RESURGENCE OF THE AIRY FUNCTION AND OTHER EXPONENTIAL INTEGRALS

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1. Hypergeometric functions as Borel transform of second order ODE (series normales de Ier ordre)

Let us consider the following linear second order ODE

$$(1.1) \qquad \qquad \left[P(\frac{\partial}{\partial z}) + \frac{1}{z} Q(\frac{\partial}{\partial z}) + \frac{1}{z} R(\frac{1}{z}) \right] f(z) = 0$$

with $\deg P=2$, $\deg Q=1$ and $R=O(\frac{1}{z})$. We denote by α_1,α_2 the roots of $P(-\lambda)$ and we assume they are distinct. Furthermore we assume $\tau_j:=\frac{Q(\alpha_j)}{P'(\alpha_j)}\neq 0$. The latter assumption guarantees the formal solution \tilde{f} being slight, while the former assumption implies there will be two independent solutions.

Under the previous assumptions we prove that the Borel transformed solution $\hat{f}(\zeta_j)$ is a Gauss hypergeometric function, $\zeta_j = \zeta - \alpha_j$.

Proposition 1.1. Let $P(\lambda) = \lambda^2 + a_1\lambda + a_0$, $Q(\lambda) = b_1\lambda + b_0$ and $R(\frac{1}{z}) = \frac{c_1}{z}$ satisfying the previous assumptions. Then

(1.2)
$$\hat{f}(\zeta_1) = \left(1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)^{c-1} {}_2F_1\left(a, b; c; 1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)$$

(1.3)
$$\hat{f}(\zeta_2) = \left(1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)^{c-1} {}_2F_1\left(a, b; c; 1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)$$

where the coefficients a, b, c depend on the parameter of P, Q, R.

Proof. We start by taking the Borel transform of (1.1):

(1.4)

$$(\zeta^{2} - a_{1}\zeta + a_{0})\hat{f}(\zeta) + \int_{0}^{\zeta} b_{1}(-\zeta')\hat{f}(\zeta')d\zeta' + b_{0}\int_{0}^{\zeta} \hat{f}(\zeta')d\zeta' + c_{1}\int_{0}^{\zeta} (\zeta - \zeta')\hat{f}(\zeta')d\zeta' = 0$$

then we differentiate twice in order to have a differential equation which can be easier recognized as a hypergeometric equation. Since \tilde{F} is slight and locally integrable at 0 by assumption, Proposition 1 Resurgent Airy doc by Aaron tells we are not loosing information taking derivatives, and that $\hat{f}(\zeta)$ is a solution of (1.4) if and only

if it is a solution of (1.5)

$$(1.5) \qquad \left[(\zeta^2 - a_1 \zeta + a_0) \partial_{\zeta}^2 + (4\zeta - b_1 \zeta - 2a_1 + b_0) \partial_{\zeta} + (c_1 + 2 - b_1) \right] \hat{f}(\zeta) = 0$$

We introduce some notation to simplify the computations, we denote by $\beta_1 = 4 - b_1$, $\beta_0 = b_0 - 2a_1$, $\gamma = c_1 + 2 - b_1$ so (1.5) turns into

$$\left[(\zeta - \alpha_1)(\zeta - \alpha_2) \partial_{\zeta}^2 + (\beta_1 \zeta + \beta_0) \partial_{\zeta} + \gamma \right] \hat{f}(\zeta) = 0$$

