::array<T, 2 * N> tree;
    segment_tree() {
        tree.fill(T());
    }

    void update(int pos, T val) {
        pos += N;
        tree[pos] += val;
        pos >>= 1;
        while (pos > 0) {
            tree[pos] = tree[pos << 1] + tree[(pos << 1) | 1];
            pos >>= 1;
        }
    }

    T get_sum(int l, int r) {
        l += N;
        r += N;

        T ans = T();
        while (l < r) {
            if (l & 1) {
```

```
                ans += tree[l++];
            }
            if (r & 1) {
                ans += tree[--r];
            }
            l >>= 1;
            r >>= 1;
        }
        return ans;
    }

    T get(int pos) {
        return tree[N + pos];
    }
};
```

lazy-segment-tree.h
Description: Segment tree, update(+=) at segment, sum at segment. R is excluded.

Time: update - $\mathcal{O}(\log N)$, get - $\mathcal{O}(\log N)$

<array>, <vector>hash82 lines

```
template<typename T> struct lazy_segment_tree {
    struct node{
        T sum = 0;
        T promise = 0;
    };

    int n;
    std::vector<node> tree;

    lazy_segment_tree(int n_, const vector<T>& init): n(n_) {
        tree.assign(4 * n, node{});
        build(1, 0, n, init);
    }

    void build(int v, int l, int r, const vector<T>& init) {
        if (l + 1 == r) {
            tree[v].sum = init[l];
            return;
        }
        if (l >= r)
            return;
        int mid = (l + r) / 2;
        build(2 * v, l, mid, init);
        build(2 * v + 1, mid, r, init);

        tree[v].sum = (tree[2 * v].sum + tree[2 * v + 1].sum);
    }

    void update(int l, int r, T value) {
        update(1, 0, n, l, r, value);
    }

    T get(int l, int r) {
        return get(1, 0, n, l, r);
    }

    T get(int pos) {
        return get(1, 0, n, pos, pos + 1);
    }

    void push(int v, int l, int r) {
        if (tree[v].promise == 0)
            return;

        tree[v].sum += tree[v].promise * (r - l);
        if (l + 1 < r) {
            tree[2 * v].promise += tree[v].promise;
            tree[2 * v + 1].promise += tree[v].promise;
```

```

    }
    tree[v].promise = 0;
}

void update(int v, int tl, int tr, int l, int r, T value) {
    push(v, tl, tr);
    if (l >= tr || tl >= r)
        return;
    if (l <= tl && tr <= r) {
        tree[v].promise += value;
        push(v, tl, tr);
        return;
    }
    int mid = (tl + tr) / 2;
    update(2 * v, tl, mid, l, r, value);
    update(2 * v + 1, mid, tr, l, r, value);

    tree[v].sum = tree[2 * v].sum + tree[2 * v + 1].sum;
}

T get(int v, int tl, int tr, int l, int r) {
    push(v, tl, tr);
    if (l >= tr || tl >= r)
        return 0;
    if (l <= tl && tr <= r) {
        return tree[v].sum;
    }
    int mid = (tl + tr) / 2;
    auto left = get(2 * v, tl, mid, l, r);
    auto right = get(2 * v + 1, mid, tr, l, r);

    return left + right;
}
};

```

persistent-segment-tree.h

Description: Persistent segment tree, update(+=) at segment, sum at segment. R is excluded.

Time: update - $\mathcal{O}(\log N)$, get - $\mathcal{O}(\log N)$

<array> hash83 lines

```

template<typename T> struct persistent_segment_tree {
    struct node {
        T sum;
        int left, right;

        node(T val = T()): sum(val), left(-1), right(-1) {}
        node(int left_, int right_): sum(T()), left(left_), right(right_) {}
    };
    std::vector<node> tree;

    node create_node(T val = 0) {
        return node(val);
    }
    node create_node(int left, int right) {
        auto v = node(left, right);
        v.sum = (left != -1 ? tree[left].sum : 0) + (right != -1 ? tree[right].sum : 0);

        return v;
    }
    int LAST = 0;
    template<typename... params>
    int new_node(params... args) {
        tree[++LAST] = create_node(args...);
        return LAST;
    }
    int n;
};

```

```

persistent_segment_tree(int n_, int sz_, const vector<T>& a,
    int& first_root): n(n_) {
    tree.resize(sz_);
    first_root = build(0, n, a);
}

int build(int l, int r, const vector<T>& a) {
    if (l + 1 == r) {
        return new_node(a[l]);
    }
    int mid = (r + 1) / 2;
    int left = build(l, mid, a);
    int right = build(mid, r, a);
    return new_node(left, right);
}

int update(int root, int pos, T val) {
    return update(root, 0, n, pos, val);
}

T get(int root, int l, int r) {
    return get(root, 0, n, l, r);
}

T get(int root, int pos) {
    return get(root, 0, n, pos, pos + 1);
}

int update(int v, int l, int r, int pos, T val) {
    if (l + 1 == r) {
        return new_node(val + tree[v].sum);
    }

    int mid = (l + r) / 2;
    if (pos < mid) {
        return new_node(
            update(tree[v].left, l, mid, pos, val),
            tree[v].right
        );
    } else {
        return new_node(
            tree[v].left,
            update(tree[v].right, mid, r, pos, val)
        );
    }
}

T get(int v, int tl, int tr, int l, int r) {
    if (tr <= l || r <= tl)
        return 0;
    if (l <= tl && tr <= r) {
        return tree[v].sum;
    }

    int mid = (tl + tr) / 2;
    return get(tree[v].left, tl, mid, l, r) + get(tree[v].right, mid, tr, l, r);
}
};

```

segment-tree-2d.h

Description: 2D segment tree, update(+=) at element, sum at segment. R is excluded.

Time: update - $\mathcal{O}(\log N * \log M)$, get - $\mathcal{O}(\log N * \log M)$

hash76 lines

```

template<typename T>
struct segment_tree_2d {
    int n, m;
    vector<vector<T>> tree;
};

```

```

segment_tree_2d(const vector<vector<T>>& arr) {
    n = arr.size();
    m = arr[0].size();
    tree.assign(2 * n, vector<T>(2 * m));
    for (int i = 2 * n - 1; i > 0; i--) {
        for (int j = 2 * m - 1; j > 0; j--) {
            if (i < n) {
                tree[i][j] = tree[2 * i][j] + tree[2 * i + 1][j];
            } else if (j < m) {
                tree[i][j] = tree[i][2 * j] + tree[i][2 * j + 1];
            } else {
                tree[i][j] = arr[i - n][j - m];
            }
        }
    }
}

void update_point(int x, int y, T newval) { // arr[x][y] := newval
    x += n;
    y += m;
    int curx = x;
    while (curx > 0) {
        int cury = y;
        while (cury > 0) {
            if (curx < n) {
                tree[curx][cury] = tree[2 * curx][cury] + tree[2 * curx + 1][cury];
            } else if (cury < m) {
                tree[curx][cury] = tree[curx][2 * cury] + tree[curx][2 * cury + 1];
            } else {
                tree[curx][cury] = newval;
            }
            cury >>= 1;
        }
        curx >>= 1;
    }
}

T find_sum(int lx, int rx, int ly, int ry) { // [lx, rx) * [ly, ry)
    lx += n;
    rx += n;

    T ans = 0;
    while (lx < rx) {
        int curly = ly + m;
        int curry = ry + m;
        while (curly < curry) {
            if (curly & 1) {
                if (lx & 1) {
                    ans += tree[lx][curly];
                }
                if (rx & 1) {
                    ans += tree[rx - 1][curly];
                }
            }
            if (curry & 1) {
                if (lx & 1) {
                    ans += tree[lx][curry - 1];
                }
                if (rx & 1) {
                    ans += tree[rx - 1][curry - 1];
                }
            }
        }
    }
}

```



```
        curly = (curly + 1) >> 1;
        curry >>= 1;
    }
    lx = (lx + 1) >> 1;
    rx >>= 1;
}
return ans;
}
};
```

li-chao-tree.h
Description: Li-Chao tree, online convex hull for maximizing $f(x) = k * x + b$, for minimization use $(-k) * x + (-b)$
Time: add - $\mathcal{O}(\log N)$, get - $\mathcal{O}(\log N)$

hash74 lines

```
template<typename T> struct li_chao_tree {
    const T MX = 1e9 + 1;
    struct line {
        T k = 0;
        T b = -INF;

        T f(T x) const {
            return k * x + b;
        }
    };
    struct node {
        line ln;
        node* left = nullptr;
        node* right = nullptr;
    };

    node* new_node() {
        const int N = 100000;
        static node* block;
        static int count = N;

        if (count == N) {
            block = new node[N];
            count = 0;
        }
        return (block + count++);
    };

    node* root = new_node();

