LINIT Y: SYNCHRONIZATION AND CONCURRENCY CONTROL LONCURRENCY: Principle: It refers to the simultaneous execution of multiple process or threads to improve system efficiency, resource utilization, and responsiveness. It is essential for multitasking operating system and distributive system. Issues with Concurrency: 1. Race condition: Occurs when multiple process / threads access shared resource and the result depend on execution order, potentially leading to inwansistent states. 2. Deadlock: A situation where two or more process are stuck waiting for resources held by each other preventing further 3. Starvation: A process is perpetually denied access to critical resources due to resource allocation policy or priority scheduling. 4. Live lock: (similar to deadlock) The process keeps changing states (eg. retrying operations) without progress. 5. Resource Contention: Multiple process competing for limited resource, leading to delays or bottlenecks. 10) MUTUAL EXCLUSION: It ensures that only one process/thread can access a shared resource or critical section at a time preventing conflicts and maintaining data consistency. 2) Approach to achieve Mutual Exclusion: 1. HARDWARE APPROACH. · Disable Interrupts: Prevents context switching during critical section execution by disabling CPU interrupts. This approach is simple but not suitable for long critical sections or multi core systems. · Test and set lock: A hardware instruction that atomically tests and Modifies a memory location to implement locks It prevents race condition but can cause busy waiting · Compare and swap: Updates and modifies a memory location only if its urrent value matches an expected value, enabling atomic operation and avoiding

inconsistent states.

SCIFTWARE APPROACH

- · Peterson's Algorithm: A classic solution for two process mutual exclusion using shared flags and turn variables.
- · Dekker's Algorithm: Another early algorithm for achieving mutual exclusion for two processes
- · Bakery Algorithm: Designed for multiple processes; it uses ticket number to decide which process enters the critical section next.

SYNCHRUNIZATION TOOLS

1. Semaphore: A synchronization primitive used to control access to shared resourcemolding namper of noopbord

Types:

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- · Binary: Can take values 0 or 1 similar to a lock.
- · Counting: Maintains a count of available resources.

Operations:

- · wait () : Decreases semaphore value; block if zero
- · signal(): Increases semaphore value; unblocks waiting.
- 2. Mutex: A mutual exclusion box lock that ensures A only one thread can access the critical section. Unlike semaphore, a mutex is owned by a thread that locks it and must be explicitly released.
 - · use: provides exclusive access to resource in multithread application.
- 3. Monitor: A high level synchronization construct that encapsulate all safely share me allows process to safely share resources. Monitors encapsulate shared data, procedures and synchronization
 - Automatically ensures mutual exclusion by allowing only one process to execute a monitor procedure at a time.

Classical Syncronization/ concurrency Problems A multiplia accorded.

1. Reader Writer problem:

rules: Only one writer may write at attime

- · When writer is writing no read operations
- · when reader is reading no write operations
- · Multiple readers may read at a time.

challenge: Avoid starvation of readers & writers

Solution: Use semaphore to implement reader or writer priority.

2. Producer Consumer problem:

Aproducer produces. A consumer consumers

· When a producer produces more than capacity of consumer (buffer overflow)

· When a consumer doesn't have any resource to consum (buffer underflow)

Challenge: prevent buffer overflow / underflow.

Solution: use semaphore and mutex to synchronize producer and consumer.

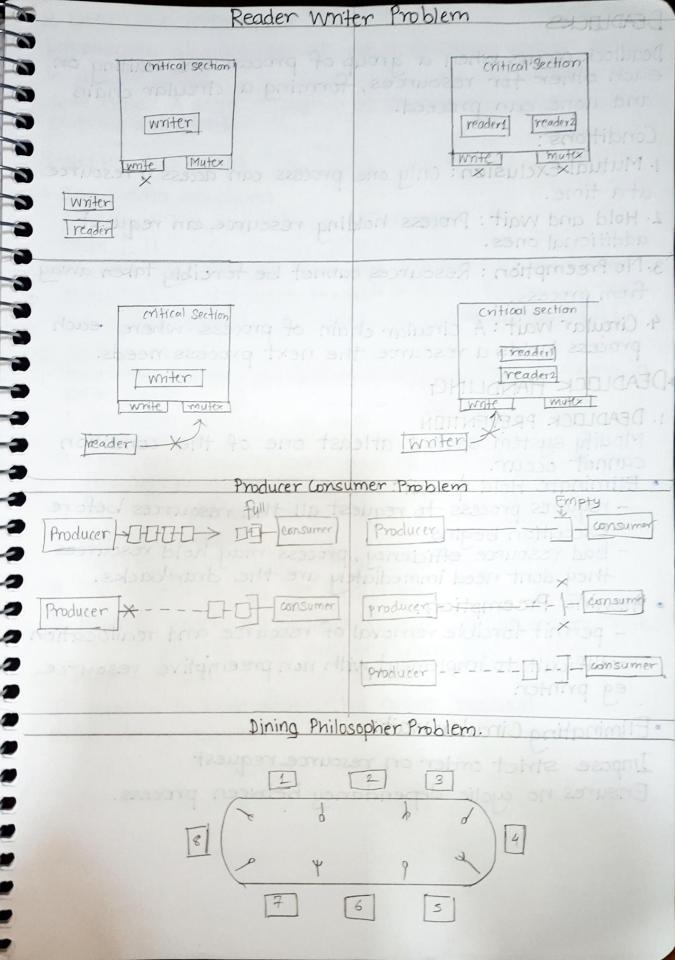
eg. halt production when overflow halt consumption when underflow.