We consider the following change of coordinates $\zeta = \alpha_2 - (\alpha_2 - \alpha_1)\xi^1$

$$\begin{split} & \big[(\alpha_2 - (\alpha_2 - \alpha_1)\xi - \alpha_1)(\alpha_2 - (\alpha_2 - \alpha_1)\xi - \alpha_2)(\alpha_1 - \alpha_2)^{-2} \partial_\xi^2 + (\beta_1(\alpha_2 - (\alpha_2 - \alpha_1)\xi) + \beta_0)(\alpha_1 - \alpha_2)^{-1} \partial_\xi + \gamma \big] \hat{f}(\xi) = 0 \\ & \big[(\alpha_2 - \alpha_1)(1 - \xi)(\alpha_1 - \alpha_2)\xi(\alpha_1 - \alpha_2)^{-2} \partial_\xi^2 + (\beta_1\alpha_2 - \beta_1(\alpha_2 - \alpha_1)\xi + \beta_0)(\alpha_1 - \alpha_2)^{-1} \partial_\xi + \gamma \big] \hat{f}(\xi) = 0 \\ & \big[-(1 - \xi)\xi \partial_\xi^2 + ((\beta_1\alpha_2 + \beta_0)(\alpha_1 - \alpha_2)^{-1} + \beta_1\xi)\partial_\xi + \gamma \big] \hat{f}(\xi) = 0 \\ & \big[(1 - \xi)\xi \partial_\xi^2 - ((\beta_1\alpha_2 + \beta_0)(\alpha_1 - \alpha_2)^{-1} + \beta_1\xi)\partial_\xi - \gamma \big] \hat{f}(\xi) = 0 \end{split}$$

The latter equation is an hypergeometric equation of parameters

$$C = (\beta_1 \alpha_2 + \beta_0)(\alpha_2 - \alpha_1)^{-1}$$

$$A + B + 1 = \beta_1 = 4 - b_1 \Rightarrow A + B = 3 - b_1$$

$$AB = \gamma = c_1 + 2 - b_1$$

and a solution is given by

$$\begin{split} \hat{f}(\xi) &= \xi^{1-C}{}_2F_1(A-C+1,B-C+1;2-C;\xi) \\ &= \left(\frac{\alpha_2 - \zeta}{\alpha_2 - \alpha_1}\right)^{1-C}{}_2F_1\bigg(A-C+1,B-C+1;2-C;\frac{\alpha_2 - \zeta}{\alpha_2 - \alpha_1}\bigg) \\ &= \left(1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)^{1-C}{}_2F_1\bigg(A-C+1,B-C+1;2-C;1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\bigg) \end{split}$$

Proposition 1.2. We verify that

(1.6)
$$\hat{f}(\zeta_1) = \left(1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)^{1 - C} {}_2F_1\left(A - C + 1, B - C + 1; 2 - C; 1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)$$

$$(1.7) \qquad \hat{f}(\zeta_2) = \left(1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)^{1 - C} {}_2F_1\left(A - C + 1, B - C + 1; 2 - C; 1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)$$

are indeed resurgent.

$$\overline{{}^1\partial_\zeta = (\alpha_1 - \alpha_2)^{-1}\partial_\xi \text{ and } \partial_\zeta^2 = (\alpha_1 - \alpha_2)^{-2}\partial_\xi^2}$$

Proof. Recall that the analytic continuation of Gauss hypergeometric functions is given in terms of other hypergeometric functions (see DLMF 15.2.3):

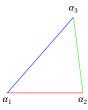
$$\begin{split} \hat{f}(\zeta_{1}+i0) - \hat{f}(\zeta_{1}-i0) &\propto \left(\frac{\zeta_{1}}{\alpha_{1}-\alpha_{2}}\right)^{C-A-B} \left(1 - \frac{\zeta_{1}}{\alpha_{2}-\alpha_{1}}\right)^{1-C} {}_{2}F_{1}\left(1 - A, 1 - B; C + 1 - A - B; \frac{\zeta_{1}}{\alpha_{2}-\alpha_{1}}\right) \\ &= (-1)^{C-A-B} \left(1 - \frac{\zeta_{2}}{\alpha_{1}-\alpha_{2}}\right)^{C-A-B} \left(\frac{\zeta_{2}}{\alpha_{1}-\alpha_{2}}\right)^{1-C} \cdot \\ &\cdot {}_{2}F_{1}\left(1 - A, 1 - B; C + 1 - A - B; 1 - \frac{\zeta_{2}}{\alpha_{1}-\alpha_{2}}\right) \end{split}$$

