

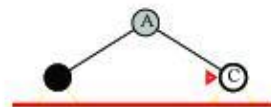
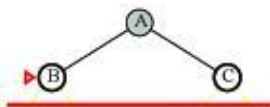
Iterative Deepening Search

- **Depth First Iterative Deepening (DFID)**: DFS with depth bound
- QueuingFn is LIFO as with DFS
 - Expand(state) only returns children such that $\text{depth}(\text{child}) \leq \text{threshold}$
 - This prevents search from going down infinite path
- First threshold is 1
 - If do not find solution, increment threshold and repeat

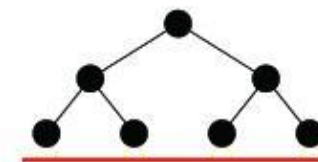
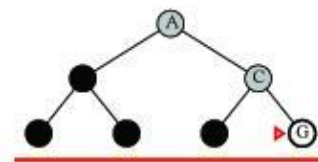
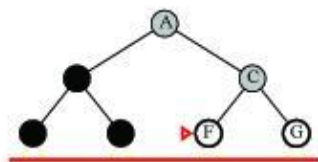
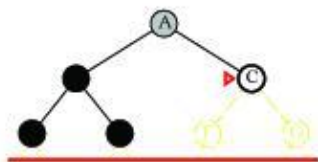
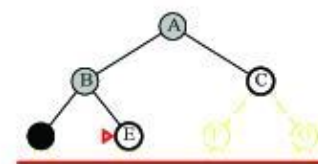
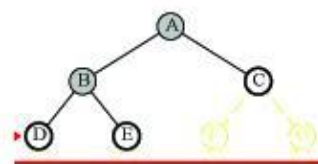
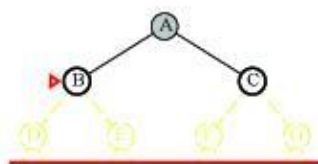
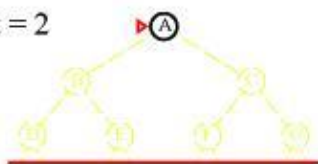
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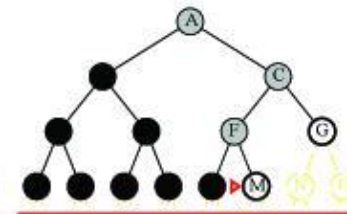
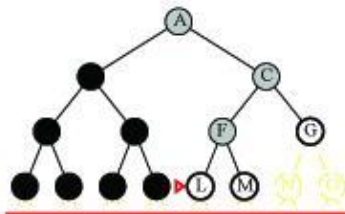
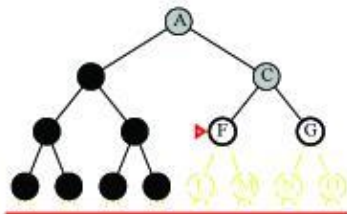
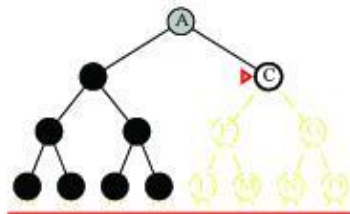
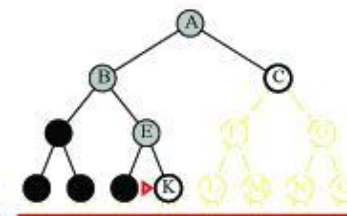
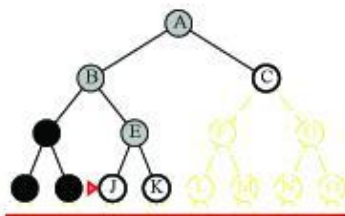
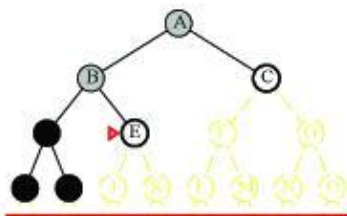
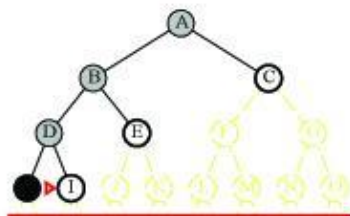
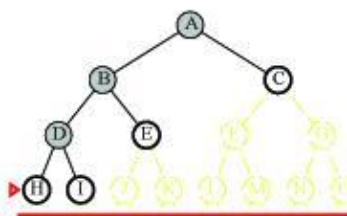
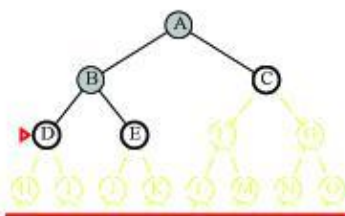
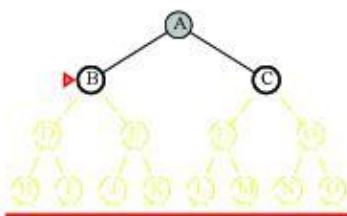
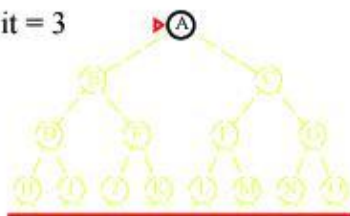
Limit = 1