    T get(T x) {
        return get(root, -MX, MX, x);
    }

    void add(line ln) {
        add(root, -MX, MX, ln);
    }

    T get(node*& v, T l, T r, T x) {
        if (!v || l > r) {
            return -INF;
        }
        T ans = v->ln.f(x);
        if (r == l) {
            return ans;
        }
        T mid = (r + l) / 2;
        if (x <= mid) {
            return max(ans, get(v->left, l, mid, x));
        } else {
            return max(ans, get(v->right, mid + 1, r, x));
        }
    }

    void add(node*& v, T l, T r, line ln) {
```

```
        if (l > r)
            return;
        if (!v) {
            v = new_node();
        }
        T m = (r + l) / 2;
        bool left = v->ln.f(l) < ln.f(l);
        bool md = v->ln.f(m) < ln.f(m);
        if (md)
            swap(v->ln, ln);
        if (l == r) {
            return;
        }
        if (left != md) {
            add(v->left, l, m, ln);
        } else {
            add(v->right, m + 1, r, ln);
        }
    }
};
```

rope.h
Description: Rope data structure
Time: all get queries $\mathcal{O}(\log N)$

<ext/rope> hash11 lines

```
using namespace __gnu_cxx;

rope<int> v;
for(int i = 1; i <= n; ++i)
    v.push_back(i);
rope<int> cur = v.substr(l, r - l + 1); // start, length
v.erase(l, r - l + 1); // start, length
v.insert(v.mutable_begin(), cur);

for(rope<int>::iterator it = v.mutable_begin(); it != v.mutable_end(); ++it)
    cout << *it << " ";
```

ordered-set.h
Description: A red-black tree with the ability to get an element by index (find.by.order) and index of a specific element (order.of.key)
Time: get - $\mathcal{O}(\log N)$, segment tree is 2 times faster

<ext/pb_ds/assoc.container.hpp>, <ext/pb_ds/tree.policy.hpp> hash4 lines

```
using namespace __gnu_pbds;

template<typename T>
using ordered_set = tree<T, null_type, less<T>, rb_tree_tag,
    tree_order_statistics_node_update>;
```

sparse-table.h
Description: Min sparse table.
Time: build - $\mathcal{O}(N * \log N)$, get - $\mathcal{O}(1)$

<cassert>, <array>, <vector> hash29 lines

```
template<typename T>
struct sparse_table {
    static const int K = 20;
    std::array<std::vector<T>, K> ar;
    std::vector<int> lg;
    int n;

    sparse_table(int n, const vector<T>& a): n(n) {
        lg.resize(n + 1);
        lg[1] = 0;
        for (int i = 2; i <= n; i++)
            lg[i] = lg[i >> 1] + 1;

        ar[0] = a;
```

```
        for (int k = 0; k + 1 < K; k++) {
            ar[k + 1].resize(n);
            for (int i = 0; i + (1 << k) < n; i++) {
                ar[k + 1][i] = min(ar[k][i], ar[k][i + (1 << k)]);
            }
        }

        T get(int l, int r) {
            assert(0 <= l < n && 1 < r && r <= n);
            int power = lg[r - l];
            return min(ar[power][l], ar[power][r - (1 << power)]);
        }
    };
};
```

xor-trie.h
Description: Binary t for integer numbers. Get finds maximum xor of two numbers.
Time: add - $\mathcal{O}(\log A)$, get - $\mathcal{O}(\log A)$

<cassert>, <array> hash35 lines

```
struct xor_trie_node {
    int cnt = 0;
    std::array<xor_trie_node*, 2> mp = {nullptr, nullptr};

    void add(int mask, int k = 30) {
        cnt++;
        if (k == -1)
            return;
        int bit = (mask >> k) & 1;

        if (!mp[bit])
            mp[bit] = new xor_trie_node();
        mp[bit]->add(mask, k - 1);
    }

    void remove(int mask, int k = 30) {
        cnt--;
        if (k == -1)
            return;
        int bit = (mask >> k) & 1;

        assert(mp[bit] && mp[bit]->cnt > 0);
        mp[bit]->remove(mask, k - 1);
    }

    int get(int mask, int k = 30) {
        if (k == -1)
            return 0;
        int bit = (mask >> k) & 1;
        int cur = bit;
        if (mp[!bit] && mp[!bit]->cnt)
            cur = !bit;
        return ((cur ^ bit) << k) | mp[cur]->get(mask, k - 1);
    }
};
```

cartesian-tree.h
Description: Cartesian tree
Time: all get queries $\mathcal{O}(\log N)$

hash63 lines

```
struct Node {
    int val;
    int y;
    int l, r;
    int cnt;

    Node(int val = -1) {
```

```

        this->val = val;
        y = rand();
        l = -1;
        r = -1;
        cnt = 1;
    }
};
array<Node, 2 * N> tree;

int getCnt(int v) {
    if (v == -1)
        return 0;
    return tree[v].cnt;
}

void upd(int v) {
    tree[v].cnt = getCnt(tree[v].l) + getCnt(tree[v].r) + 1;
}

pair<int, int> split(int v, int k) {
    if (v == -1)
        return {-1, -1};
    if (k == 0)
        return {-1, v};
    pair<int, int> res;
    if (getCnt(tree[v].l) >= k) {
        res = split(tree[v].l, k);
        tree[v].l = res.second;
        res.second = v;
    } else {
        res = split(tree[v].r, k - getCnt(tree[v].l) - 1);
        tree[v].r = res.first;
        res.first = v;
    }
    upd(v);
    return res;
}

int merge(int u, int v) {
    if (u == -1)
        return v;
    if (v == -1)
        return u;
    int res = -1;
    if (tree[u].y > tree[v].y) {
        res = merge(tree[u].r, v);
        tree[u].r = res;
        res = u;
    } else {
        res = merge(u, tree[v].l);
        tree[v].l = res;
        res = v;
    }
    upd(res);
    return res;
}

```

link-cut-tree.h

Description: Represents a forest of unrooted trees. You can add and remove edges (as long as the result is still a forest), and check whether two nodes are in the same tree.

Time: All operations take amortized $O(\log N)$.

hash90 lines

```

struct Node { // Splay tree. Root's pp contains tree's parent.
    Node *p = 0, *pp = 0, *c[2];
    bool flip = 0;
    Node() { c[0] = c[1] = 0; fix(); }
    void fix() {
        if (c[0]) c[0]->p = this;

```

```

        if (c[1]) c[1]->p = this;
        // (+ update sum of subtree elements etc. if wanted)
    }
    void pushFlip() {
        if (!flip) return;
        flip = 0; swap(c[0], c[1]);
        if (c[0]) c[0]->flip ^= 1;
        if (c[1]) c[1]->flip ^= 1;
    }
    int up() { return p ? p->c[1] == this : -1; }
    void rot(int i, int b) {
        int h = i ^ b;
        Node *x = c[i], *y = b == 2 ? x : x->c[h], *z = b ? y : x;
        if ((y->p = p)) p->c[up()] = y;
        c[i] = z->c[i ^ 1];
        if (b < 2) {
            x->c[h] = y->c[h ^ 1];
            y->c[h ^ 1] = x;
        }
        z->c[i ^ 1] = this;
        fix(); x->fix(); y->fix();
        if (p) p->fix();
        swap(pp, y->pp);
    }
    void splay() {
        for (pushFlip(); p; ) {
            if (p->p) p->p->pushFlip();
            p->pushFlip(); pushFlip();
            int c1 = up(), c2 = p->up();
            if (c2 == -1) p->rot(c1, 2);
            else p->p->rot(c2, c1 != c2);
        }
    }
    Node* first() {
        pushFlip();
        return c[0] ? c[0]->first() : (splay(), this);
    }
};

struct LinkCut {
    vector<Node> node;
    LinkCut(int N) : node(N) {}

    void link(int u, int v) { // add an edge (u, v)
        assert(!connected(u, v));
        makeRoot(&node[u]);
        node[u].pp = &node[v];
    }
    void cut(int u, int v) { // remove an edge (u, v)
        Node *x = &node[u], *top = &node[v];
        makeRoot(top); x->splay();
        assert(top == (x->pp ? x->c[0]));
        if (x->pp) x->pp = 0;
        else {
            x->c[0] = top->p = 0;
            x->fix();
        }
    }
    bool connected(int u, int v) { // are u, v in the same tree?
        Node* nu = access(&node[u])->first();
        return nu == access(&node[v])->first();
    }
    void makeRoot(Node* u) {
        access(u);
        u->splay();
        if (u->c[0]) {
            u->c[0]->p = 0;
            u->c[0]->flip ^= 1;
            u->c[0]->pp = u;

```

