# **VERIFICATION TEST PLAN**

# ECE-593: Fundamentals of Pre-Silicon Validation

Maseeh College of Engineering and Computer Science Winter 2025



Github link: <a href="https://github.com/naidumaheshchowdary/Team\_15\_Async\_FIFO">https://github.com/naidumaheshchowdary/Team\_15\_Async\_FIFO</a>

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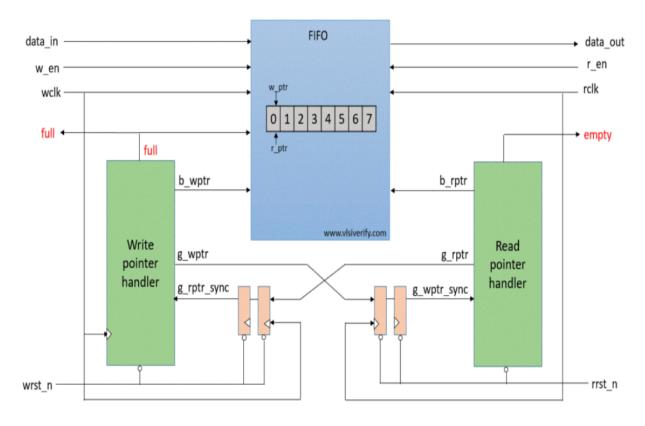
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# 2 Introduction:

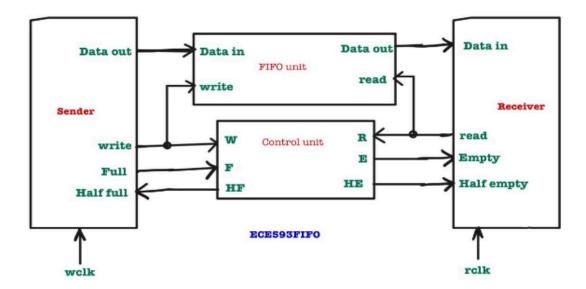
# 2.1 Objective of the verification plan

The objective of the verification plan is to ensure the Asynchronous FIFO correctly transfers data between independent write 120 MHz and read 50 MHz clock domains while maintaining data integrity. The testbench validates that data written into the FIFO is correctly read in a first-in, first-out (FIFO) manner. It checks that the full flag prevents writes when the FIFO is full and the empty flag blocks reads when empty. The design's ability to handle idle cycles (4 cycles between writes, 2 cycles between reads) is also verified. Random data is generated and stored in a queue expected\_data to compare with actual FIFO output rd\_data. The simulation runs through multiple iterations, ensuring FIFO functionality under different conditions before termination.

## 2.2 Top Level block diagram



Asynchronous FIFO



# 2.3 Specifications for the design

The design consists of a memory buffer, a write pointer, a read pointer, and control logic to handle data movement while preventing overflow and underflow conditions. The write pointer keeps track of the memory location where the next data item will be written, while the read pointer indicates the current location from which data should be read. Since the FIFO operates in two different clock domains i.e, Writing frequency of sender is 120MHz and Read Frequency of receiver is 50MHz, it is crucial to implement a synchronization mechanism to avoid metastability issues.

During initialization or reset, both the read and write pointers are set to zero, indicating that the FIFO is empty. Data is written to the location specified by the write pointer, and after every successful write operation, the pointer is incremented. Similarly, the read pointer moves forward after every read operation. The FIFO remains empty when both pointers are equal, and the empty flag is asserted to prevent unintended reads. When the write pointer wraps around and catches up with the read pointer, the FIFO is considered full, and the full flag is asserted to prevent additional writes.

One of the key challenges in asynchronous FIFO design is distinguishing between the full and empty states, as both occur when the read and write pointers are equal. To address this, an extra bit is added to each pointer, which toggles when the FIFO wraps around. If the extra bit of the write pointer differs from that of the read pointer, it indicates that the FIFO has wrapped around and is full. On the other hand, when both pointers, including the extra bit, are equal, the FIFO is empty. Another critical aspect of the design is the use of Gray-coded pointers for synchronization. When transferring data between different clock domains, binary counters can lead to metastability because multiple bits may change simultaneously. Using Gray code ensures that only one bit changes at a time, reducing the likelihood of metastability and improving the stability of pointer synchronization.

