

Final Internship Review On ZED 2i AI CAMERA & Jetson Nano

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ZED 2 Camera and SDK Overview

Dr Anuradha Yenkikar

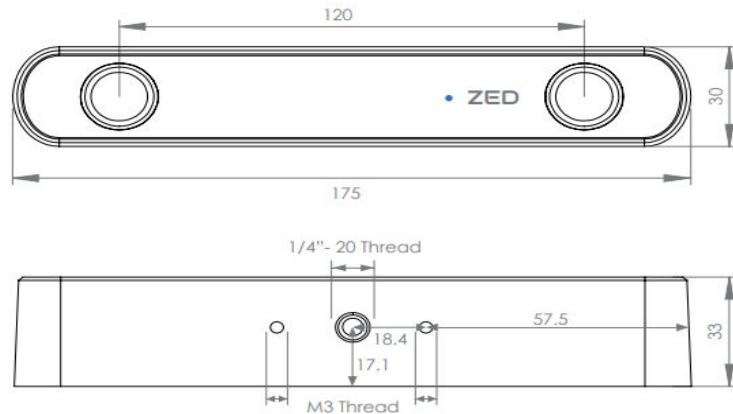
Mr Kaushal Sharma

INTERNSHIP MENOTR'S

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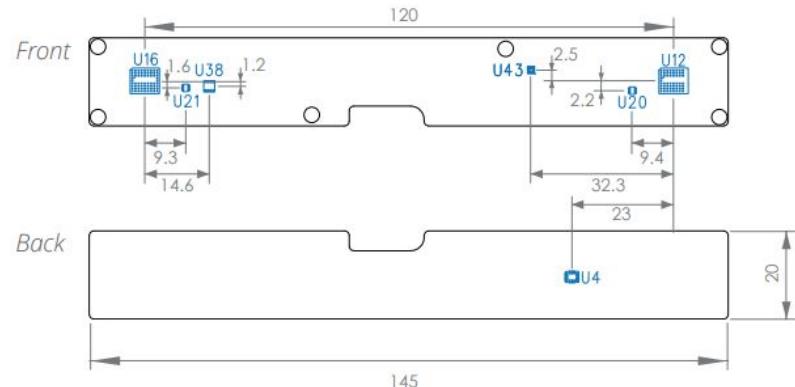
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ARCHITECTURE



- Dimensions: 175 mm × 30 mm × 33 mm
- Weight: 229 grams
- Stereo baseline: 120 mm
- Depth range: to 35 meter with 4 mm lens
- < 1% of depth error
- Sensor resolution: 2 × 4MP (2688 × 1520 each)
- Field of view is up to 120 degrees—2.1mm lens
- Lens option: 2.1mm wide/4mm zoom
- Built-in polarizer filter

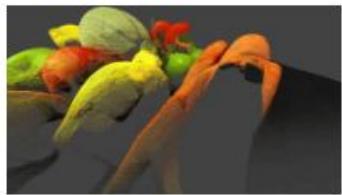
Sensors Diagram



- Environmental rating 1p66
- All-aluminum, sealed enclosure
- Mounting thread: 1/4" 20 UNC + dual m3
- Integrated 9 dof imu
- Additional sensors include temperature sensors & barometers.
- Connectivity through USB Type-C
- Power Consumption: 5V @ 380mA (~1.9W)

ADVANCED TASK IT CAN PERFORM

DEPTH SENSING



OBJECT DETECTION



BODY TRACKING



PLANE DETECTION



POSITIONAL TRACKING



GEO TRACKING



SPATIAL MAPPING



MULTI CAMERA FUSION



DEPTH SENSING

Depth Camera Capabilities

Depth Representation

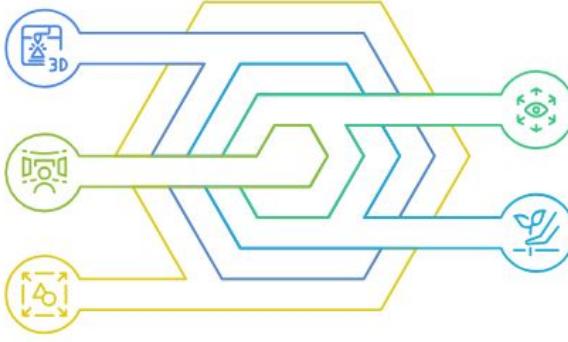
Depth Representation in the form of 3D Point Cloud

Depth Capture

Depth can be captured at longer ranges, up to 35m.

Depth Accuracy

Precision of depth measurements is typically around 1% to 9%

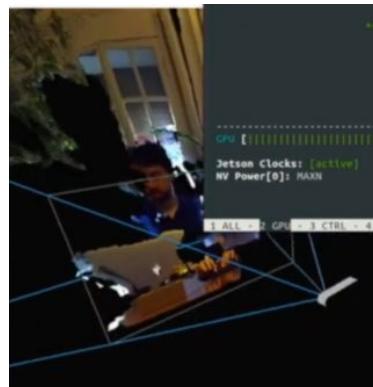
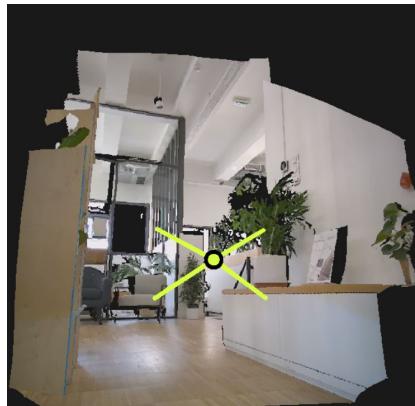
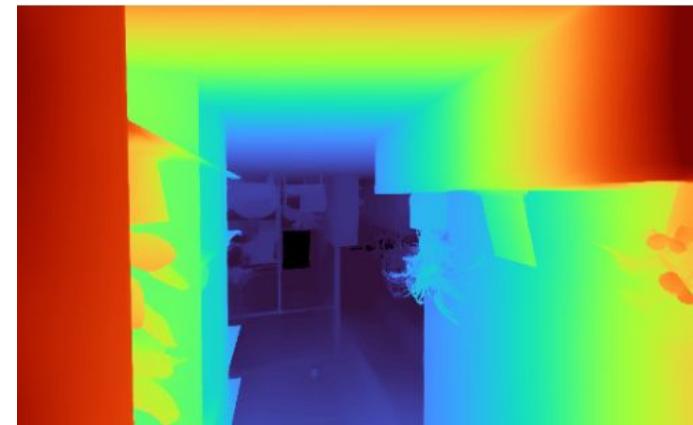


