

neighbourDetected: nat    objectSeen: real    goalSeen

Control

Ⓡ IOperations  
 ✕ distance: real  
 ✕ d: nat, n: nat, neighbours: nat  
 π close: real, Ta: nat, Tb: nat, Tc: nat, Td: nat, Te: nat, S: nat  
 ✕ goal: boolean  
 ⌚ T  
 ⌚ N  
 ⌚ C  
 ⓘ IEvents

