

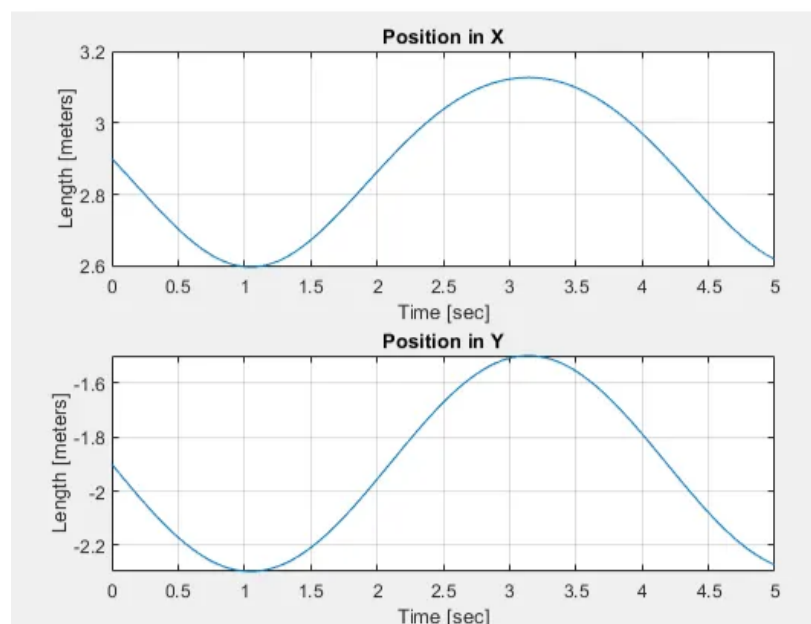
Project 6 - points

Made by Zvonarova Viktoriia

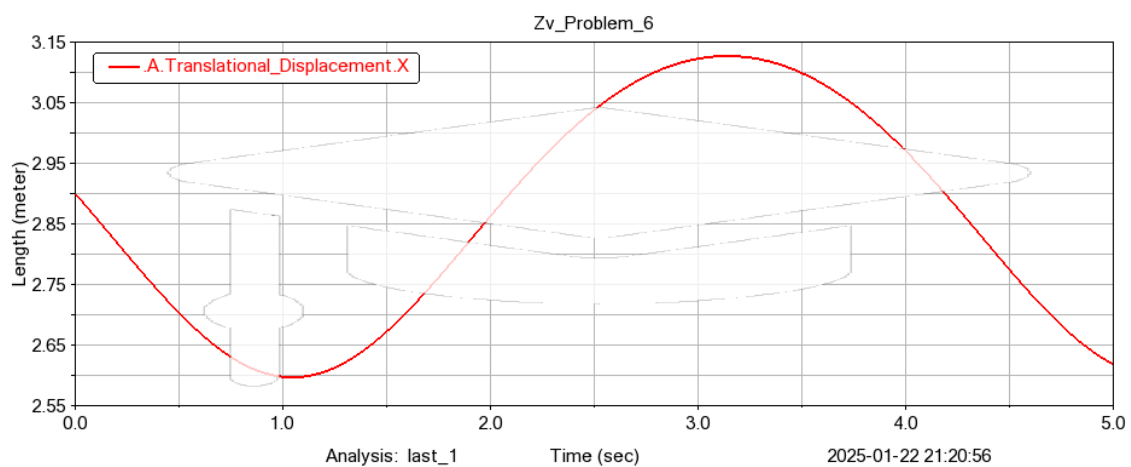
Point A = 3

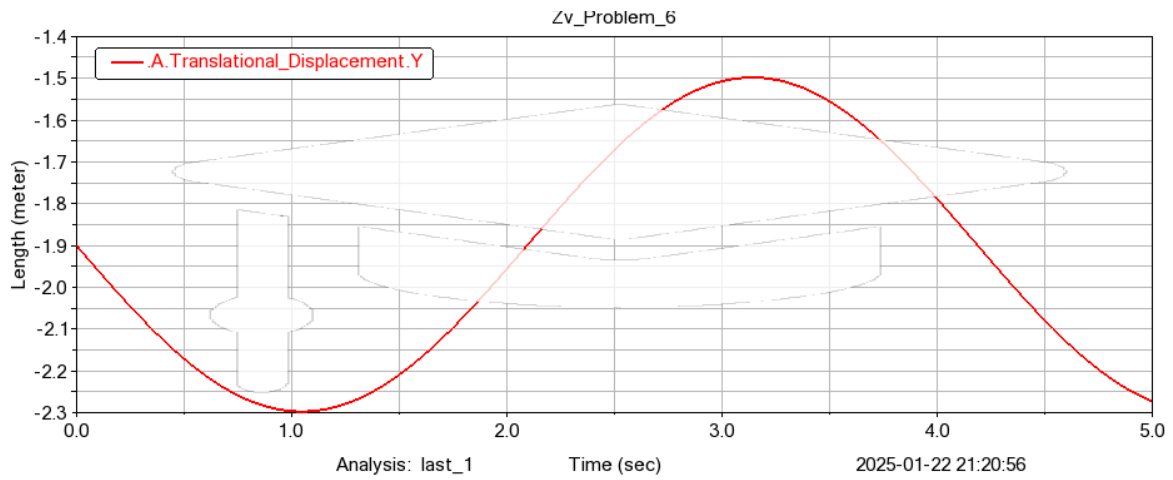
Position

Matlab



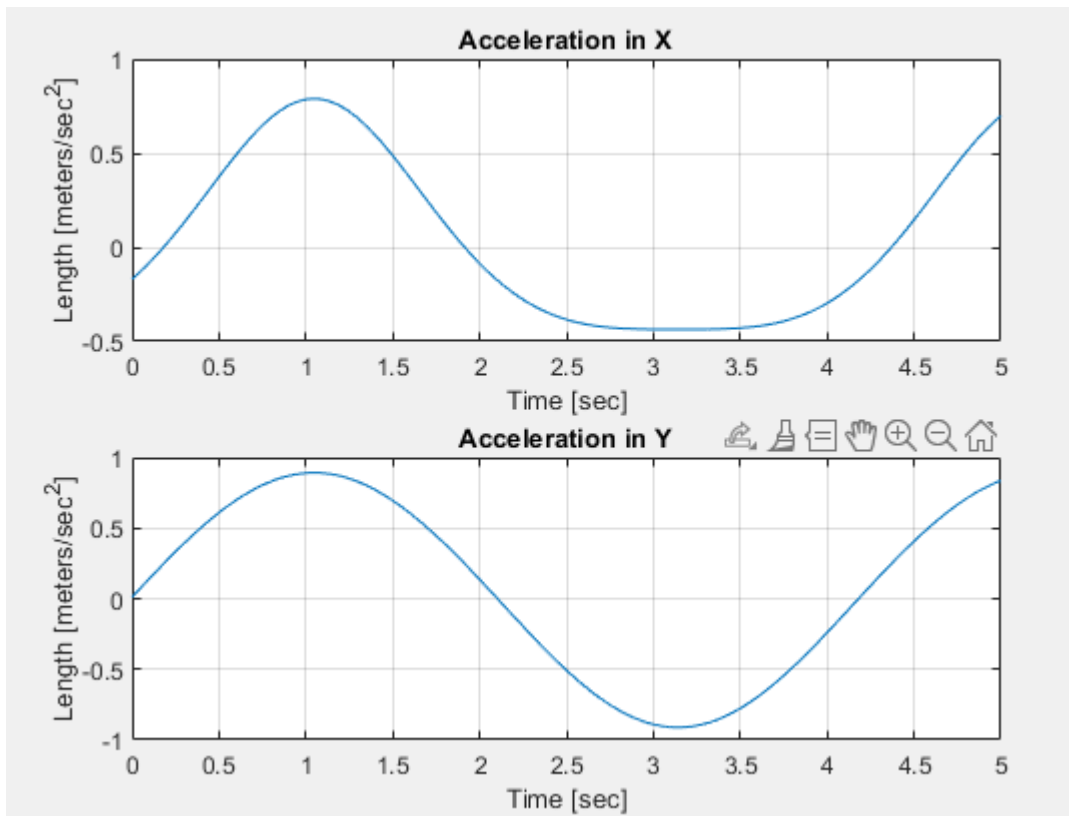
Adams



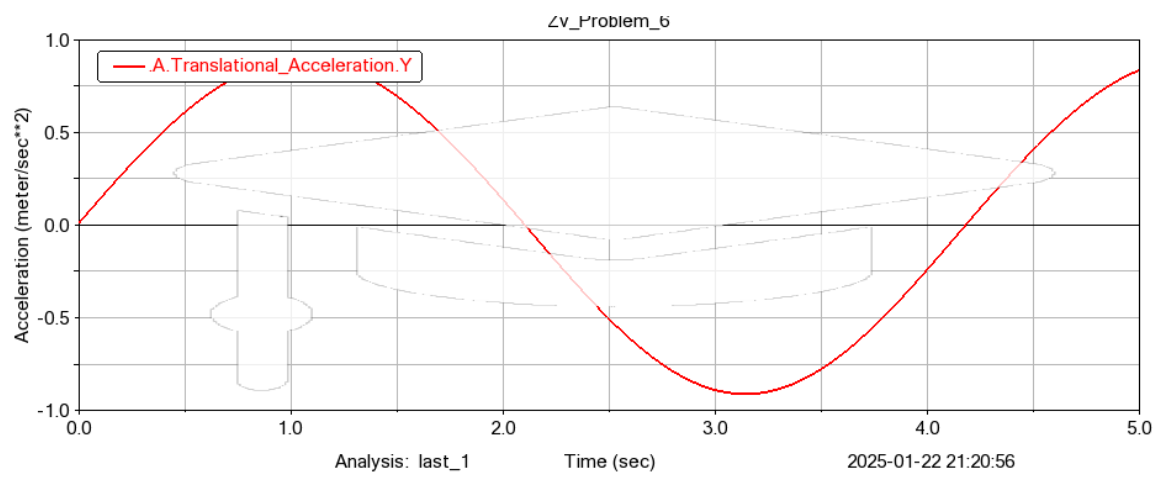
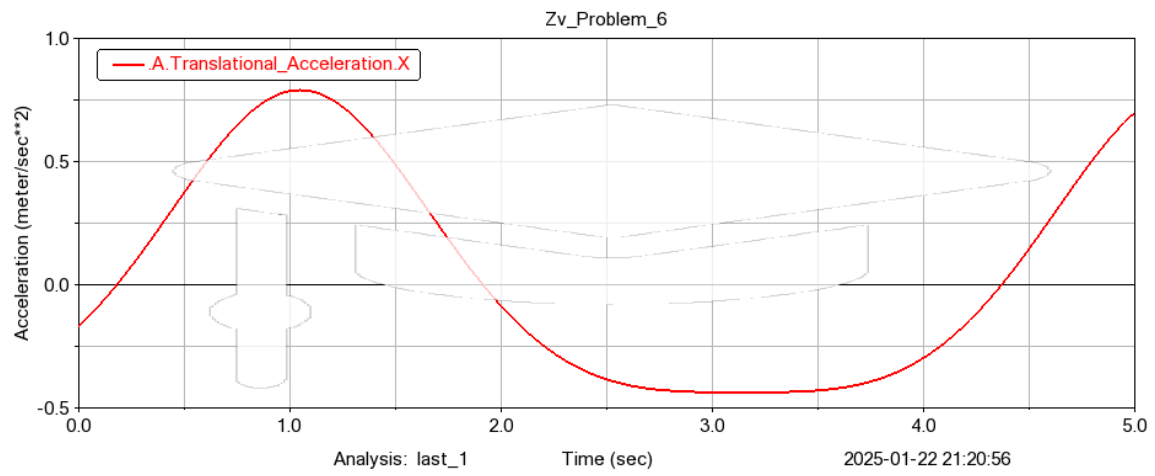


