

# Simple Minimization Formulation

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*By the end of this lecture, you will understand how to craft a simple minimization function*

# Loss function minimization

- *A function* that *outputs a real number*
- That function takes as *input some parameters*
- By *searching for parameter values*
- Use a *smart search*
  - Gradient descent
  - Newton-Raphson
  - Other
- That loss function should capture *some meaning of the domain*
- There can be *several local minima*
- *Loss surface* may not be smooth

# Key Steps

- **STEP 1:** Input is a vector (e.g.  $w$  vector)
  - If it is a matrix, flatten to a vector and input
  - *It is an array of numbers*
  - *It corresponds to parameters*
- **STEP 2:** Output is a *number*
- **STEP 3:** Choose a *minimization method*
  - There are a dozen minimization methods (aka *search methods*)
  - For example, for Gradient Descent – You need to supply gradient function (aka Jacobian)  $\nabla L(w)$
  - You may not need to supply gradient function
    - Nelder-Mead's method
    - Variants of Secant method
    - Popular – BFGS method (Broyden-Fletcher-Goldfarb-Shanno)

# Revisiting the linear regression formulation

- Example of squared error:  $L(w) = (w \cdot x - y)^2$ 
  - Here  $x$  and  $y$  are given and therefore constant
  - $w$  is parameter vector
- $x$  is a vector of  $k$  dimensions ( $k \times 1$  matrix)
- $w$  is a vector of  $k$  dimensions ( $k \times 1$  matrix)
- $x \cdot w$  is the dot product of the  $x$  and  $w$  vectors
- $y$  is the given actual value
- On the right side, squared error is calculated

# Other non-trivial examples... To find inverse of a matrix?

- **Given:** Let  $A$  be a square matrix
  - **Task:** We need to find  $B = A^{-1}$  inverse of  $A$
  - **Constraint:** We need to use Loss function minimization formulation
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- $L(B) = \text{norm}(\text{vector}(BA - I)) = 0$

# An example of low dimensional transformation

(1)

Let input be  $k$  dimensional

There are  $N$  data points

The  $X$  matrix *is of shape*  $(N \times k)$

(2)

**Task:** Each and every  $k$  dimensional point we need to transform to become a 2 dimensional point

(3)

Let  $Q$  be the **transformation matrix** of shape  $(k \times 2)$

**New  $x \mapsto Qx$**

The transformation is  $X_{N \times k} Q_{k \times 2} = X'_{N \times 2}$

(4)

**Constraint:** It should satisfy some constraints... such as ***pairwise similarities/distances be maintained***

(5)

**Loss function:** Design a loss function and minimize it!

We need:  $XX^T = X'X'^T$

***Minimum difference in pairwise similarities***

:  $XX^T - XQ(QQ^T)X^T = XX^T - X(QQ^T)X^T$

(6)

Write a program to code for loss function

$$L(Q) = ||\text{vec}(XX^T - X(QQ^T)X^T)||_2$$