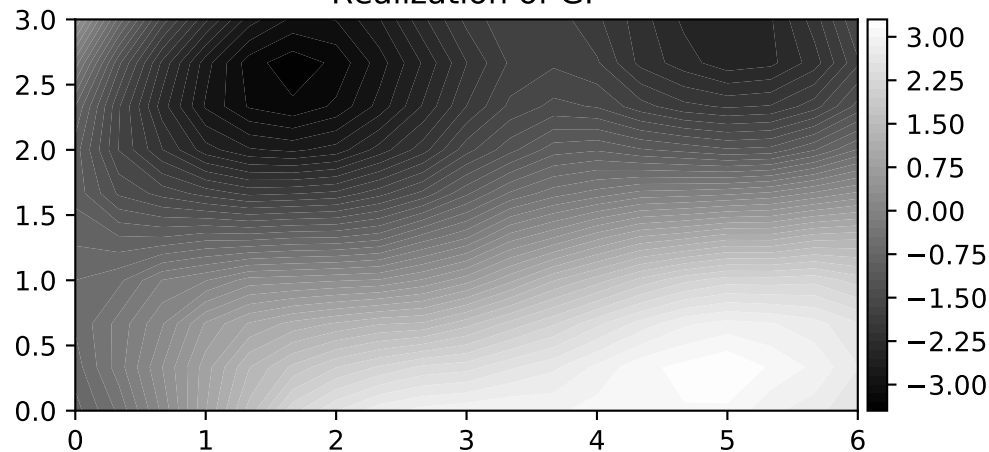
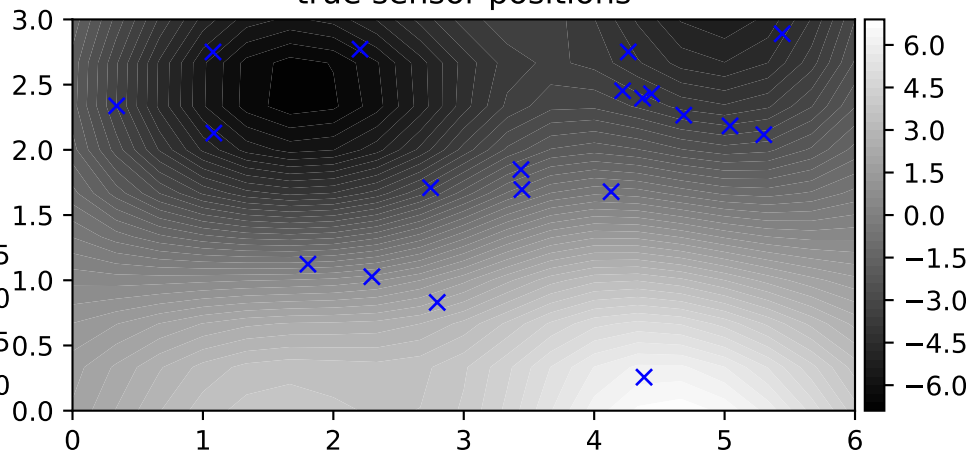


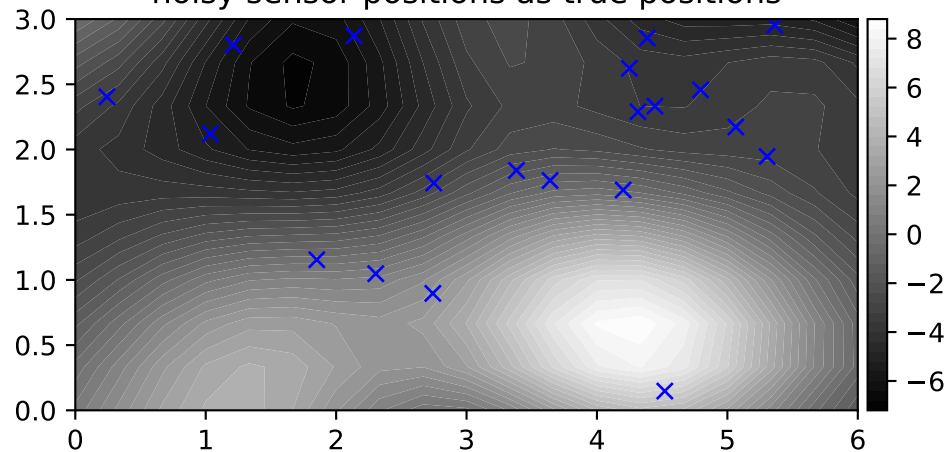
Realization of GP



GP mean value regression using true sensor positions



GP mean value regression using noisy sensor positions as true positions



GP mean value regression using noisy sensor positions and MC approximation