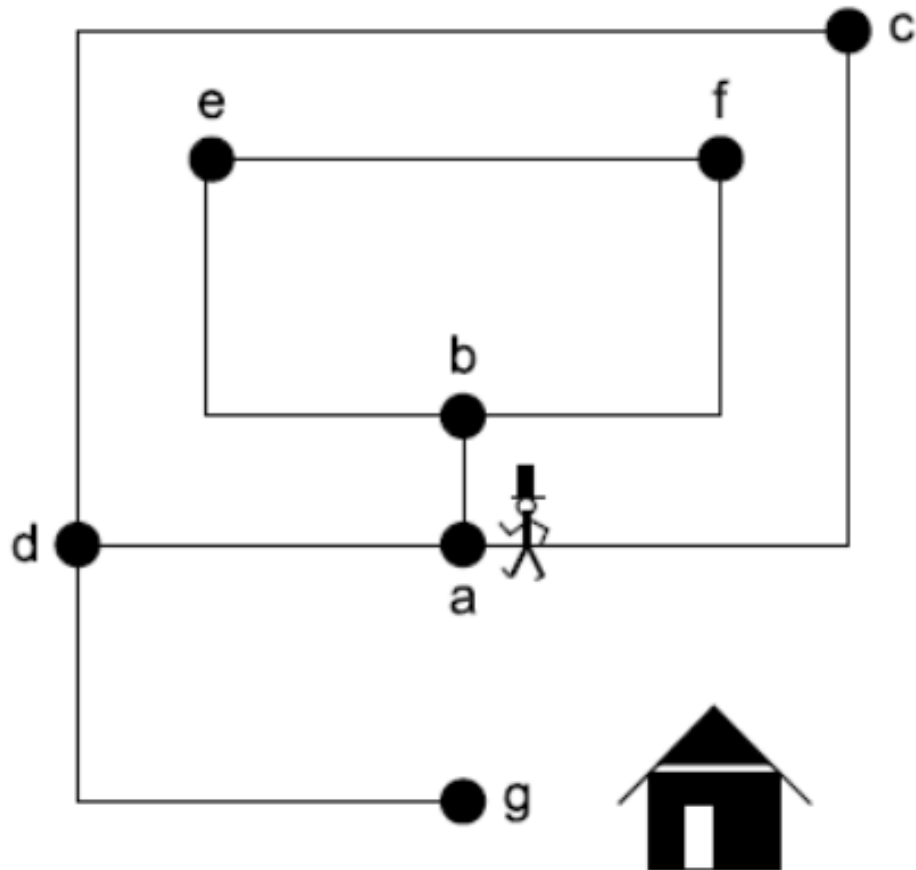
Limit = 2



Limit = 3



Example



Analysis

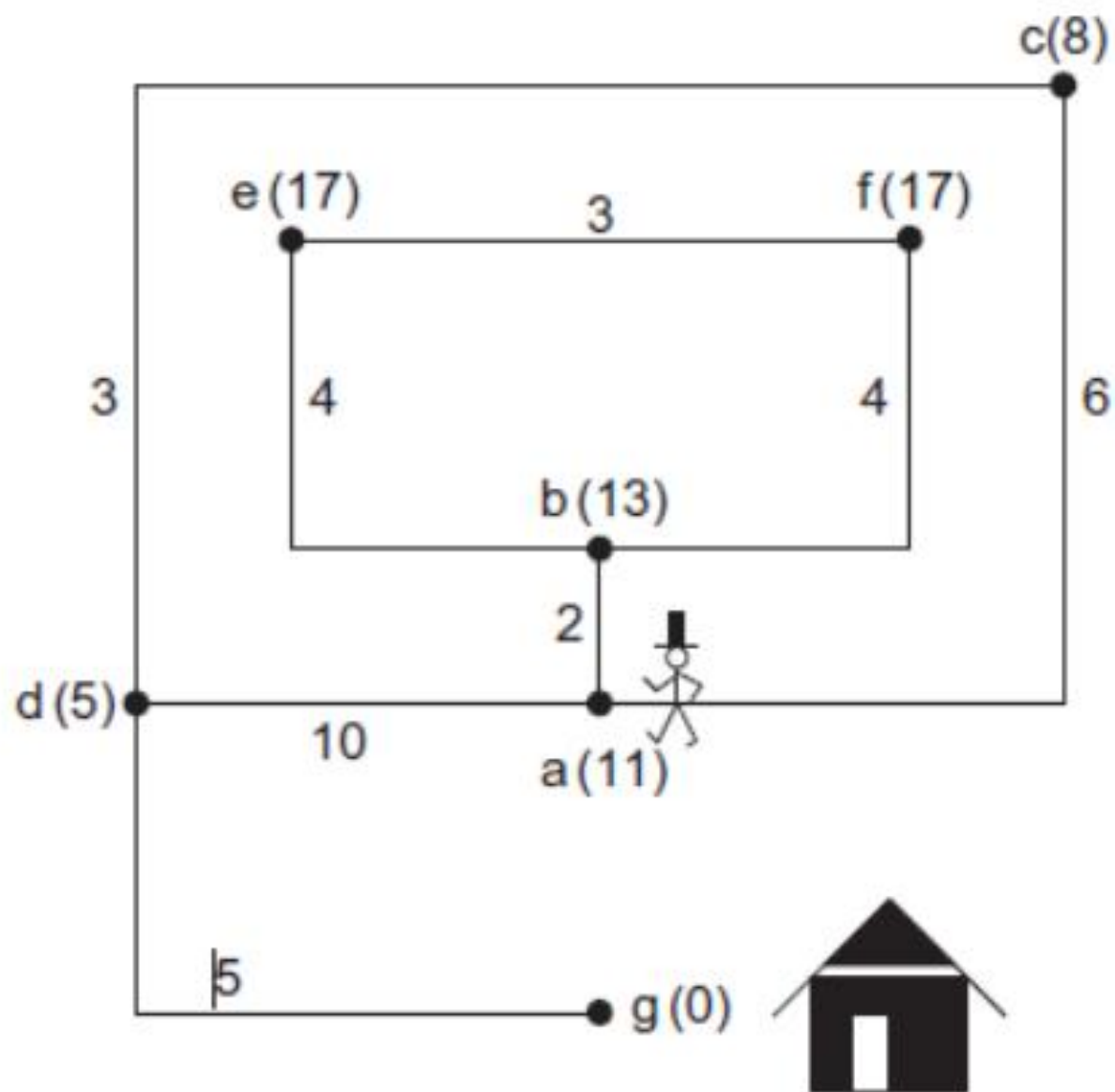
- What about the repeated work?
- Time complexity (number of generated nodes)
 - $[1+b] + [1+b + b^2] + .. + [1+b + b^2 + .. + b^d]$
 - $d+(d)b + (d-1) b^2 + ... + (1) b^d$
 - $O(b^d)$
- Repeated work is approximately $1/b$ of total work
 - Negligible
 - Example: $b=10, d=5$
 - $N(\text{BFS}) = 1,111,100$
 - $N(\text{DFID}) = 123,450$
- Features
 - Shortest solution, not necessarily least cost
 - Is there a better way to decide threshold?