The design also includes logic to handle overflow and underflow conditions. When the FIFO is full, additional write operations are ignored to prevent data corruption. Likewise, when the FIFO is empty, read operations are blocked to avoid retrieving invalid data. The FIFO operates efficiently by ensuring that the read pointer always points to the next valid data, minimizing the number of clock cycles required for data retrieval.

Overall, the design of the Asynchronous FIFO focuses on efficient memory utilization, proper synchronization, and robust pointer management to provide reliable data transfer across different clock domains.

# 3 Verification Requirements

## 3.1 Verification Levels

- 3.1.1 What hierarchy level are you verifying and why?
  - The code is verifying the module-level functionality of the asynchronous FIFO.
  - This is the initial stage (Checkpoint 1), where the focus is on basic read/write operations, pointer behavior, and flag assertions (full/empty).
- 3.1.2 How is the controllability and observability at the level you are verifying?
- 3.1.3 Are the interfaces and specifications clearly defined at the level you are verifying. List them.
  - Yes, the interfaces are clearly defined:

### Inputs:

- wr\_en, wr\_clk, wr\_reset, wr\_data (write interface).
- rd\_en, rd\_clk, rd\_reset (read interface).

### Outputs:

- rd\_data (read data).
- fifo\_full (full flag).
- fifo\_empty (empty flag).

# 4 Required Tools

4.1 List of required software and hardware toolsets needed.

The Siemens EDA Questa tool is utilized for SystemVerilog simulation in an object-oriented programming (OOP)-based verification environment.

4.2 Directory structure of your runs, what computer resources you will be using.

# 5 Risks and Dependencies

5.1 List all the critical threats or any known risks. List contingency and mitigation plans.

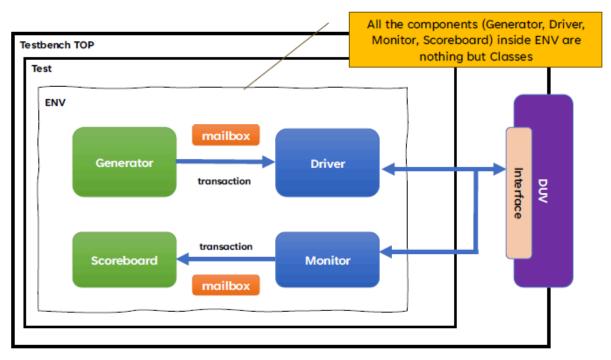
# 6 Functions to be Verified.

- 6.1 Functions from specification and implementation
- 6.1.1 List of functions that will be verified. Description of each function
  - Basic Write/Read: Ensure data is written and read correctly.
  - Full/Empty Flags: Verify FIFO full and empty conditions.

- Pointer Increment: Check write and read pointer updates.
- Reset Operation: Ensure FIFO initializes correctly.
- Cross-Clock Sync: Validate data transfer between clock domains.
- Concurrent R/W: Test simultaneous read and write operations.
- 6.1.2 List of functions that will not be verified. Description of each function and why it will not be verified.
  - Error Handling: Overflow/underflow checks deferred.
  - Power-On Reset: Advanced verification for later.
  - Performance Metrics: Throughput/latency not tested yet.
- 6.1.3 List of critical functions and non-critical functions for tapeout

# 7 Tests and Methods

- 7.1.1 Testing methods to be used: Black/White/Gray Box.
- 7.1.2 State the PROs and CONs for each and why you selected the method for this DUV.
- 7.1.3 Testbench Architecture; Component used (list and describe Drivers, Monitors, scoreboards, checkers etc.)



SystemVerillog testbench architecture

In digital design verification, a SystemVerilog testbench is a structured environment that simulates real-world conditions to test a Design Under Test (DUT). It follows a transaction-based verification approach, where stimulus is generated, applied to the DUT, and results are checked automatically. The testbench consists of several components, each performing a specific role. These components interact using mailboxes, which facilitate communication between

different testbench blocks. The testbench is designed using Object-Oriented Programming (OOP) principles, making it modular, reusable, and scalable.

### Testbench:

At the highest level, the Testbench is the top module that connects the Test and DUT using an Interface. It is responsible for generating the clock and initializing the test environment.

## **Environment:**

The Test component creates the Environment and sets the number of transactions to be generated. The Environment is the heart of the testbench, containing all major verification components: Generator, Driver, Monitor, Scoreboard, and Transaction.

It facilitates the interaction between these components, ensuring proper synchronization and execution of transactions.

