```
In[*]:= Remove["Global`*"]
```

In[•]:=

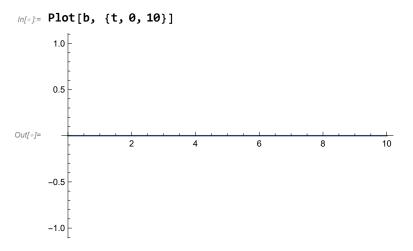
Given a nonlinear second order differential equation, $d^2x/dt^2 = x^2 - x$ that can be thought of as Newton's second law for x(t) of a particle moving in one dimension, i try solving the equation using Dsolve function but it doesn't work because this function can only be solved numerically

$$ln[*] = solm = DSolve[{x''[t] == (x[t]^2) - x[t], x[0] == 0, x'[0] == 0}, x[t], t];$$

••• DSolve: General solution contains implicit solutions. In the boundary value problem, these solutions will be ignored, so some of the solutions will be lost.

Now i try again to solve it using the NDSolve function which solves numerically

I then plot my resulting numerical answer and its just a line at 0



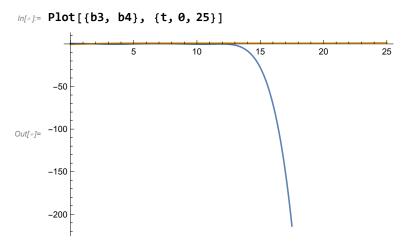
I adjusted the boundary conditions to get two new functions with x(0)=0.1 and x(0)=-0.1

-0.10

The resulting graph from the two new boundary conditions resembles a cos function and an inverse cos function. considering that the main difference is a negative sign on the boundary condition, this tells me that the boundary condition can have a significant effect on the motion of the graph. I now try new boundary conditions to get new functions and check the resulting graph

$$\begin{aligned} & \textit{InterpolatingFunction} [x''[t] = (x[t]^2) - x[t], \ x[\theta] = \theta.5, \ x'[\theta] = \theta\}, \ x[t], \ \{t, \, \theta, \, 1\theta\}] \\ & b a = x[t] \ /. \ sol3 \\ & sol4 = NDSolve[\{x''[t] = (x[t]^2) - x[t], \ x[\theta] = -\theta.5, \ x'[\theta] = \theta\}, \ x[t], \ \{t, \, \theta, \, 1\theta\}] \\ & b a = x[t] \ /. \ sol4 \\ & out[*] = \left\{ \left\{ x[t] \rightarrow InterpolatingFunction \left[\begin{array}{c} \blacksquare & Domain: \{\{0, \, 10.\}\} \\ Output: scalar \end{array} \right] [t] \right\} \right\} \\ & out[*] = \left\{ \left\{ x[t] \rightarrow InterpolatingFunction \left[\begin{array}{c} \blacksquare & Domain: \{\{0, \, 10.\}\} \\ Output: scalar \end{array} \right] [t] \right\} \right\} \\ & out[*] = \left\{ \left\{ x[t] \rightarrow InterpolatingFunction \left[\begin{array}{c} \blacksquare & Domain: \{\{0, \, 10.\}\} \\ Output: scalar \end{array} \right] [t] \right\} \right\} \\ & out[*] = \left\{ InterpolatingFunction \left[\begin{array}{c} \blacksquare & Domain: \{\{0, \, 10.\}\} \\ Output: scalar \end{array} \right] [t] \right\} \end{aligned}$$

The resulting graph of the new boundary conditions of x(0)=0.5 and x(0)=-0.5 shows one line seemingly constant at 0 and another dropping to negative infinity at 12 or 13



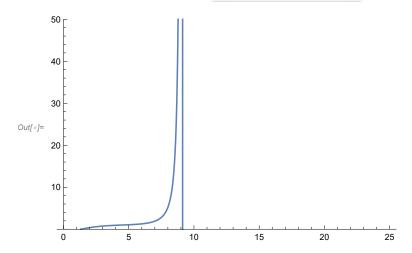
I now only check for the motion with x(0)=-0.51 and adjust the plot range to get a graph that seems to have an error at some 8 or 9 value

$$ln[*]= sol5 = NDSolve[{x''[t] == (x[t]^2) - x[t], x[0] == -0.51, x'[0] == 0}, x[t], {t, 0, 10}]$$

b5 = x[t] /. sol5
Plot[b5, {t, 0, 25}, PlotRange \rightarrow {0, 50}]

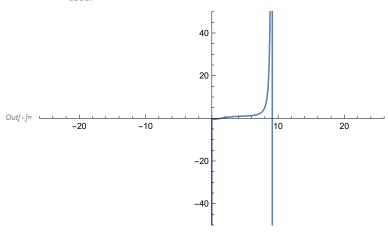
••• NDSolve: At t == 9.13171850100183, step size is effectively zero; singularity or stiff system suspected.

$$\textit{Out[*]} = \left\{ \begin{aligned} & \mathsf{InterpolatingFunction} \left[& \mathsf{E} & \mathsf{Domain:} \{\{0., 9.13\}\} \\ & \mathsf{Output:} \ \mathsf{scalar} \end{aligned} \right] [t] \right\}$$



$$ln[a]:= Plot[b5, \{t, -25, 25\}, PlotRange \rightarrow \{-50, 50\}]$$

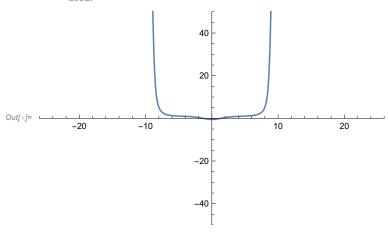
••• InterpolatingFunction: Input value {-24.999} lies outside the range of data in the interpolating function. Extrapolation will be used.



I then adjust the boundary conditions for solving the differential equation and plotting the function one more time

$$ln[\cdot]:= Plot[b6, \{t, -25, 25\}, PlotRange \rightarrow \{-50, 50\}]$$

... InterpolatingFunction: Input value (-24.999) lies outside the range of data in the interpolating function. Extrapolation will be used.



The resulting graph shows the motion with the -0.51 boundary condition .

In[*]:= ? Integrate

Integrate
$$[f, x]$$
 gives the indefinite integral $\int f dx$.

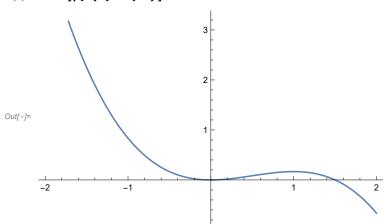
Integrate $[f, \{x, x_{min}, x_{max}\}]$ gives the definite integral $\int_{X_{min}}^{X_{max}} f dx$.

Integrate $[f, \{x, x_{min}, x_{max}\}, \{y, y_{min}, y_{max}\}, \dots]$ gives the multiple integral $\int_{X_{min}}^{X_{max}} dx \int_{y_{min}}^{y_{max}} dy \dots f$.

Integrate $[f, \{x, y, \dots\}] \in reg$ integrates over the geometric region reg .

$$ln[*]:= p = -Integrate[x^2 - x, x]$$

$$Out[@] = \frac{x^2}{2} - \frac{x^3}{3}$$



The plot for potential energy shows how at around 0.5 the potential energy goes to zero which means the energy is converted from potential energy to kinetic energy. for a mass traveling down a hill with set potential energy, at 0.5 the potential energy of the mass would get converted to kinetic energy and the mass would continue travelling which isn't shown in the graph.