ML Curve Fitting Perspective of the World

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Find equation of line passing through two points

• Point A: (0,4)

• Point B: (1,7)

Find equation of line passing through two points

- Point A: (0,4)
- Point B: (1,7)
- Line is: y = 3x+4

Find equation of line passing through three points

- Point A: (0,4)
- Point B: (1,7)
- Point C: (-1,1)

Happy go lucky!

Find equation of line passing through three points..

- Point A: (0,4)
- Point B: (1,7)
- Point C: (-1,1) Point C: (-1,2)

Happy go lucky!

Through an error saying no line can pass through the given three points i.e. they are not collinear

Find equation of line passing through JUST ONE

- Point A: (0,4)
- Point B: (1,7)
- Point C: (-1,1) Point C: (-1,2)

Happy go lucky!

Through an error saying no line can pass through the given three points i.e. they are not collinear

Infinite number of solutions!

Non ML World?

RANK of the matrix X

$$X_{N \times k} w_{k \times 1} = y_{N \times 1}$$

There are k variables
There are N equations
Rank of X is r
When there is NO SOLUTION \rightarrow r > k
When there are INFINITE NUMBER OF SOLUTIONS \rightarrow r < k

ML Wold?

RANK of the matrix X

$$X_{N \times k} w_{k \times 1} = y_{N \times 1}$$

LOSS FUNCTION

There are k variables parameters

There are N equations terms of the loss function

Rank of X is r

When there is NO SOLUTION -> r > k

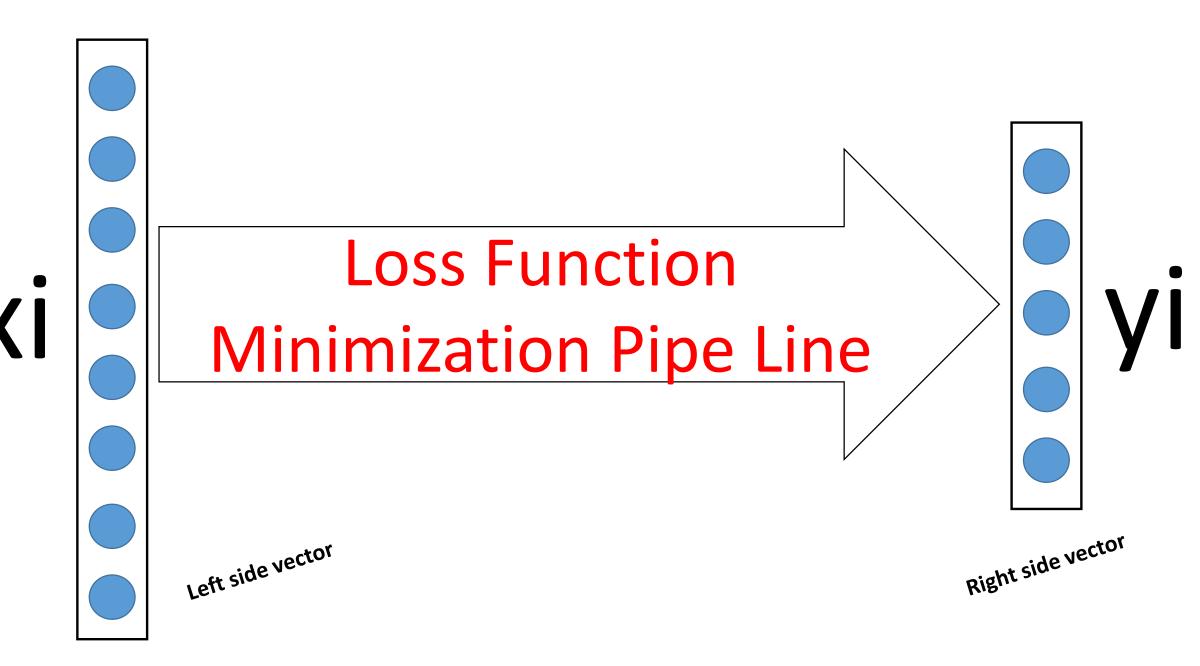
When there are INFINITE NUMBER OF SOLUTIONS → r < k

