

Review of Probability Theory Part 2



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Fundamentals of Reinforcement Learning

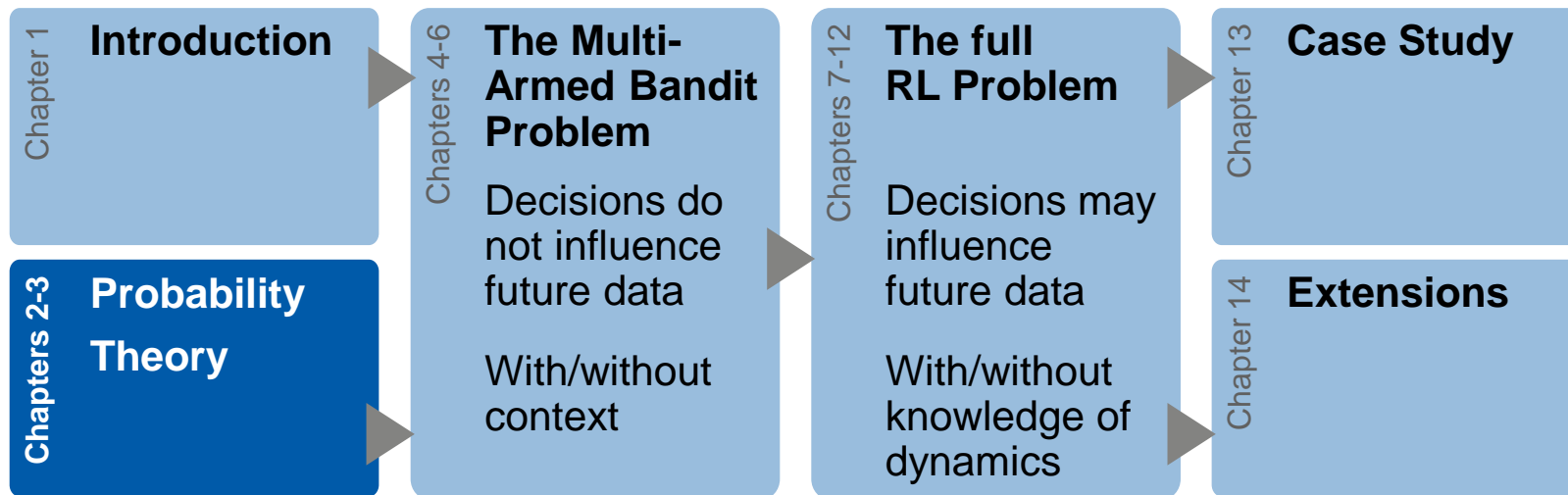
Institut für Nachrichtentechnik

Fachgebiet Kommunikationstechnik

Prof. Dr.-Ing. Anja Klein

Dr. Sabrina Klos & Dr. Andrea Ortiz

Lecture Overview





Learning Goals

- You can determine characteristics of continuous random variables and relate important examples to their applications.
- You can apply the formulas for multiple random variables and operations on random variables to compute probabilities, distributions, expectation and variance.
- You can distinguish the fundamental concepts of statistics and apply results and formulas for point estimation and confidence intervals.

Outline

- Continuous Random Variables
- Multiple Random Variables
- Operations on Random Variables
- Statistics



Recap: Random Variables (RVs)

RVs link sample spaces and events to data

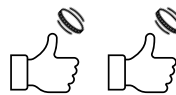
Definition (Random Variable)

A **random variable (RV)** is a function $X : \Omega \rightarrow \mathcal{X}$ that assigns an element of \mathcal{X} to each $\omega \in \Omega$.

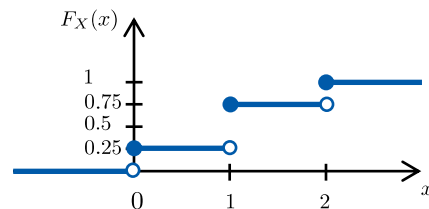
- The distribution of an RV X can be completely determined by its **cumulative distribution function (CDF)**

$$F_X(x) := \mathbb{P}(X \leq x).$$

- Example:** $X(\omega)$: Number of “heads” in 2 coin tosses



$$\begin{aligned} \mathbb{P}(X = 0) &= \mathbb{P}(TT) = \frac{1}{4} \\ \mathbb{P}(X = 1) &= \mathbb{P}(HT, TH) = \frac{1}{2} \\ \mathbb{P}(X = 2) &= \mathbb{P}(HH) = \frac{1}{4} \end{aligned} \quad \Rightarrow \quad F_X(x) = \begin{cases} 0 & x < 0 \\ \frac{1}{4} & 0 \leq x < 1 \\ \frac{3}{4} & 1 \leq x < 2 \\ 1 & x \geq 2 \end{cases}$$





Recap: Discrete Random Variables (RVs)

RVs with countably many values


Definition (Discrete Random Variable)

A random variable X is **discrete** if it takes only countably many values $\{x_1, x_2, \dots\}$.