Comparison of Search Techniques

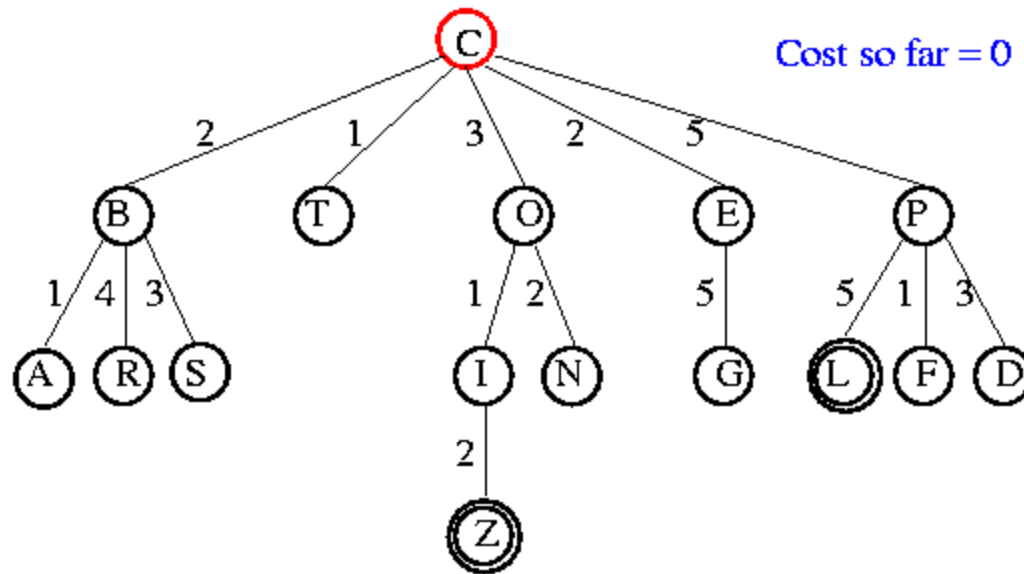
	DFS	BFS	DFID
Complete	N	Y	Y
Optimal	N	N	N
Heuristic	N	N	N
Time	b^m	b^{d+1}	b^d
Space	bm	b^{d+1}	bd

Uniform Cost Search

- QueueingFn is SortByCostSoFar
- Cost from root to current node n is $g(n)$
 - Add operator costs along path
- First goal found is least-cost solution
- Space & time can be exponential because large subtrees with inexpensive steps may be explored before useful paths with costly steps
- If costs are equal, time and space are $O(b^d)$
 - Otherwise, complexity related to cost of optimal solution