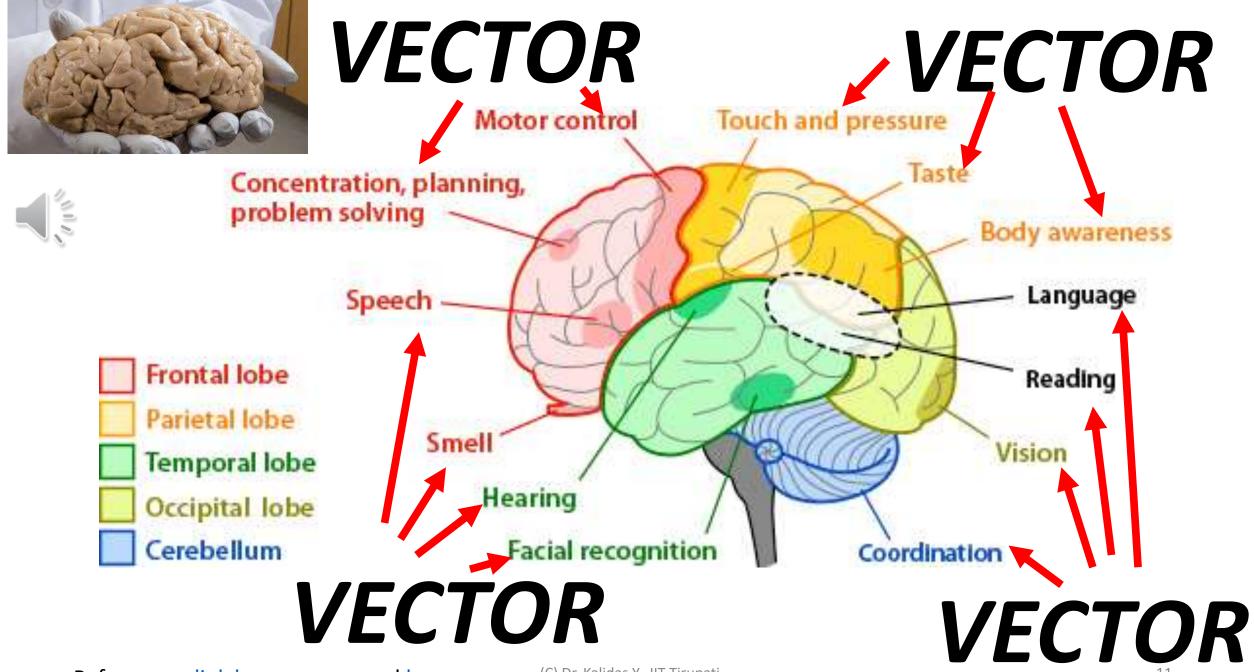
Loss function perspective -> ML world

$$L(w) = (Xw - y)^T (Xw - y)$$

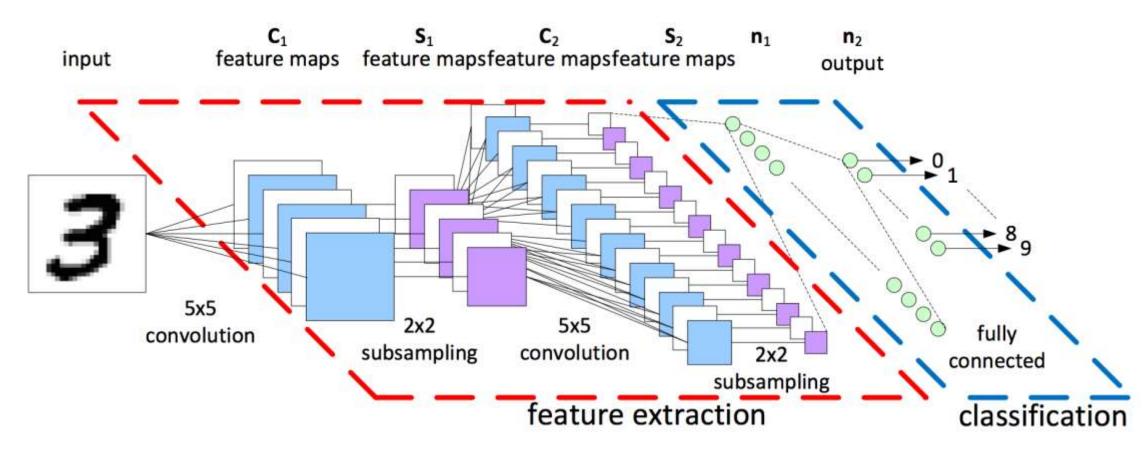
$$L(w) = \sum_{i=1}^{i=N} \left(y_i - \left(\sum_{j=1}^{j=k} w_j \ x_{i,j} \right) \right)^2$$