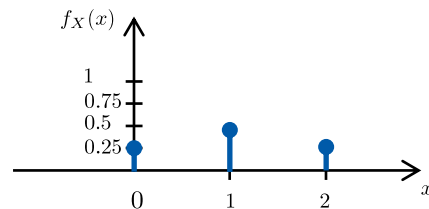
Definition (Probability Mass Function)

For a discrete random variable X , we define the **probability mass function (PMF)** of X by

$$f_X(x) := \mathbb{P}(X = x).$$

- Example:** $X(\omega)$: Number of “heads” in 2 coin tosses 

$$\begin{aligned} \mathbb{P}(X = 0) &= \mathbb{P}(TT) = \frac{1}{4} \\ \mathbb{P}(X = 1) &= \mathbb{P}(HT, TH) = \frac{1}{2} \\ \mathbb{P}(X = 2) &= \mathbb{P}(HH) = \frac{1}{4} \end{aligned} \quad \Rightarrow \quad f_X(x) = \begin{cases} \frac{1}{4} & x = 0 \\ \frac{1}{2} & x = 1 \\ \frac{1}{4} & x = 2 \\ 0 & x \notin \{0, 1, 2\} \end{cases}$$



- **Continuous Random Variables**
- Multiple Random Variables
- Operations on Random Variables
- Statistics

Continuous RVs and Probability Density Functions

RVs with a density

We also consider RVs with an uncountable number of values in $\mathcal{X} = \mathbb{R}$.

Definition (Continuous Random Variable and Probability Density Function)

A random variable X is **continuous** if there exists a function f_X such that $f_X(x) \geq 0$ for all x , $\int_{-\infty}^{\infty} f_X(x)dx = 1$ and for every $a \leq b$,

$$\mathbb{P}(a < X < b) = \int_a^b f_X(x')dx'.$$

The function f_X is called the **probability density function (PDF)**. We have that

$$F_X(x) = \int_{-\infty}^x f_X(x')dx'$$

and $f_X(x) = \frac{dF_X(x)}{dx}$ at all points x at which $F_X(x)$ is differentiable.

- **Note:** For a continuous random variable X , $\mathbb{P}(X = x) = 0$ for all x .

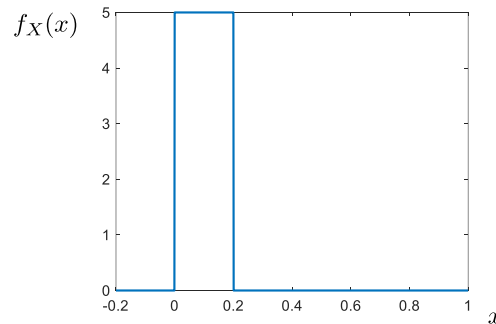
Important Continuous Random Variables

Example: Uniform Distribution

Definition (Uniform Distribution)

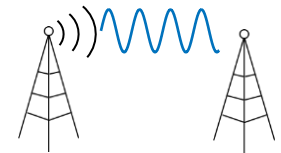
A random variable X has a **(continuous) uniform distribution** on the interval $[a, b]$, written $X \sim \mathcal{U}(a, b)$, if it has the PDF

$$f_X(x) = \begin{cases} \frac{1}{b-a} & \text{for } x \in [a, b] \\ 0 & \text{otherwise.} \end{cases}$$



Uniform distribution on $[0, 0.2]$

- **Application:** Can be used to model the belief of a receiver about the unknown phase of a transmitted radio frequency sinusoid in a communications system.



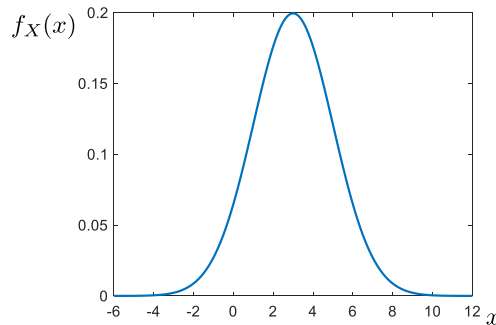
Important Continuous Random Variables

Example: Normal/Gaussian Distribution

Definition (Normal/Gaussian Distribution)

A random variable X has a **Normal/Gaussian distribution** with parameters $\mu \in \mathbb{R}$ and $\sigma > 0$, written $X \sim \mathcal{N}(\mu, \sigma^2)$, if it has the PDF

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma^2}(x - \mu)^2\right).$$



The Normal distribution is very important:

- Many quantities can be approximated by a normal distribution.
- It has convenient mathematical properties.
- **Application:** Can be used to model e.g., noise in wireless communication channels and thermal noise in electronic circuits.