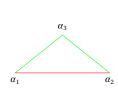
2. Hypergeometric functions as Borel transform of third order ODE Let us consider the following linear third order ODE

(2.1)
$$\left[P\left(\frac{\partial}{\partial z}\right) + \frac{1}{z}Q\left(\frac{\partial}{\partial z}\right) + \frac{1}{z}R\left(\frac{1}{z}\right) \right] f(z) = 0$$

with deg P=3, deg Q=2 and $R=O(\frac{1}{z})$. We denote by $\alpha_1,\alpha_2,\alpha_3$ the roots of $P(-\lambda)$ and we assume they are distinct. There are three possible scenarios illustrated in figure **??** below:

- $|\alpha_1 \alpha_2| < |\alpha_2 \alpha_3| < |\alpha_1 \alpha_3|$
- $|\alpha_2 \alpha_3| = |\alpha_1 \alpha_3| < |\alpha_1 \alpha_2|$
- $|\alpha_1 \alpha_2| = |\alpha_2 \alpha_3| = |\alpha_1 \alpha_3|$







Furthermore we assume $\tau_j := \frac{Q(\alpha_j)}{P'(\alpha_j)} \in \mathbb{Q}$. The latter assumption guarantees the formal solution \tilde{f} being slight, while the former assumption implies there will be three independent solutions.

Under the previous assumptions we prove that the Borel transformed solution $\hat{f}(\zeta_j)$ is hypergeometric, $\zeta_j = \zeta - \alpha_j$.

Proposition 2.1. Let $P(\lambda) = \lambda^3 + a_2\lambda^2 + a_1\lambda + a_0$, $Q(\lambda) = b_2\lambda^2 + b_1\lambda + b_0$ and $R(\frac{1}{z}) = \frac{c_1}{z} + \frac{c_2}{z^2}$ satisfying the previous assumptions. Then

• if
$$|\alpha_1 - \alpha_2| < |\alpha_2 - \alpha_3| < |\alpha_1 - \alpha_3|$$

(2.2)
$$\hat{f}(\zeta_1) = \left(1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)^{c-1} {}_2F_1\left(\mathbf{m}; \mathbf{n}; 1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)$$

(2.3)
$$\hat{f}(\zeta_2) = \left(1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)^{c-1} {}_2F_1\left(\mathbf{m}; \mathbf{n}; 1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)$$

(2.4)
$$\hat{f}(\zeta_3) = \left(1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)^{c-1} {}_2F_1\left(\mathbf{m}; \mathbf{n}; 1 - \frac{\zeta_3}{\alpha_2 - \alpha_1}\right)$$

• if
$$|\alpha_1 - \alpha_2| < |\alpha_2 - \alpha_3| = |\alpha_1 - \alpha_3|$$

(2.5)
$$\hat{f}(\zeta_1) = \left(1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)^{c-1} {}_2F_1\left(\mathbf{m}; \mathbf{n}; 1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)$$

(2.6)
$$\hat{f}(\zeta_2) = \left(1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)^{c-1} {}_2F_1\left(\mathbf{m}; \mathbf{n}; 1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)$$

$$(2.7) \hat{f}(\zeta_3) = ?$$

• if
$$|\alpha_1 - \alpha_2| = |\alpha_2 - \alpha_3| = |\alpha_1 - \alpha_3|$$

(2.8)
$$\hat{f}(\zeta_1) = \left(1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)^{c-1} {}_{3}F_{2}\left(\mathbf{m}; \mathbf{n}; 1 - \frac{\zeta_1}{\alpha_2 - \alpha_1}\right)$$