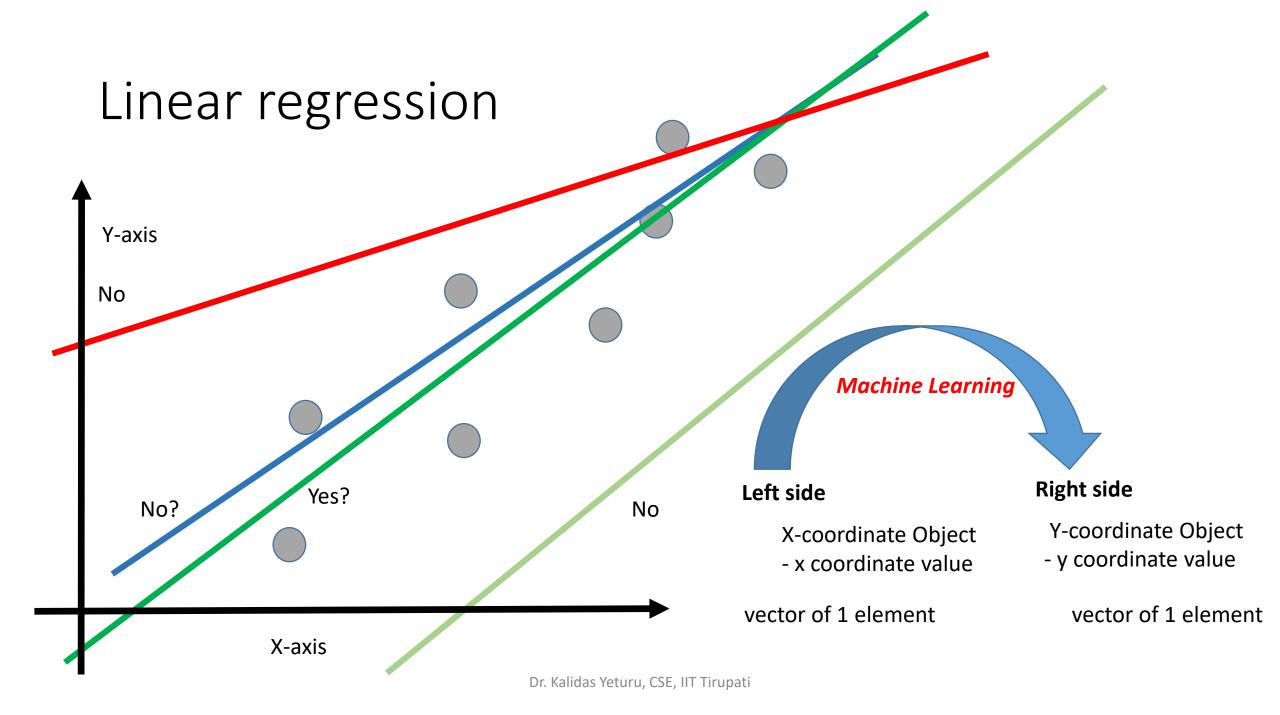
$$w_{(new)} = w_{(old)} - \eta \nabla L \Big|_{w = w_{(old)}}$$