Normal distribution with $\mu = 3, \sigma = 2$

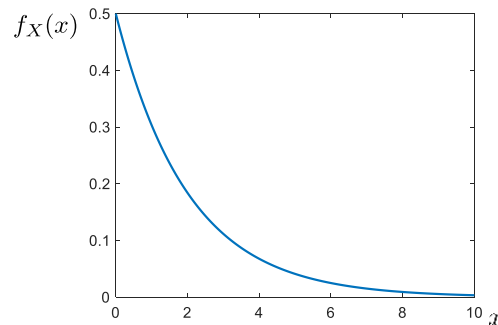
Important Continuous Random Variables

Example: Exponential Distribution

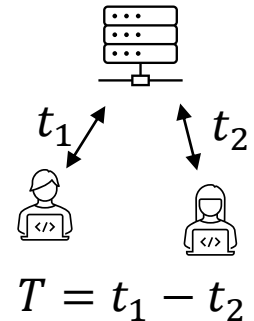
Definition (Exponential Distribution)

A random variable X has an **Exponential** distribution with parameter $\lambda > 0$, written $X \sim \text{Exp}(\lambda)$, if it has the PDF

$$f_X(x) = \lambda e^{-\lambda x} \quad \text{for } x > 0.$$



- **Application:** Can be used to describe the waiting time for a memoryless process, e.g., the interarrival times between independent accesses to a server.



Exponential distribution with $\lambda = 2$

- Continuous Random Variables
- **Multiple Random Variables**
- Operations on Random Variables
- Statistics

Joint Distributions

Joint distribution functions characterize the joint distribution of multiple RVs

Definition (Joint Distribution and Joint Density Function)

- For n random variables X_1, X_2, \dots, X_n , the function

$$F_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) = \mathbb{P}(X_1 \leq x_1, X_2 \leq x_2, \dots, X_n \leq x_n)$$

is called the **joint (cumulative) distribution function (joint CDF)**.

- In the discrete case, we define the **joint (probability) mass function (joint PMF)** by

$$f_{X_1, X_2, \dots, X_n}(x_1, \dots, x_n) := \mathbb{P}(X_1 = x_1, \dots, X_n = x_n).$$

- In the continuous case, we call a function $f_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n)$ a **joint (probability) density function (joint PDF)** if

- $f_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) \geq 0$ for all (x_1, x_2, \dots, x_n)
- $\int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} f_{X_1, \dots, X_n}(x_1, \dots, x_n) dx_1 \dots dx_n = 1$
- For any $A \subset \mathbb{R}^n$: $\mathbb{P}((X_1, X_2, \dots, X_n) \in A) = \int_A f_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n$

Marginal Distributions

Marginal distribution functions characterize the distribution of one of multiple RVs

Definition (Marginal Distribution Function)

- Let $F_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n)$ denote the joint distribution of X_1, X_2, \dots, X_n . The **marginal distribution function** of X_i is given by

$$F_{X_i}(x_i) = \lim_{\substack{x_j \rightarrow \infty \\ j=1, \dots, i-1, i+1, \dots, n}} F_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n).$$

- In the discrete case, the **marginal mass function** for X_i is defined by

$$f_{X_i}(x_i) := \mathbb{P}(X_i = x_i) = \sum_{x_1} \cdots \sum_{x_{i-1}} \sum_{x_{i+1}} \cdots \sum_{x_n} f_{X_1, \dots, X_n}(x_1, \dots, x_n).$$

- In the continuous case, we obtain the **marginal density function** by

$$f_{X_i}(x_i) = \int_{\mathbb{R}^{n-1}} f_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) dx_1 \dots dx_{i-1} dx_{i+1} \dots dx_n.$$

- Marginals can be defined for any subset of the RVs X_1, X_2, \dots, X_n .

Joint and Marginal Distributions

Example: A bivariate distribution for two discrete RVs

Here is a bivariate distribution for two discrete RVs X, Y each taking values 0 or 1:

	Y=0	Y=1	
X=0	1/9	2/9	1/3
X=1	2/9	4/9	2/3
	1/3	2/3	1

- The inner part of the table shows the joint mass function $f_{X,Y}(x, y) = \mathbb{P}(X = x, Y = y)$.