Acceleration

Matlab

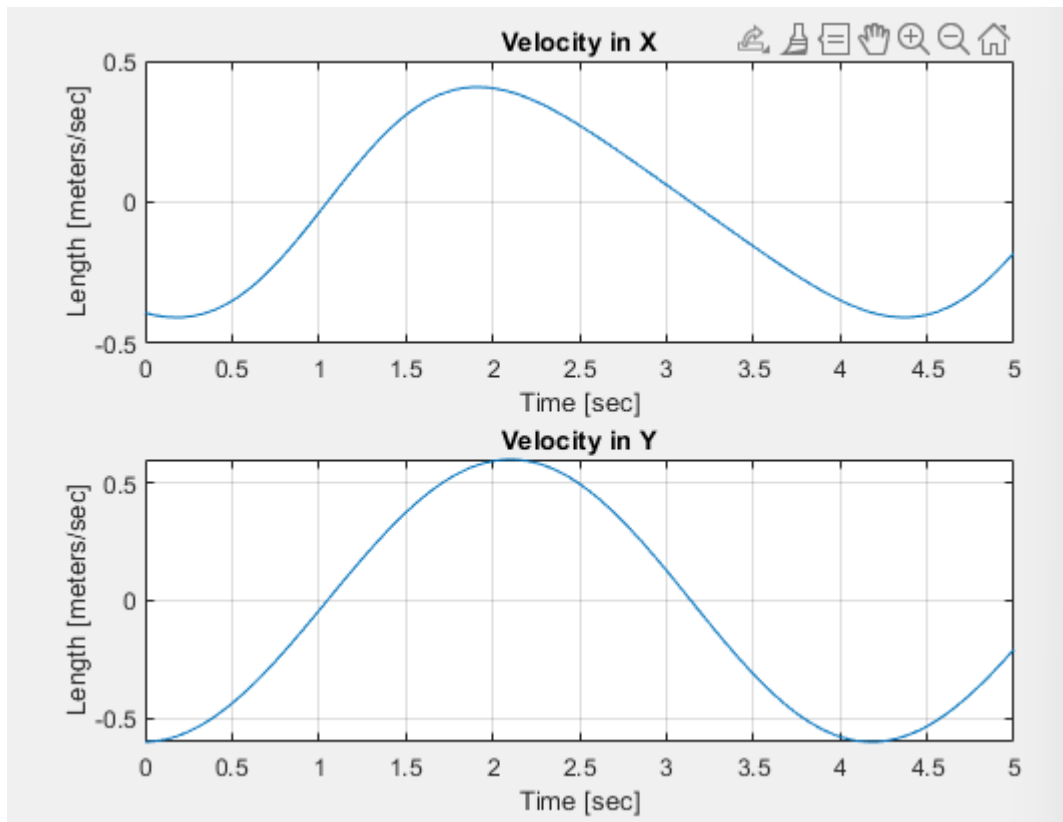


Adams

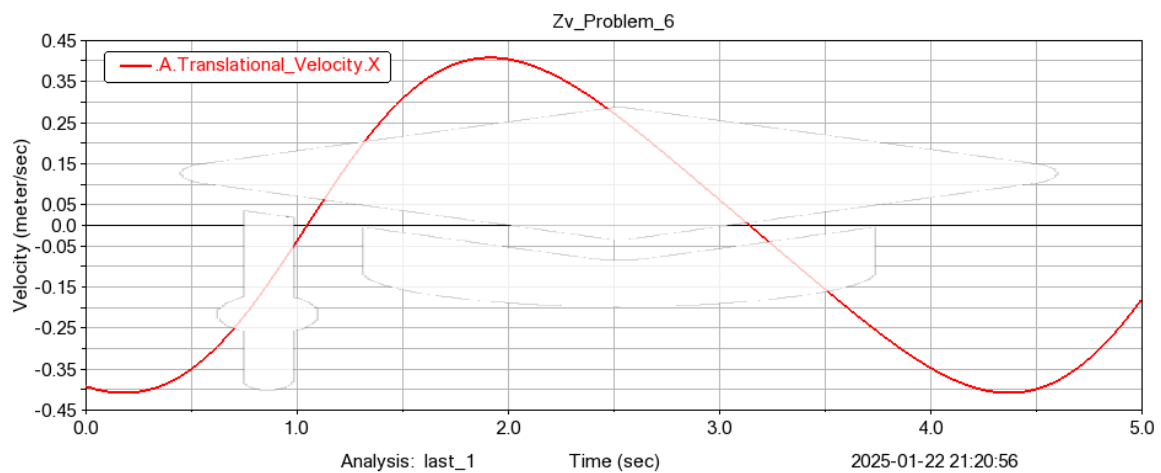


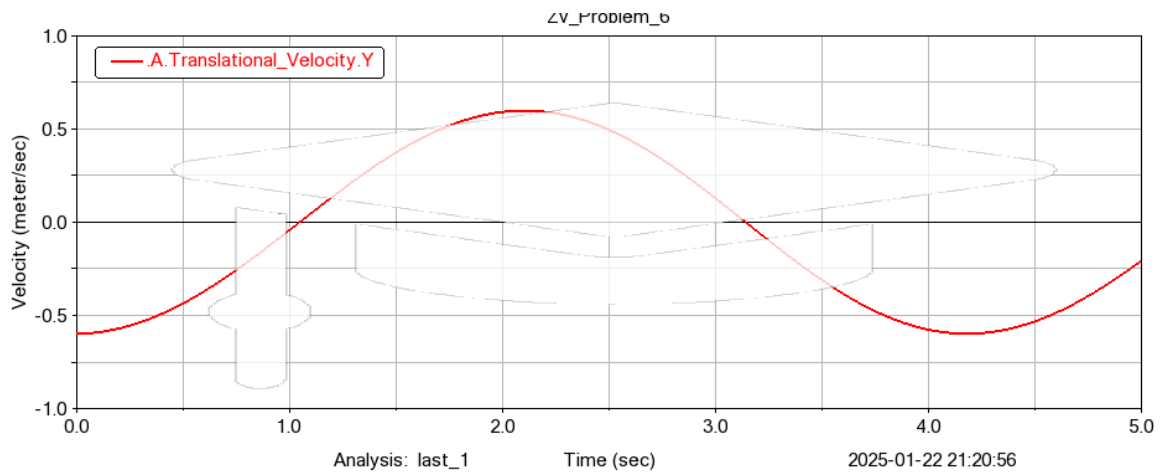
Velocity

Matlab



Adams

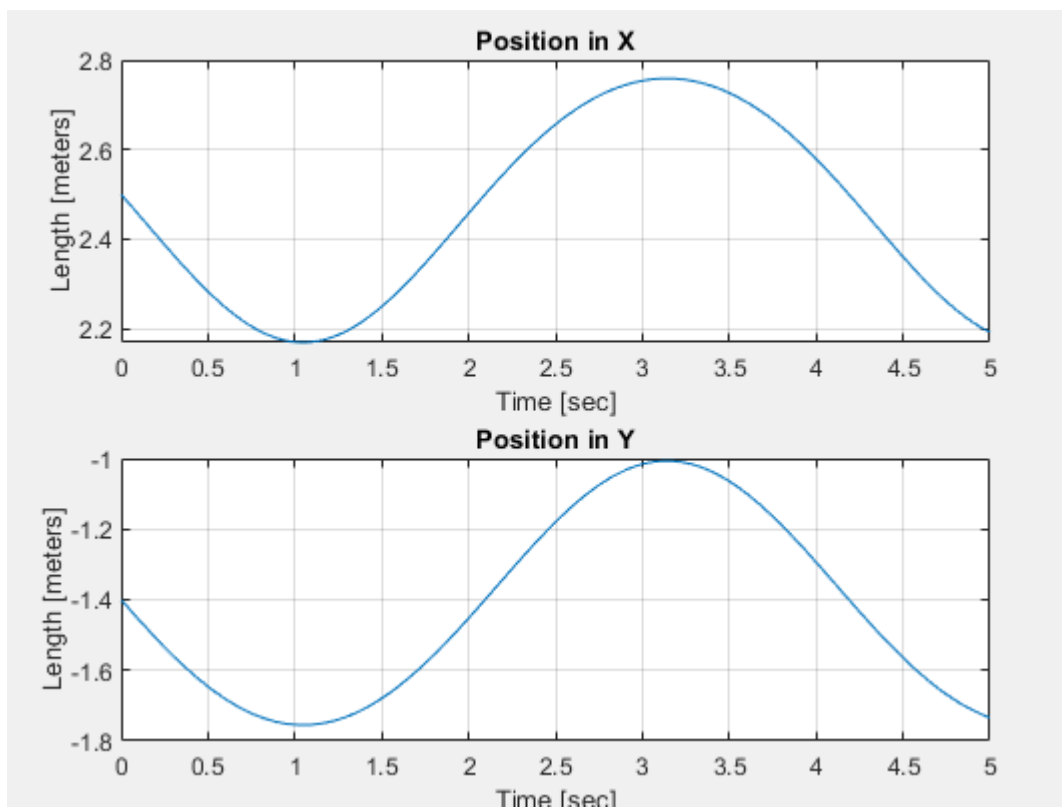




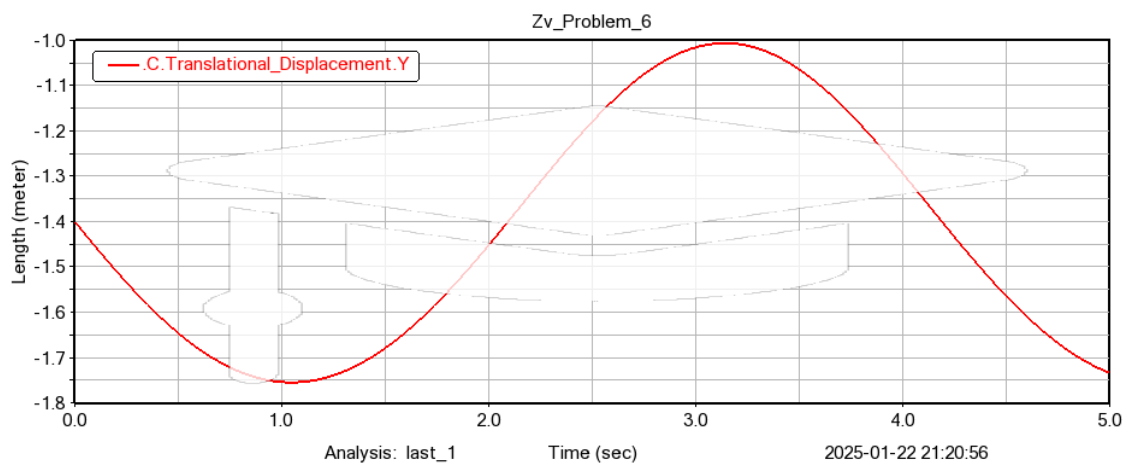
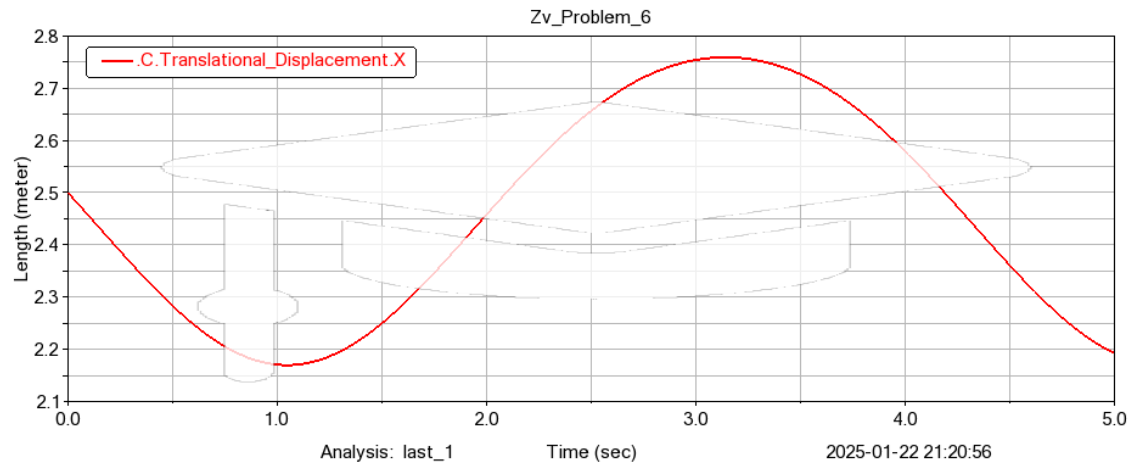
Point C = 2