3. Dining Philosophen problem:

Philosophers sitting around a table alternate between thinking and eating requiring shared fork (resources) to eat.

Challenge: prevent deadlock or starvation.

Solution: Implement sta strategies like resource hierarchy, limit the number of philosophers or implement waiter process for resource allocation.



DEADLICKS

Deadlock occurs when a group of process are waiting on each other for resources, forming a circular chain and none can proceed.

Reader uniter Problem

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Conditions:

- 1. Mutual Exclusion: only one process can access a resource at a time.
- 2. Hold and wait: Process holding resource can request additional ones.
- 3. No Preemption: Resources cannot be forcibly taken away from process.
- 4. Circular wait: A circular chain of process where each process holds a resource the next process needs.

DEADLOCK HANDLING

- 1. DEADLUCK PREVENTION
 Modify system so that atleast one of the condition cannot occur.
- · Eliminate Hold & wait: remuzina resultary
 - requires process to request all the resources before execution begins
 - bad resource efficiency, process may hold resources they don't need immediately are the drawbacks.
- · Allowing Preemption:
 - permit forcible removal of resource and reallocation -difficult to implement with non preemptive resource eq printer.
- · Eliminating Circular wait: grading prints
- Impose strict order on resource request Ensures no cyclic dependancy between process.

2. DEAD LOCK AVOIDANCE Dynamically allocate resoure while ensuring system is in a safe state safe state: A state in which all process are running without entering a deadlock. -Represents process and resour BANKERS ALGURITHM: · Wait for Graphs (WFG) 1. Input data structures: Available []: units of available resource Max [][]: Max demand of each process for resource type Allocation [][]: Resource currently allocated for each process.

Need [][]: Remaining resource & needs for each process. Calculation: Need [i][j] = Max [i][j] - Allocation [i][j] 2. Safety Check:
simulate granting request to ensure system remains in 2. Safety Check: 1. Initialize Work [] as Available [] Horim 2. Mark all process with finish = false 3. Find a process Pi such that need[i] <= work & finish[i] = false. 4. If such process is found then allocate resources to lection Criteria for termination: so [] xrow work[j] = Work[j] + Allocation[i][j] . Mark process Pi as finished = true 5. Repeat untill all process marked finish = true (safe) or no process can proceed (unsafe) 3. Grant request: If system in safe state the grant re else deny request. are preemption may not always be termination risks losing critical data or tunctionality:

3. DEADLOCK DETECTION. 2. DEADLICK AVOIDANCE Allow deadlock to occur but detect and resolve when they happen. · Resource Allocation Graphs (RAG - Represents process and resources as nodes. - A deadlock exists if graph . has a cycle. · Wait for Graphs (WFG) - Simplified version of RAG used for system with multiple resources. - A cycle indicates deadlock. · Periodic deadlock checks: - perform deadlock detection at regular intervals or when resource request is denied. 4. DEADLOCK RECOVERY -After detecting a deadlock, recover the system by breaking the cycle and freeing resources. · Process termination: -- Abort all deadlocked Process: Simplifies recovery but can result in significant data loss or incomplete task. - Abort one process at a time: incrementally terminate process until the deadlock is resolved. - Selection Criteria for termination: · Priority of the process · Execution time (cshortest to longest) · Resources used or required · Impact on other processes. · Resources Preemption. - temporarily remove resources from a process and reallocate to other processes to break the cycle. - Requires mechanism to roll back the states of preempted processes All I · Challenges - Resource preemption may not always be teasible - Process termination risks losing critical data or functionality.