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EB16A HW3

IA $\begin{bmatrix} 1 & 1 \\ 2 & 0 \end{bmatrix}$ $\det = (1 \cdot 0) - (2 \cdot 1)$
 $= -2 \neq 0$ invertible

IB $\begin{bmatrix} 3 & 2 \\ 1 & -1 \end{bmatrix}$ $\det = (3 \cdot -1) - (2 \cdot 1)$
 $= -3 - 2 = -5 \neq 0$ invertible

IC $\begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix}$ $\det = \left(\frac{1}{2}\right)^2 - \left(\frac{\sqrt{3}}{2}\right)^2$
 $\frac{1}{4} - \frac{3}{4} = -\frac{1}{2} \neq 0$ invertible

ID $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ $\det = 4 \neq 0$ invertible.

IE $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix}$ $\det = (1+0+0) - (0+1+0) = 1-1=0$
not invertible

IF $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 2 \\ 1 & 4 & 4 \end{bmatrix}$ $\det = (8+0+0) - (0+8+0) = 8-8=0$
not invertible

IG $\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & 1 & -1 \end{bmatrix}$ $\det = 1 \det \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} + 0 + 0$
 $\det \begin{vmatrix} -1 & 1 \\ 1 & -1 \end{vmatrix} = (-1) - 1 = 0$ $1 \cdot 0 = 0 \neq 0$
not invertible

IH $\begin{bmatrix} -1 & 1 & -\frac{1}{2} \\ 1 & 1 & -\frac{1}{2} \\ 0 & 1 & 1 \end{bmatrix}$ $\det = (-1+0+\frac{-1}{2}) - (0+\frac{1}{2}+1) = -2 \neq 0$
invertible

$$1 \begin{vmatrix} 1 & 3 & 0 & -2 & 1 \\ -1 & 0 & 2 & 1 & 3 \\ 1 & 3 & 1 & 0 & 4 \\ -1 & 1 & 0 & 0 & 1 \end{vmatrix} \text{ det} = -1 \begin{vmatrix} 0 & -2 & 1 \\ 2 & 1 & 3 \\ 1 & 0 & 4 \end{vmatrix} + \begin{vmatrix} 3 & 0 & -2 \\ 0 & 2 & 1 \\ 3 & 1 & 0 \end{vmatrix}$$

$$(-1) \begin{vmatrix} 0 & -2 & 1 \\ 2 & 1 & 3 \\ 1 & 0 & 4 \end{vmatrix} = (0 - 6 + 0) - (1 + 0 - 16) = -(-6 - (-15)) = -9$$

$$(1) \begin{vmatrix} 3 & 0 & -2 \\ 0 & 2 & 1 \\ 3 & 1 & 0 \end{vmatrix}^2 = \frac{(0 + 0 + 0)}{(-12 + 3 + 0)} = 9$$

$$\det = -9 + 9 = 0 \text{ not invertible}$$

$$2A \quad \begin{matrix} 1 & 1 \\ 0 & 0 \end{matrix}^2 = \text{corresponding transition matrix}$$

$$\vec{x}[n+1] = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \vec{x}[n]$$

$$2B \quad x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix} \quad \vec{x}[1] = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Unreduced

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0.3 \\ 0.7 \end{bmatrix} \quad \vec{x}[1] = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0.3 \\ 0.7 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Alt. Unreduced

2C Using the data from timestep 1, we are unable to determine the water levels at timestep 0 because there are many previous timestep or initial states that when multiplied together with the corresponding transition matrix.

For Example in case 1:

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

alt
 $x = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 0.3 \\ 0.7 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0.3 \\ 0.7 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

As these two answers with different starting points show, it is impossible to determine the previous timestep, as this information is not preserved.

2D $A \cdot \vec{x}_1 = \vec{x}_2$ in order to determine previous timestep \vec{x}_1 , A must be invertible.

$$\text{In } A \cdot A^{-1} \cdot \vec{x}_1 = \vec{x}_2 \quad A^{-1}$$

$$\vec{x}_1 = \vec{x}_2 \cdot A^{-1}$$

Since $\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$ is not invertible, we are unable to recover the information in the previous matrix

Matrix A must be invertible for this to be true.