- The row totals show the marginal mass function of X

$$f_X(x) = \mathbb{P}(X = x) = \sum_y f_{X,Y}(x, y).$$

- The column totals show the marginal mass function of Y

$$f_Y(y) = \mathbb{P}(Y = y) = \sum_x f_{X,Y}(x, y).$$



Question

What are the probabilities $\mathbb{P}(X = 1, Y = 1), \mathbb{P}(X = 1), \mathbb{P}(Y = 1)$?

Here is a bivariate distribution for two discrete RVs X, Y each taking values 0 or 1:

	Y=0	Y=1	
X=0	1/9	2/9	1/3
X=1	2/9	4/9	2/3
	1/3	2/3	1

- The inner part of the table shows the joint mass function $f_{X,Y}(x, y) = \mathbb{P}(X = x, Y = y)$.

- The row totals show the marginal mass function of X

$$f_X(x) = \mathbb{P}(X = x) = \sum_y f_{X,Y}(x, y).$$

- The column totals show the marginal mass function of Y

$$f_Y(y) = \mathbb{P}(Y = y) = \sum_x f_{X,Y}(x, y).$$



Answer

Read probabilities $\mathbb{P}(X = 1, Y = 1)$, $\mathbb{P}(X = 1)$, $\mathbb{P}(Y = 1)$ from table



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We read the probabilities from the joint and marginal mass functions in the table:

	Y=0	Y=1	
X=0	1/9	2/9	1/3
X=1	2/9	4/9	2/3
	1/3	2/3	1

$$\mathbb{P}(X = 1, Y = 1) = f_{X,Y}(1, 1) = 4/9$$

$$\mathbb{P}(X = 1) = f_X(1) = 2/3$$

$$\mathbb{P}(Y = 1) = f_Y(1) = 2/3$$

Independent Random Variables

RVs are independent iff joint density is product of marginal densities

Definition (Independent Random Variables)

The random variables X_1, X_2, \dots, X_n are said to be **independent** if for every A_1, A_2, \dots, A_n

$$\mathbb{P}(X_1 \in A_1, X_2 \in A_2, \dots, X_n \in A_n) = \prod_{i=1}^n \mathbb{P}(X_i \in A_i) \quad \Leftrightarrow \quad f(x_1, x_2, \dots, x_n) = \prod_{i=1}^n f_{X_i}(x_i)$$

where f is the PMF in the discrete case and the PDF in the continuous case.

Definition (i.i.d. Random Variables)

If X_1, X_2, \dots, X_n are independent and all X_i have the same marginal distribution F , we say that X_1, X_2, \dots, X_n are **independent and identically distributed (i.i.d.)**.

- We can also see the i.i.d. RVs X_1, X_2, \dots, X_n as a random sample of size n from distribution F .
→ This idea is important for statistical inference.

Independent Random Variables

Example: Check independence in a bivariate distribution for two discrete RVs

Consider again the bivariate distribution for two discrete RVs X, Y each taking values 0 or 1:

	Y=0	Y=1	
X=0	1/9	2/9	1/3
X=1	2/9	4/9	2/3
	1/3	2/3	1

Joint mass function:

$$\begin{aligned}f_{X,Y}(0,0) &= 1/9 \\f_{X,Y}(0,1) &= 2/9 \\f_{X,Y}(1,0) &= 2/9 \\f_{X,Y}(1,1) &= 4/9\end{aligned}$$

Marginal mass function of X:

$$\begin{aligned}f_X(0) &= 1/3 \\f_X(1) &= 2/3\end{aligned}$$

Marginal mass function of Y:

$$\begin{aligned}f_Y(0) &= 1/3 \\f_Y(1) &= 2/3\end{aligned}$$

\Rightarrow

$$\begin{aligned}f_{X,Y}(0,0) &= f_X(0)f_Y(0) \\f_{X,Y}(0,1) &= f_X(0)f_Y(1) \\f_{X,Y}(1,0) &= f_X(1)f_Y(0) \\f_{X,Y}(1,1) &= f_X(1)f_Y(1)\end{aligned}$$

$\Rightarrow X$ and Y are independent.

Conditional Distributions

We can condition an RV on the value of another RV

For simplicity, consider two RVs X_1 and X_2 with a joint distribution F_{X_1, X_2} .

We are interested in the distribution of X_1 for a given value of X_2 .