```

        u->c[0] = 0;
        u->fix();
    }
}
Node* access(Node* u) {
    u->splay();
    while (Node* pp = u->pp) {
        pp->splay(); u->pp = 0;
        if (pp->c[1]) {
            pp->c[1]->p = 0; pp->c[1]->pp = pp; }
        pp->c[1] = u; pp->fix(); u = pp;
    }
    return u;
}
};

```

Graphs (6)

articulation-points.h

Description: Finds all articulation points.

Time: $O(N + M)$

<set>, <vector>, <functional> hash35 lines

```

template<typename T>
using graph = std::vector<std::vector<T>>;

```

```

std::set<int> find_articulation_points(int n, graph<int> g) {
    std::vector<int> used(n), tin(n), fup(n);
    int T = 0;
    std::set<int> nodes;
    std::function<void(int, int)> dfs = [&](int v, int p = -1)
    {
        used[v] = true;
        tin[v] = fup[v] = T++;
        int cnt = 0;
        for (auto to : g[v]) {
            if (to == p)
                continue;
            if (used[to]) {
                fup[v] = std::min(fup[v], tin[to]);
            } else {
                dfs(to, v);
                fup[v] = std::min(fup[v], fup[to]);
                if (fup[to] >= tin[v] && p != -1) {
                    nodes.insert(v);
                }
                cnt++;
            }
        }

        if (cnt > 1 && p == -1)
            nodes.insert(v);
    };
    for (int i = 0; i < n; i++) {
        if (!used[i])
            dfs(i, -1);
    }
    return nodes;
}

```

bridges.h

Description: Finds all bridges in the undirected graph.

Time: $O(N + M)$

<vector>, <functional> hash30 lines

```

template<typename T>
using graph = std::vector<std::vector<T>>;

```

```

std::vector<std::pair<int, int>> find_bridges(int n, graph<int>
g) {
    std::vector<int> used(n), tin(n), fup(n);
    int T = 0;
    std::vector<std::pair<int, int>> edges;
    std::function<void(int, int)> dfs = [&](int v, int p = -1)
    {
        used[v] = true;
        tin[v] = fup[v] = T++;
        for (auto to : g[v]) {
            if (to == p)
                continue;
            if (used[to]) {
                fup[v] = std::min(fup[v], tin[to]);
            } else {
                dfs(to, v);
                fup[v] = std::min(fup[v], fup[to]);
                if (fup[to] == tin[to]) {
                    edges.push_back({v, to});
                }
            }
        }
    };
    for (int i = 0; i < n; i++) {
        if (!used[i])
            dfs(i, -1);
    }
    return edges;
}

```

dsu.h

Description: Disjoint Set Union

Time: $\mathcal{O}(n)$ time (amortized) by sizes

<algorithm>, <cassert>, <vector> hash59 lines

```

struct dsu {
public:
    dsu() : _n(0) {}
    dsu(int n) : _n(n), parent_or_size(n, -1) {}

    int merge(int a, int b) {
        assert(0 <= a && a < _n);
        assert(0 <= b && b < _n);
        int x = leader(a), y = leader(b);
        if (x == y) return x;
        if (-parent_or_size[x] < -parent_or_size[y]) std::swap(
            x, y);
        parent_or_size[x] += parent_or_size[y];
        parent_or_size[y] = x;
        return x;
    }

    bool same(int a, int b) {
        assert(0 <= a && a < _n);
        assert(0 <= b && b < _n);
        return leader(a) == leader(b);
    }

    int leader(int a) {
        assert(0 <= a && a < _n);
        if (parent_or_size[a] < 0) return a;
        return parent_or_size[a] = leader(parent_or_size[a]);
    }

    int size(int a) {
        assert(0 <= a && a < _n);
        return -parent_or_size[leader(a)];
    }

    std::vector<std::vector<int>> groups() {

```

```

        std::vector<int> leader_buf(_n), group_size(_n);
        for (int i = 0; i < _n; i++) {
            leader_buf[i] = leader(i);
            group_size[leader_buf[i]]++;
        }
        std::vector<std::vector<int>> result(_n);
        for (int i = 0; i < _n; i++) {
            result[i].reserve(group_size[i]);
        }
        for (int i = 0; i < _n; i++) {
            result[leader_buf[i]].push_back(i);
        }
        result.erase(
            std::remove_if(result.begin(), result.end(),
                [&](const std::vector<int>& v) {
                    return v.empty(); }),
            result.end());
        return result;
    }

private:
    int _n;
    // root node: -1 * component size
    // otherwise: parent
    std::vector<int> parent_or_size;
};

```

dynamic-connectivity-problem.h

Description: Disjoint Set Union with roolbacks

Time: $\mathcal{O}(q * \log(q) * \log(n))$, q - number of queries, n - number of vertices

<array>, <vector> hash110 lines

```

struct Query {
    int v, u;
    bool united;
    Query(int _v, int _u) : v(_v), u(_u) {}
};

```

```

struct DSU
{
    struct DSU_save
    {
        int v, rang_v;
        int u, rang_u;
    };
    int n;
    std::vector<int> pred, rang;
    std::vector<DSU_save> saves;

    DSU(int n_) : n(n_) {
        pred.resize(n);
        rang.resize(n);
        for (int i = 0; i < n; i++) {
            pred[i] = i;
            rang[i] = 0;
        }
    }

    int get(int v) {
        if (pred[v] == v) {
            return v;
        }
        return get(pred[v]);
    }
}

```

```

bool merge(int u, int v) {
    u = get(u);
    v = get(v);
    if (u == v)
        return false;
    if (rang[u] < rang[v])

```

```

        std::swap(u, v);
        saves.push_back({v, rang[v], u, rang[u]});
        pred[v] = u;

        if (rang[u] == rang[v]) {
            rang[u]++;
        }
        return true;
    }
}

```

```

void rollback() {
    if (saves.empty())
        return;
    auto [v, rang_v, u, rang_u] = saves.back();
    rang[v] = rang_v;
    rang[u] = rang_u;

```

```

    pred[v] = v;
    pred[u] = u;

```

```

    saves.pop_back();
}

```

```

};

```

```

struct dynamic_connectivity_problem {
    std::vector<std::vector<Query>> tree;
    int q, n;
    DSU dsu;
    dynamic_connectivity_problem(int q_, int n_) : q(q_), n(n_),
        dsu(DSU(n_)) {
        tree.resize(4 * q);
    }
}

```

```

void add(Query a, int l, int r) {
    add(1, 0, q, l, r, a);
}

```

```

void add(int v, int tl, int tr, int l, int r, const Query& a)
{
    if (l <= tl && tr <= r) {
        tree[v].push_back(a);
        return;
    }
    if (l >= tr || tl >= r)
        return;
    int mid = (tr + tl) / 2;
    add(2 * v, tl, mid, l, r, a);
    add(2 * v + 1, mid, tr, l, r, a);
}

```

```

void dfs(int v, int l, int r) {
    if (l >= r)
        return;

    for (auto& q: tree[v]) {
        q.united = dsu.merge(q.u, q.v);
    }
    if (l + 1 == r) {
        int x = dsu.get(0);
        // do something
    } else {
        int mid = (r + 1) / 2;
        dfs(2 * v, l, mid);
        dfs(2 * v + 1, mid, r);
    }

    for (auto& q: tree[v]) {
        if (q.united)
            dsu.rollback();
    }
}

```

```
        q.united = false;
    }
}
};

kuhn-matching.h
Description: Fast pair matching algorithm. To find the minimum vertex
cover start dfs from each vertice in the left that is not in maximum matching,
from the left side choce unvisited vertices and from right chose visited.
Time:  $\mathcal{O}(n * (n + m))$ 
<vector>, <utility> hash44 lines
using namespace std;

template<typename T>
using graph = vector<vector<T>>;

bool dfs(int v, graph<int>& g, vector<int>& mt, vector<int>&
rev_mt, vector<int>& used) {
    if (used[v] == 1)
        return false;
    used[v] = 1;
    for (auto to : g[v]) {
        if (mt[to] == -1) {
            rev_mt[v] = to;
            mt[to] = v;
            return true;
        }
    }
    for (auto to : g[v]) {
        if (dfs(mt[to], g, mt, rev_mt, used)) {
            rev_mt[v] = to;
            mt[to] = v;
            return true;
        }
    }
    return false;
}

pair<int, vector<int>> pair_matching(int n, int m, graph<int> g
) {
    vector<int> mt(m, -1), used, rev_mt(n, -1);
    int cnt = 0;
    for (int it = 0; ; it++) {
        bool found = false;
        used.assign(n, 0);
        for (int i = 0; i < n; i++) {
            if (rev_mt[i] == -1 && dfs(i, g, mt, rev_mt, used))
            {
                cnt++;
                found = true;
            }
        }
        if (!found) {
            break;
        }
    }
    return {cnt, mt};
}
```

max-flow.h

Description: Maximum flow problem

Time: $\mathcal{O}\left(\min(n^2/3) * m, m^3/2\right)$ - all capacities are 1, $\mathcal{O}(n^2, m)$ - general