Position

Matlab

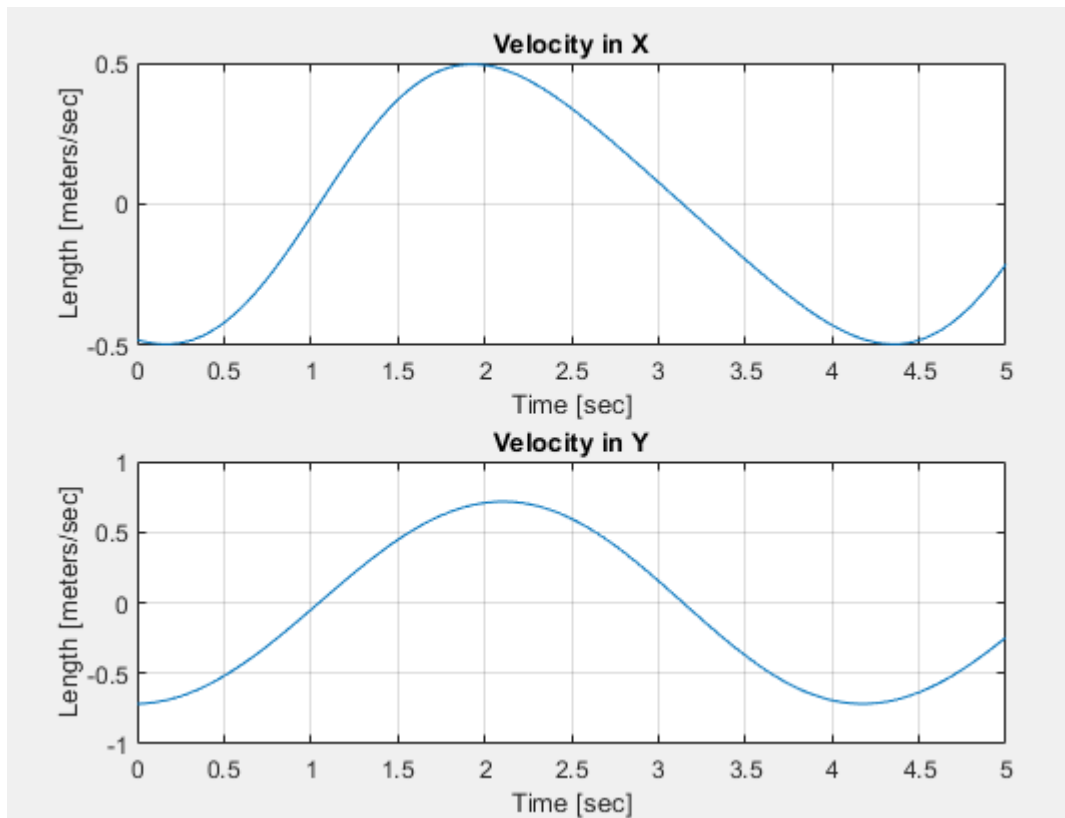


Adams

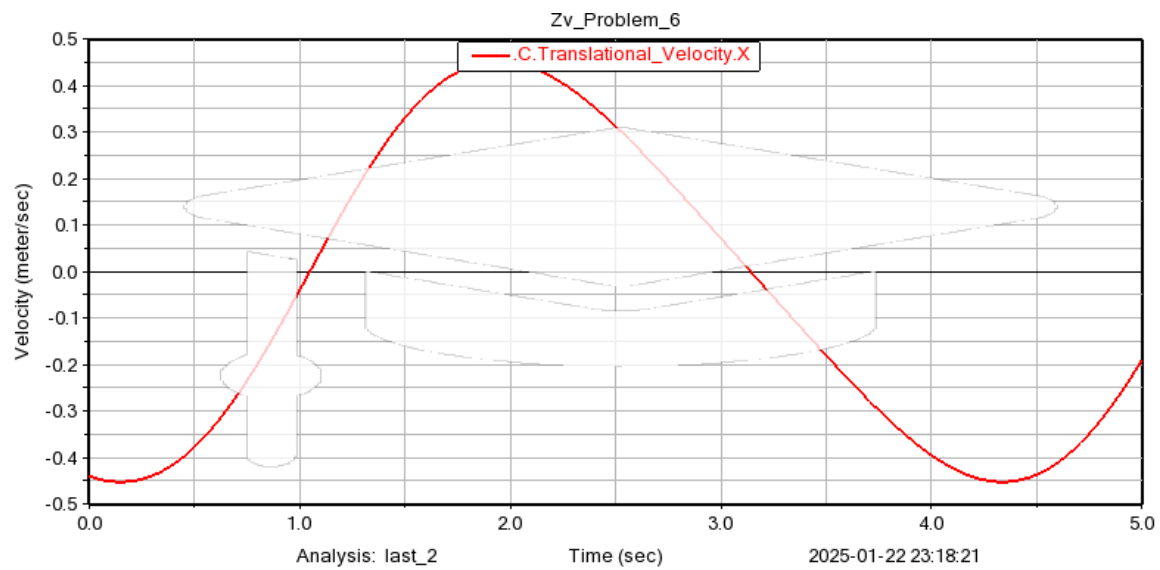


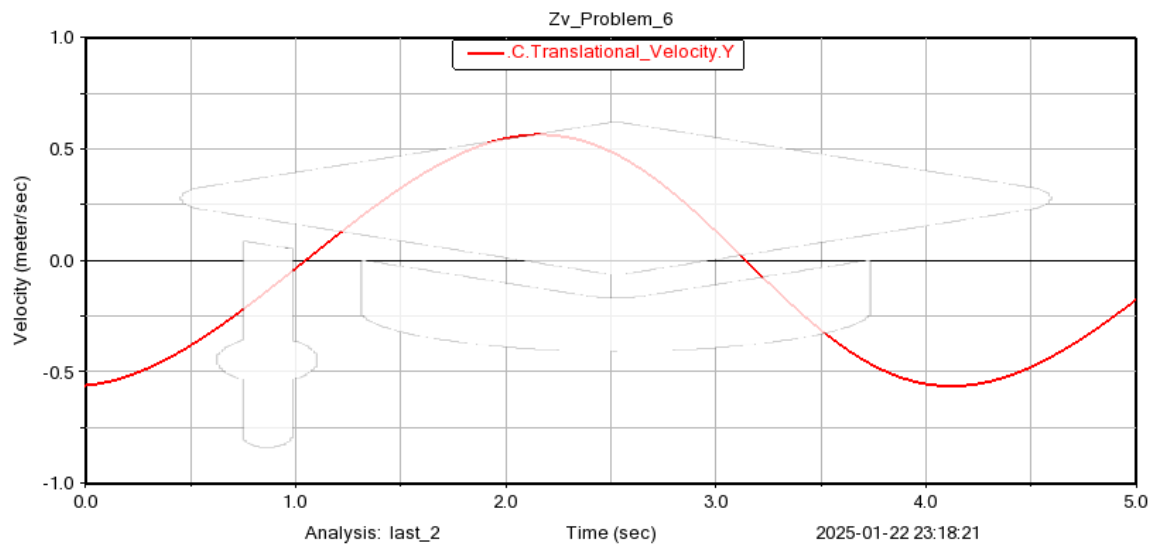
Velocity

Matlab



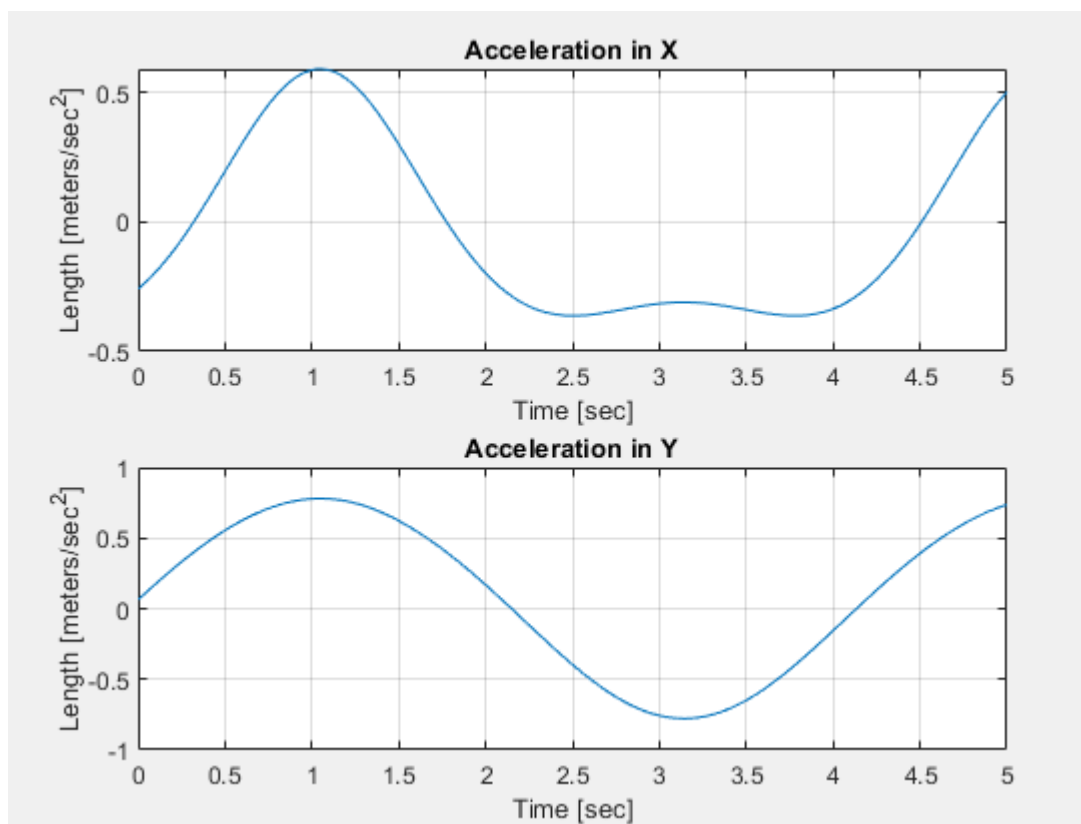