Definition (Conditional Probability Mass and Density Functions)

- For X_1, X_2 discrete and $f_{X_2}(x_2) > 0$, the **conditional probability mass function** is

$$f_{X_1|X_2}(x_1|x_2) := \mathbb{P}(X_1 = x_1 | X_2 = x_2) = \frac{\mathbb{P}(X_1 = x_1, X_2 = x_2)}{\mathbb{P}(X_2 = x_2)} = \frac{f_{X_1, X_2}(x_1, x_2)}{f_{X_2}(x_2)}.$$

- For X_1, X_2 continuous and $f_{X_2}(x_2) > 0$, the **conditional probability density function** is

$$f_{X_1|X_2}(x_1|x_2) := \frac{f_{X_1, X_2}(x_1, x_2)}{f_{X_2}(x_2)} \quad \text{and} \quad \mathbb{P}(a_1 \leq X_1 \leq b_1 | X_2 = x_2) = \int_{a_1}^{b_1} f_{X_1|X_2}(x_1|x_2) dx_1.$$

Outline

- Continuous Random Variables
- Multiple Random Variables
- **Operations on Random Variables**
- Statistics

Expectation of an RV

The expectation of an RV is its “average” value

In applications, the full distribution of an RV is usually inaccessible.

→ We therefore consider certain summary functions.

Definition (Expectation)

- The **expected value**, or **mean**, or **first moment**, of a discrete RV X is defined as

$$\mathbb{E}[X] = \sum_{x \in \mathcal{X}} x f_X(x),$$

where $f_X(x)$ is the PMF of X .

- The **expected value**, or **mean**, or **first moment**, of a continuous RV X is defined as

$$\mathbb{E}[X] = \int_{-\infty}^{\infty} x f_X(x) dx,$$

where $f_X(x)$ is the PDF of X .

- Generalization to multiple random variables is straightforward.



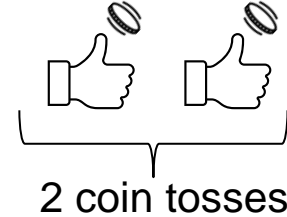
Question

What is the expected value of the number of heads in two coin tosses?



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- **Random Variable:** Let $X(\omega)$ be the number of “heads”
in the sequence $\omega \in \Omega$ of two coin tosses,
where $\Omega = \{H, T\} \times \{H, T\}$.



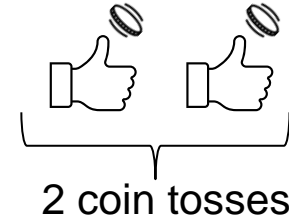
What is the expected value of this RV?



Answer

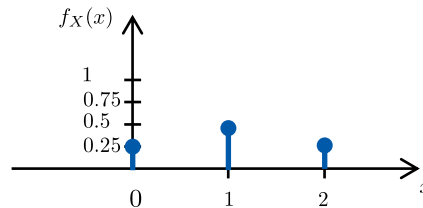
Sum up PMF weighted by values of RV

- Random Variable:** Let $X(\omega)$ be the number of “heads” in the sequence $\omega \in \Omega$ of two coin tosses, where $\Omega = \{H, T\} \times \{H, T\}$.



We already found the PMF:

$$f_X(x) = \begin{cases} \frac{1}{4} & x = 0 \\ \frac{1}{2} & x = 1 \\ \frac{1}{4} & x = 2 \\ 0 & x \notin \{0, 1, 2\} \end{cases}$$



$$\begin{aligned} \Rightarrow \mathbb{E}(X) &= \sum_x x f_X(x) \\ &= 0 \cdot f_X(0) + 1 \cdot f_X(1) + 2 f_X(2) \\ &= 0 \cdot \frac{1}{4} + 1 \cdot \frac{1}{2} + 2 \frac{1}{4} \\ &= 1 \end{aligned}$$

Properties of the Expectation

The expectation is a linear, monotone operator

Theorem (The rule of the lazy statistician)

For an RV X with density $f_X(x)$ and a function g , define the new RV $Y = g(X)$. Then

$$\mathbb{E}[Y] := \mathbb{E}[g(X)] = \int_{-\infty}^{\infty} g(x) f_X(x) dx .$$

Theorem (Properties of Expectation)

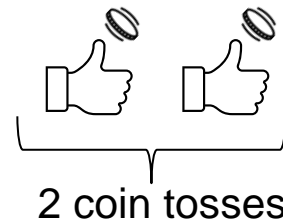
Let X, Y be general RVs with $\mathbb{E}[X], \mathbb{E}[Y] < \infty$.