### **Generator:**

The Generator is responsible for creating test stimulus by randomizing transaction data. It sends these transactions to the Driver using a Mailbox. Additionally, the Generator includes an event mechanism to signal the completion of packet generation using a triggering mechanism.

#### **Driver:**

The Driver receives transactions from the Generator, converts them into signal-level activity, and applies them to the DUT via the Interface. It ensures that the correct signals are driven and tracks the number of packets processed during the simulation.

#### Monitor:

The Monitor passively observes the DUT's response by sampling interface signals. It converts the captured signals into transaction-level data and forwards them to the Scoreboard via a Mailbox. The Monitor is a passive component and does not drive signals, ensuring a non-intrusive verification methodology.

### Scoreboard:

The Scoreboard is responsible for checking the correctness of the DUT's output. It compares the actual response received from the Monitor with the expected results. If there is a mismatch, it reports an error. This component plays a critical role in ensuring functional correctness.

### Interface:

The Interface acts as a bridge between the testbench and DUT. It groups multiple signals into a single structured entity, simplifying the connection. A virtual interface allows the same code to be reused for different DUT configurations, making the testbench more flexible and scalable.

## Mailbox:

A Mailbox is a SystemVerilog built-in feature that facilitates communication between different testbench components. It temporarily stores transactions in system memory, enabling synchronization between components. This testbench uses two mailboxes:

- 1. Generator → Driver
- 2. Monitor  $\rightarrow$  Scoreboard

Mailboxes ensure that transactions are transferred efficiently, maintaining the testbench's modularity

### **Transaction:**

The Transaction class defines the structure of the data used in the testbench. It includes fields required to generate test stimulus, and the rand keyword is used to create randomized inputs. This randomization technique improves test coverage by allowing a variety of test cases to be generated dynamically.

- 7.1.4 Verification Strategy: (Dynamic Simulation, Formal Simulation, Emulation etc.) Describe why you chose the strategy.
- 7.1.5 What is your driving methodology?
- 7.1.5.1 List the test generation methods (Directed test, constrained random) we have used Constraint Random method.
- 7.1.6 What will be your checking methodology?
- 7.1.6.1 From specification, from implementation, from context, from architecture etc

## 7.1.7 Testcase Scenarios (Matrix)

### 7.1.7.1 Basic Tests

TESTCASE	DESCRIPTION	EXPECTED OUTCOME	
Reset Functionality	Verify that when the reset signals are activated, all FIFO internal states, including pointers and status flags, are reset to their default values.	The FIFO should clear all stored data, reset both read and write pointers, and assert the empty flag while deasserting full and half-full indicators.	
Basic Write and Read Operations	Ensure that data written to the FIFO is correctly stored and retrieved in the same order when read operations occur.	Each read should return the corresponding previously written data, maintaining the FIFO order. The empty and full flags should update accordingly during operations.	
Write pointer	Validate that the write pointer incre- ments only when a write operation occurs and stops when the FIFO	The write pointer should advance with each valid write cycle and should halt once the FIFO is full, asserting the full	

	reaches full capacity.	flag.
Read Pointer	correctly when data is read from the	The read pointer should advance with each valid read operation and should stop when the FIFO is empty, asserting the empty flag.

## 7.1.7.2 Complex Tests

me / Number	scription/ Features
	rent events (R+W)
	pns: fifo_full/fifo_empty/always_full/always empty etc.

### 7.1.7.3 Regression Tests (Must pass every time)

me / Number	scription/Features	
	at should always pass	

## 7.1.7.4 Any special or corner cases testcases

me / Number	scription	
	Case testing tests and conditions	
	ction and testing scenario	

# 8 Coverage Requirements

8.1.1.1 Describe Code and Functional Coverage goals for the DUV

Functional coverage plays a vital role in ensuring that the FIFO operates correctly across all possible scenarios. It verifies that the design meets its intended specifications and behaves as expected under different conditions. The coverage model is implemented using SystemVerilog covergroups, where each functional aspect is represented as a coverpoint to ensure complete verification. The key functional areas covered are described below.

- <u>Read and Write Transactions</u>: Validates that data is written into the FIFO and retrieved in the same order, ensuring proper storage and retrieval functionality.
- <u>Boundary Conditions</u>: Tests FIFO behavior when it is full, empty, half-full, and half-empty to verify correct assertion of wfull and rempty flags.
- <u>Clock Domain Crossing</u>: Ensures seamless data transfer across asynchronous write and read clocks, preventing metastability issues.

