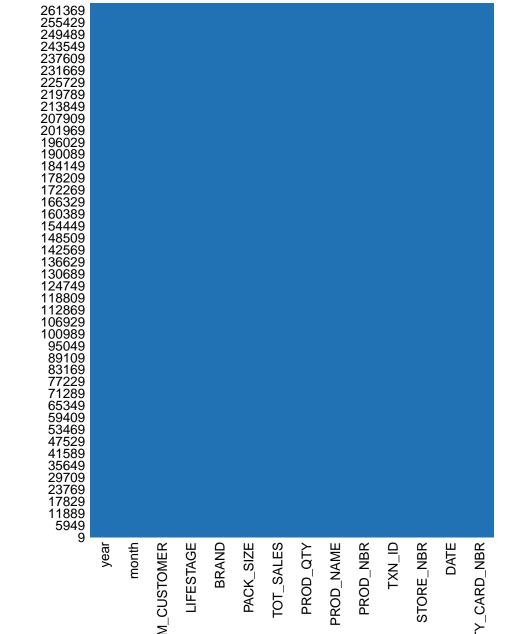
Missingness Map



Missing (0%)
Observed (100%)