- **Linearity:** $\mathbb{E}[\alpha X + \beta Y] = \alpha \mathbb{E}[X] + \beta \mathbb{E}[Y]$ for constants α, β .
- **Monotonicity:** If $X \leq Y$ ($F_X(x) \geq F_Y(x), \forall x$), then also $\mathbb{E}[X] \leq \mathbb{E}[Y]$.
- For X, Y independent: $\mathbb{E}[X \cdot Y] = \mathbb{E}[X] \cdot \mathbb{E}[Y]$

Properties of the Expectation

Example: Expected profit in game with two coin tosses

- **Random Variable:** Let $X(\omega)$ be the number of “heads” in the sequence $\omega \in \Omega$ of two coin tosses, where $\Omega = \{H, T\} \times \{H, T\}$.
- **Game:** After the two coin tosses, you are paid a profit of $2^{X(\omega)}$.
- **Expected Profit:** Set $Y = g(X) := 2^X$ and apply rule of the lazy statistician.



$$\begin{aligned}\mathbb{E}(Y) &= \sum_x g(x) f_X(x) \\ &= 2^0 \cdot f_X(0) + 2^1 \cdot f_X(1) + 2^2 \cdot f_X(2) \\ &= 1 \cdot \frac{1}{4} + 2 \cdot \frac{1}{2} + 4 \cdot \frac{1}{4} \\ &= \frac{9}{4}\end{aligned}$$

Variance

The variance measures the “spread“ of a distribution

Definition (Variance)

For an RV X with $\mathbb{E}[X], \mathbb{E}[X^2] < \infty$, the variance is defined as

$$\mathbb{V}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2].$$

- The variance can also be written as $\mathbb{V}[X] = \mathbb{E}[X^2] - \mathbb{E}[X]^2$.
- It is a measure of the spread of a distribution around its mean.
- The standard deviation is related to the variance via $\text{std}[X] = \sqrt{\mathbb{V}[X]}$.
- The variance is often denoted by σ^2 and the standard deviation by σ .

- Continuous Random Variables
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- Operations on Random Variables
- **Statistics**

Statistical Inference

The process of using data to infer the distribution that generated the data

Basic statistical inference problem:

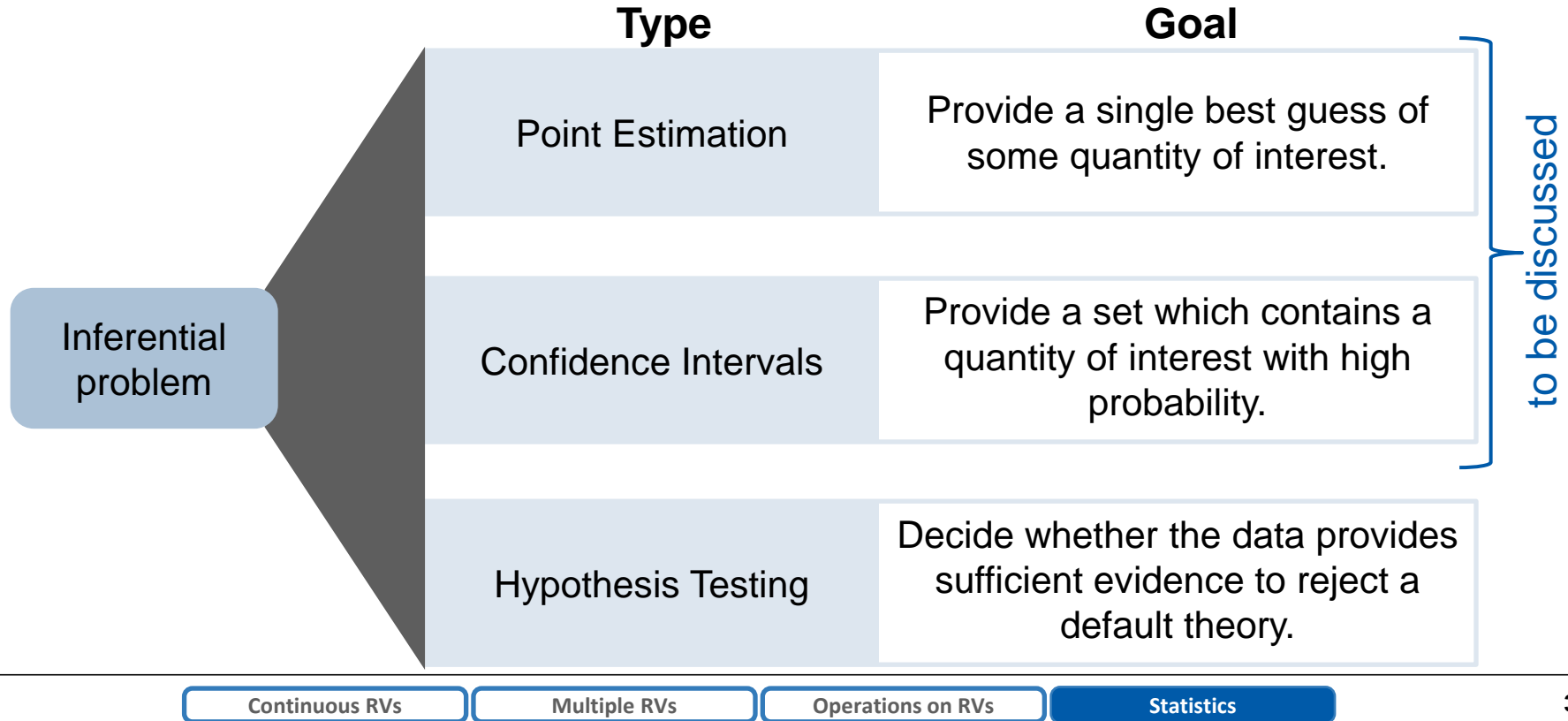
We observe $X_1, X_2, \dots, X_n \sim F$ i.i.d.