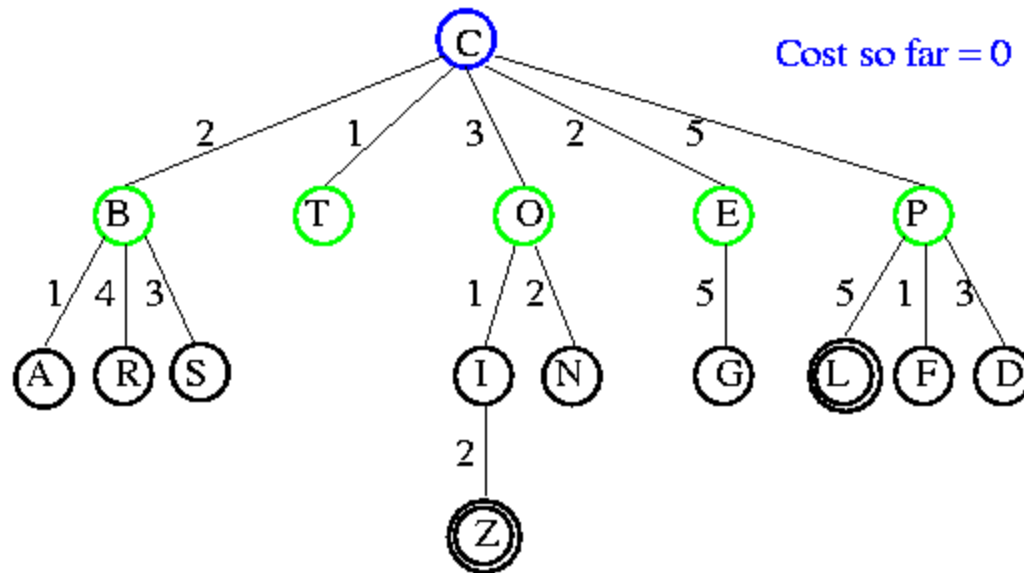


UCS Example



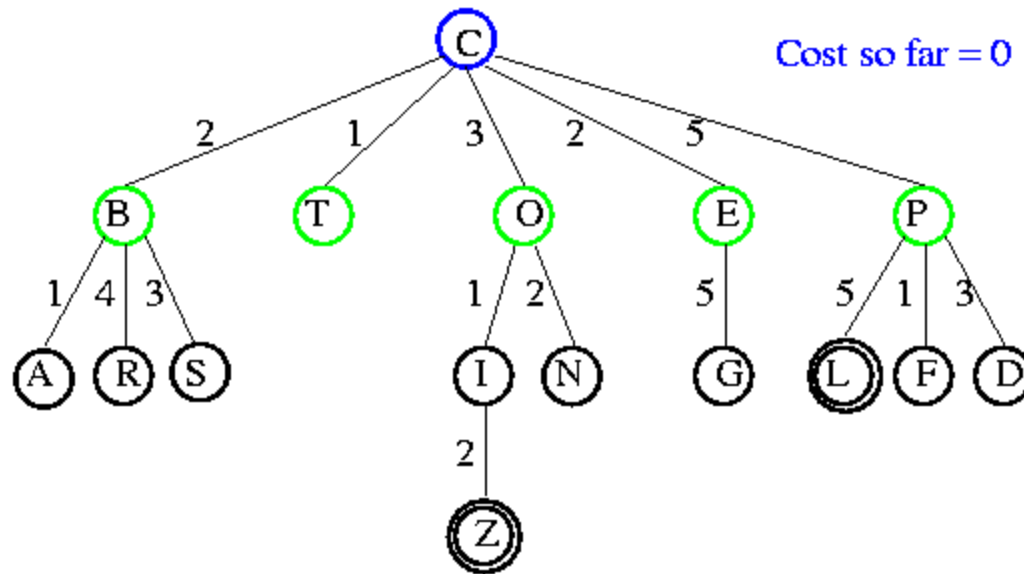
Open list: C

UCS Example



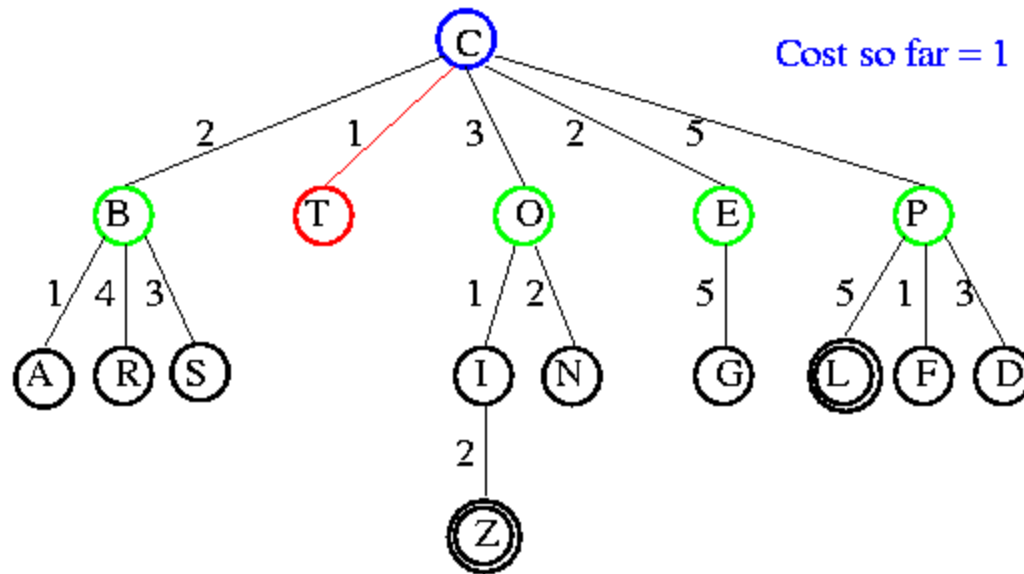
Open list: B(2) T(1) O(3) E(2) P(5)

UCS Example



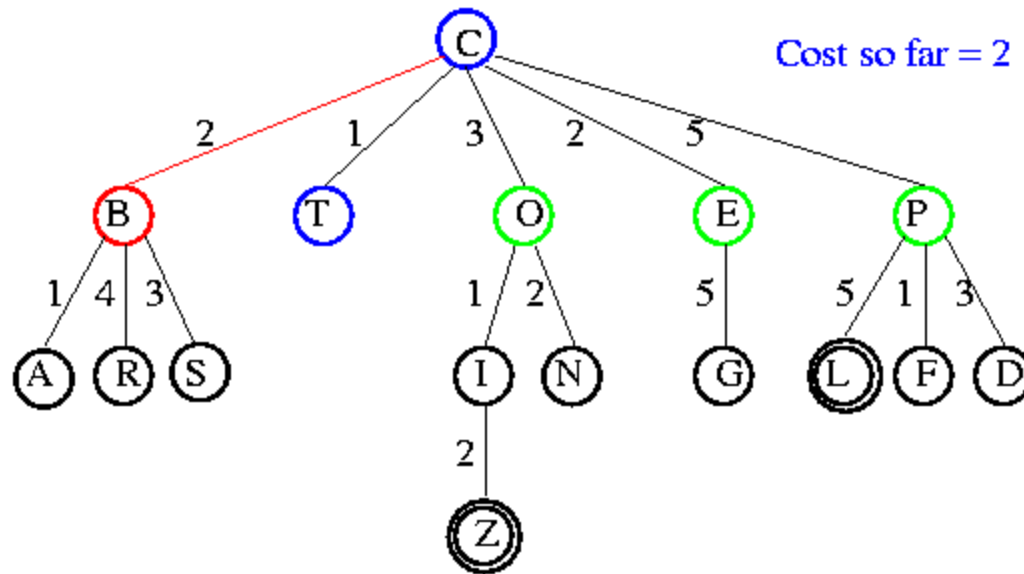
Open list: T(1) B(2) E(2) O(3) P(5)