Field of View

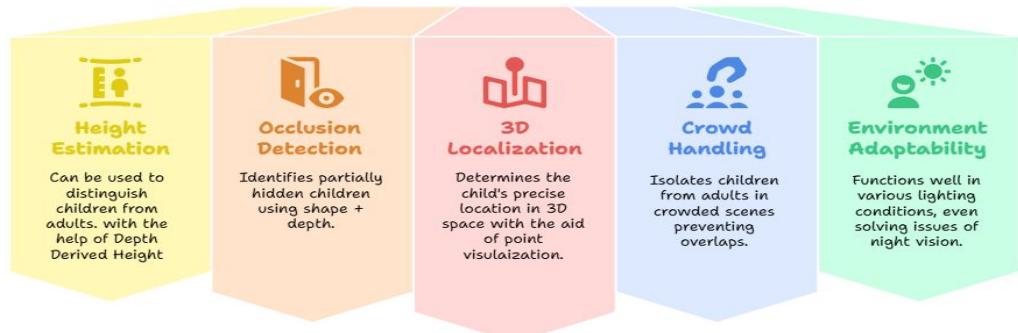
Field of view is much larger, up to 110° (H) x 95° (V).

Environmental Versatility

The camera can work indoors & outdoors



Application of Depth Camera in Child Detection



VIEW

LEFT



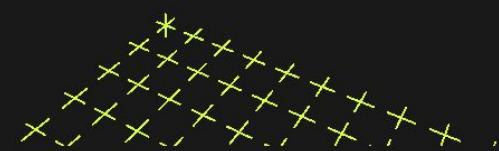
POINT CLOUD

- DEPTH SHADING
- LIDAR VIEW
- IMU ORIENTATION
- CONFIDENCE 95



MEASURE

DEPTH

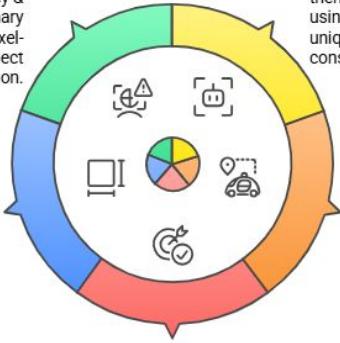


Object Detection

Object Tracking System Features

Confidence Scoring & Segmentation

Assigns a confidence score (0–100) for detection accuracy & Generates a binary mask for precise pixel-level object segmentation.



Object Status Tracking

Monitors the object's tracking state: Ok, Searching, Off, or Terminated & Helps assess if the system is actively following or has lost the target.



Object Detection & Classification

Detects objects and classifies them as "person" or "vehicle" using onboard AI & assigns a unique ID for each object for consistent tracking over time.

3D Localization & Movement

Estimates real-world position [x, y, z] and velocity [vx, vy, vz] of each object & Determines action state (Idle or Moving) to understand object behavior



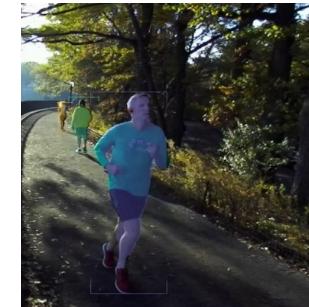
Bounding Box & Size estimation

Outputs 2D bounding boxes in the image and 3D bounding boxes in real space. Calculates object dimensions: width, height, and length in meters.

Child Detection Features

Bounding Boxes

Creates 2D and 3D boxes around the child for detection and visual overlay. Ignores irrelevant objects.



Object Status Tracking

Assigns a unique ID to each person, indicating if the child is being followed or lost.

3D Localization

Provides real-world coordinates to determine the child's location in space and detects movement.