How can we **infer** (or **estimate** or **learn**) the distribution F or some features of F ?

- This task is known as **statistical inference** or **learning**.
- Statistics is deeply connected with **machine learning**.

Fundamental Concepts in Statistical Inference

Many inferential problems can be identified as being one of 3 types



Point Estimation

Point estimators provide a single best guess of some quantity of interest

Definition (Point estimator)

Assume we have X_1, X_2, \dots, X_n i.i.d. samples from a distribution F_θ from a class of candidate distributions defined by some parameter vector $\theta \in \Theta$.

- A **point estimator** $\hat{\theta}_n$ of θ is a function

$$\hat{\theta}_n = g(X_1, \dots, X_n).$$

- We define the **bias** of $\hat{\theta}_n$ to be

$$\text{bias}[\hat{\theta}_n] = \mathbb{E}[\hat{\theta}_n] - \theta.$$

- We call $\hat{\theta}_n$ **unbiased** if

$$\mathbb{E}[\hat{\theta}_n] = \theta.$$

- We call $\hat{\theta}_n$ **consistent** if

$$\hat{\theta}_n \longrightarrow \theta \quad \text{for } n \rightarrow \infty.$$

- Point estimators often have a limiting Normal distribution.

Point Estimation

Two important point estimators are sample mean and sample variance

Definition (Sample Mean and Sample Variance)

If X_1, X_2, \dots, X_n are random variables, then we define the **sample mean** to be

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

and the **sample variance** to be

$$S_n^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}_n)^2 .$$

- The sample mean is an **unbiased** and **consistent** estimator of the true expected value.
- The sample variance is an **unbiased** and **consistent** estimator of the true variance.



→ Exercise 2

Limit Theorems

Theorems describe the limiting behaviour of sequences of random variables

The behavior of the sample mean for a large number of samples is described by two important theorems.

Let $\mu = \mathbb{E}[X] < \infty$ and $\sigma^2 = \text{Var}[X] < \infty$ denote expected value and variance of X with $X \sim F$.

Theorem (Weak Law of Large Numbers (WLLN))

Let X_1, X_2, \dots, X_n be i.i.d. random variables from F . Then

$$\bar{X}_n \longrightarrow \mu \quad \text{for } n \rightarrow \infty.$$

Theorem (Central limit theorem (CLT))

Let X_1, X_2, \dots, X_n be i.i.d. random variables from F . Then

$$Z_n = \frac{\bar{X}_n - \mu}{\sqrt{\text{Var}[\bar{X}_n]}} \longrightarrow Z \sim \mathcal{N}(0, 1) \quad \text{for } n \rightarrow \infty.$$

Point Estimation

Example: How to estimate the probability of heads in coin tossing

- **Experiment:** Consider tossing a coin for which the probability of heads is p .
- **Random Variable:** Let X_i be the outcome of a single coin toss, where



$$X_i(\omega) = \begin{cases} 1, \omega = H \\ 0, \omega = T. \end{cases}$$



Question

What is the distribution of this RV and what is its expected value?



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- **Experiment:** Consider tossing a coin for which the probability of heads is p .
- **Random Variable:** Let X_i be the outcome of a single coin toss, where



$$X_i(\omega) = \begin{cases} 1, \omega = H \\ 0, \omega = T. \end{cases}$$

- **Distribution:** ?
- **Expected Value:** ?



Answer

The RV is Bernoulli distributed with expected value p



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- **Experiment:** Consider tossing a coin for which the probability of heads is p .
- **Random Variable:** Let X_i be the outcome of a single coin toss, where



$$X_i(\omega) = \begin{cases} 1, \omega = H \\ 0, \omega = T. \end{cases}$$

- **Distribution:** $X_i \sim \text{Bernoulli}(p)$
- **Expected Value:**
$$\begin{aligned} \mathbb{E}(X_i) &= \sum_x x f_{X_i}(x) \\ &= 0 \cdot f_{X_i}(0) + 1 \cdot f_{X_i}(1) \\ &= 0 \cdot \mathbb{P}[X_i = 0] + 1 \cdot \mathbb{P}[X_i = 1] \\ &= p \end{aligned}$$



Question

How could we estimate parameter p ?