- <u>Control Signals</u>: Confirms that wr\_en and rd\_en operate as expected and that status flags (wfull, rempty, half wfull, half rempty) activate correctly.
- Reset Behavior: Ensures that applying wrst or rrst resets all pointers and status flags to their default values.
- <u>Back-to-Back Transactions</u>: Verifies FIFO functionality under continuous high-speed read and write operations without data corruption.

By covering these scenarios, the verification strategy guarantees a robust and fully functional FIFO design. In our verification, the achieved functional coverage is 83.33%, ensuring that the FIFO meets the expected performance criteria.

Code coverage analysis was conducted to evaluate how effectively the FIFO RTL design was exercised during verification. The current achieved total coverage stands at 46.01%, indicating a significant portion of the design has been tested. However, our target is to achieve at least 53.48% coverage to ensure a more rigorous and comprehensive validation of the design.

- <u>Statement Coverage</u>: Ensured 96.34% of all executable lines in the RTL were exercised at least once.
- <u>Branch Coverage:</u> Verified all decision points (if-else, case statements) were tested under both true and false conditions, achieving 50% coverage.
- FSM Coverage: Ensured all FIFO state transitions were visited and exercised.
- <u>Toggle Coverage</u>: Verified that all flip-flops, registers, and storage elements toggled between 0 and 1 at least once, achieving 37.73% coverage.

To achieve this, we have already implemented constrained-random stimulus generation, which introduces variability in test scenarios, covering a broader range of operational conditions. Moving forward, we will further enhance our randomization constraints, introduce additional corner-case scenarios, and refine our test plan to improve coverage in unexplored branches, and toggle conditions. This approach will help close the coverage gap while maintaining an efficient and scalable verification environment.

8.1.1.2 Formulate conditions of how you will achieve the goals. Explain the Covergroups and Coverpoints and your selection of bins.

To improve code coverage from 53.48% to 83%, we will refine constrained-random testing to generate diverse inputs, ensuring better branch and condition coverage. Directed test cases will be added to target untested logic, while toggle coverage will be enhanced by activating rarely toggled signals, particularly in corner cases. Functional coverage will be strengthened using covergroups and coverpoints, ensuring all critical FIFO behaviors are tested.

#### 8.1.2 Assertions

8.1.2.1 Describe the assertions that you are planning to use and how it will help you improve the overall coverage and functional aspects of the design.

# 9 Resources requirements

- 9.1 Team members and who is doing what and expertise.
  - Mahesh Naidu: Led the development of the top-level module, ensuring proper parameterization and integration of internal components. Designed and implemented the clock generation and reset logic, guaranteeing correct synchronization and initialization. Integrated the FIFO module with the testbench, streamlining simulation and verification efforts.
  - Venkata Sai Dhilli: Focused on functional verification, creating and executing test cases to validate data flow, flag operations, and reset behavior. Analyzed coverage reports to identify untested scenarios and enhance test completeness. Debugged issues encountered during simulation to ensure FIFO operates reliably under all conditions.
  - Alaina Anand Nekuri: Developed a coverage-driven verification approach, implementing checks for statement, branch, and expression coverage. Worked closely with the team to optimize test strategies, ensuring comprehensive scenario validation. Compiled verification documentation, detailing test methodologies and outcomes.
  - Siddhartha Kaushik Gatta: Studied the FIFO design specifications and created the scoreboard class to validate read and write operations. Implemented logic for handling half-full, half-empty, full, and empty states, ensuring accurate condition monitoring. Designed the interface for the testbench, managing signal connections and clock synchronization. Led efforts in functional coverage modeling, ensuring all critical behaviors were thoroughly tested.

# 10 Schedule

10.1 Create a table with a plan of completion. You can use milestones as a guide to fill this.

	Tasks	Timeline
1	Design specs, Verification Plan, RTL implementation, basic testbench.	Week 1-4

2	Class-based TB, transactions, generator, driver, randomized data tests.	Week 4-7
3	Finalize RTL, complete class-based TB, coverage reports.	Week 8-10
4	Develop UVM TB, add UVM plan, implement logging.	Week 11-13
5	Complete UVM TB, final coverage, bug injection, final docs, presentation.	Week 14-16

# 11 References Uses / Citations/Acknowledgements

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