Confidence Scoring

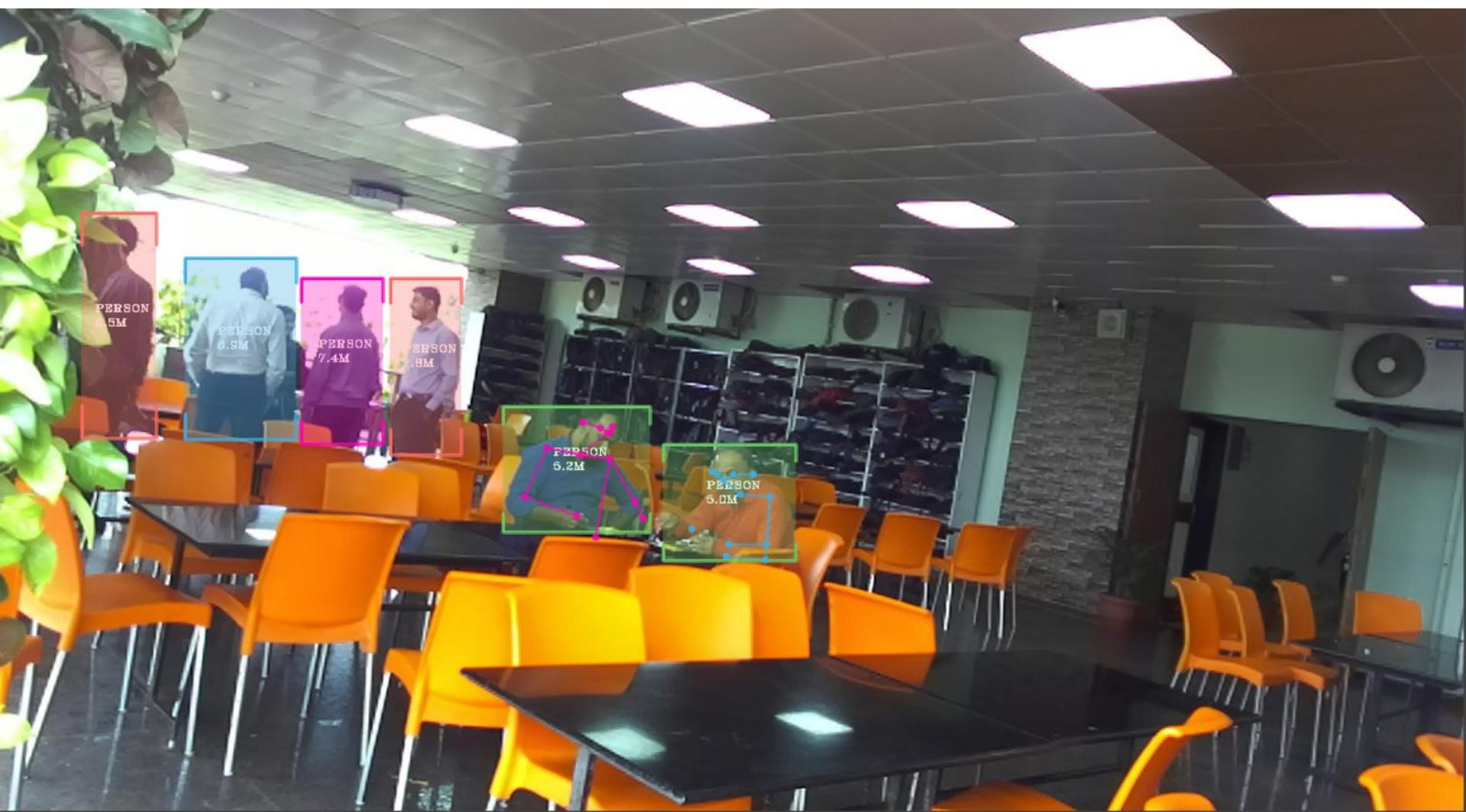
Outputs a 0–100 score to show confidence in each child detection.

Body Size Estimation

Measures height, width, and length to differentiate children from taller adults.

Pixel-Level Masking

Generates binary masks to segment the child from complex or crowded backgrounds.

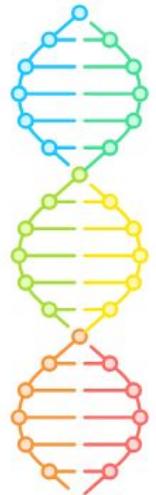


Body Tracking

AI-Driven Body Tracking

Keypoint Detection

AI extracts skeletal keypoints in 2D and 3D, representing joints from 18 keypoints following the COCO18 skeleton representation.



Head Positioning

AI calculates precise 3D head center position.



Confidence Scoring

AI assigns confidence values to detected body points.



Head Bounding Box

AI defines 2D and 3D bounding boxes around the head for facial and identity tracking.



Joint Motion Understanding

AI tracks the local position and orientation of body joints in 3D using AI.



Global Orientation

AI estimates the global rotation of the body's root joint help understand the direction of child facing



Application in Child Movement Analysis

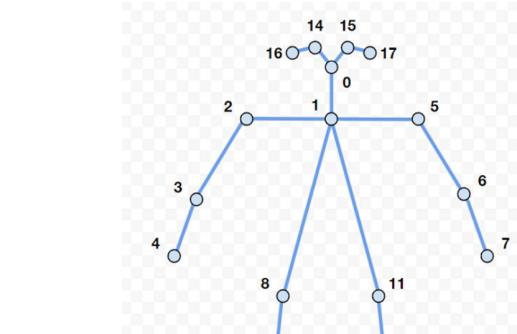
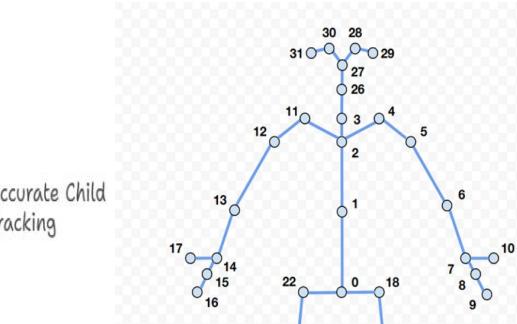
2D & 3D Keypoint Tracking

Head Position & Bounding Box

Joint Orientation Monitoring

Body Rotation Estimation

Keypoint Confidence Scoring



Spatial Mapping

Spatial Mapping Capabilities

Custom Resolution & Range

Adjusts resolution for optimal mapping at long distances from 1–12 cm (detail) and 1–12 m (distance) to suit application needs.



Real-Time Mapping

Continuously scans and updates 3D maps in both indoor and outdoor environments.