```
template<typename Cap>
struct mf_graph {
    struct mf_edge {
        int from, to;
```

```
        Cap cap, flow;
        int back_id;
        int _id;
    };
    int n;
    vector<vector<mf_edge>> g;
    bool need_clear = false;

    mf_graph(int n): n(n) {
        g.assign(n, {});
    }

    void add_edge(int from, int to, Cap cap, int id = -1) {
        int id1 = g[from].size();
        int id2 = g[to].size();

        g[from].push_back(mf_edge {
            .from = from,
            .to = to,
            .cap = cap,
            .flow = Cap(),
            .back_id = id2,
            ._id = id
        });
        g[to].push_back(mf_edge {
            .from = to,
            .to = from,
            .cap = Cap(),
            .flow = Cap(),
            .back_id = id1,
            ._id = -1
        });
    }

    void clear() {
        for (int i = 0; i < n; i++) {
            for (mf_edge& e: g[i])
                e.flow = Cap();
        }
    }

    Cap flow(int s, int t, Cap limit) {
        if (need_clear)
            clear();

        vector<int> dist(n, n + 1);
        auto bfs = [&](int s, int t) {
            dist.assign(n, n + 1);
            dist[s] = 0;
            deque<int> q;
            q.push_back(s);

            while (!q.empty())
            {
                int v = q.front();
                q.pop_front();

                for (mf_edge& e : g[v]) {
                    if (e.flow < e.cap && dist[e.to] == n + 1)
                    {
                        dist[e.to] = dist[v] + 1;
                        q.push_back(e.to);
                    }
                }
            }

            return dist[t] != n + 1;
        };
        vector<int> lst(n);
```

```
function<Cap(int, int, Cap)> dfs = [&](int v, int
target, Cap F) {
    if (v == target)
        return F;

    Cap pushed = Cap();
    for (; lst[v] < g[v].size(); lst[v]++) {
        mf_edge& e = g[v][lst[v]];
        if (dist[e.to] == dist[v] + 1 && e.flow < e.cap
            ) {
            Cap x = dfs(e.to, target, min(F, e.cap - e.
                flow));

            if (x) {
                e.flow += x;
                g[e.to][e.back_id].flow -= x;
                pushed += x;
                F -= x;
            }
        }
    }
    return pushed;
};

Cap flow = 0;
while (bfs(s, t)) {
    lst.assign(n, 0);
    while (Cap f = dfs(s, t, limit)) {
        flow += f;
    }
}
need_clear = true;
return flow;
};

lca.h
Description: Finds lowest common ancestor of two vertices using sparce
table
Time:  $\mathcal{O}(n * \log(n))$  - build,  $\mathcal{O}(1)$  - get hash30 lines
struct LCA {
    vector<pair<int, int>> traversal;
    vector<int> pos;
    graph<int> g;
    int n;
    sparse_table<pair<int, int>> st;

    LCA(int n_, graph<int> g_, int root = 0): n(n_), g(g_) {
        pos.resize(n);
        dfs(root, -1, 0);
        st = sparse_table<pair<int, int>>(traversal.size(),
            traversal);
    }

    void dfs(int v, int pred, int depth) {
        pos[v] = traversal.size();
        traversal.push_back({depth, v});
        for (auto to : g[v]) {
            if (to != pred) {
                dfs(to, v, depth + 1);
                traversal.push_back({depth, v});
            }
        }
    }

    int get(int a, int b) {
        if (a == b)
            return a;
```

```

    return st.get(min(pos[a], pos[b]), max(pos[a], pos[b]) + 1)
        .second;
}
};

two-sat.h
Description: 2-sat implementation
Time:  $\mathcal{O}(n)$ 
<vector> hash74 lines
template<typename T>
using graph = std::vector<std::vector<T>>;

struct two_sat {
    graph<int> g, rev;
    std::vector<int> used, order, comp, ans;
    int n;

    two_sat(int _n): n(_n) {
        g.assign(2 * n, {});
        rev.assign(2 * n, {});
    }

    void add_edge(int u, int v) {
        g[u].push_back(v);
        rev[v].push_back(u);
    }

    void add_clause_or(int a, bool val_a, int b, bool val_b) {
        add_edge(a + val_a * n, b + !val_b * n);
        add_edge(b + val_b * n, a + !val_a * n);
    }

    void add_clause_xor(int a, bool val_a, int b, bool val_b) {
        add_clause_or(a, val_a, b, val_b);
        add_clause_or(a, !val_a, b, !val_b);
    }

    void add_clause_and(int a, bool val_a, int b, bool val_b) {
        add_clause_xor(a, !val_a, b, val_b);
    }

    void top_sort(int v) {
        used[v] = 1;
        for (auto to : g[v]) {
            if (!used[to])
                top_sort(to);
        }
        order.push_back(v);
    }

    void compress(int v, int id) {
        comp[v] = id;
        for (auto to : rev[v]) {
            if (comp[to] == -1)
                compress(to, id);
        }
    }

    bool satisfiable() {
        order.clear();
        used.assign(2 * n, 0);
        comp.assign(2 * n, -1);
        ans.assign(n, 0);

        for (int i = 0; i < 2 * n; i++) {
            if (!used[i])
                top_sort(i);
        }
        reverse(order.begin(), order.end());
    }
};

```

```

    int id = 0;
    for (auto v : order) {
        if (comp[v] == -1)
            compress(v, id++);
    }

    for (int i = 0; i < n; i++) {
        if (comp[i] == comp[i + n])
            return false;
        ans[i] = (comp[i + n] < comp[i]);
    }
    return true;
}
};

eulerian-path.h
Description: Finds eulerian path and cycle for undirected graph
Time:  $\mathcal{O}(m * \log m)$ 
<vector>, <set> hash101 lines
using namespace std;
struct eulerian_path
{
    vector<multiset<int>> graph;
    eulerian_path(vector<vector<int>>&g)
    {
        graph.resize(g.size());
        for(int i=0;i<g.size();i++)
        {
            for(int j:g[i])
            {
                graph[i].insert(j);
            }
        }
    }

    void dfs(int u, vector<int>&cycle)
    {
        auto p = graph[u];
        for(int j:p)
        {
            if(graph[u].find(j) != graph[u].end())
            {
                graph[u].erase(graph[u].find(j));
                graph[j].erase(graph[j].find(u));
                dfs(j, cycle);
            }
        }
        cycle.push_back(u);
    }

    vector<int> find_cycle(int v = 0)
    {
        for(int i = 0; i < graph.size(); i++)
        {
            if(graph[i].size() % 2)
                return {};
        }
        vector<int> cycle;
        dfs(v, cycle);
        for(auto x:graph)
        {
            if(x.size())
                return {};
        }
        return cycle;
    }

    vector<int> find_path()
    {

```

```

        int st = -1, fi = -1;
        int mx = 0;
        for(int i = 0; i < graph.size(); i++)
        {
            if(graph[i].size() % 2)
            {
                if(st == -1)
                    st = i;
                else
                    if(fi == -1)
                        fi = i;
                else
                    return {};
            }
            if(graph[mx].size() < graph[i].size()) mx = i;
        }
        if(fi == -1)
        {
            auto cycle = find_cycle(mx);
            return cycle;
        }
        graph[st].insert(fi);
        graph[fi].insert(st);
        auto cycle = find_cycle(st);
        if(!cycle.size())
            return {};
        cycle.pop_back();
        if(cycle[0]==st and cycle.back()==fi or cycle[0]==fi
            and cycle.back()==st)
        {
            return cycle;
        }
        vector<int> path;
        for(int i=0;;i++)
        {
            if(cycle[i] == st and cycle[i+1] == fi or cycle[i]
                == fi and cycle[i+1] == st)
            {
                for(int j = i + 1; j < cycle.size(); j++)
                {
                    path.push_back(cycle[j]);
                }
                for(int j = 0; j <= i; j++)
                {
                    path.push_back(cycle[j]);
                }
                break;
            }
        }
        return path;
    }
};

max-flow.h
Description: Maximum flow problem
Time:  $\mathcal{O}\left(\min(n^{2/3} * m, m^{3/2})\right)$  - all capacities are 1,  $\mathcal{O}(n^2, m)$  - general
hash104 lines
template<typename Cap>
struct mf_graph {
    struct mf_edge {
        int from, to;
        Cap cap, flow;
        int back_id;
        int _id;
    };
    int n;
    vector<vector<mf_edge>> g;
};

```