Adams



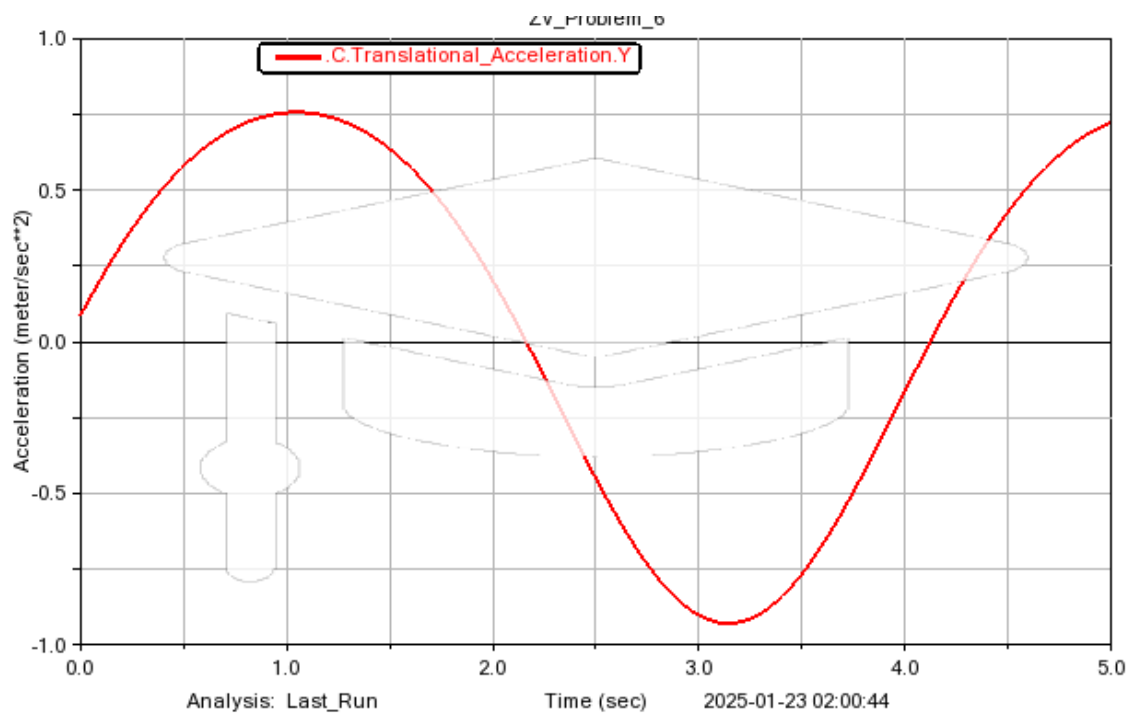
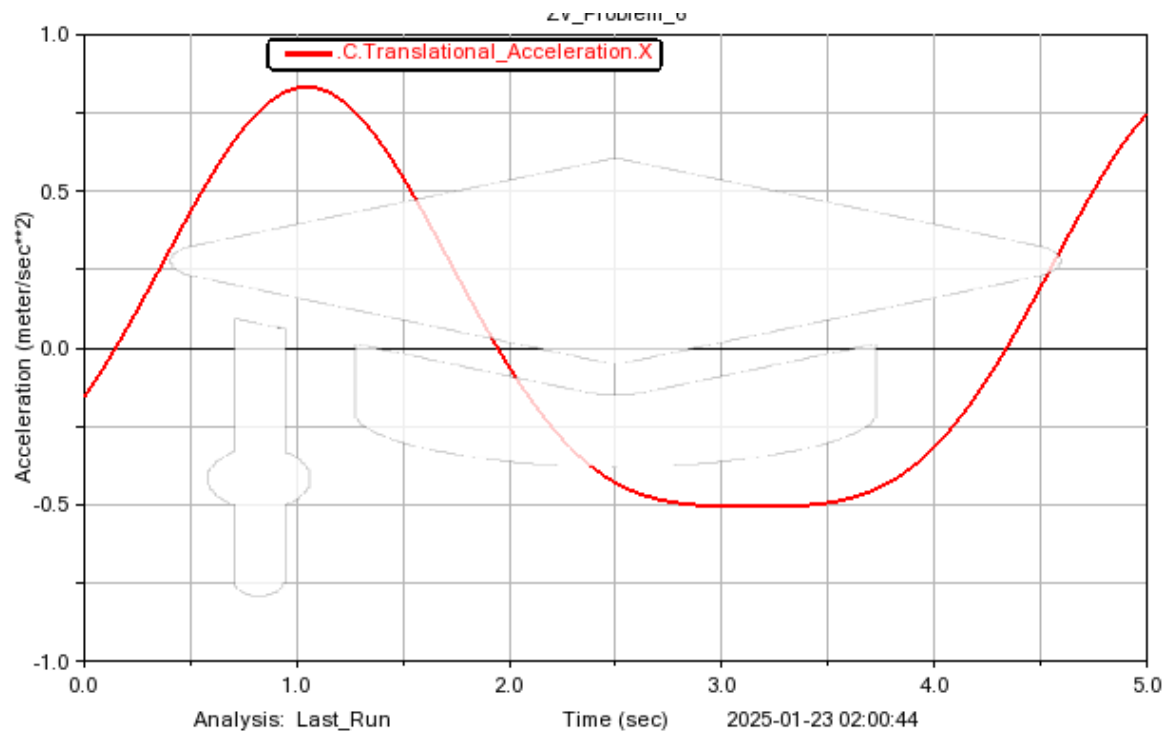


Acceleration

Matlab



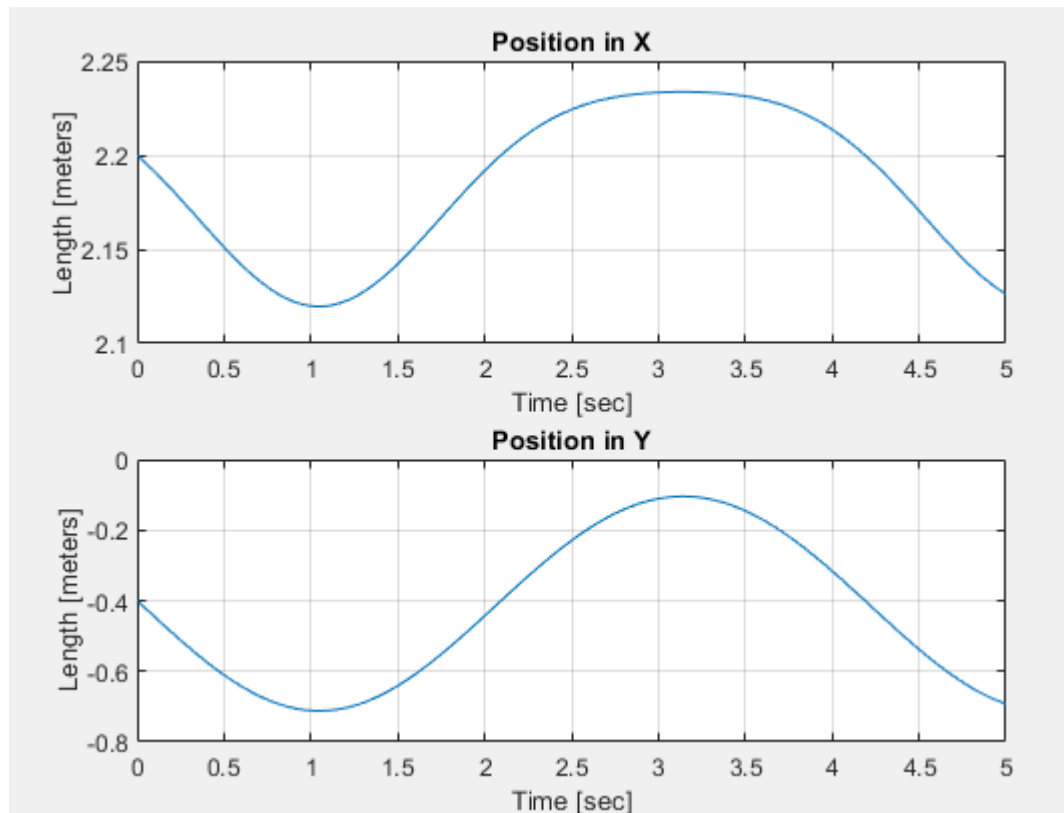
Adams



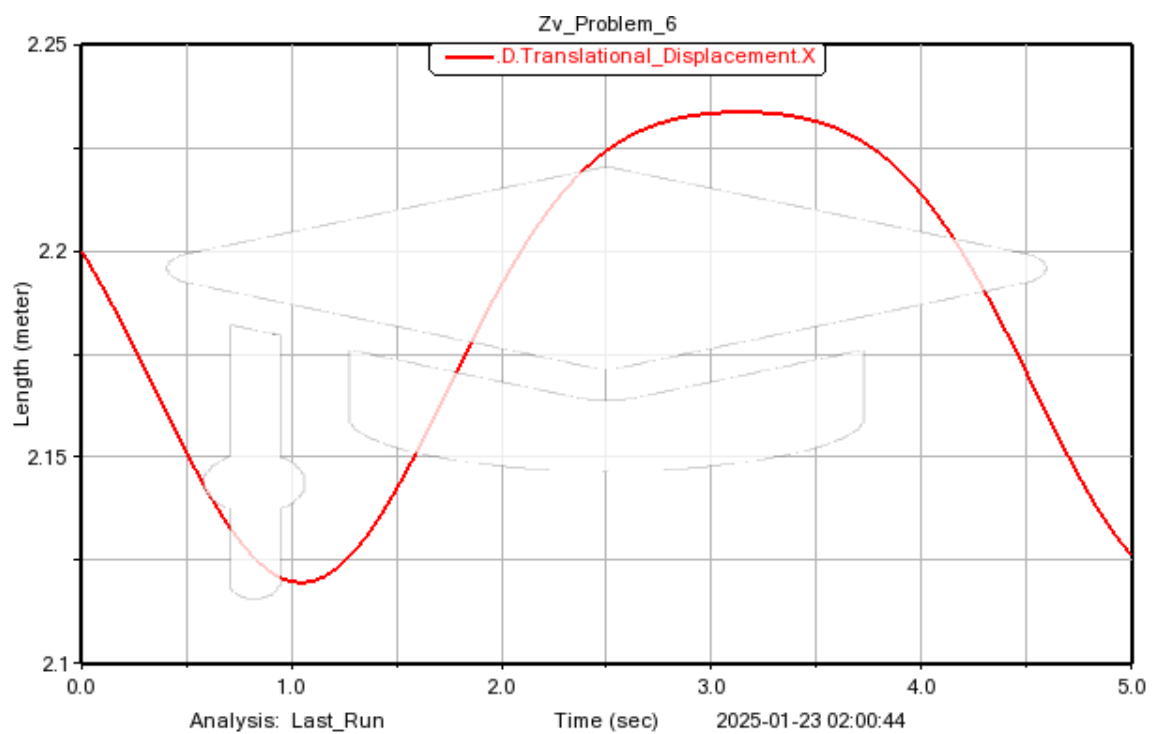
Point D = 1:

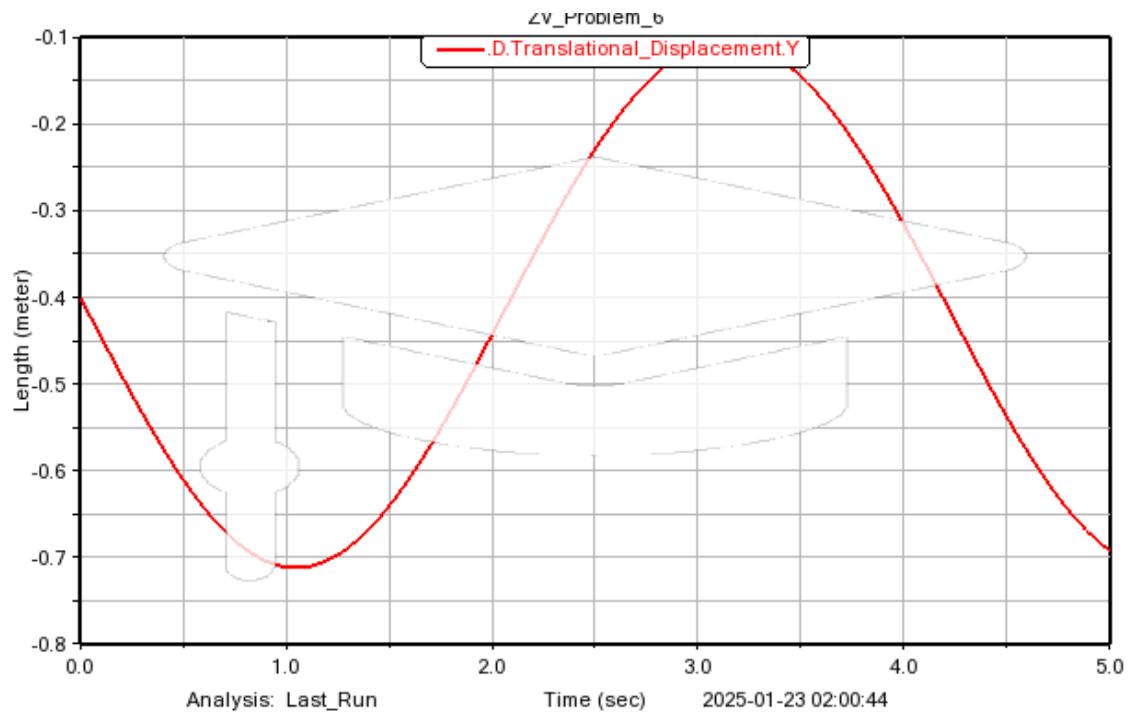
Position

Matlab



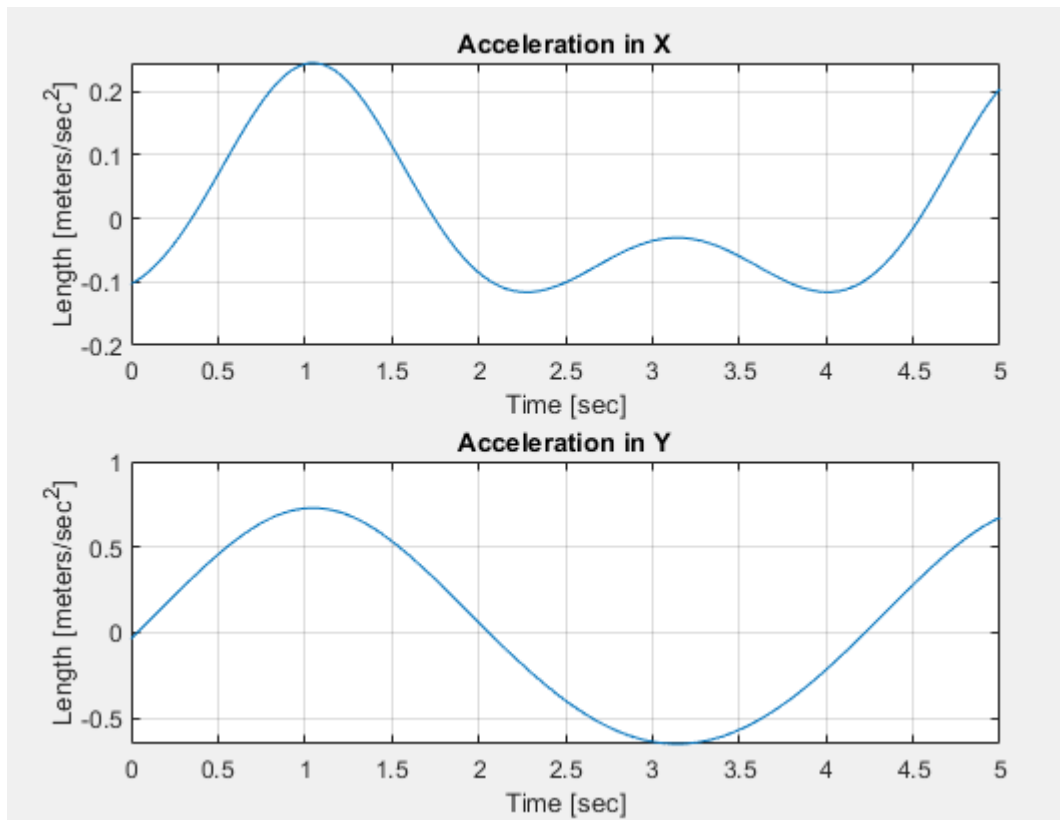
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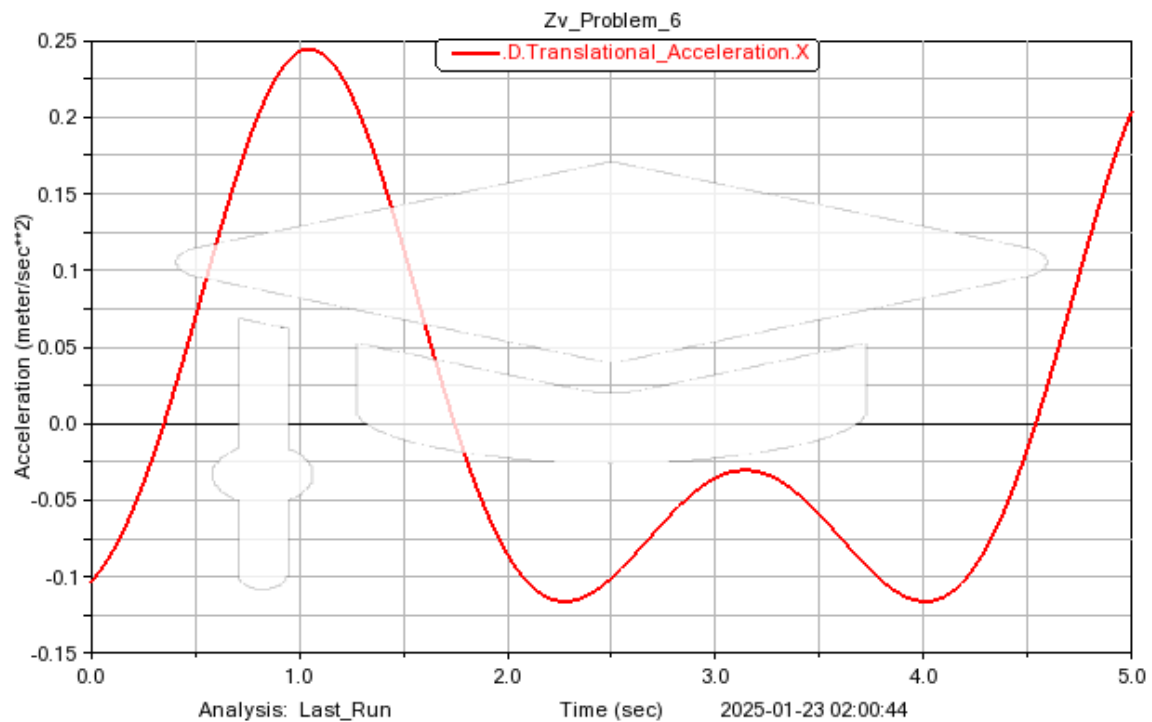