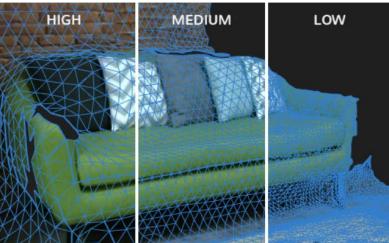
Mesh Filtering

Three presets (High, Medium, Low) to clean, simplify, and optimize 3D models.

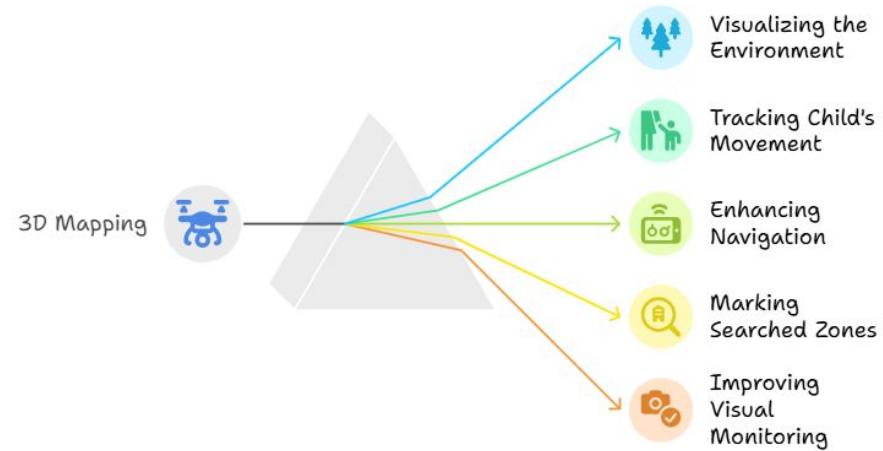


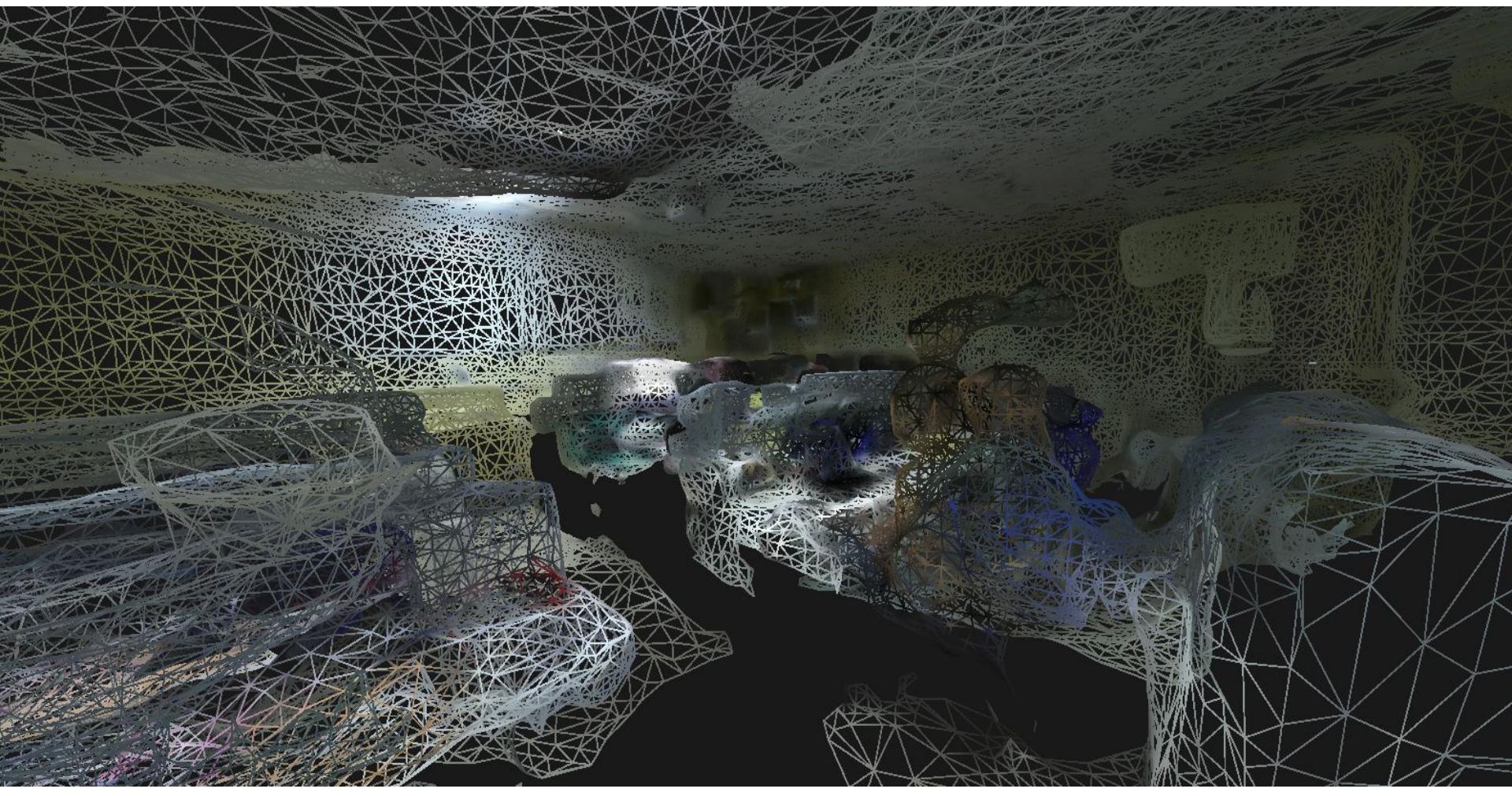
Textured Models

Uses camera images to apply realistic textures to 3D surfaces for visual accuracy.