```

bool need_clear = false;

mf_graph(int n): n(n) {
    g.assign(n, {});
}

void add_edge(int from, int to, Cap cap, int id = -1) {
    int id1 = g[from].size();
    int id2 = g[to].size();

    g[from].push_back(mf_edge {
        .from = from,
        .to = to,
        .cap = cap,
        .flow = Cap(),
        .back_id = id2,
        ._id = id
    });
    g[to].push_back(mf_edge {
        .from = to,
        .to = from,
        .cap = Cap(),
        .flow = Cap(),
        .back_id = id1,
        ._id = -1
    });
}

void clear() {
    for (int i = 0; i < n; i++) {
        for (mf_edge& e: g[i])
            e.flow = Cap();
    }
}

Cap flow(int s, int t, Cap limit) {
    if (need_clear)
        clear();

    vector<int> dist(n, n + 1);
    auto bfs = [&](int s, int t) {
        dist.assign(n, n + 1);
        dist[s] = 0;
        deque<int> q;
        q.push_back(s);

        while (!q.empty())
        {
            int v = q.front();
            q.pop_front();

            for (mf_edge& e : g[v]) {
                if (e.flow < e.cap && dist[e.to] == n + 1)
                {
                    dist[e.to] = dist[v] + 1;
                    q.push_back(e.to);
                }
            }

            return dist[t] != n + 1;
        };
    };
    vector<int> lst(n);
    function<Cap(int, int, Cap)> dfs = [&](int v, int
        target, Cap F) {
        if (v == target)
            return F;

        Cap pushed = Cap();

```

```

        for (; lst[v] < g[v].size(); lst[v]++) {
            mf_edge& e = g[v][lst[v]];
            if (dist[e.to] == dist[v] + 1 && e.flow < e.cap
                ) {
                Cap x = dfs(e.to, target, min(F, e.cap - e.
                    flow));

                if (x) {
                    e.flow += x;
                    g[e.to][e.back_id].flow -= x;
                    pushed += x;
                    F -= x;
                }
            }
        }
        return pushed;
    };

    Cap flow = 0;
    while (bfs(s, t)) {
        lst.assign(n, 0);
        while (Cap f = dfs(s, t, limit)) {
            flow += f;
        }
    }
    need_clear = true;
    return flow;
}
};

```

min-cut.h

Description: Start dfs from source and using edges with capacity - flow > 0, mark visited vertices. Min cut is edges between marked and unmarked vertices.

Time: $\mathcal{O}(n + m)$

min-cost-flow.h

Description: Solves minimum-cost flow problem for specific flow value (or infinity).

Time: $\mathcal{O}(F * (n + m) * \log(n + m))$, where F is the amount of the flow and m is the number of added edges.

hash106 lines

```

template<typename Cap, typename Cost>
struct mcf_graph
{
    struct mcf_edge {
        int from, to;
        Cap cap, flow;
        Cost cost;
        int back_id;
        int _id;
    };
    int n;
    vector<vector<mcf_edge>> g;
    mcf_graph(int n): n(n) {
        g.assign(n, {});
    }

    void add_edge(int from, int to, Cap cap, Cost cost, int _id
        = -1) {
        int id1 = g[from].size();
        int id2 = g[to].size();
        g[from].push_back(mcf_edge{
            .from = from,
            .to = to,
            .cap = cap,
            .flow = Cap(),
            .cost = cost,

```

```

            .back_id = id2,
            ._id = _id
        });

        g[to].push_back(mcf_edge{
            .from = to,
            .to = from,
            .cap = Cap(),
            .flow = Cap(),
            .cost = -cost,
            .back_id = id1,
            ._id = -1
        });
    }

    pair<Cap, Cost> flow(int s, int t, Cap target_flow) {
        Cap flow = Cap();
        vector<pair<int, int>> pred(n);
        vector<Cost> dist(n, dual(n, 0));
        auto shortestst_path = [&](int s, int t) {
            pred.assign(n, {-1, -1});
            dist.assign(n, numeric_limits<Cost>::max());
            dist[s] = Cost();
            set<pair<int, int>> q;
            q.insert({dist[s], s});

            while (!q.empty()) {
                int v = q.begin()->second;
                q.erase(q.begin());

                for (int i = 0; i < g[v].size(); i++) {
                    mcf_edge& e = g[v][i];
                    if (e.flow >= e.cap)
                        continue;

                    Cost cost = e.cost - dual[e.to] + dual[v];
                    if (dist[e.to] > dist[v] + cost) {
                        q.erase({dist[e.to], e.to});
                        dist[e.to] = dist[v] + cost;
                        pred[e.to] = {v, i};
                        q.insert({dist[e.to], e.to});
                    }
                }

                if (dist[t] == numeric_limits<Cost>::max())
                    return false;
                for (int v = 0; v < n; v++) {
                    if (dist[v] == numeric_limits<Cost>::max())
                        continue;
                    dual[v] -= dist[t] - dist[v];
                }

                return true;
            };
        };
        Cost total_cost = {};
        while (flow < target_flow) {
            if (!shortestst_path(s, t))
                break;
            Cap f = target_flow - flow;
            int cur = t;
            while (cur != s) {
                auto [p, id] = pred[cur];
                mcf_edge& e = g[p][id];
                f = min(f, e.cap - e.flow);
                cur = p;
            }
            cur = t;
            while (cur != s) {
                auto [p, id] = pred[cur];

```

```
        mcf_edge& e = g[p][id];
        e.flow += f;
        g[e.to][e.back_id].flow -= f;
        cur = p;
    }
    Cost d = -dual[s];
    flow += f;
    total_cost += f * d;
}
return {flow, total_cost};
};
```

ford-bellman.h

Description: Single source shortest path with negative weight edges in dircteted graph

Time: $\mathcal{O}(n * m)$ hash16 lines

```
vector<int> d(n, INF);
d[v] = 0;
vector<int> p(n, -1);

for (;;) {
    bool any = false;
    for (Edge e : edges)
        if (d[e.a] < INF)
            if (d[e.b] > d[e.a] + e.cost) {
                d[e.b] = d[e.a] + e.cost;
                p[e.b] = e.a;
                any = true;
            }
    if (!any)
        break;
}
```

spfa.h

Description: Single source shortest path with negative weight edges in dircteted graph

Time: $\mathcal{O}(n * m)$ hash36 lines

```
const int INF = 1000000000;
vector<vector<pair<int, int>>> adj;

bool spfa(int s, vector<int>& d) {
    int n = adj.size();
    d.assign(n, INF);
    vector<int> cnt(n, 0);
    vector<bool> inqueue(n, false);
    queue<int> q;

    d[s] = 0;
    q.push(s);
    inqueue[s] = true;
    while (!q.empty()) {
        int v = q.front();
        q.pop();
        inqueue[v] = false;

        for (auto edge : adj[v]) {
            int to = edge.first;
            int len = edge.second;

            if (d[v] + len < d[to]) {
                d[to] = d[v] + len;
                if (!inqueue[to]) {
                    q.push(to);
                    inqueue[to] = true;
                    cnt[to]++;
                    if (cnt[to] > n)

```

```
                return false; // negative cycle
            }
        }
    }
    return true;
}
```

directed-mst.h

Description: finds directed mst from given root

Time: $\mathcal{O}(|E| * \log|V|)$ hash82 lines

```
struct RollbackUF {
    vector<int> e; vector<pair<int, int>> st;
    RollbackUF(int n) : e(n, -1) {}
    int size(int x) { return -e[find(x)]; }
    int find(int x) { return e[x] < 0 ? x : find(e[x]); }
    int time() { return (int)st.size(); }
    void rollback(int t) {
        for (int i = time(); i --> t;)
            e[st[i].first] = st[i].second;
        st.resize(t);
    }
    bool join(int a, int b) {
        a = find(a), b = find(b);
        if (a == b) return false;
        if (e[a] > e[b]) swap(a, b);
        st.push_back({a, e[a]});
        st.push_back({b, e[b]});
        e[a] += e[b]; e[b] = a;
        return true;
    }
};
```

```
struct Edge { int a, b; ll w; };
struct Node {
    Edge key;
    Node *l, *r;
    ll delta;
    void prop() {
        key.w += delta;
        if (l) l->delta += delta;
        if (r) r->delta += delta;
        delta = 0;
    }
    Edge top() { prop(); return key; }
};

Node *merge(Node *a, Node *b) {
    if (!a || !b) return a ? b;
    a->prop(), b->prop();
    if (a->key.w > b->key.w) swap(a, b);
    swap(a->l, (a->r = merge(b, a->r)));
    return a;
}

void pop(Node*& a) { a->prop(); a = merge(a->l, a->r); }

pair<ll, vector<int>> dmst(int n, int r, vector<Edge>& g) {
    RollbackUF uf(n);
    vector<Node*> heap(n);
    for (Edge e : g) heap[e.b] = merge(heap[e.b], new Node{e});
    ll res = 0;
    vector<int> seen(n, -1), path(n), par(n);
    seen[r] = r;
    vector<Edge> Q(n), in(n, {-1,-1}), comp;
    deque<tuple<int, int, vector<Edge>>> cyps;
    for(int s = 0; s<n; s++) {
        int u = s, qi = 0, w;
        while (seen[u] < 0) {
            if (!heap[u]) return {-1, {}};

```

