

# FYS3150 - Project 1

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Abstract om du vil

## I. THEORY

### A. Matrix formulation of the discrete one-dimensional Poisson equation

The one-dimensional Poisson equation with Dirichlet boundary conditions is given by equation 1.

$$-\frac{d^2 u(x)}{dx^2} = f(x), \quad x \in (0, 1), \quad u(0) = u(1) = 0 \quad (1)$$

We define the discretized approximation to  $u$  to be  $v_i$  at points  $x_i = ih$  evenly spaced between  $x_0 = 0$  and  $x_{n+1} = 1$ . The step length between the points is  $h = 1/(n+1)$ . The boundary conditions from equation 1 then give  $v_0 = v_{n+1} = 0$ . An approximation to the second derivative of  $u$ , derived from the Taylor expansion, is

$$\frac{-v_{i-1} + 2v_i - v_{i+1}}{h^2} = f_i \quad \text{for } i = 1, 2, \dots, n \quad (2)$$

where  $f_i = f(x_i)$ .

Written out for all  $i$ , equation 2 becomes

$$\begin{aligned} -v_0 + 2v_1 - v_2 &= h^2 f_1 \\ -v_1 + 2v_2 - v_3 &= h^2 f_2 \\ &\dots \\ -v_{n-2} + 2v_{n-1} - v_n &= h^2 f_{n-1} \\ -v_{n-1} + 2v_n - v_{n+1} &= h^2 f_n \end{aligned}$$

In general, this can be rearranged slightly so that

$$\begin{aligned} 2v_1 - v_2 &= h^2 f_1 + v_0 \\ -v_1 + 2v_2 - v_3 &= h^2 f_2 \\ &\dots \\ -v_{n-2} + 2v_{n-1} - v_n &= h^2 f_{n-1} \\ -v_{n-1} + 2v_n &= h^2 f_n + v_{n+1} \end{aligned}$$

This system of equations can be written in matrix form as

$$\mathbf{A}\mathbf{v} = \tilde{\mathbf{b}}, \quad (3)$$

explicitly

$$\begin{bmatrix} 2 & -1 & 0 & 0 & \dots & 0 \\ -1 & 2 & -1 & 0 & \dots & 0 \\ \vdots & & & & & \\ \vdots & & & & & \\ 0 & \dots & 0 & -1 & 2 & -1 \\ 0 & \dots & 0 & 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ \vdots \\ v_{n-1} \\ v_n \end{bmatrix} = \begin{bmatrix} h^2 f_1 + v_0 \\ h^2 f_2 \\ \vdots \\ \vdots \\ h^2 f_{n-1} \\ h^2 f_n + v_{n+1} \end{bmatrix}$$

With  $v_0 = v_{n+1} = 0$ , the right side reduces to  $\tilde{b}_i = h^2 f_i$ .

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- [1] Engeland, Hjorth-Jensen, Viefers, Raklev og Flekkøy, 2020, *Kompendium i FYS2140 Kvantefysikk, Versjon 3*, s. 81  
 [2] Griffiths, D. J., Schroeter, D. F., 2018, *Introduction to Quantum Mechanics, Third edition*, s. 44  
 [3] Griffiths, D. J., Schroeter, D. F., 2018, *Introduction to Quantum Mechanics, Third edition*, s. 75  
 [4] Griffiths, D. J., Schroeter, D. F., 2018, *Introduction to Quantum Mechanics, Third edition*, s. 133

## II. APPENDIX

### A. Utregninger til oppgave 3c

Likning

$$\mathbf{B}_0 \cdot \nabla = \frac{B(\theta)}{r(\theta)} \frac{\partial}{\partial \theta}$$

blir

$$\begin{aligned} \mu_0 \rho(\theta) \frac{\partial^2}{\partial t^2} \left( \frac{\xi(\theta, t)}{h_a(\theta)} \right) &= \frac{1}{h_a^2(\theta)} \frac{B(\theta)}{r(\theta)} \frac{\partial}{\partial \theta} \left( h_a^2(\theta) \frac{B(\theta)}{r(\theta)} \frac{\partial}{\partial \theta} \left( \frac{\xi}{h_a(\theta)} \right) \right) \\ \mu_0 \rho(\theta) \left( -\frac{\omega^2 \xi(\theta, t)}{h_a(\theta)} \right) &= \frac{1}{h_a^2(\theta)} \frac{B(\theta)}{r(\theta)} \frac{\partial}{\partial \theta} \left( h_a^2(\theta) \frac{B(\theta)}{r(\theta)} \frac{\partial}{\partial \theta} \left( \frac{\xi}{h_a(\theta)} \right) \right) \\ -\mu_0 \rho(\theta) \frac{\omega^2 \Xi(\theta) e^{i\omega t}}{h_a(\theta)} &= \frac{1}{h_a^2(\theta)} \frac{B(\theta)}{r(\theta)} \frac{\partial}{\partial \theta} \left( h_a^2(\theta) \frac{B(\theta)}{r(\theta)} \frac{\partial}{\partial \theta} \left( \frac{\Xi(\theta) e^{i\omega t}}{h_a(\theta)} \right) \right) \end{aligned}$$

Den tidsavhengige faktoren  $e^{i\omega t}$  kan strykes på begge sider siden derivasjonen med hensyn på  $\theta$  som vist ikke virker på den. Da får vi

$$\begin{aligned} -\mu_0 \rho(\theta) \frac{\omega^2 \Xi(\theta)}{h_a(\theta)} &= \frac{1}{h_a^2(\theta)} \frac{B(\theta)}{r(\theta)} \frac{\partial}{\partial \theta} \left( h_a^2(\theta) \frac{B(\theta)}{r(\theta)} \frac{\partial}{\partial \theta} \left( \frac{\Xi(\theta)}{h_a(\theta)} \right) \right) \\ \text{Deler på } B^2(\theta) \text{ på begge sider} \\ -\frac{\mu_0 \rho(\theta)}{B^2(\theta)} \omega^2 \frac{\Xi(\theta)}{h_a(\theta)} &= \frac{1}{B(\theta) h_a^2(\theta)} \frac{1}{r(\theta)} \frac{\partial}{\partial \theta} \left( B(\theta) h_a^2(\theta) \frac{1}{r(\theta)} \frac{\partial}{\partial \theta} \left( \frac{\Xi(\theta)}{h_a(\theta)} \right) \right) \\ v_A(\theta) &= \frac{B(\theta)}{\sqrt{\mu_0 \rho(\theta)}} \quad \text{gir} \\ -\frac{\omega^2}{v_A^2(\theta)} \frac{\Xi(\theta)}{h_a(\theta)} &= \frac{1}{B(\theta) h_a^2(\theta)} \frac{1}{r(\theta)} \frac{\partial}{\partial \theta} \left( B(\theta) h_a^2(\theta) \frac{1}{r(\theta)} \frac{\partial}{\partial \theta} \left( \frac{\Xi(\theta)}{h_a(\theta)} \right) \right) \end{aligned}$$

## III. KODE