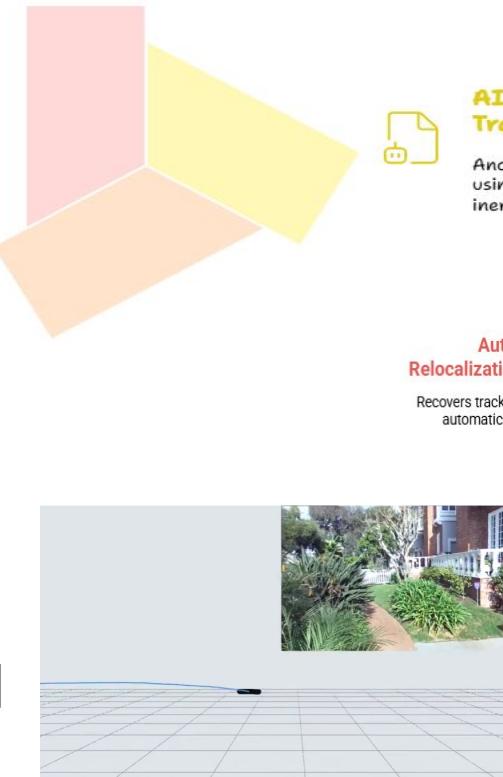
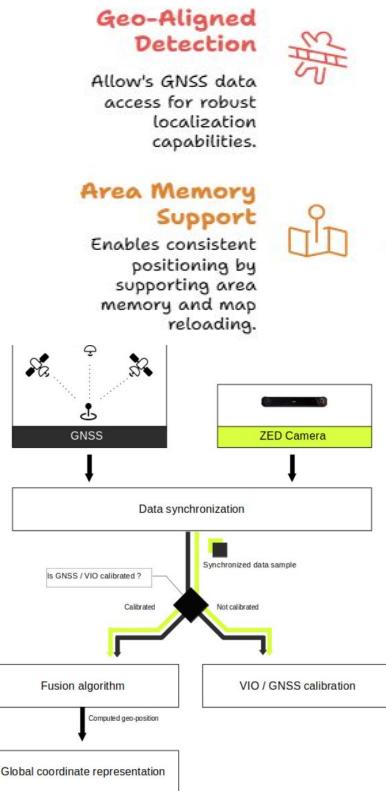
Application of spatial mapping in child detection system





Other features

GEO TRACKING CAPABILITIES



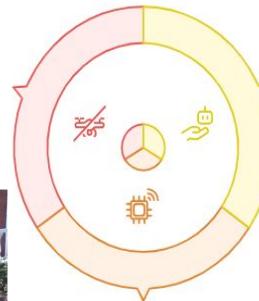
AI Powered Tracking

Anchors tracking using AI and visual-inertial SLAM.

Positional Tracking Capabilities

Auto-Relocalization

Recovers tracking automatically



AI-Powered Tracking

Integrates AI-driven visual odometry and IMU data (ie gyroscope + accelerometer) for stable tracking.

Detect Areas

Helps detect areas where a child might be seated, lying, or hidden (e.g., floor, bench, wall, base).



Detect Surfaces

detects horizontal and vertical flat surfaces from the 3D point cloud in real time.

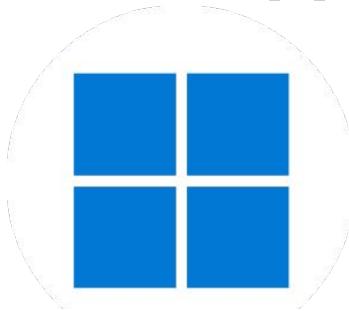


AI Filters Data

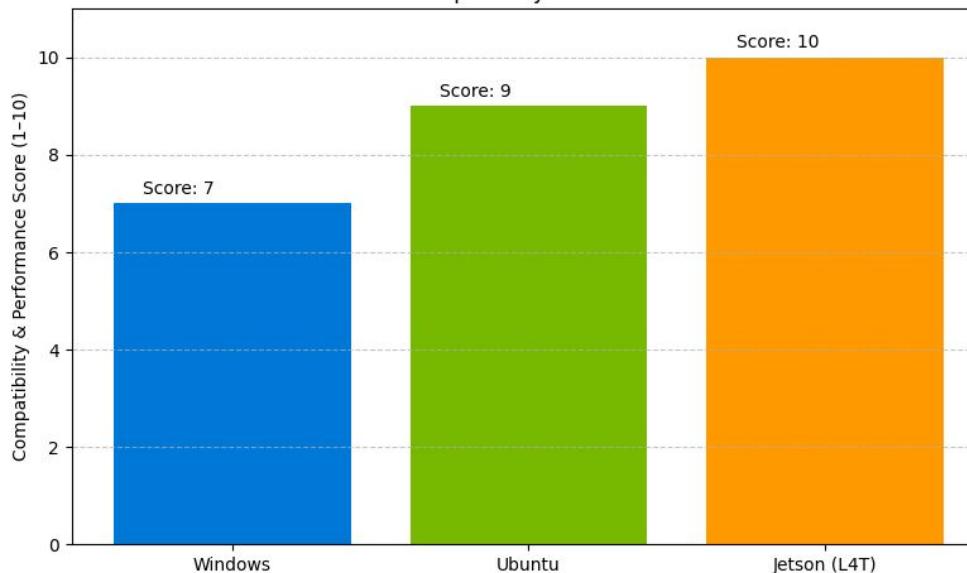
AI filters noisy data and isolates reliable planes using geometry and depth fusion.



