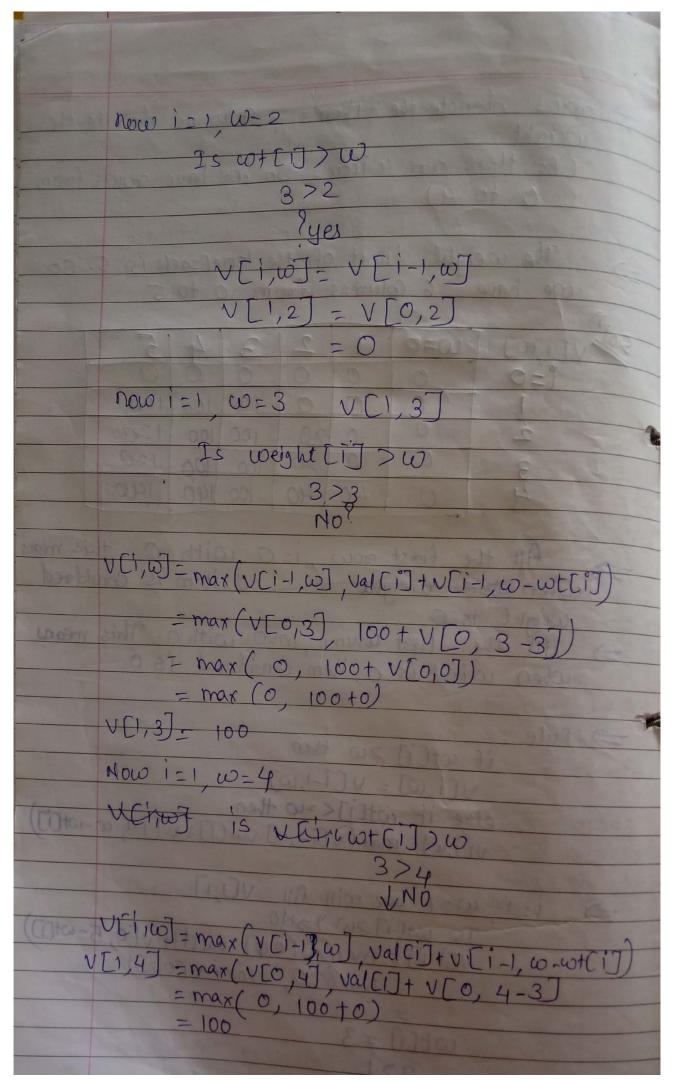
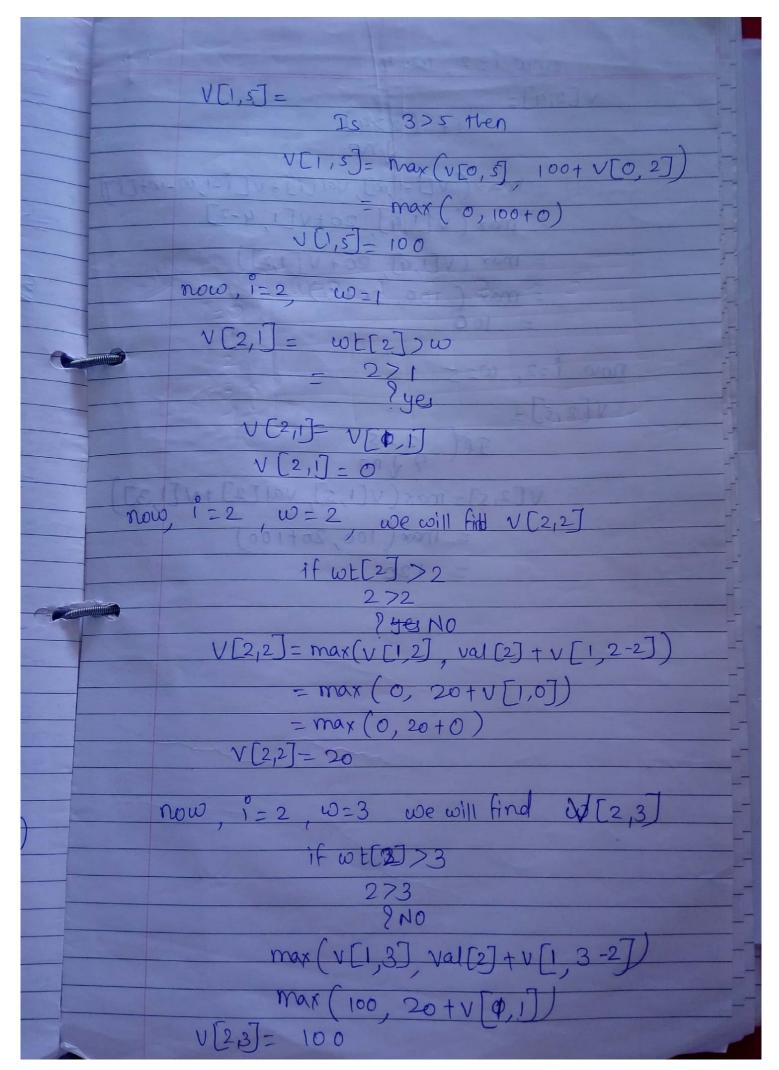
Dynamica programming  1) It is used to solve optimisation problem  2) It is similar to devide a Conquer such that them are going to be subproblem & the given problem is solved by Combining the announce of sub-problems.  3) untile divide a Conquer the subproblems are not independent  a) It is based on assumption that smaller subproblem results are needed frequently.  Divide a Conquer Dynamic programming to partition the problem into a partition the problem into independent sub-problem averlapping subproblems  is doein't store the solution of a Avoids recompution by storing the subproblem  (identical subproblems are (space compensity is move) recomputed again)  3) It is a top down approach  4) It is not used for 4) It is used for optimasation optimisation problem  problem  (identical subproblem beaution of thomasation approach  3) It is used for optimasation optimisation problem  problem  (identical subproblem beaution of thomasation approach  3) It is a top down approach  3) It is used for optimasation optimisation problem  problem  (identical subproblem beaution of thomasation approach  3) It is used for optimasation optimisation problem  problem  (identical subproblem are subtropoblem result)  (in eg. nth term of fibonacu med solve a smaller subproblem result)	
them are going to be subproblem? the given problem is solved by combining the anwers of sub problems.  3) untitle clivide & conquer the subproblems are not independent.  3) It is based on assumption that smaller subproblem results are needed frequently.  Divide & conquer Dynamic programming partition the problem into 10 partition the problems.  3) doesn't store the solution of 2) Avoids recompution by Storing the subproblem (subproblem the result into a table the subproblem (subproblem again).  3) It is a top down 3) It is a bottom up approach approach approach approach problem problem.  4) It is not used fore 4) It is used for optimasation optimisation problem problem.	Dynamia programming
not independent  a) It is based on assumption that smaller  Subproblem results are needed frequently.  Divide & Conquer  Dynamic programmies  Dynamic progra	there are going to be subproblem & the given problem is solved by combining the anwers of sub-problems.
1) partition the problem into 0 partition the problems independent Sub problem overlapping subproblems  2) doesn't store the solution of 2) Avoids recompution by storing the subproblem the result into a table (identical subproblems are (space complexity is more) recomputed again)  3) It is a top down approach approach  4) It is used for optimasation optimisation problem problem  optimisation problem  5) for eg. n'th term of fibonacci solvieued Series if Computed the through array (table of Series if Computed the smaller subproblem result)  Complexity as $0(2^n)$ smaller subproblem result)	not independent  a) It is based on assumption that smaller  subproblem results are needed frequently.
the subproblem the result into a raise (identical subproblems are (space complexity is more) recomputed again)  3) It is a top down 3) It is a bottom up approach approach  4) It is not used for 4) It is used for optima sation problem problem  optimisation problem problem  s) for eg. n'th term of fibonacia s) for eg. fibonacia is achieved series if computed the through array (table of series if computed the smaller subproblem result)  complexity as O(2n) smaller subproblem result	1) partition the problem into 1) partition the problems
3) It is a top down approach approach  4) It is not used for 4) It is used for optima sation approach optimisation problem problem  5) for eg. n'th term of fibonacci so achieved series if Computed the through array (table of series if Computed the smaller subproblem result) Complexity as O(2n)  3) It is a bottom up approach  4) It is used for optima sation problem  problem  smaller subproblem result)	the subproblem the result into a table.  (identical subproblems are (space complexity is more).
optimisation problem  optimisation problem  s) for eg. nth term of fibonacci s) for eg. fibonacci is achieved  series if Computed the through array (table of  series if Computed the smaller subproblem result)  complexity as O(2n)  smaller subproblem result	3) It is a top down 3) It is a bottom up approach
Series if Computed the through array (table of smaller subproblem result)	optimisation problem problem
ie exponetial complexity	thereal many (table of