```
            Edge e = heap[u]->top();
            heap[u]->delta -= e.w, pop(heap[u]);
            Q[qi] = e, path[qi++] = u, seen[u] = s;
            res += e.w, u = uf.find(e.a);
            if (seen[u] == s) {
                Node* cyc = 0;
                int end = qi, time = uf.time();
                do cyc = merge(cyc, heap[w = path[--qi]]);
                while (uf.join(u, w));
                u = uf.find(u), heap[u] = cyc, seen[u] = -1;
                cyps.push_front({u, time, {&Q[qi], &Q[end]}});
            }
        }
        for(int i = 0; i<qi; i++) in[uf.find(Q[i].b)] = Q[i];
    }

    for (auto& [u,t,comp] : cyps) { // restore sol (optional)
        uf.rollback(t);
        Edge inEdge = in[u];
        for (auto& e : comp) in[uf.find(e.b)] = e;
        in[uf.find(inEdge.b)] = inEdge;
    }
    for(int i=0; i<n; i++) par[i] = in[i].a;
    return {res, par};
}
```

Strings (7)

z-function.h

Description: Z-functions, z[i] equal to the length of largest common prefix of string s and suffix of s starting at i.

Time: $\mathcal{O}(N)$, N - size of string s hash18 lines

```
vector<int> z_function(const string& s) {
    int n = s.size();
    vector<int> z(n);
    int l = 0, r = 0;
    for(int i = 1; i < n; i++) {
        if(i < r) {
            z[i] = min(r - i, z[i - l]);
        }
        while(i + z[i] < n && s[z[i]] == s[i + z[i]]) {
            z[i]++;
        }
        if(i + z[i] > r) {
            l = i;
            r = i + z[i];
        }
    }
    return z;
}
```

prefix-function.h

Description: The prefix function for this string is defined as an array p of length n, where p[i] is the length of the longest valid prefix of the substring s[0...i], which is also a suffix of this substring.

Time: $\mathcal{O}(N)$, N - size of string s hash13 lines

```
vector<int> prefix_function(string s) {
    int n = (int)s.length();
    vector<int> pi(n);
    for (int i = 1; i < n; i++) {
        int j = pi[i-1];
        while (j > 0 && s[i] != s[j])
            j = pi[j-1];
        if (s[i] == s[j])
            j++;
        pi[i] = j;
    }
}
```

```
    }
    return pi;
}
```

suffix-array.h

Description: Suffix array will contain integers that represent the starting indexes of the all the suffixes of a given string, after the aforementioned suffixes are sorted.
Time: $\mathcal{O}(N * \log(N))$, N - size of string s

hash65 lines

```
vector<int> suffix_arrays(string s) {
    s = s + "$";
    int n = s.size();

    std::vector<int> p(n);
    vector<vector<int>>> c(20, vector<int>(n));
    int alphabet = 256;

    auto set_classes = [&](int k) {
        int classes = 0;
        c[k][p[0]] = classes++;
        for (int i = 1; i < n; i++) {
            auto cur = pair{c[k - 1][p[i]], c[k - 1][(p[i] + (1<<(k - 1))) % n]};
            auto prev = pair{c[k - 1][p[i - 1]], c[k - 1][(p[i - 1] + (1<<(k - 1))) % n]};
            if (cur == prev) {
                c[k][p[i]] = c[k][p[i - 1]];
            } else {
                c[k][p[i]] = classes++;
            }
        }
    };

    vector<int> cnt(alphabet);
    for (int i = 0; i < n; i++) {
        cnt[s[i]]++;
    }
    for (int i = 1; i < alphabet; i++) {
        cnt[i] += cnt[i - 1];
    }
    for (int i = n - 1; i >= 0; i--) {
        p[cnt[s[i]] - 1] = i;
        cnt[s[i]]--;
    }

    int classes = 0;
    c[0][p[0]] = classes++;
    for (int i = 1; i < n; i++) {
        if (s[p[i]] == s[p[i - 1]]) {
            c[0][p[i]] = c[0][p[i - 1]];
        } else {
            c[0][p[i]] = classes++;
        }
    }

    for (int k = 0; (1<<k) < n; k++) {
        vector<int> pn(n), cnt(n);
        for (int i = 0; i < n; i++) {
            pn[i] = (p[i] - (1<<k) + n) % n;
            cnt[c[k][pn[i]]]++;
        }

        for (int i = 1; i < n; i++)
            cnt[i] += cnt[i - 1];

        for (int i = n - 1; i >= 0; i--) {
            p[cnt[c[k][pn[i]]] - 1] = pn[i];
            cnt[c[k][pn[i]]]--;
        }
    }
}
```

```
    }

    set_classes(k + 1);
}

p.erase(p.begin());
return p;
}
```

lcp-array.h

Description: Largest common prefix of substrings. Given a string s of length n, it returns the LCP array of s. Here, the LCP array of s is the array of length n-1, such that the i-th element is the length of the LCP (Longest Common Prefix) of s[sa[i]..n) and s[sa[i+1]..n).
Time: $\mathcal{O}(N)$, N - size of string s

hash31 lines

```
template <class T>
std::vector<int> lcp_array(const std::vector<T>& s,
                           const std::vector<int>& sa) {
    int n = int(s.size());
    assert(n >= 1);
    std::vector<int> rnk(n);
    for (int i = 0; i < n; i++) {
        rnk[sa[i]] = i;
    }
    std::vector<int> lcp(n - 1);
    int h = 0;
    for (int i = 0; i < n; i++) {
        if (h > 0) h--;
        if (rnk[i] == 0) continue;
        int j = sa[rnk[i] - 1];
        for (; j + h < n && i + h < n; h++) {
            if (s[j + h] != s[i + h]) break;
        }
        lcp[rnk[i] - 1] = h;
    }
    return lcp;
}

std::vector<int> lcp_array(const std::string& s, const std:::
    vector<int>& sa) {
    int n = int(s.size());
    std::vector<int> s2(n);
    for (int i = 0; i < n; i++) {
        s2[i] = s[i];
    }
    return lcp_array(s2, sa);
}
```

hash.h

Description: Polynomial hashes for strings
Time: $\mathcal{O}(n * \log(M))$, n - size of string s, m - module

hash47 lines

```
template<int P, int MOD>
struct hash_st {
    int n;
    vector<int> hash_, rev_, p, rev_p;
    hash_st(string s) {
        n = s.size();
        hash_.resize(n);
        rev_.resize(n);
        p.resize(n);
        rev_p.resize(n);

        p[0] = 1;
        rev_p[0] = 1;
        for (int i = 1; i < n; i++) {
            p[i] = (p[i - 1] * P) % MOD;
            rev_p[i] = fast_pow(p[i], MOD - 2, MOD);
        }
    }
}
```

```
    }

    int last = 0;
    for (int i = 0; i < n; i++) {
        hash_[i] = (last + p[i] * (s[i] - 'a' + 1)) % MOD;
        last = hash_[i];
    }
    last = 0;
    for (int i = n - 1; i >= 0; i--) {
        rev_[i] = (last + p[n - 1 - i] * (s[i] - 'a' + 1))
            % MOD;
        last = rev_[i];
    }
}

int get(int l, int r) {
    r--;
    if (l == 0)
        return hash_[r];
    int x = (MOD + hash_[r] - hash_[l - 1]) % MOD;
    return (x * rev_p[l]) % MOD;
}

int get_rev(int l, int r) {
    r--;
    if (r == n - 1)
        return rev_[l];
    int x = (MOD + rev_[l] - rev_[r + 1]) % MOD;
    int st = n - 1 - r;
    return (x * rev_p[st]) % MOD;
}

};
```

trie.h

Description: Trie implementation
Time: $\mathcal{O}(n)$

hash63 lines

```
template<int N = (int)1e6 + 1>
struct trie {
    struct node {
        int cnt = 0;
        array<int, 27> links;

        node() {
            links.fill(-1);
            cnt = 0;
        }
    };

    array<node, N> tree;
    int sz = 0;
    int root = 0;

    trie() {
        root = sz++;
    }

    void add(string s) {
        int cur = root;
        tree[cur].cnt++;
        for (int i = 0; i < s.size(); i++) {
            int nxt = tree[cur].links[s[i] - 'a'];
            if (nxt == -1) {
                nxt = sz++;
                tree[cur].links[s[i] - 'a'] = nxt;
            }
            tree[nxt].cnt++;
            cur = nxt;
        }
    }
}
```