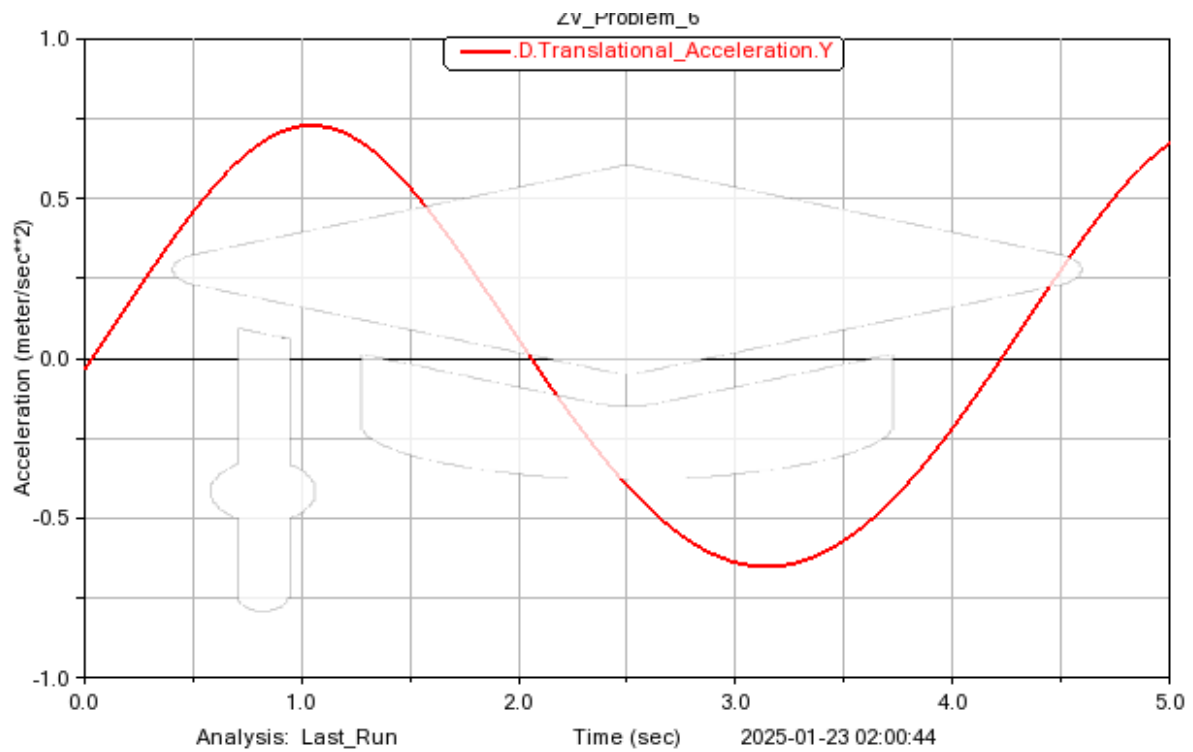
Acceleration

Matlab



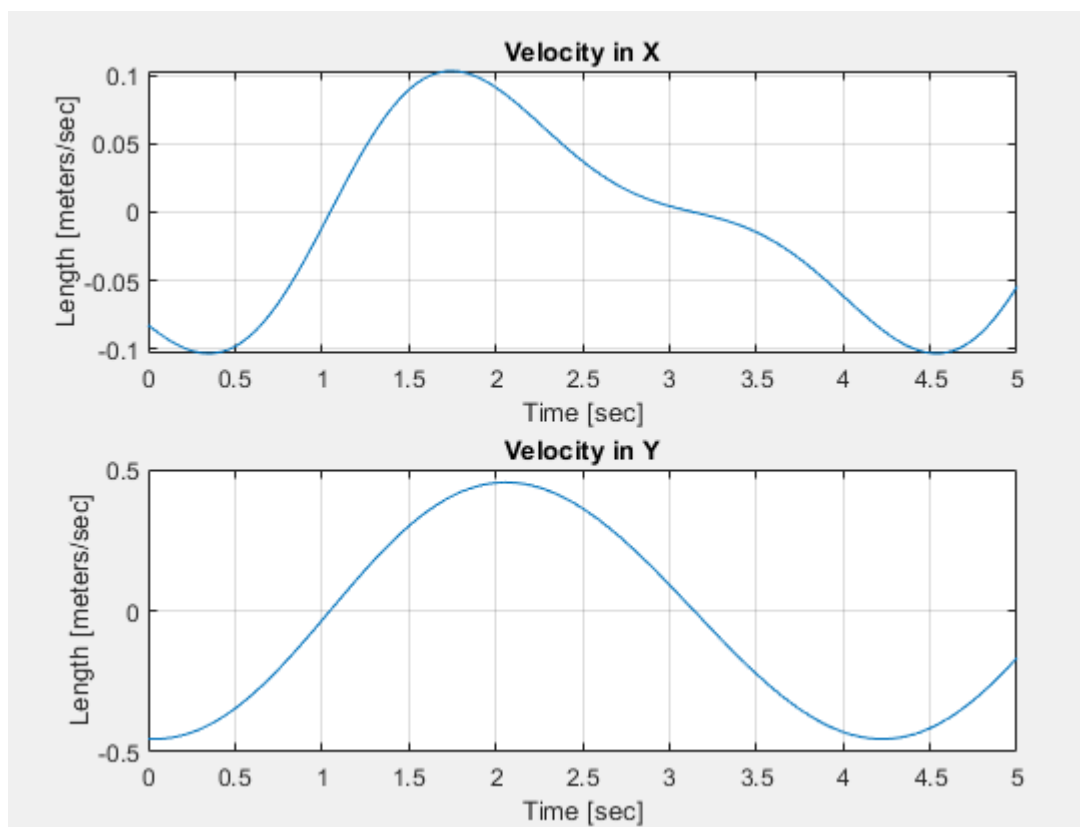
Adams



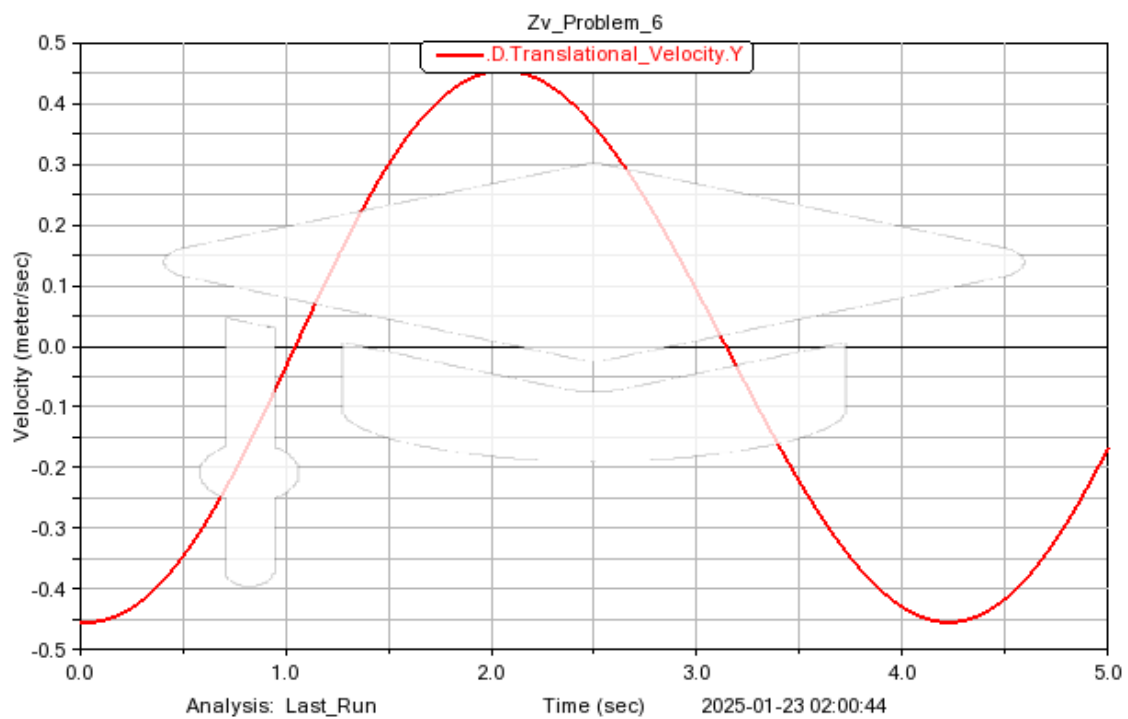
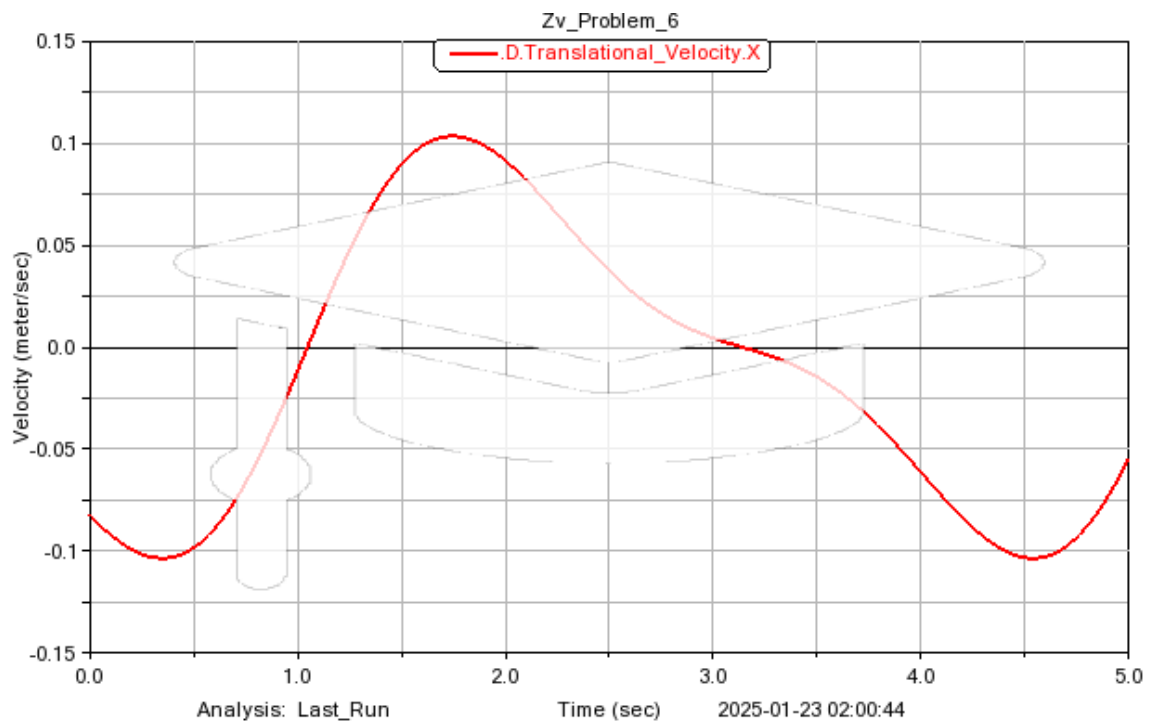