Compatibility with Supported Platform



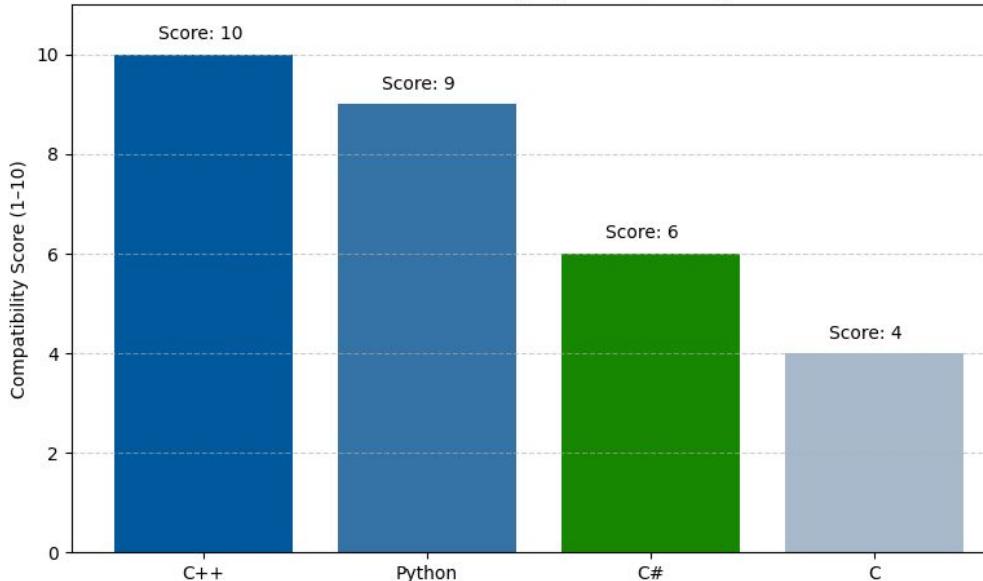
ZED 2i Compatibility Across Platforms



Compatibility with programming language



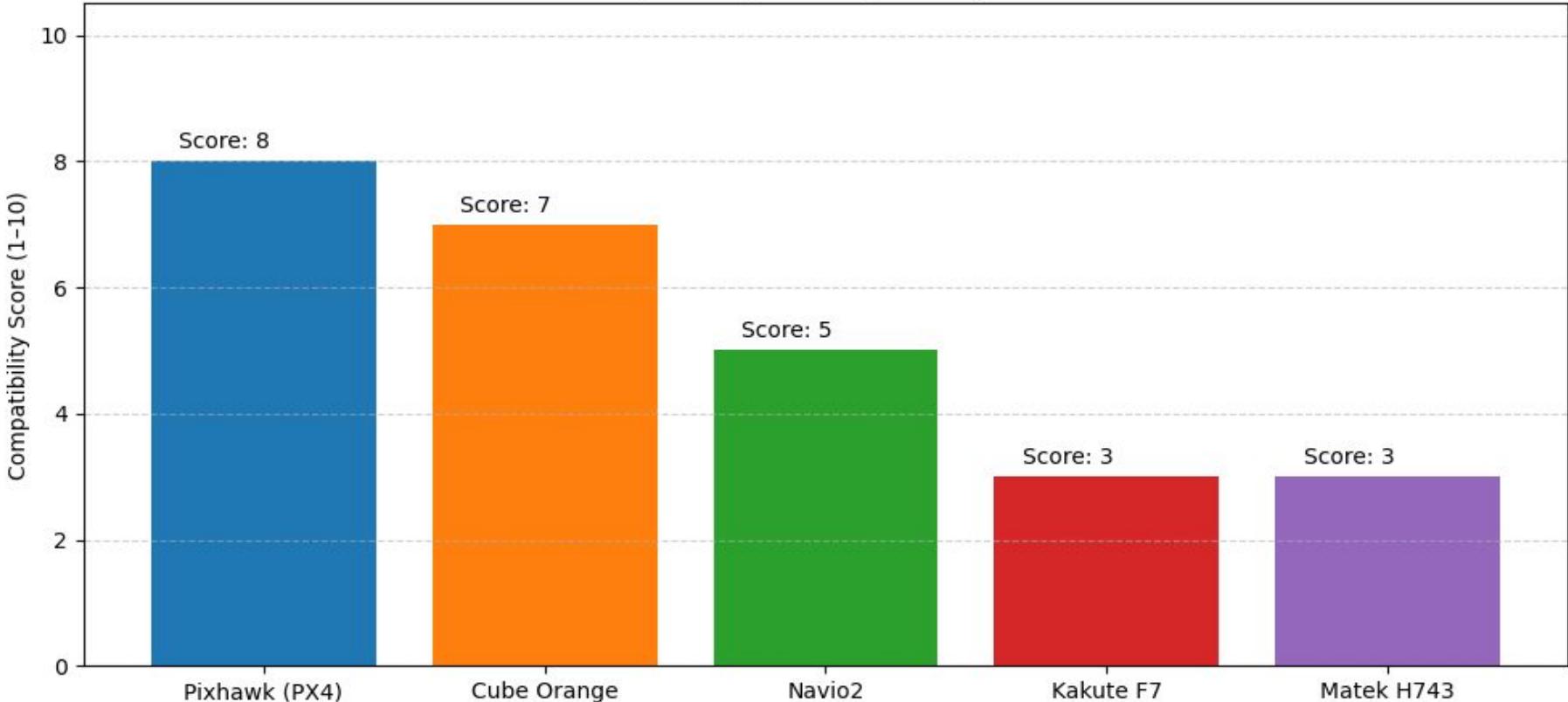
ZED 2i SDK Language Compatibility



*The scores are
Derived based on
official SDK/API
support

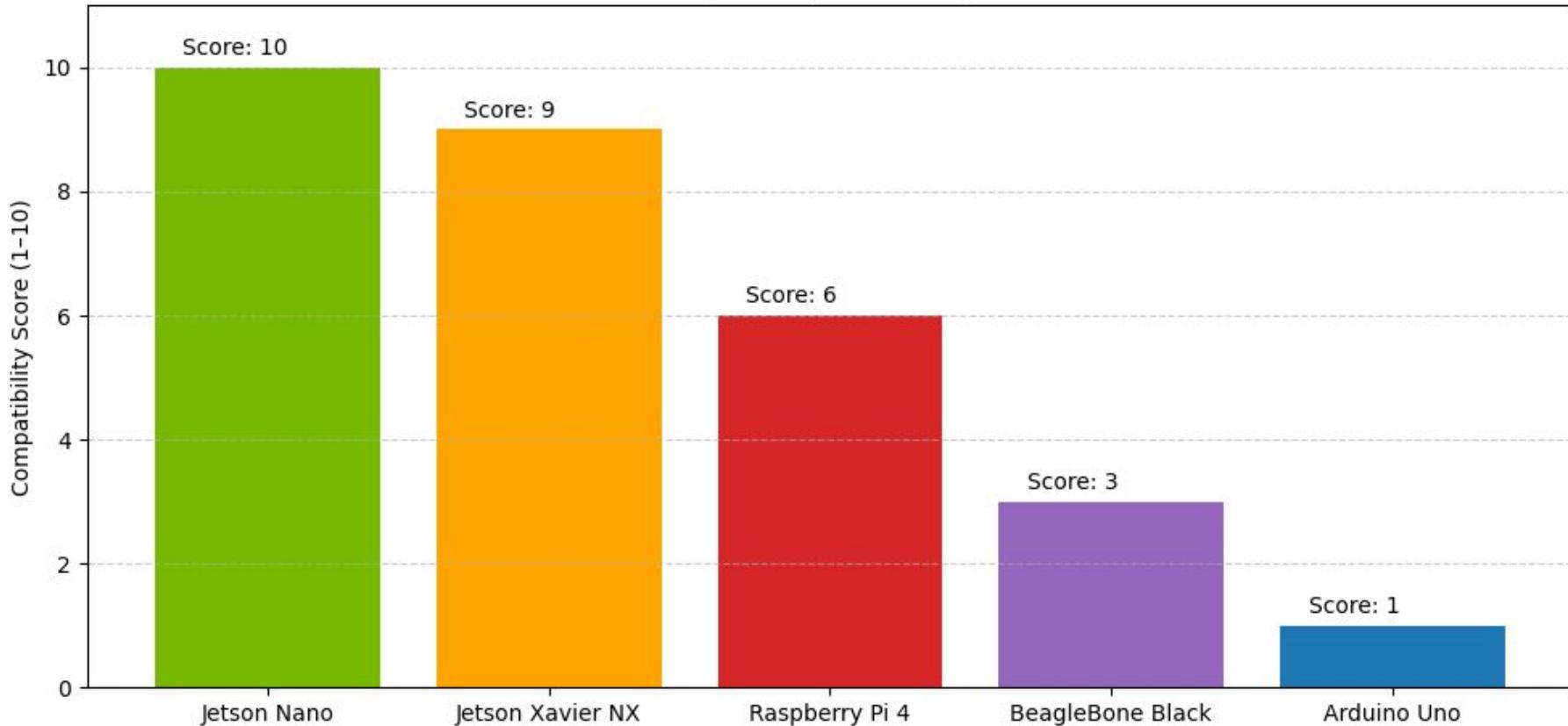