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- **Experiment:** Consider tossing a coin for which the probability of heads is p .
- **Random Variable:** Let X_i be the outcome of a single coin toss, where



$$X_i(\omega) = \begin{cases} 1, \omega = H \\ 0, \omega = T. \end{cases} \Rightarrow X_i \sim \text{Bernoulli}(p), \mathbb{E}(X_i) = p.$$

- **Point Estimation:** ?



Answer

Use fraction of heads after n tosses as point estimator

- **Experiment:** Consider tossing a coin for which the probability of heads is p .
- **Random Variable:** Let X_i be the outcome of a single coin toss, where



$$X_i(\omega) = \begin{cases} 1, \omega = H \\ 0, \omega = T. \end{cases} \Rightarrow X_i \sim \text{Bernoulli}(p), \mathbb{E}(X_i) = p.$$

- **Point Estimation:** A possible point estimator \hat{p}_n for parameter p is the fraction of heads after n coin tosses, given by the (unbiased and consistent) sample average, i.e.,

$$\hat{p}_n := \bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i.$$

Likelihood-based inference

Maximum likelihood is most common method for parameter estimation

Idea: If $X \sim F_\theta$, we can understand this as a distribution conditional on parameter θ .

Definition (Likelihood Function)

Let X_1, X_2, \dots, X_n i.i.d. be continuous random variables with PDF $f(X_i|\theta)$.

The **likelihood function** $L_n(\theta)$ is defined as the joint conditional

$$L_n(\theta) \equiv f(x_1, \dots, x_n | \theta) = \prod_{i=1}^n f(x_i | \theta).$$

Definition (Maximum Likelihood Estimator (MLE))

The **maximum likelihood estimator (MLE)** is defined as the value of θ that maximizes the likelihood, i.e.,

$$\hat{\theta}_n = \arg \max_{\theta} L_n(\theta) = \arg \max_{\theta} \log L_n(\theta).$$



→ Exercise 2

Confidence Intervals

Confidence intervals contain a quantity of interest with high probability

Definition (Confidence Interval)

Assume we have X_1, X_2, \dots, X_n i.i.d. samples from a distribution F_θ from a class of candidate distributions defined by some (one-dimensional) parameter θ . Let $\alpha \in [0, 1]$.

A $1 - \alpha$ **confidence interval** for θ is an interval

$$C_n = (a, b)$$

where $a = a(X_1, \dots, X_n)$ and $b = b(X_1, \dots, X_n)$ are functions of X_1, X_2, \dots, X_n such that

$$\mathbb{P}[\theta \in C_n] \geq 1 - \alpha \quad \forall \theta \in \Theta.$$

- I.e., $C_n = (a, b)$ traps θ with probability $1 - \alpha$. Note that $C_n = (a, b)$ is random and θ is fixed!
- (Approximate) confidence intervals can often be constructed based on point estimators with limiting Normal distribution.
- If θ is a vector, we use a **confidence set** (e.g., a sphere or an ellipse) instead of an interval.

Hoeffding's Inequality

This inequality is useful for constructing confidence intervals

Theorem (Hoeffding's Inequality)

Let X_1, X_2, \dots, X_n be i.i.d. RVs with values in $[0, 1]$ and expected value $\mathbb{E}[X]$ and let

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

be the sample mean. Then, for any $u > 0$,

$$\mathbb{P}[\mathbb{E}[X] \geq \bar{X}_n + u] \leq e^{-2nu^2}$$

and

$$\mathbb{P}[|\bar{X}_n - \mathbb{E}[X]| \geq u] \leq 2e^{-2nu^2}.$$

- There exist also variants of Hoeffding's inequality for independent random variables with bounded supports $a_i \leq X_i \leq b_i, i = 1, \dots, n$.
- We can use Hoeffding's inequality to construct confidence intervals of samples of i.i.d. RVs.



→ Exercise 2



→ Chapter 5



Learning Goals

- You can determine the characteristics of continuous random variables and relate important examples to their applications.
 - Probability Density Function; Uniform / Gaussian / Exponential Distribution.
- You can apply the formulas for multiple random variables and operations on random variables to compute probabilities, distributions, expectation and variance.
 - Joints; Marginals; Independence; Conditionals; Expectation and its properties; Variance.
- You can distinguish the fundamental concepts of statistics and apply results and formulas for point estimation and confidence intervals.
 - Point Estimators and their properties; Sample Mean and Variance; Limit Theorems; Maximum Likelihood; Confidence Intervals; Hoeffding's Inequality.

Lecture Overview

Next week, we'll study a simplified version of RL