(2.9)
$$\hat{f}(\zeta_2) = \left(1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)^{c-1} {}_{3}F_2\left(\mathbf{m}; \mathbf{n}; 1 - \frac{\zeta_2}{\alpha_1 - \alpha_2}\right)$$

(2.10)
$$\hat{f}(\zeta_3) = \left(1 - \frac{\zeta_3}{\alpha_2 - \alpha_1}\right)^{c-1} {}_3F_2\left(\mathbf{m}; \mathbf{n}; 1 - \frac{\zeta_3}{\alpha_2 - \alpha_1}\right)$$

where the coefficients $\mathbf{m} = (m_1, m_2, m_3)$, $\mathbf{n} = (n_1, n_2)$ depend on the parameter of P, Q, R.

Proof. The strategy is analogous to the one for second order ODEs. Hence, we first consider the Borel transform of equation 2.1:

$$P(-\zeta)\hat{f} + \int_0^{\zeta} Q(-\zeta')\hat{f}(\zeta')d\zeta' + c_1 \int_0^{\zeta} (\zeta - \zeta')\hat{f}(\zeta')d\zeta' + \frac{c_2}{2} \int_0^{\zeta} (\zeta - \zeta')^2 \hat{f}(\zeta')d\zeta' = 0$$

Although equation (2.11) is an integral equation, since \tilde{f} is slight, \hat{f} is a solution of (2.11) if and only if it is a solution of the third order ODE obtained by differentiating (2.11) three times:

$$\big[P(-\zeta) \partial_{\zeta}^{3} + (-3P'(-\zeta) + Q(-\zeta)) \partial_{\zeta}^{2} + (3P''(-\zeta) - 2Q'(-\zeta) + c_{1}) \partial_{\zeta} + (-P'''(-\zeta) + Q''(-\zeta) + c_{2}) \big] \hat{f} = 0$$

Notice that

$$P(-\zeta) = (\zeta - \alpha_1)(\zeta - \alpha_2)(\zeta - \alpha_3)$$

$$-P'(-\zeta) = (\zeta - \alpha_2)(\zeta - \alpha_3) + (\zeta - \alpha_1)(\zeta - \alpha_3) + (\zeta - \alpha_2)(\zeta - \alpha_1)$$

$$P''(-\zeta) = 6\zeta - 2\alpha_1 - 2\alpha_2 - 2\alpha_3$$

We now study separately the three scenarios:

- if $\ell = |\alpha_1 \alpha_2| < |\alpha_2 \alpha_3| < |\alpha_1 \alpha_3|$ we claim that (2.12) is ??
- if $\alpha_2 = \alpha_3 + \ell$, $\alpha_1 = \alpha_3 \ell$ we claim that (2.12) is a ?? Change coordinates $y = \frac{\zeta \alpha_1}{\ell}$:

$$P(-\zeta)\partial_{\zeta}^{3} \longrightarrow -\ell^{3}y(\ell y + \alpha_{1} - \alpha_{2})(\ell y + \alpha_{1} - \alpha_{3})\frac{1}{\ell^{3}}\partial_{y}^{3} = y(1 - y^{2})\partial_{y}^{3}$$

$$(-3P'(-\zeta) + Q(-\zeta))\partial_{\zeta}^{2} \longrightarrow (3\ell^{2}(3y^{2} - 1) + Q(-\ell y - \alpha_{1}))\frac{1}{\ell^{2}}\partial_{y}^{2}$$

$$(3P''(-\zeta) - 2Q'(-\zeta) + c_{1})\partial_{\zeta} \longrightarrow (-18\ell y - 2Q'(-\ell y - \alpha_{1}) + c_{1})\frac{1}{\ell}\partial_{y}$$

$$-P'''(-\zeta) + Q''(-\zeta) + c_{2} \longrightarrow -6 + 2b_{2} + c_{2}$$

Change coordinates $s = y^2$:

$$\begin{split} y(1-y^2)\partial_y^3 &\longrightarrow 8(1-s)s^2\partial_s^3 + 12(1-s)s\partial_s^2 \\ (3\ell^2(3y^2-1) + Q(-\ell y - \alpha_1))\frac{1}{\ell^2}\partial_y^2 &\longrightarrow \left[6(3s-1) + 2(b_2s + \frac{2b_2\alpha_1 - b_1}{\ell}y + \frac{b_2\alpha_1^2 - \alpha_1b_1 + b_0}{\ell^2})\right](\partial_s + 2s\partial_s^2) \\ (-18\ell y - 2Q'(-\ell y - \alpha_1) + c_1)\frac{1}{\ell}\partial_y &\longrightarrow 4(2b_2 - 9)s\partial_s + 2\frac{4b_2\alpha_1 - 2b_1 + c_1}{\ell}y\partial_s \end{split}$$

$$(2.13) \quad \left[8(1-s)s^2 \partial_s^3 + \left[4(6+b_2)s + 4\frac{2b_2\alpha_1 - b_1}{\ell}y + 4\frac{b_2\alpha_1^2 - \alpha_1b_1 + b_0}{\ell^2} \right] s \, \partial_s^2 \right] \\ \left[-2(9-2b_2)s - 2(3-2b_2) + 2\frac{b_2\alpha_1^2 - \alpha_1b_1 + b_0}{\ell^2} + 2\frac{6b_2\alpha_1 - 3b_1 + c_1}{\ell}y \, \right] \partial_s - 6 + 2b_2 + c_2 \, \hat{f} = 0$$

$$\frac{2b_2\alpha_1 - b_1}{\ell}y + \frac{b_2\alpha_1^2 - \alpha_1b_1 + b_0}{\ell^2} = 2n_1 + 2n_2 - 2$$

$$6 + b_2 = -2(3 + m_1 + m_2 + m_3)$$

$$\left[-(3 - 2b_2) + 2(\frac{b_2\alpha_1^2 - \alpha_1b_1 + b_0}{\ell^2}) + \frac{8b_2\alpha_1 - 4b_1 + c_1}{\ell}y \right] = 4n_1n_2$$

$$(9 - 2b_2) = 4(1 + m_1 + m_2 + m_3 + m_1m_2 + m_1m_3 + m_2m_3)$$

$$-6 + 2b_2 + c_2 = 8m_1m_2m_3$$

• if $|\alpha_1-\alpha_2|=|\alpha_2-\alpha_3|=|\alpha_1-\alpha_3|=\ell$ we claim that (2.12) is a generalized hypergeometric equation. Without loss of generality we assume $\alpha_2=\alpha_1+\ell$ and $\alpha_3=\alpha_1+\frac{\ell}{2}+i\frac{\sqrt{3}}{2}\ell$.

Change coordinates $y = \frac{\zeta - \alpha_1}{\ell} + \frac{\sqrt{3} + i}{2}$, then

$$P(-\zeta)\partial_{\zeta}^{3} \longrightarrow -\ell y(\ell y + \alpha_{1} - \alpha_{2})(\ell y + \alpha_{1} - \alpha_{3})\frac{1}{\ell^{3}}\partial_{y}^{3} = y(1 - y^{2})\partial_{y}^{3}$$

$$(-3P'(-\zeta) + Q(-\zeta))\partial_{\zeta}^{2} \longrightarrow (3\ell^{2}(3y^{2} - 1) + Q(-\ell y - \alpha_{1}))\frac{1}{\ell^{2}}\partial_{y}^{2}$$

$$(3P''(-\zeta) - 2Q'(-\zeta) + c_{1})\partial_{\zeta} \longrightarrow (-18\ell y - 2Q'(-\ell y - \alpha_{1}) + c_{1})\frac{1}{\ell}\partial_{y}$$

$$-P'''(-\zeta) + Q''(-\zeta) + c_{2} \longrightarrow -6 + 2b_{2} + c_{2}$$