UCS Example



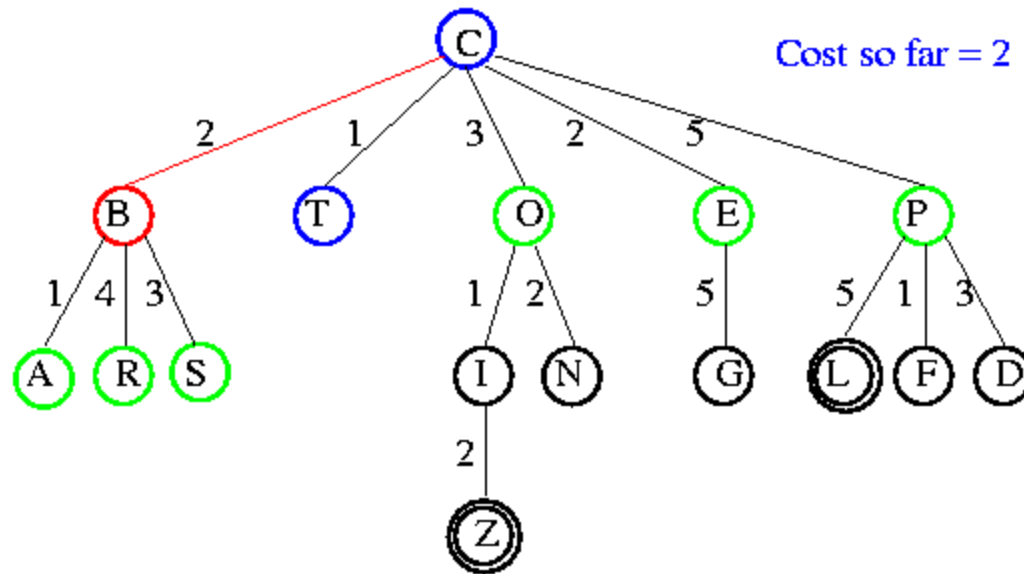
Open list: B(2) E(2) O(3) P(5)

UCS Example



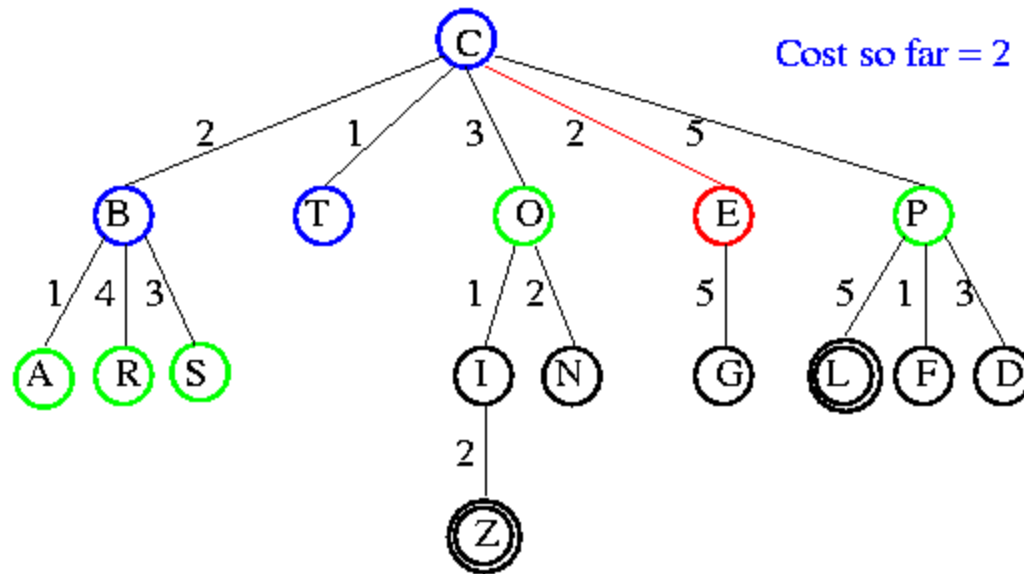
Open list: E(2) O(3) P(5)

UCS Example



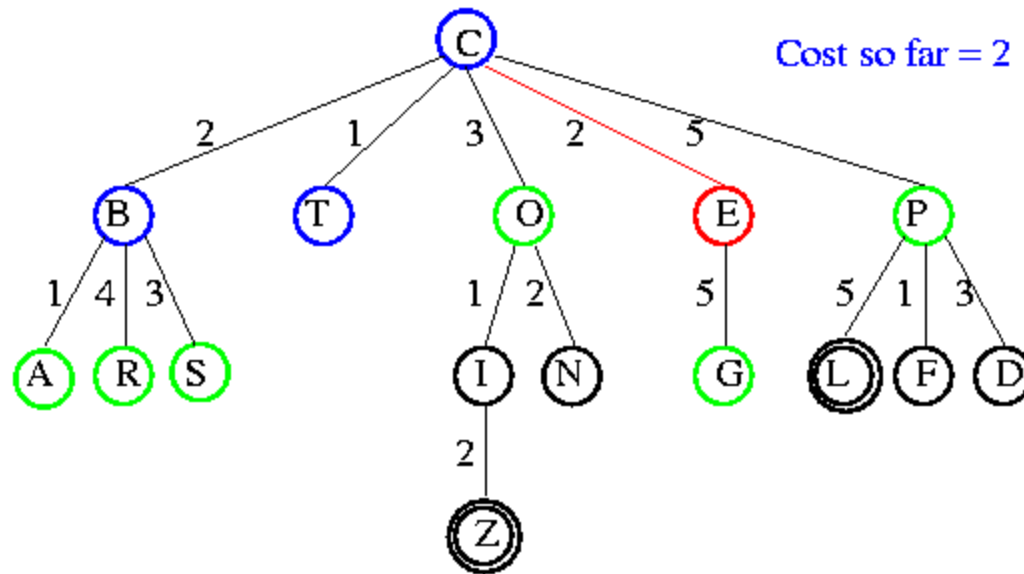
Open list: E(2) O(3) A(3) S(5) P(5) R(6)