Compatibility with Flight controllers

ZED 2i Compatibility with Popular Flight Controllers



Compatibility with Microprocessors

ZED 2i Compatibility with Microprocessors



Other Third Party Libraries & Environment

UNITY



UNREAL
ENGINE 5



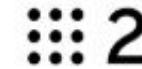
OPENCV



ROS



ROS 2



PYTORCH



YOLO



MATLAB



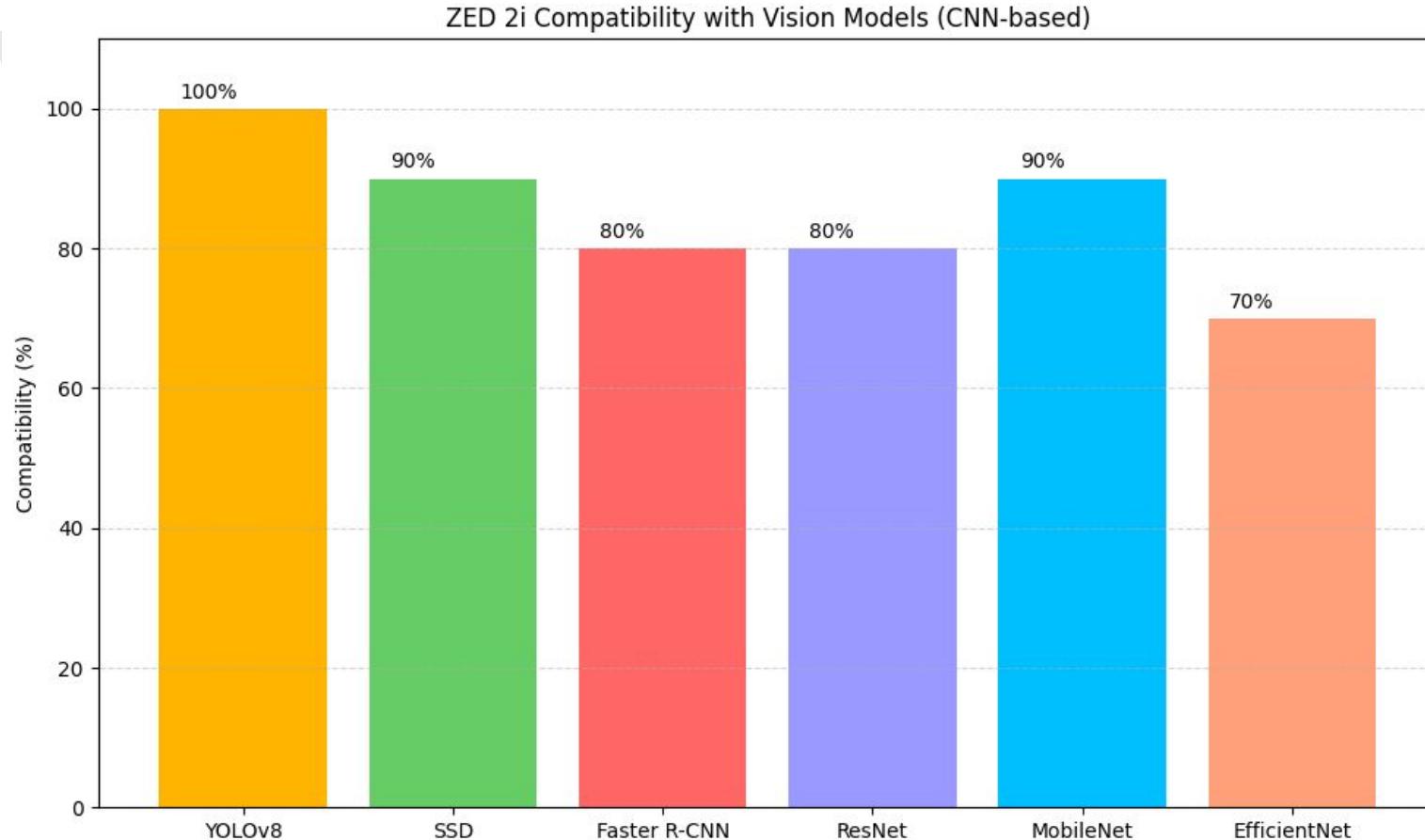