# Rules of dynamic programming  # Rules of dynamic programming
overtapping subproblem. A recursive solution overtapping subproblem. A recursive solution contains a small no of distinct subproblems repeated many times.
3) Bottom up fashion - Compute the Solution in bottom up fashion
There are 3 Components in Dp  D) Remover a relation  2) Tabular Design
3) Solution constructed by backtracking the result table.
# knapsack problem using dynamic programming (0/1 knapsack)
A bag of Capacity M is given to you. a sell of item havings weights wi, we - wn are given with their profit   value P, P2 - Po.
Objective is to add an items to the bag in Such a way that proofit earned is maximum. Items are added to the bag completely i.e fractioned of items Can't be added.
Item i 1 2 3 4  Value   Proofit V 100 20 60 40  weight W 3 2 49 1
weight of knapsack (m)=5  Create a value table v(i w) where i denotes no of items & w denotes weight of the items

Downs denote the items columns denote the !-
(As there are 4 items so we have nows from
0 to 4)
The weight limit of the knapsack is 5. so
we have 6 columns from 0 to 5
50 VEIWJ W=0 1 2 13 4 15
1 0 0 0 100 100
2 0 0 20 100 100 120
3 0 0 20 100 100 120 40 40 100 140 140
fill the first row, i=0 with 0 this means
When to weight is o item is considered
weight is O  fill the first column w=0 with 0. This means =
when weight is o, item considered is o.
=> Rule
if $\omega t CiJ > \omega$ then $V Ci, \omega J = V Ci-l, \omega J$
else it wtl] <= \oldot then  v[i, \oldot] = \max(\v[i-1, \oldo]) val[i] + \v[i-1, \oldot -\oldot \v[i])  v[i, \oldot] = \max(\v[i-1, \oldot]) val[i] + \v[i-1, \oldot -\oldot \v[i])
$= \sum_{i=1}^{n} \omega_{i} = 1  \text{we will fill } VU, I$
IS WHEID >W 9 >MO  WELL IT = max(1/10 UP) vale(1+ v[0, 5-w+0]) -
IS WHE IJ >W 7.3MO VCI IJ = max (VCO, 4) VAI [U+ V[0, 5-WHD]) - - max (O, 100+ VCO, 2)
$= (3+00)(9) \times (9)$ $\text{wt}(J=3) = 3$
3>1
50, V[1, 1] - V[0,1]
VCI, IJ = 0





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