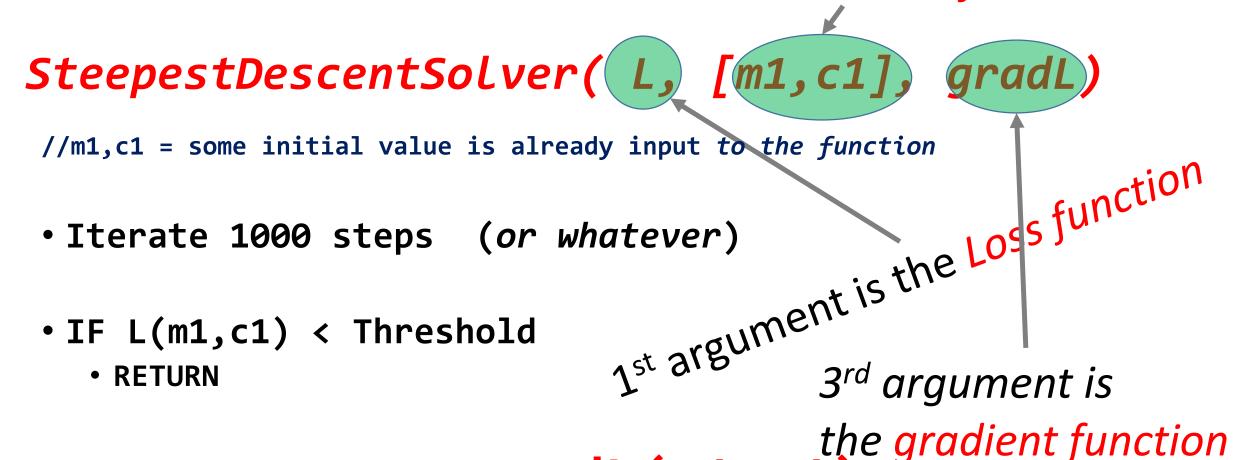






What are the different ways?

2nd argument is the list of Parameters



• [m1,c1] = [m1,c1] - gradL(m1,c1)This function outputs a list or vector

Defining a loss function

```
# Author: Kalidas Y <ykalidas at iittp dot a
c dot in>
# License: BSD 3 clause
def fun error(w) :
  diff = np.matmul(w, X.T) - y.T
  err val = np.matmul( diff, diff.T )/X.shap
e[0]
  return err val[0][0]
```

Defining Gradient Function

```
# Author: Kalidas Y <ykalidas at iittp dot ac dot
in>
# License: BSD 3 clause
def fun grad error(w) :
  grad val = 2*np.matmul( np.matmul(w, X.T) -
 y.T, X )/X.shape[0]
  return np.concatenate(grad val)
```

Invoking Optimization function

```
# Author: Kalidas Y <ykalidas at iittp dot ac dot
in>
# License: BSD 3 clause
from scipy.optimize import minimize
w init = np.random.randn(1,2)
res = minimize(fun=fun_error, x0=w init, jac=fun_g
rad_error, method= 'BFGS')

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```

Analytical Solution... another numerical method... which is not much useful in ML formulation

1.
$$Xw = y$$

$$2. X^T(Xw) = X^T(y)$$

3.
$$(X^TX)w = X^Ty$$

4.
$$(X^T X)^{-1} (X^T X) w =$$

$$(X^TX)^{-1}X^Ty$$

5.
$$w = (X^T X)^{-1} X^T y$$

There are numerical methods to compute inverse of a matrix

e.g. **Schultz Method**

$$Z^{(t+1)} = 2 \alpha Z^{(t)} - \beta Z^{(t)} X Z^{(t)}$$

 $Z^{(0)} = rand()$

Formulation

```
# Author: Kalidas Y <ykalidas at iittp dot ac dot in>
# License: BSD 3 clause

w_analytical = np.matmul( np.matmul( np.linalg.inv( np.matmul (X.T, X) ), X.T ), y)

print (w_analytical)
[[3.10219092]
```

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