

$$Q) \quad G(s) = \frac{100(s+0.8)}{(s+0.5)(s+1)^2(s+15)}$$

1) (2 marks) Compute the closed loop transfer function of the uncompensated system and generate the closed loop step response of the uncompensated system. Read off the values of the **uncompensated** closed loop step response specs: Percent Overshoot, PO, Steady State Error,  $e_{ss}(\text{step}\%)$ , Rise Time,  $T_{rise}(0-100\%)$  and Settling Time,  $T_{settle}(\pm 2\%)$ , and place your answers in the Table. Verify the specs values by running the Matlab "stepval" function.

$$\begin{aligned} G_{cl}(s) &= \frac{100(s+0.8)}{(s+0.5)(s+1)^2(s+15)} \\ &= \frac{100(s+0.8)}{(s+0.5)(s+1)^2(s+15) + 100(s+0.8)} \\ &= \frac{100s + 80}{(s^4 + 17.5s^3 + 31.5s^2 + 130.5s + 87.5)} \end{aligned}$$

$$\frac{100s + 80}{s^4 + 17.5s^3 + 31.5s^2 + 130.5s + 87.5}$$

$$G_{cl}(s) = \frac{100s + 80}{s^4 + 17.5s^3 + 31.5s^2 + 130.5s + 87.5}$$

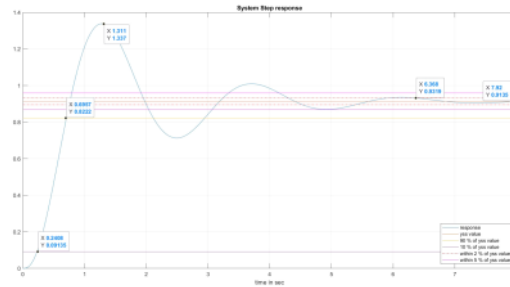
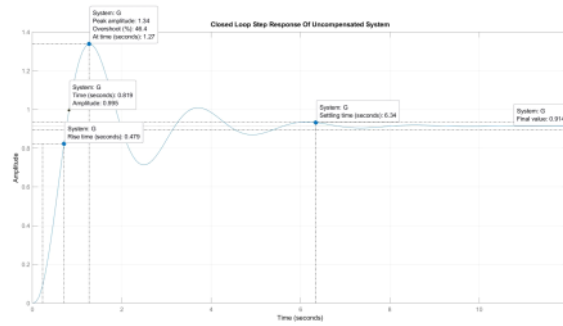
$$\begin{aligned} PO &= \frac{y_{max} - y_{ss}}{y_{ss}} \times 100 \\ &= \frac{1.387 - 0.9135}{0.9135} \times 100 \end{aligned}$$

$$PO = 46.36\%$$

$$\begin{aligned} e_{ss}(\text{step}\%) &= \frac{r_{ss} - y_{ss}}{r_{ss}} \times 100 \\ &= \frac{1 - 0.9135}{1} \times 100 \\ e_{ss}(\text{step}\%) &= 8.65\% \end{aligned}$$

$$T_{rise(0-100\%)} = 0.7759 \text{ s}$$

$$T_{settle(\pm 2\%)} = 6.3679 \text{ s}$$



2) (2 marks) Now that you know what the actual specs are, estimate these specs by first generating a closed loop model for the uncompensated system, then calculating specs based on the relationships established for the second order dominant poles model. HINT: The most straightforward way of generating the model is from the closed loop transfer function - use the "zpk" Matlab function to factorize it, and remove the near pole-zero cancellations, and the negligible poles and zeros. Are your estimates close to the actual specs? Include calculations in your report.

$$G_{cl}(s) = \frac{100 (s + 0.8)}{(s + 15.47)(s + 0.7933)(s^2 + 1.234s + 7.086)}$$

$$= (s + 15.47) \rightarrow \text{negligible}$$

$$\frac{(s + 0.8)}{(s + 0.7933)} \rightarrow \text{cancel out but not fully}$$

$$G_m(s) = \frac{100}{s^2 + 1.234s + 7.086}$$

$$G_{cl}(s) = K_{DC} \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$\omega_n = \sqrt{7.086} = 2.66$$

$$2\zeta\omega_n = 1.234$$

$$\zeta = \frac{1.234}{2 \times 2.66} = 0.23$$

$$PO \approx 47\% \text{ (estimation based on the graph)}$$

$$PO = 100 \cdot e^{\frac{-\zeta\pi}{\sqrt{1-\zeta^2}}}$$

$$= 100 \cdot e^{\frac{-0.72}{0.973}}$$

$$PO = 47.72\% \text{ (using the formula)}$$

$$e_{ss(\text{step}\%)} = 1 - K_{DC(\text{closed})}$$

$$K_{DC(\text{closed (uncompensated)})} = G_{cl}(0) = \frac{100 \times 0.8}{(15.47)(0.7933)(7.086)}$$

$$K_{DC(\text{closed (uncompensated)})} = 0.9141$$

$$e_{ss(\text{step}\%)} = (1 - K_{DC(\text{closed (uncompensated)})}) \times 100 = 8.58\%$$

$$T_{rise(0-100\%)} = \frac{\pi - \cos^{-1}\zeta}{\omega_n \sqrt{1-\zeta^2}}$$

$$T_{rise(0-100\%)} = 0.69s$$

$$T_{settling} = \frac{4}{\zeta\omega_n}$$

$$T_{\text{settle}(\pm 2\%)} = \frac{4\tau}{\zeta \omega_n}$$

$$T_{\text{settle}(\pm 2\%)} = 6.53$$

- 3) (2 marks) Generate the **uncompensated** open loop Frequency Response plot for  $G(s)$ . Read off the values of the Phase Margin,  $\Phi_m$ , and the Crossover Frequency,  $\omega_{cp}$  are, and place your answers in the Table. Use Matlab function "margin" to verify if your read-outs were accurate. Include this plot in your report.

$$G_m(\text{dB}) = n, \quad G_m(\text{v/v}) = 10^{\left(\frac{n}{20}\right)} = K_{\text{crit}}$$

$$G(s) = \frac{100(s+0.8)}{(s+0.5)(s+1)^2(s+15)}$$

$$G_{\text{open}}(s) = \frac{100 \times 0.8 (1.25s+1)}{(0.5) \times (1) (15) (2s+1) (s+1)^2 (0.066s+1)}$$

$$G_{\text{open}}(s) = \frac{10.67 \times (1.25s+1)}{(2s+1) (s+1)^2 (0.066s+1)}$$

$$G_m = 4.27 \text{ v/v}$$

$$P_m = 29.36$$

$$\omega_{cg} = 5.11$$

$$\omega_{cp} = 2.4$$