ISAAC SIM



TOUCH
DESIGNER



AI Model's Compatibility Based on Integration Factor



Basic Requirements for Jetson nano



NVIDIA Jetson module and
reference carrier board



microSD card (32GB UHS-1)

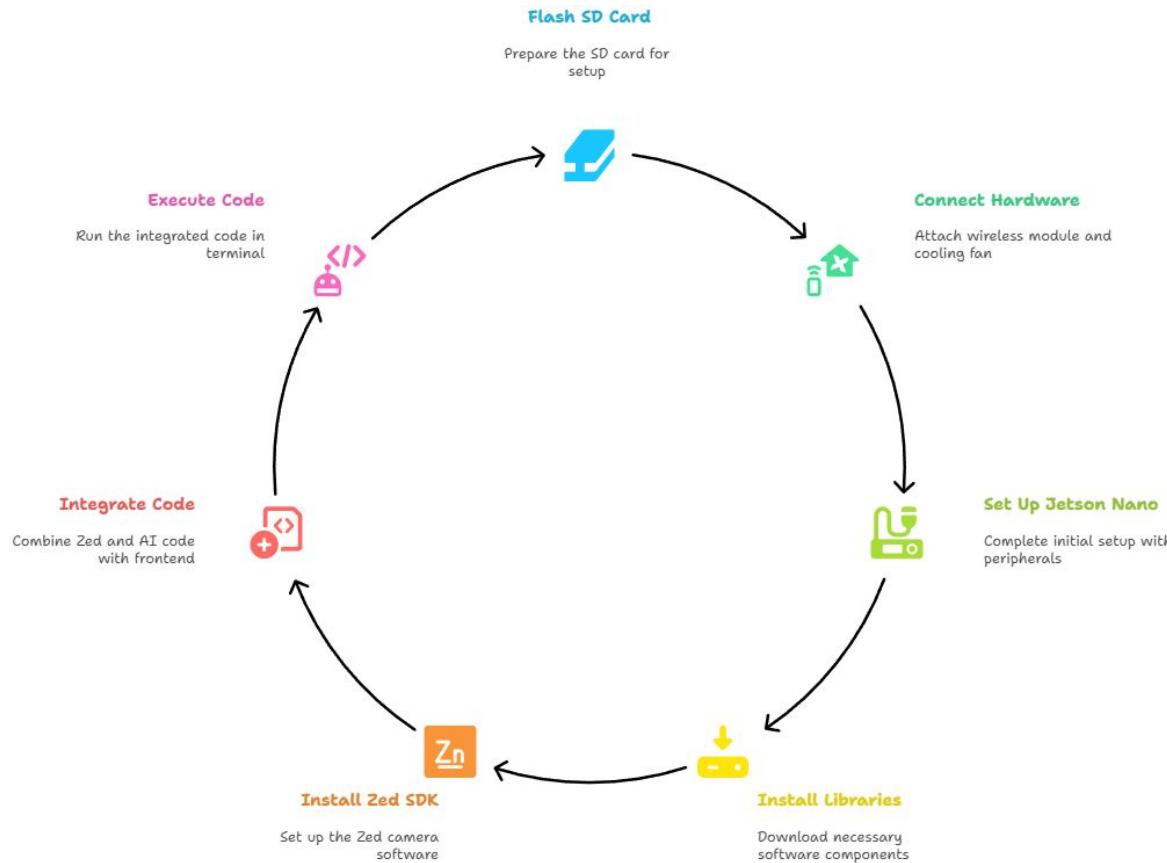


Ac8265 wireless nic module



Micro-USB power supply

Implementation steps



Thank
You