```

}

void remove(string s) {
    int cur = root;
    tree[cur].cnt--;
    for (int i = 0; i < s.size(); i++) {
        int nxt = tree[cur].links[s[i] - 'a'];
        assert(nxt != -1);
        tree[nxt].cnt--;
        cur = nxt;
    }
}

int get_cnt_of_str(const string& s) {
    int cur = root;
    for (int i = 0; i < s.size(); i++) {
        int nxt = tree[cur].links[s[i] - 'a'];
        if (nxt == -1) {
            return 0;
        }
        cur = nxt;
    }
    return tree[cur].cnt;
}

void clear() {
    for (int i = 0; i < sz; i++)
        tree[i] = node();
}
};
```

aho-corasick.h
Description: creates suffix automaton
Time: $O(|alphabet| * \sum of length of strings)$

```

const int K = 26;

struct Vertex {
    int next[K];
    bool output = false;
    int p = -1;
    char pch;
    int link = -1;
    int ans_link = -1;
    int go[K];

    Vertex(int p=-1, char ch='$') : p(p), pch(ch) {
        fill(begin(next), end(next), -1);
        fill(begin(go), end(go), -1);
    }
};

vector<Vertex> t(1);

void add_string(string const& s) {
    int v = 0;
    for (char ch : s) {
        int c = ch - 'a';
        if (t[v].next[c] == -1) {
            t[v].next[c] = t.size();
            t.emplace_back(v, ch);
        }
        v = t[v].next[c];
    }
    t[v].output = true;
}

int go(int v, char ch);
```

```

int get_link(int v) {
    if (t[v].link == -1) {
        if (v == 0 || t[v].p == 0)
            t[v].link = 0;
        else
            t[v].link = go(get_link(t[v].p), t[v].pch);
    }
    return t[v].link;
}

int go(int v, char ch) {
    int c = ch - 'a';
    if (t[v].go[c] == -1) {
        if (t[v].next[c] != -1)
            t[v].go[c] = t[v].next[c];
        else
            t[v].go[c] = v == 0 ? 0 : go(get_link(v), ch);
    }
    return t[v].go[c];
}

int get_ans_link(int v)
{
    if(v == 0)
        return 0;
    if(t[v].ans_link == -1)
    {
        if(t[get_link(v)].output)
        {
            t[v].ans_link = get_link(v);
        }
        else
            t[v].ans_link = get_ans_link(get_link(v));
    }
    return t[v].ans_link;
}

// returns all strings from dictionary that is suffix of given
// state
vector<string> get_ans(int v)
{
    vector<string>ans;
    if(t[v].output)
    {
        string cur = "";
        int v1 = v;
        while(v1)
        {
            cur += t[v1].pch;
            v1 = t[v1].p;
        }
        reverse(cur.begin(), cur.end());
        ans.push_back(cur);
    }
    v = get_ans_link(v);
    while(v)
    {
        string cur = "";
        int v1 = v;
        while(v1)
        {
            cur += t[v1].pch;
            v1 = t[v1].p;
        }
        reverse(cur.begin(), cur.end());
        ans.push_back(cur);
        v = get_ans_link(v);
    }
    return ans;
}
```

Geometry (8)

```

point.h
Description: geometry formulas
<complex>, <iostream> hash124 lines

class point : public std::complex<long double> {
    using ld = long double;
    static constexpr long double PI = 3.141592653589793;

public:
    point() : std::complex<long double>() {}

    point(ld x, ld y) : std::complex<long double>(x, y) {}

    point(std::complex<long double> obj) : std::complex<long double>(obj) {}

    ld x() {
        return this->real();
    }

    ld y() {
        return this->imag();
    }

    ld x() const {
        return this->real();
    }

    ld y() const {
        return this->imag();
    }

    // a_x * b_x + a_y * b_y
    static ld dot_product(const point& a, const point& b) {
        return (conj(a) * b).real();
    }

    // a_x * b_y - a_y * b_x
    static ld cross_product(const point& a, const point& b) {
        return (conj(a) * b).imag();
    }

    static ld squared_distance(const point& a, const point& b) {
        return norm(a - b);
    }

    static ld distance(const point& a, const point& b) {
        return abs(a - b);
    }

    // angle_of_elevation of line (a, b) to oX
    static ld angle_of_elevation(const point& a, const point& b)
    {
        return arg(b - a);
    }

    // k from y = k * x + b
    static ld slope_of_line(const point& a, const point& b) {
        return tan(arg(b - a));
    }

    static point from_polar(ld r, ld theta) {
        return std::polar(r, theta);
    }
}
```

```

static point rotate_above_pivot(const point& a, const ld
    theta, const point& pivot = point(0, 0)){
    return (a - pivot) * std::polar<ld>(1.0, theta) + pivot;
}

point& rotate(const ld theta, const point& pivot = point(0,
    0)) {
    *this = point::rotate_above_pivot(*this, theta, pivot);
    return *this;
}

// angle of ABC
static ld angle(const point& a, const point& b, const point&
    c) {
    return abs(remainder(arg(a-b) - arg(c-b), 2.0 * PI));
}

static point project_on_vector(const point& p, const point& v
    ) {
    return v * dot_product(p, v) / norm(v);
}

static point project_on_line(const point& p, const point& a,
    const point& b) {
    return a + (b - a) * dot_product(p - a, b - a) / norm(b - a
    );
}

static point reflect_accros(const point& p, const point& a,
    const point& b) {
    return a + conj((p - a) / (b - a)) * (b - a);
}

// intersection of lines (a, b) and (p, q). if parallel
    returns {false, ...} else {true, intersection}.
friend std::pair<bool, point> intersection_of_lines(const
    point& a, const point& b, const point& p, const point& q
    ) {
    ld c1 = cross_product(p - a, b - a), c2 = cross_product(q -
        a, b - a);
    if (c1 == c2) {
        return {false, {}};
    }
    return {true, (c1 * q - c2 * p) / (c1 - c2)}; // undefined
        if parallel
}

// returns a, b, c from a * x + b * y + c == 0 by two points
friend std::tuple<ld, ld, ld> get_line(const point& p, const
    point& q) {
    ld a = (p.y() - q.y());
    ld b = -(p.x() - q.x());
    ld c = p.y() * (p.x() - q.x()) - p.x() * (p.y() - q.y());
    return {a, b, c};
}

friend ld distance_from_point_to_line(const point& p, const
    point& a, const point& b) {
    point q = project_on_line(p, a, b);

    return point::distance(p, q);
}

friend ld distance_from_point_to_segment(const point& p,
    const point& a, const point& b) {
    point q = project_on_line(p, a, b);
    if (std::min(a.x(), b.x()) <= q.x() && q.x() <= std::max(a.
        x(), b.x()))

```

```

    return point::distance(p, q);
else
    return std::min(distance(p, a), distance(p, b));
}

friend std::istream& operator>> (std::istream& in, point& p)
    {
        ld x, y;
        in >> x >> y;
        p = point(x, y);
        return in;
    }
};

faces-of-planar-graph.h
Description: Finds faces of planar graph. Rreturns a vector of vertices for
each face, outer face goes first. Inner faces are returned in counter-clockwise
orders and the outer face is returned in clockwise order.
Time:  $\mathcal{O}(n \log(n))$ 
<vector> hash89 lines
template<typename T>
using graph = vector<vector<T>>;

struct Point {
    int64_t x, y;

    Point(int64_t x_, int64_t y_): x(x_), y(y_) {}

    Point operator - (const Point & p) const {
        return Point(x - p.x, y - p.y);
    }

    int64_t cross (const Point & p) const {
        return x * p.y - y * p.x;
    }

    int64_t cross (const Point & p, const Point & q) const {
        return (p - *this).cross(q - *this);
    }

    int half () const {
        return int(y < 0 || (y == 0 && x < 0));
    }
};

std::vector<std::vector<size_t>> find_faces(std::vector<Point>
    vertices, graph<int> adj) {
    size_t n = vertices.size();
    std::vector<std::vector<char>> used(n);
    for (size_t i = 0; i < n; i++) {
        used[i].resize(adj[i].size());
        used[i].assign(adj[i].size(), 0);
        auto compare = [&](size_t l, size_t r) {
            Point pl = vertices[l] - vertices[i];
            Point pr = vertices[r] - vertices[i];
            if (pl.half() != pr.half())
                return pl.half() < pr.half();
            return pl.cross(pr) > 0;
        };
        std::sort(adj[i].begin(), adj[i].end(), compare);
    }
    std::vector<std::vector<size_t>> faces;
    for (size_t i = 0; i < n; i++) {
        for (size_t edge_id = 0; edge_id < adj[i].size();
            edge_id++) {
            if (used[i][edge_id]) {
                continue;
            }
            std::vector<size_t> face;

```