UCS Example



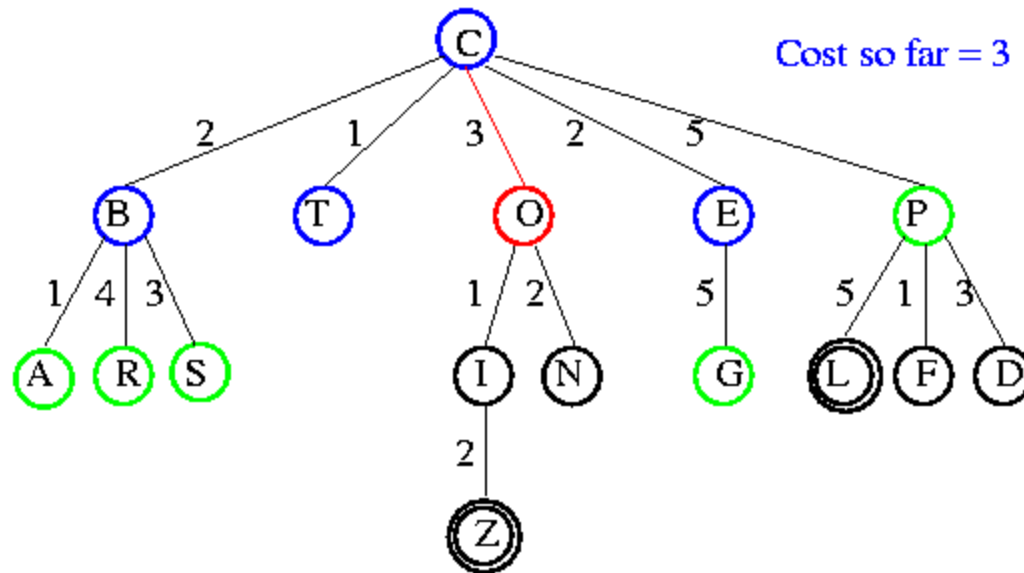
Open list: O(3) A(3) S(5) P(5) R(6)

UCS Example



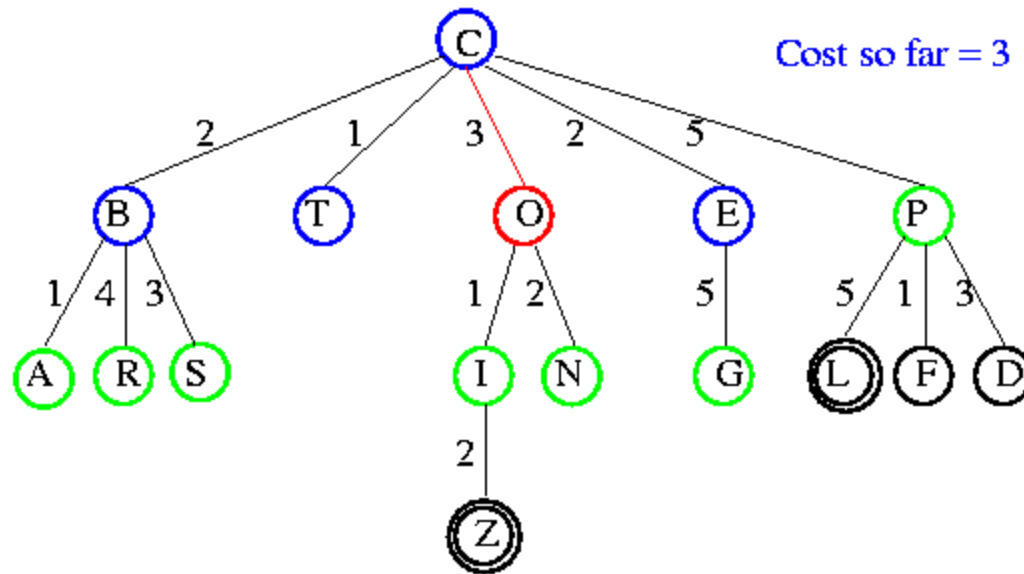
Open list: O(3) A(3) S(5) P(5) R(6) G(7)

UCS Example



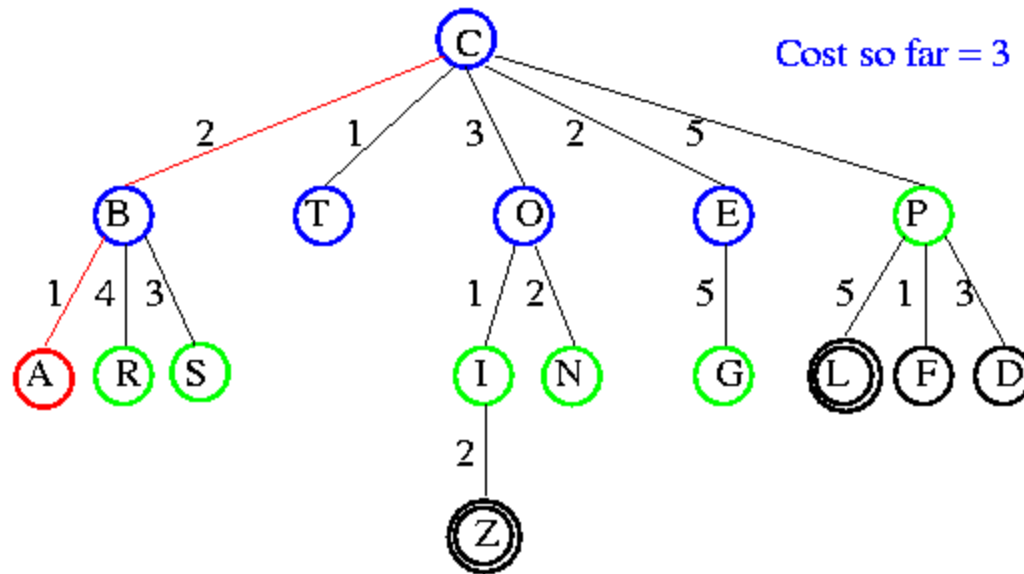
Open list: A(3) S(5) P(5) R(6) G(7)