2E This statement implies that A is invertible, and by definition of invertibility, A is linearly independent, one to one, and onto.

$$A \cdot \vec{x}_1 = \vec{x}_2$$

in order to get \vec{x}_1 (previous know)

$$A^{-1} \cdot A \cdot \vec{x}_1 = \vec{x}_2 \cdot A^{-1}$$

A must be invertible

$$I \cdot \vec{x}_1 = \vec{x}_2 \cdot A^{-1}$$

2F If the entries of each column vector sum to one, the total water in the system is constant. No water is added or removed from this system

2G $\begin{bmatrix} 0 & 0 & 0 \\ 0.4 & 0.5 & 0.2 \\ 0 & 0.6 & 0.35 \end{bmatrix}$ The A matrix physically implies that there is an external source of water so the total amount of water in the system is changing and is NOT constant. We know this because the rows and columns do not add up to 1.

$$2H \quad \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \quad (a_{11} \dots a_{1n}) = 1$$

$$\begin{bmatrix} x_1 & \dots & x_{1n} \end{bmatrix} = x \begin{bmatrix} a_{11} & \dots & a_{1n} \end{bmatrix} = x$$

Because the sum of the rows is one, multiplying by a unit vector essentially becomes the uniform vector, regardless of how many columns / rows the two matrices have, as long as they are multiplicable.

3A The state transition matrix A is like as follows:

$$\begin{bmatrix} a & f & d \\ b & e & d \\ c & e & f \end{bmatrix} = A \quad \begin{array}{l} a + f + d = 1 \\ b + e + d = 1 \\ c + e + f = 1 \\ 0 < a, b, c, d, e, f < 1 \end{array}$$

$\vec{s}[n+1] = A \vec{s}[n]$ ← keeps track of the water distribution among the three reservoirs

3B $\begin{bmatrix} a & f & d \\ b & e & d \\ c & e & f \end{bmatrix}$ where $a + f + d = 1$
 $b + e + d = 1$
 $c + e + f = 1$

Because we know that the reservoir system is conservative, we know that the state transition matrix above rows sum to one which means that applying this system to a uniform vector will return by same uniform vector as proven in prop 2H.

Therefore $\vec{s}[n+1] = \vec{s}[n] = \vec{s}$ for any value of n .

The rows in this matrix add up to one so we know that the total water stays the same and we can use the properties with uniform vectors.

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$$A_2 \begin{bmatrix} \frac{4}{5} & \frac{2}{5} & \frac{3}{5} \\ \frac{2}{5} & \frac{4}{5} & \frac{2}{5} \\ \frac{3}{5} & \frac{2}{5} & \frac{1}{5} \end{bmatrix} = S$$

In order to determine $\vec{s}[n]$ from the subsequent state $\vec{s}[n+1]$, A must be an invertible matrix

$$A \cdot \vec{s}[n] = \vec{s}[n+1]$$

$$A^{-1} A \cdot \vec{s}[n] = A^{-1} \vec{s}[n+1]$$

In $\vec{s}[n] = A^{-1} \vec{s}[n+1]$ so A must be invertible

In order to determine whether it is possible to determine $\vec{s}[n]$ from $\vec{s}[n+1]$

$$\det \begin{pmatrix} \frac{4}{5} & \frac{2}{5} & \frac{3}{5} \\ \frac{2}{5} & \frac{4}{5} & \frac{2}{5} \\ \frac{3}{5} & \frac{2}{5} & \frac{1}{5} \end{pmatrix} = \left(\frac{1}{5^3} + \frac{8}{5^3} + \frac{8}{5^3} \right) - \left(\frac{4}{5^3} + \frac{4}{5^3} + \frac{4}{5^3} \right) = \frac{17}{5^3} - \frac{12}{5^3} = \frac{5}{5^3} = \frac{1}{25} \neq 0 \text{ so } A \text{ is invertible}$$

$$\frac{17}{5^3} - \frac{12}{5^3} = \frac{5}{5^3} = \left[\frac{1}{25} \right] \quad \frac{1}{25} \neq 0 \text{ so } A \text{ is invertible}$$

so it is possible to determine $\vec{s}[n]$ from $\vec{s}[n+1]$

$\vec{x} \begin{bmatrix} p \\ \dot{p} \\ \theta \\ \dot{\theta} \end{bmatrix}$
 ← position
 ← velocity
 ← angle
 ← angular velocity

$\vec{x}[n+1] = A\vec{x}[n] + \vec{b}u[n]$
 ↑ ↑
 $\in \mathbb{R}^4 \times 4$ $\in \mathbb{R}^{4 \times 1}$