```

            size_t v = i;
            size_t e = edge_id;
            while (!used[v][e]) {
                used[v][e] = true;
                face.push_back(v);
                size_t u = adj[v][e];
                size_t el = std::lower_bound(adj[u].begin(),
                    adj[u].end(), v, [&](size_t l, size_t r) {
                        Point pl = vertices[l] - vertices[u];
                        Point pr = vertices[r] - vertices[u];
                        if (pl.half() != pr.half())
                            return pl.half() < pr.half();
                        return pl.cross(pr) > 0;
                    }) - adj[u].begin() + 1;
                if (el == adj[u].size()) {
                    el = 0;
                }
                v = u;
                e = el;
            }
            std::reverse(face.begin(), face.end());
            int sign = 0;
            for (size_t j = 0; j < face.size(); j++) {
                size_t j1 = (j + 1) % face.size();
                size_t j2 = (j + 2) % face.size();
                int64_t val = vertices[face[j]].cross(vertices[
                    face[j1]], vertices[face[j2]]);
                if (val > 0) {
                    sign = 1;
                    break;
                } else if (val < 0) {
                    sign = -1;
                    break;
                }
            }
            if (sign <= 0) {
                faces.insert(faces.begin(), face);
            } else {
                faces.emplace_back(face);
            }
        }
        return faces;
    }
}

mec.h
Description: Minimum enclosing circle
Time:  $\mathcal{O}(n)$ 
<algorithm>, <assert.h>, <iostream>, <math.h>, <vector>, <iomanip> hash89 lines
using namespace std;
const double INF = 1e18;
struct Point {
    double X, Y;
};
struct Circle {
    Point C;
    double R;
};
double dist(const Point& a, const Point& b)
{
    return sqrt(pow(a.X - b.X, 2)
        + pow(a.Y - b.Y, 2));
}
bool is_inside(const Circle& c, const Point& p)
{
    return dist(c.C, p) <= c.R;
}
Point get_circle_center(double bx, double by, double cx, double
    cy)

```

```
{
    double B = bx * bx + by * by;
    double C = cx * cx + cy * cy;
    double D = bx * cy - by * cx;
    return { (cy * B - by * C) / (2 * D),
             (bx * C - cx * B) / (2 * D) };
}

Circle circle_from(const Point& A, const Point& B, const Point& C)
{
    Point I = get_circle_center(B.X - A.X, B.Y - A.Y, C.X - A.X, C.Y - A.Y);

    I.X += A.X;
    I.Y += A.Y;
    return { I, dist(I, A) };
}

Circle circle_from(const Point& A, const Point& B)
{
    Point C = { (A.X + B.X) / 2.0, (A.Y + B.Y) / 2.0 };
    return { C, dist(A, B) / 2.0 };
}

bool is_valid_circle(const Circle& c, const vector<Point>& P)
{
    for (const Point& p : P)
        if (!is_inside(c, p))
            return false;
    return true;
}

Circle min_circle_trivial(vector<Point>& P)
{
    assert(P.size() <= 3);
    if (P.empty()) {
        return { { 0, 0 }, 0 };
    }
    else if (P.size() == 1) {
        return { P[0], 0 };
    }
    else if (P.size() == 2) {
        return circle_from(P[0], P[1]);
    }
    for (int i = 0; i < 3; i++) {
        for (int j = i + 1; j < 3; j++) {

            Circle c = circle_from(P[i], P[j]);
            if (is_valid_circle(c, P))
                return c;
        }
    }
    return circle_from(P[0], P[1], P[2]);
}

Circle welzl_helper(vector<Point>& P, vector<Point> R, int n)
{
    if (n == 0 || R.size() == 3) {
        return min_circle_trivial(R);
    }
    int idx = rand() % n;
    Point p = P[idx];
    swap(P[idx], P[n - 1]);
    Circle d = welzl_helper(P, R, n - 1);
    if (is_inside(d, p)) {
        return d;
    }
    R.push_back(p);
    return welzl_helper(P, R, n - 1);
}

Circle welzl(const vector<Point>& P)
{
    vector<Point> P_copy = P;
```

```
    random_shuffle(P_copy.begin(), P_copy.end());
    return welzl_helper(P_copy, {}, P_copy.size());
}
```

Misc. algorithms (9)

primes.txt3 lines

p = 962592769 is such that $221 \mid p - 1$, which may be useful.
For hashing use 970592641
(31-bit number), 31443539979727 (45-bit), 3006703054056749 (52-bit). There are 78498 primes less than 1 000 000.

sos-dp.hDescription: Sum over submasksTime: $\mathcal{O}(n * 2 * n)$ hash7 lines

```
for (int i = 0; i < n; i++) {
    for (int mask = 0; mask < (1<<n); mask++) {
        if (mask&(1<<i)) {
            dp[mask] += dp[mask^(1<<i)];
        }
    }
}
```

Techniques (A)

techniques.txt	161 lines
Recursion	
Divide and conquer	
Finding interesting points in N log N	
Algorithm analysis	
Master theorem	
Amortized time complexity	
Greedy algorithm	
Scheduling	
Max contiguous subvector sum	
Invariants	
Huffman encoding	
Graph theory	
Dynamic graphs (extra book-keeping)	
Breadth first search	
Depth first search	
* Normal trees / DFS trees	
Dijkstra's algorithm	
MST: Prim's algorithm	
Bellman-Ford	
Konig's theorem and vertex cover	
Min-cost max flow	
Lovasz toggle	
Matrix tree theorem	
Maximal matching, general graphs	
Hopcroft-Karp	
Hall's marriage theorem	
Graphical sequences	
Floyd-Warshall	
Euler cycles	
Flow networks	
* Augmenting paths	
* Edmonds-Karp	
Bipartite matching	
Min. path cover	
Topological sorting	
Strongly connected components	
2-SAT	
Cut vertices, cut-edges and biconnected components	
Edge coloring	
* Trees	
Vertex coloring	
* Bipartite graphs (=> trees)	
* 3^n (special case of set cover)	
Diameter and centroid	
K'th shortest path	
Shortest cycle	
Dynamic programming	
Knapsack	
Coin change	
Longest common subsequence	
Longest increasing subsequence	
Number of paths in a dag	
Shortest path in a dag	
Dynprog over intervals	
Dynprog over subsets	
Dynprog over probabilities	
Dynprog over trees	
3^n set cover	
Divide and conquer	
Knuth optimization	
Convex hull optimizations	
Slope trick	
Aliens trick	
RMQ (sparse table a.k.a 2^k-jumps)	
Bitonic cycle	

Log partitioning (loop over most restricted)	
Combinatorics	
Computation of binomial coefficients	
Pigeon-hole principle	
Inclusion/exclusion	
Catalan number	
Pick's theorem	
Number theory	
Integer parts	
Divisibility	
Euclidean algorithm	
Modular arithmetic	
* Modular multiplication	
* Modular inverses	
* Modular exponentiation by squaring	
Chinese remainder theorem	
Fermat's little theorem	
Euler's theorem	
Phi function	
Frobenius number	
Quadratic reciprocity	
Pollard-Rho	
Miller-Rabin	
Hensel lifting	
Vieta root jumping	
Game theory	
Combinatorial games	
Game trees	
Mini-max	
Nim	
Games on graphs	
Games on graphs with loops	
Grundy numbers	
Bipartite games without repetition	
General games without repetition	
Alpha-beta pruning	
Probability theory	
Optimization	
Binary search	
Ternary search	
Unimodality and convex functions	
Binary search on derivative	
Numerical methods	
Numeric integration	
Newton's method	
Root-finding with binary/ternary search	
Golden section search	
Matrices	
Gaussian elimination	
Exponentiation by squaring	
Sorting	
Radix sort	
Geometry	
Coordinates and vectors	
* Cross product	
* Scalar product	
Convex hull	
Polygon cut	
Closest pair	
Coordinate-compression	
Quadtrees	
KD-trees	
All segment-segment intersection	
Sweeping	
Discretization (convert to events and sweep)	
Angle sweeping	
Line sweeping	
Discrete second derivatives	
Strings	

Longest common substring	
Palindrome subsequences	
Knuth-Morris-Pratt	
Tries	
Rolling polynomial hashes	
Suffix array	
Suffix tree	
Aho-Corasick	
Manacher's algorithm	
Letter position lists	
Combinatorial search	
Meet in the middle	
Brute-force with pruning	
Best-first (A*)	
Bidirectional search	
Iterative deepening DFS / A*	
Data structures	
LCA (2^k-jumps in trees in general)	
Pull/push-technique on trees	
Heavy-light decomposition	
Centroid decomposition	
Lazy propagation	
Self-balancing trees	
Convex hull trick (wcipeg.com/wiki/Convex_hull_trick)	
Monotone queues / monotone stacks / sliding queues	
Sliding queue using 2 stacks	
Persistent segment tree	