UCS Example



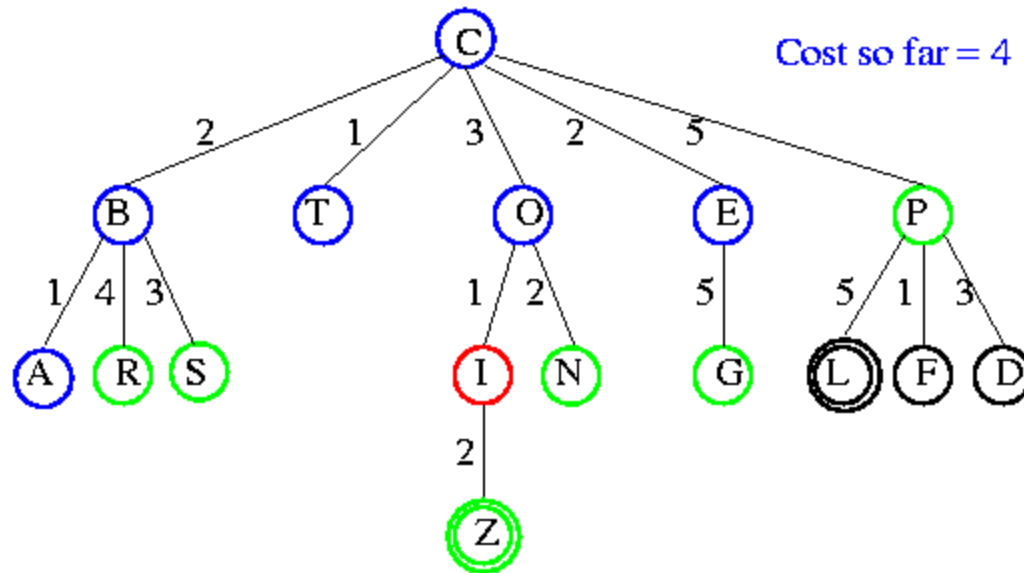
Open list: A(3) I(4) S(5) N(5) P(5) R(6) G(10)

UCS Example



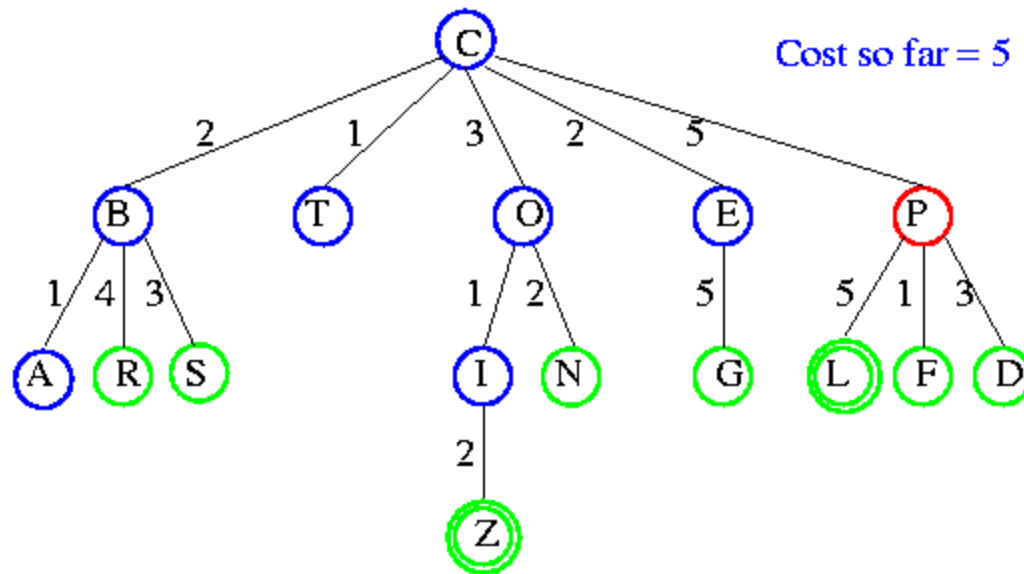
Open list: I(4) P(5) S(5) N(5) R(6) G(10)

UCS Example



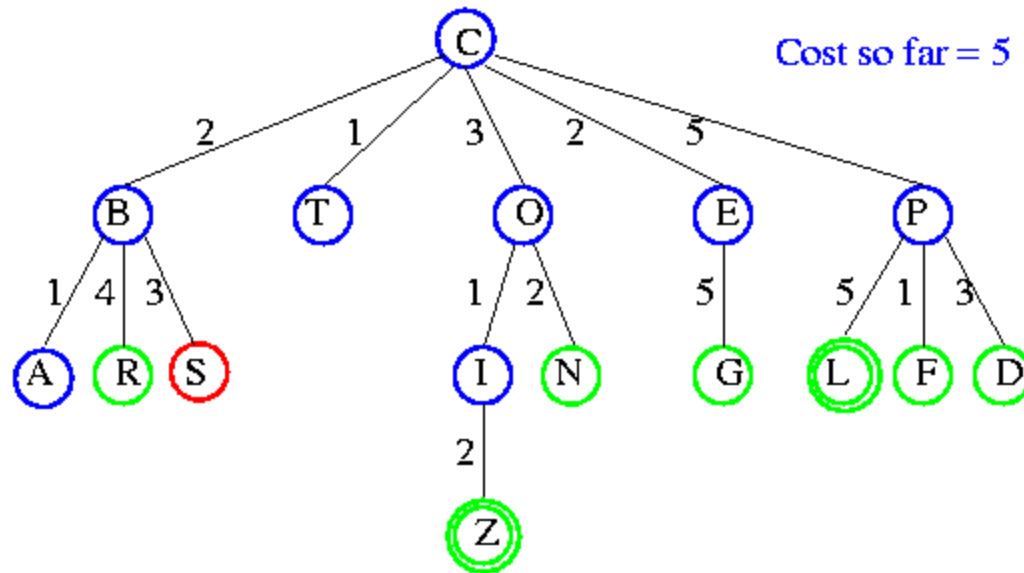
Open list: P(5) S(5) N(5) R(6) Z(6) G(10)

