

# BUTCHI VENKATESH ADARI

 +1 7746707192  badari@wpi.edu  linkedin.com/in/abven  https://github.com/VenkateshRoshan

## Education

### Masters in Robotics Engineering - GPA:3.8/4.0

Worcester Polytechnic Institute

Aug 2023 - May 2025 (Expected)

Worcester, Massachusetts

### PG Certification of AI & ML

IIT Guwahati (Remote)

June 2020 - May 2021

### Bachelors in Computer science and Engineering - GPA:7.77/10

Anil Neerukonda Institute of Technology and Sciences

July 2017 - May 2021

Visakhapatnam, India

## Experience

### ELPIS LAB | Worcester Polytechnic Institute

#### Graduate Researcher

Jan 2024 - Ongoing

Currently working on a project focused on fine-tuning Apple's Depth-Pro model for monocular depth estimation, reduced error from 10 cm to 3-4 cm. Developed a Grasp Transformer to predict grasp poses from RGB images and predicted monocular depth, with testing ongoing in PyBullet simulation and planned implementation on Universal Robot UR10.

### Tata Consultancy Services | Hyderabad, India

#### Machine Learning Engineer

May 2022 - June 2023

Designed and implemented a Computer Vision Pipeline for real-time object search using Google Vertex AI, integrating Continuous Integration and Continuous Deployment practices, and fine-tuned custom OCR models for extracting text from complex document layouts, improving document processing efficiency.

#### Python Developer

July 2021 - April 2022

Partnered with Proximus and Vodafone clients to optimize data processing, analysis, and automation workflows, leading to more efficient script execution and reduced processing times.

### Machine Learning Intern | Innovidu

May 2020 - June 2020

Conducted an in-depth analysis of Titanic survivor data using Exploratory Data Analysis (EDA), identifying Random Forest as the most effective algorithm for classification with minimal false discovery.

## Projects

### Research Paper Analysis System with RAG Architecture and MLOps

Oct 2024 - Dec 2024

- Architected an end-to-end Research Paper Analysis System using RAG and LLMs, processing paper's abstract with FAISS and Flan-T5, achieving sub-second query responses.
- Implemented a production-grade MLOps pipeline with FastAPI microservices, Docker containerization, and deployment on Google Cloud Vertex AI, ensuring scalable and efficient processing.
- Developed automated CI/CD workflows with GitHub Actions, utilizing GCP service accounts for seamless integration and deployment, and built a responsive Gradio UI for real-time paper analysis and queries.

### Real-Time Customer Support Chatbot | LLM, NLP, CI/CD, AWS SageMaker, MLflow

Oct 2024 - Nov 2024

- Built and fine-tuned a Large Language Model Chatbot for customer support, delivering accurate real-time responses for diverse customer queries while tracking experiments and metrics using MLflow.
- Implemented CI/CD pipelines for AWS SageMaker deployment, enabling scalable production environments with robust version control and continuous model improvements.

### Image Captioning with Vision Transformer and GPT-2 | AWS, ViT, NLP, CI/CD

Aug 2024 - Oct 2024

- Developed an image captioning model combining Vision Transformer and GPT-2, integrating visual feature extraction with natural language processing to generate accurate and contextually relevant image captions.
- Integrated CI/CD pipelines for automated deployment on AWS and Hugging Face, ensuring scalability and reliability while enabling real-time caption generation and version control.

### High-Fidelity 3D Scene Reconstruction Using NeRF | Machine Learning, Computer Vision

Mar 2024 - Apr 2024

- Implemented a neural radiance fields (NeRF) model to reconstruct photorealistic 3D scenes from 2D images, enhancing rendering accuracy and depth perception using PyTorch.

### Indoor Robot Navigation | Motion Planning, Computer Vision, Perception

Sep 2023 - Dec 2023

- Assessed traditional algorithms like RRT and RRT\* alongside reinforcement learning-based end-to-end action strategies for indoor robot navigation in habitat environments.

### Self Driving Car | Deep Learning, Computer Vision

Jan 2021 - May 2021

- Developed and deployed a custom object detection model on a Raspberry Pi 4, enabling real-time detection of traffic signs, pedestrians, and obstacles with 94% accuracy.
- Integrated the model into a miniature vehicle for autonomous navigation in a controlled environment.

**Voice Comparer** | *Deep Learning Neural Networks , Kivy , Tensorflow , SQL*

**Dec 2019 - Mar 2020**

- Using a dataset for voice analysis and designed a user interface software using the Kivy framework and inferred model using Neural Networks to compare voice recordings, and achieved a 91% accuracy rate.

## Technical Skills

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**Languages:** Python, C++, Java, C, SQL

**Developer Tools:** VS Code, Android Studio, Firebase, MySQL, Git, Blender

**Technologies/Frameworks:** Tensorflow, PyTorch, Hugging Face, Linux, OpenCV, CI/CD , GCP, VertexAI, Docker, AWS, LangChain.

## Certifications/Courses

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**Coursera:** Neural Networks and Deep Learning by Andrew Ng, Deep Learning Specialisation.

**Microsoft:** End-to-end machine learning operations (MLOps) with Azure Machine Learning.