4F $\vec{x}[1]$ when $n=0$

$$\vec{x}[1] = A\vec{x}[0] + \vec{b}u[0]$$

4B $\vec{x}[2] = A\vec{x}[1] + \vec{b}u[1]$
 $= A[A\vec{x}[0] + \vec{b}u[0]] + \vec{b}u[1]$
 $= A^2\vec{x}[0] + A\vec{b}u[0] + \vec{b}u[1]$

$\vec{x}[2] = A\vec{x}[2] + \vec{b}u[2]$
 $= A[A^2\vec{x}[0] + A\vec{b}u[0] + \vec{b}u[1]] + \vec{b}u[2]$
 $= A^3\vec{x}[0] + A^2\vec{b}u[0] + A\vec{b}u[1] + \vec{b}u[2]$

$\vec{x}[4] = A\vec{x}[3] + \vec{b}u[3]$
 $= A[A^3\vec{x}[0] + A^2\vec{b}u[0] + A\vec{b}u[1] + \vec{b}u[2]] + \vec{b}u[3]$
 $= A^4\vec{x}[0] + A^3\vec{b}u[0] + A^2\vec{b}u[1] + A\vec{b}u[2] + \vec{b}u[3]$

4C $\vec{x}[n] = A^n\vec{x}[0] + \vec{b} \sum_{i=0}^{n-1} A^{n-i-1} \vec{b}u[i]$

$$A = \begin{bmatrix} 1 & 0.05 & -0.01 & 0 \\ 0 & 0.22 & -0.17 & -0.01 \\ 0 & 0.10 & 1.14 & 0.10 \\ 0 & 1.6 & 1.5 & 1.14 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 0.01 \\ 0.21 \\ -0.03 \\ -0.49 \end{bmatrix}$$

4 (cont)

$$\vec{x}[0] = \begin{bmatrix} -0.3853493 \\ 6.1032227 \\ 0.8120005 \\ -14 \end{bmatrix}$$

$$\vec{x}[f] = A^f \cdot \vec{x}[0] + \sum_{i=0}^{f-1} A^{f-1-i} b u[i]$$

4D Two time steps

$$0 \quad \vec{x}[2] = A^2 \cdot \vec{x}[0] + A b u[0] + b u[1]$$

$$-A^2 \vec{x}[0] = A b u[0] + b u[1]$$

$$Ax = b$$

$$\begin{bmatrix} Ab & b & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} u[0] \\ u[1] \\ u[2] \\ u[3] \end{bmatrix} = \begin{bmatrix} 1 \\ A^2 \vec{x}[0] \\ 1 \\ 1 \end{bmatrix}$$

(python), not possible in 3 time steps

4E Three time steps

$$0 \quad \vec{x}[3] = A^3 \vec{x}[0] + A^2 b u[0] + A b u[1] + b u[2]$$

$$Ax = b, \text{ not poss}$$

$$\begin{bmatrix} A^2 b & Ab & b & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} u[0] \\ u[1] \\ u[2] \\ u[3] \end{bmatrix} = \begin{bmatrix} 1 \\ A^3 \vec{x}[0] \\ 1 \\ 1 \end{bmatrix}$$

4F Four Time step

$$\vec{x}[3] = A^3 \vec{x}[0] + A^2 \vec{b} v[0] + A \vec{b} v[1] + \vec{b} v[2]$$

$$A^3 \vec{x}[0] = \vec{x}[3] - A^2 \vec{b} v[0] + A \vec{b} v[1] + \vec{b} v[2]$$

$$A \vec{x} = b$$

$$\begin{bmatrix} A^3 b & A^2 b & A b & b \\ | & | & | & | \end{bmatrix} \begin{bmatrix} v[0] \\ v[1] \\ v[2] \\ v[3] \end{bmatrix} = A^4 \vec{x}[0]$$

yes 4 step is enough

4G I python

4H A must be invertible and be an $N \times N$ matrix

4I A must be invertible and be an $N \times N$ matrix

5 Check Invertibility

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \det = 4 - 6 = 2 \neq 0, \text{ invertible}$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \det = 0 \neq 0 \text{ invertible}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 5 & 2 & 1 \\ 7 & 8 & 6 \end{bmatrix} \det = (62 + 120 + 48) - (72 + 48 + 120) = 0 \text{ not invertible}$$

6 Worked on our HW also. Finished last Thursday
if I'm being honest. I'm doing bad today,
24 is as long as red at this