UCS Example



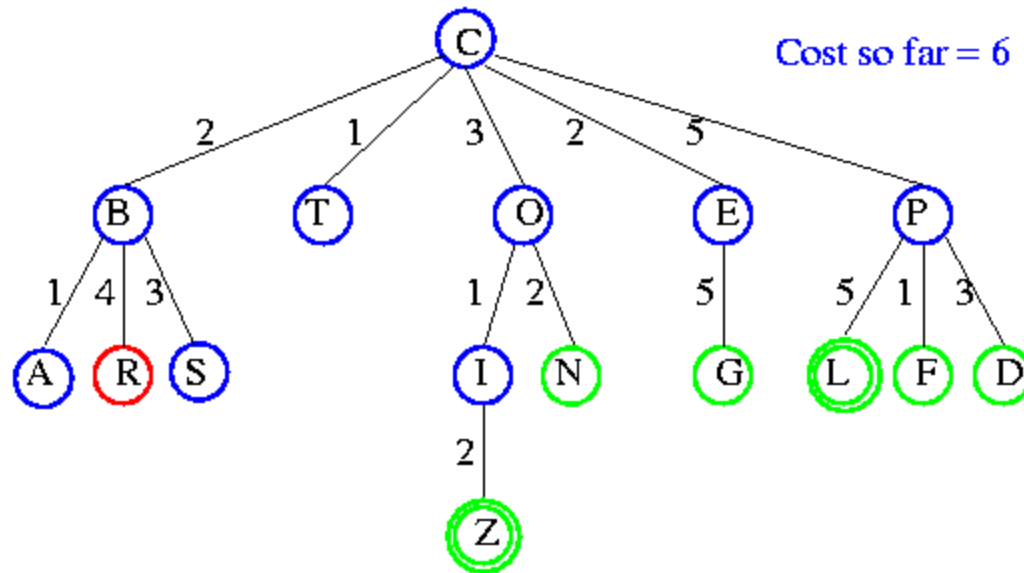
Open list: S(5) N(5) R(6) Z(6) F(6) G(7) D(8) L(10)

UCS Example



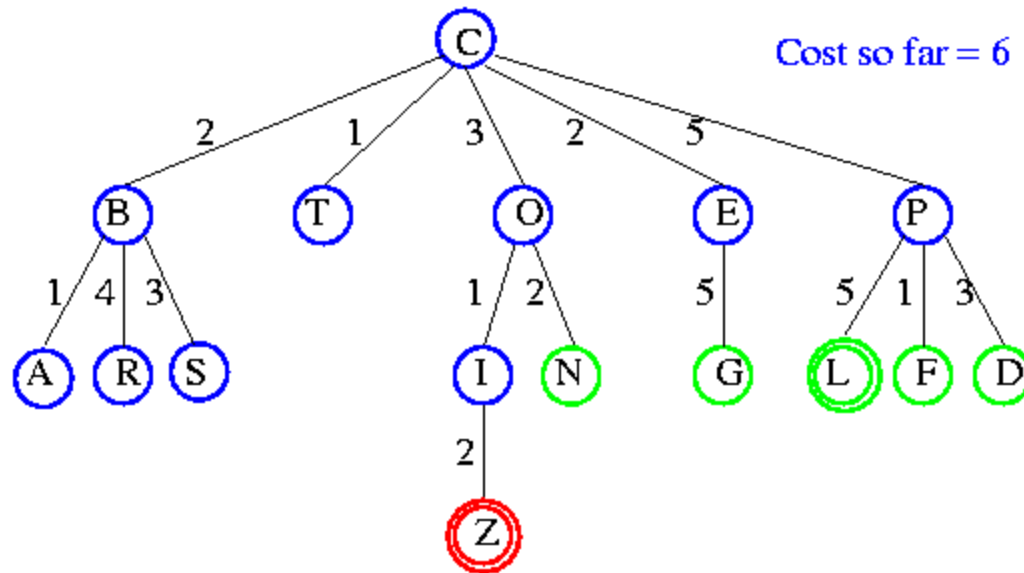
Open list: N(5) R(6) Z(6) F(6) D(8) G(10) L(10)

UCS Example



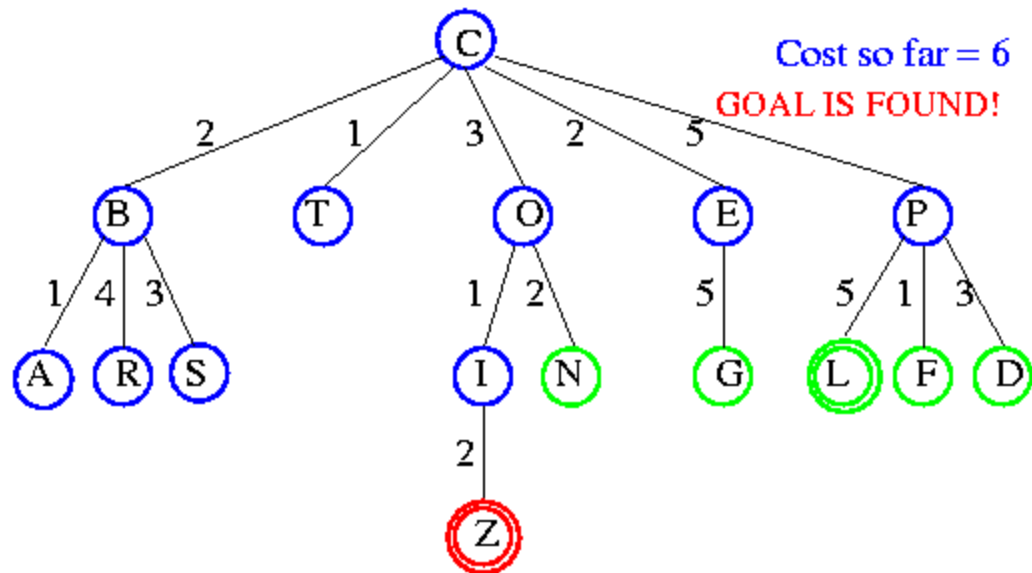
Open list: Z(6) F(6) D(8) G(10) L(10)

UCS Example



Open list: F(6) D(8) G(10) L(10)

UCS Example



Comparison of Search Techniques

	DFS	BFS	UCS	DFID
Complete	N	Y	Y	Y
Optimal	N	N	Y	N
Heuristic	N	N	N	N
Time	b^m	b^{d+1}	b^m	b^d
Space	bm	b^{d+1}	b^m	bd