Velocity

Matlab



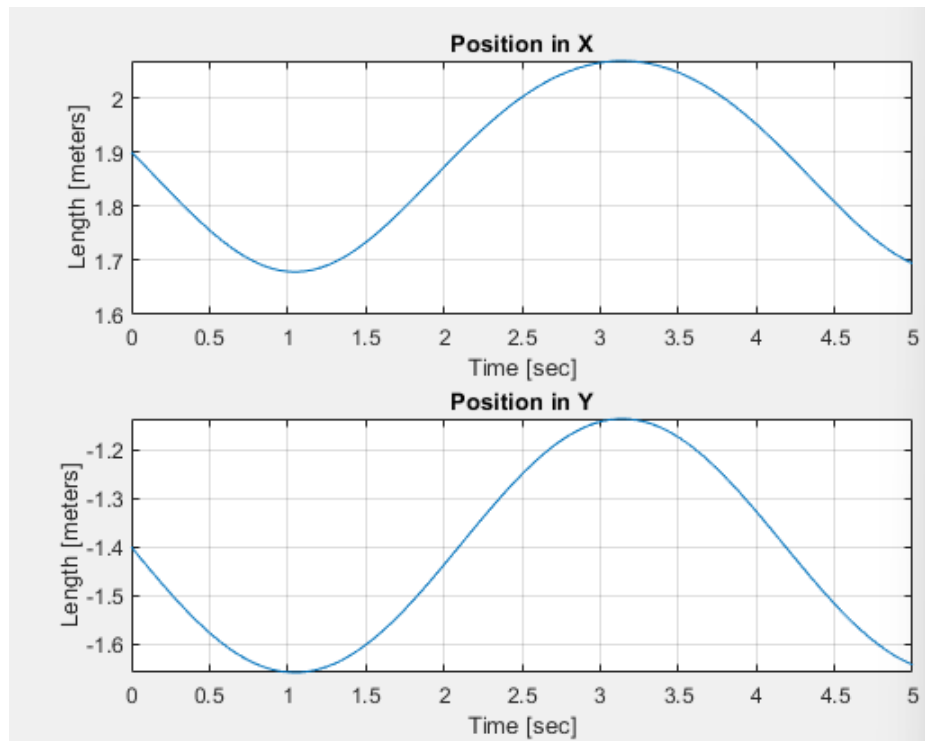
Adams



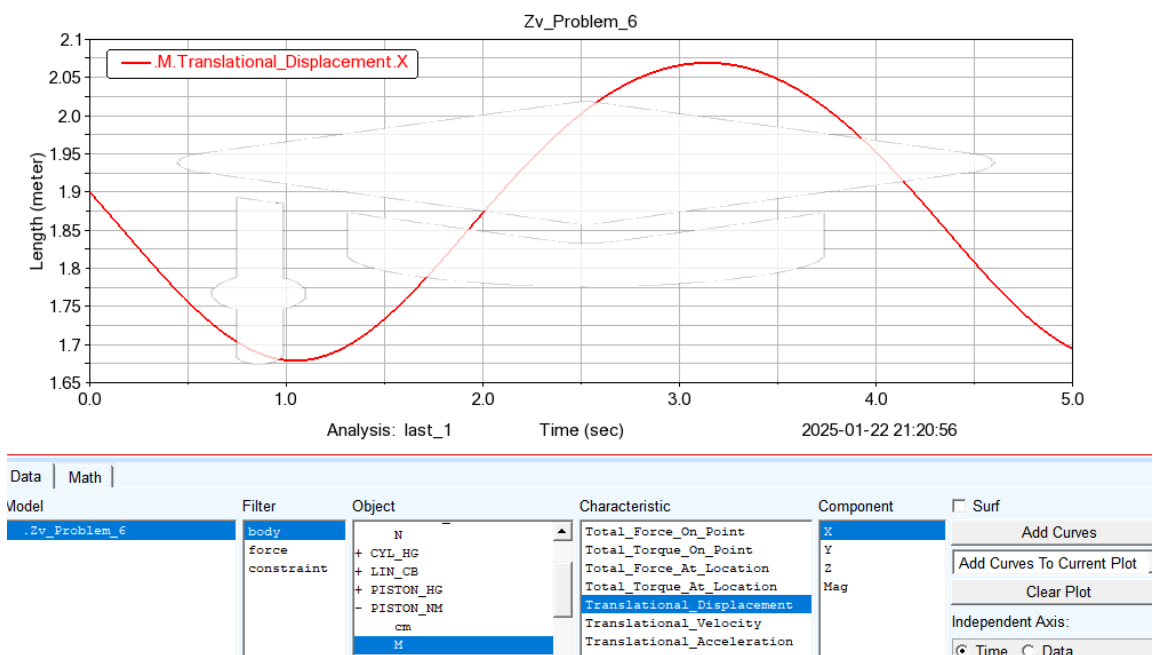
Point M = 6

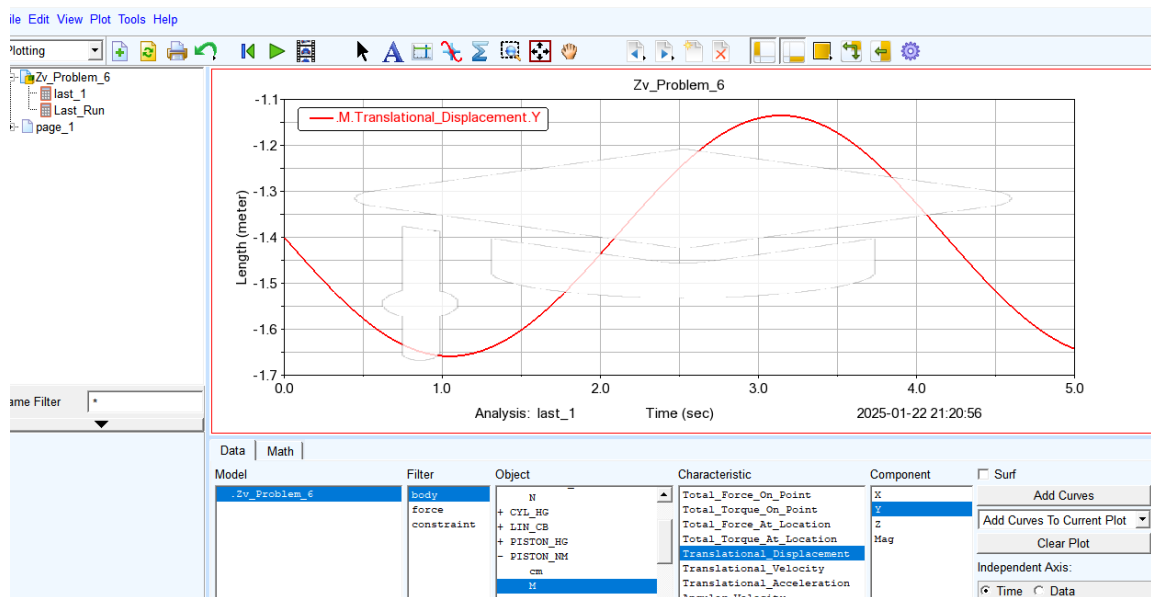
Position

Matlab



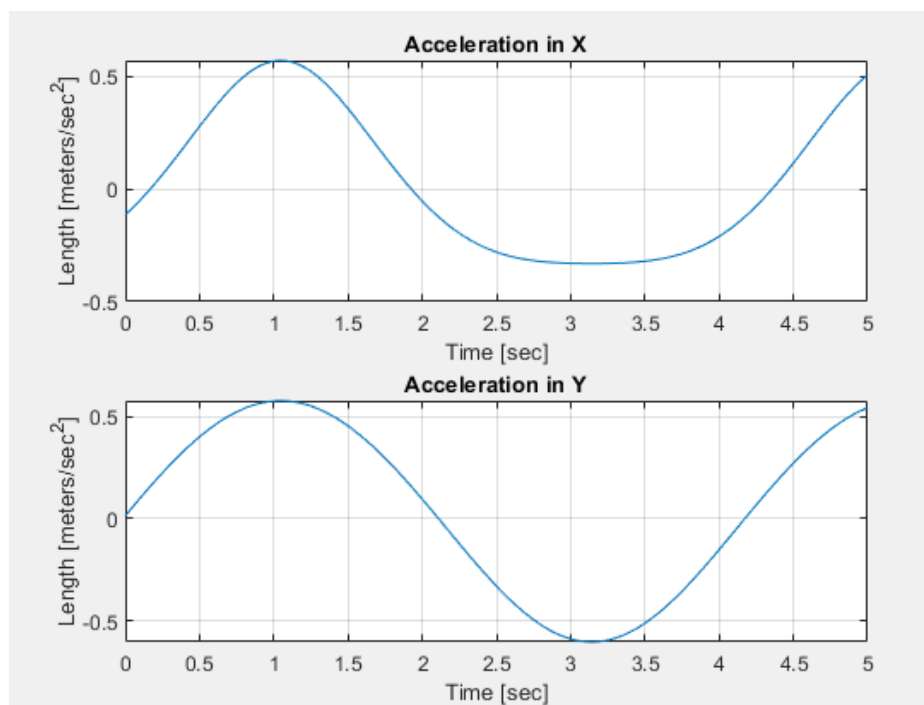
Adams:



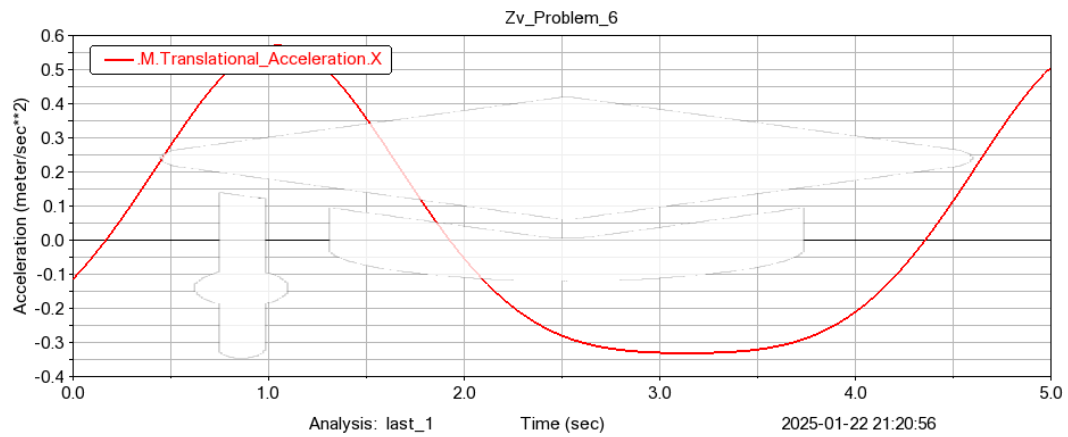


Acceleration

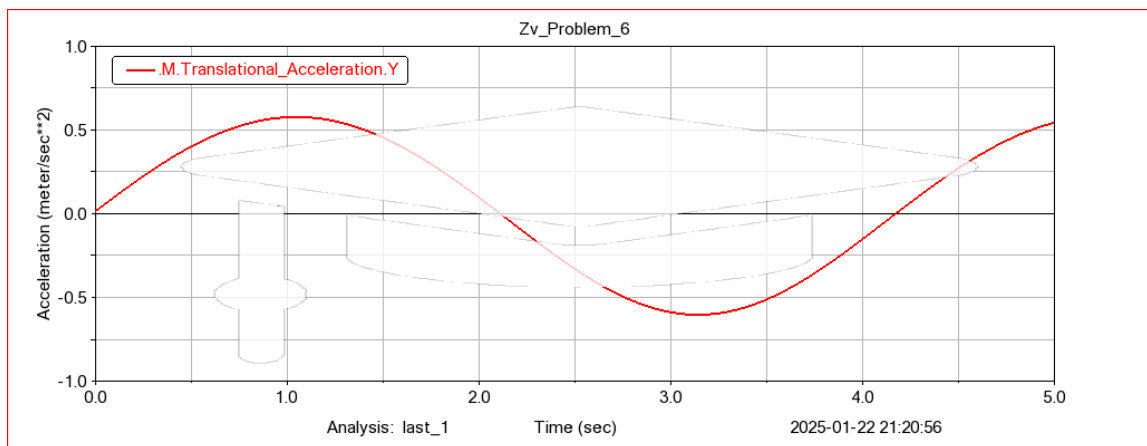
Matlab



Adams

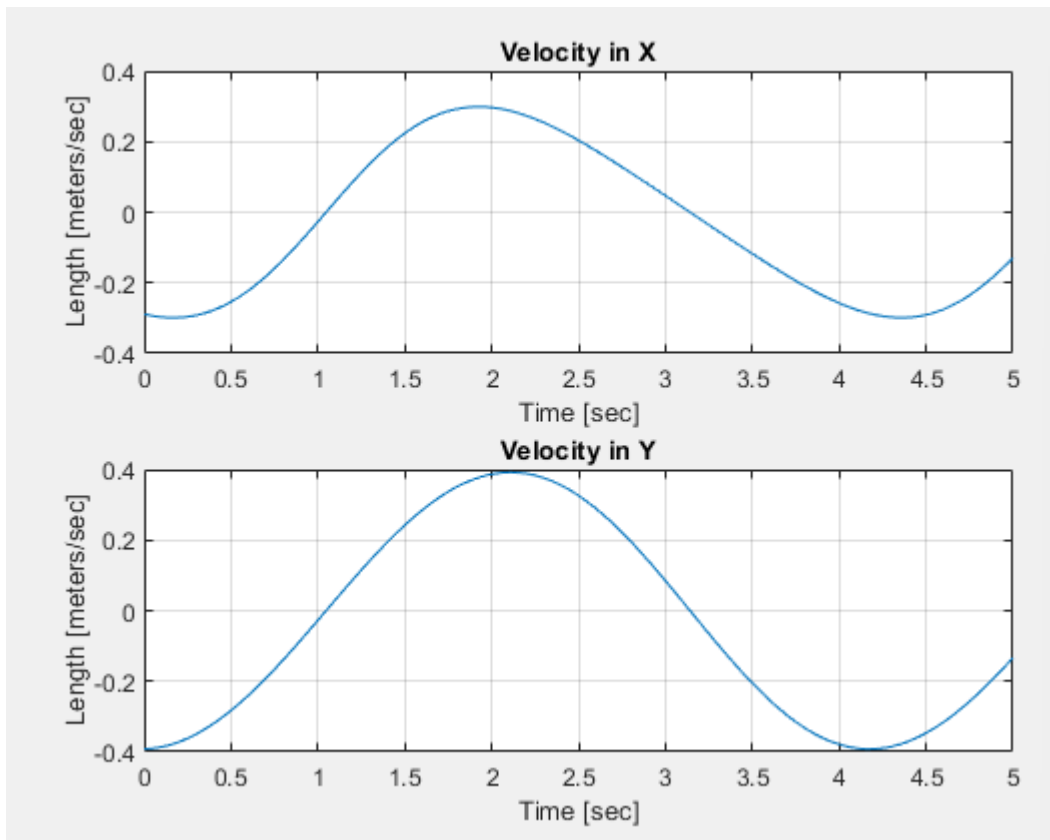


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	force
	constraint
	Object
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	+ CYL_HG
	+ LIN_CB
	+ PISTON_HG
	- PISTON_NM
	cm
	M
	MARKER_21
	MARKED 41
	Characteristic
	Total_Force_On_Point
	Total_Torque_On_Point
	Total_Force_At_Location
	Total_Torque_At_Location
	Translational_Displacement
	Translational_Velocity
	Translational_Acceleration
	Angular_Velocity
	Angular_Acceleration
	Component
	X
	Y
	Z
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	Add Curves To Current Plot
	Clear Plot
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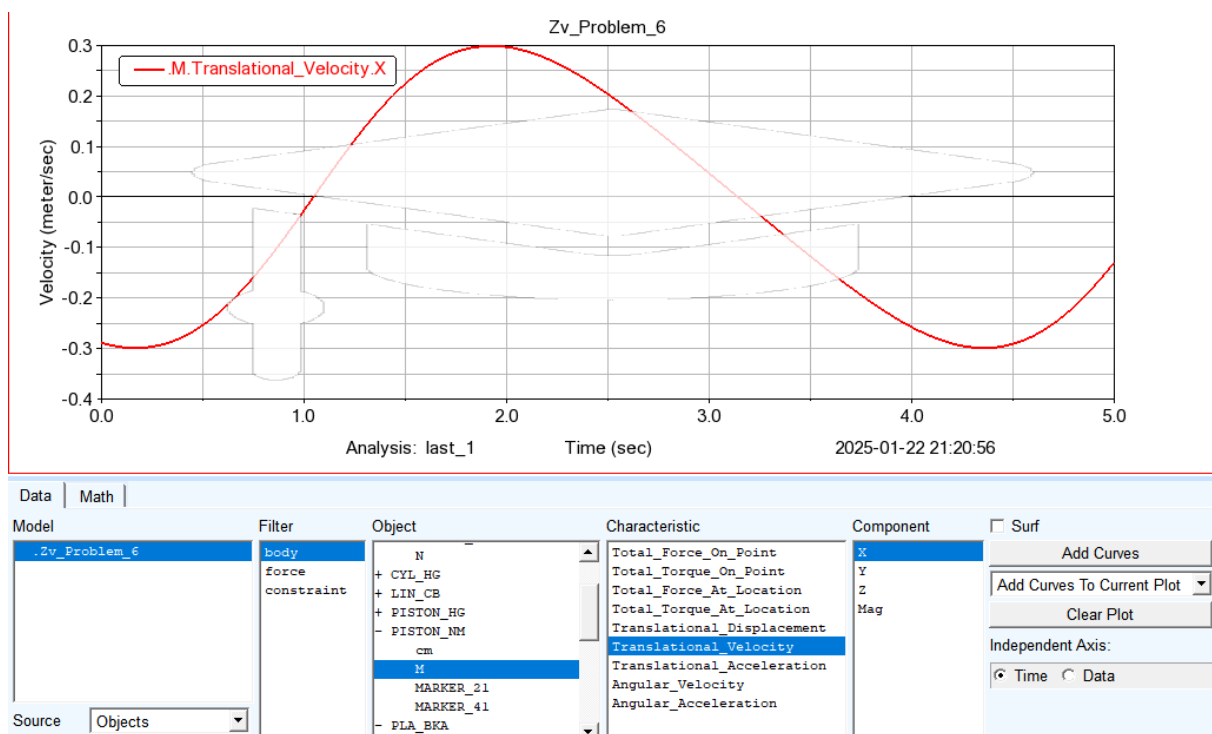


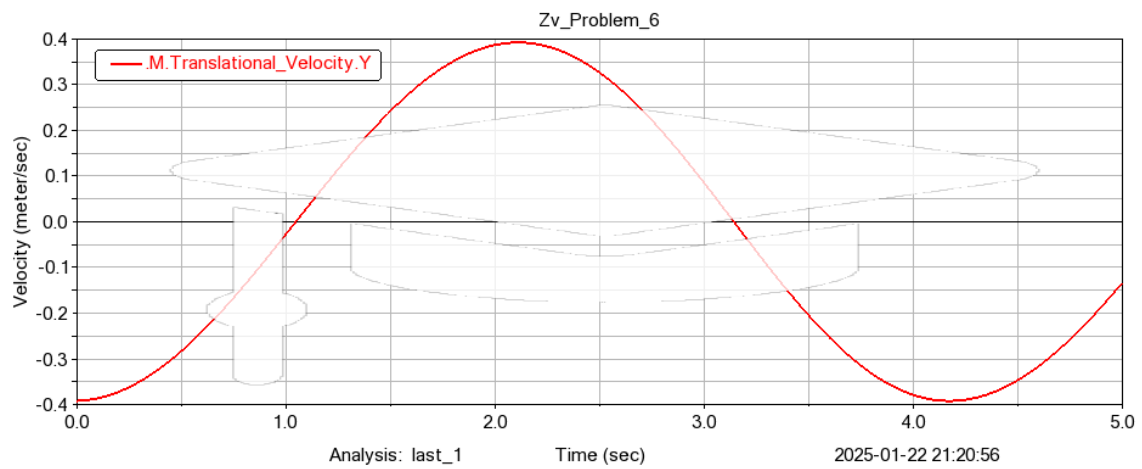
Velocity

Matlab



Adams

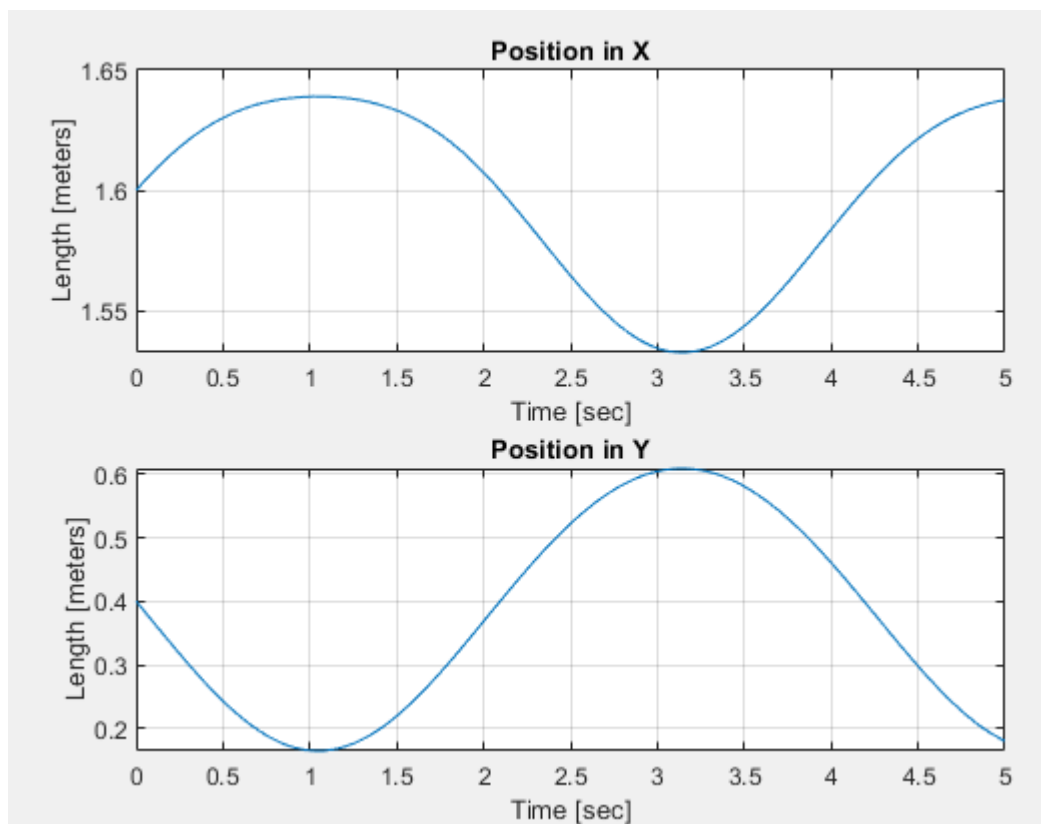




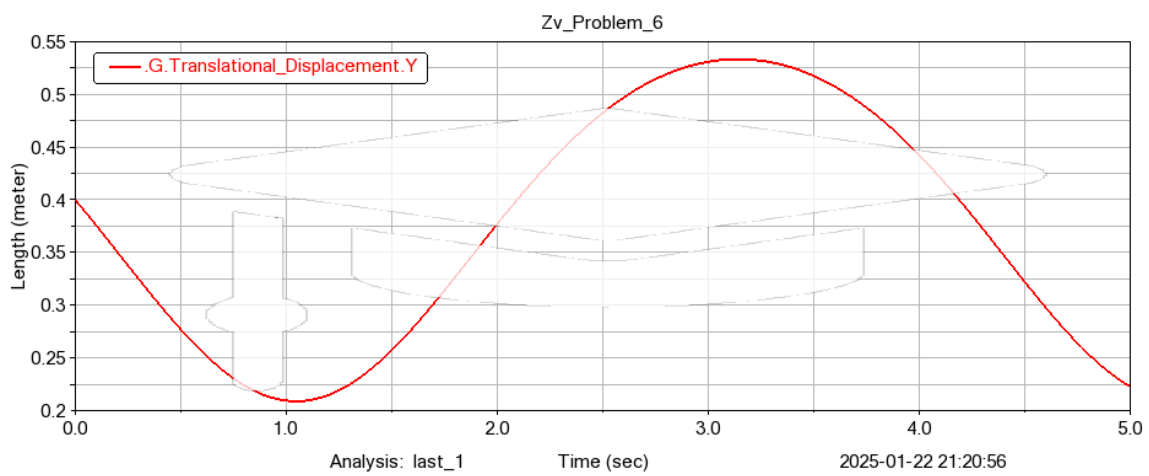
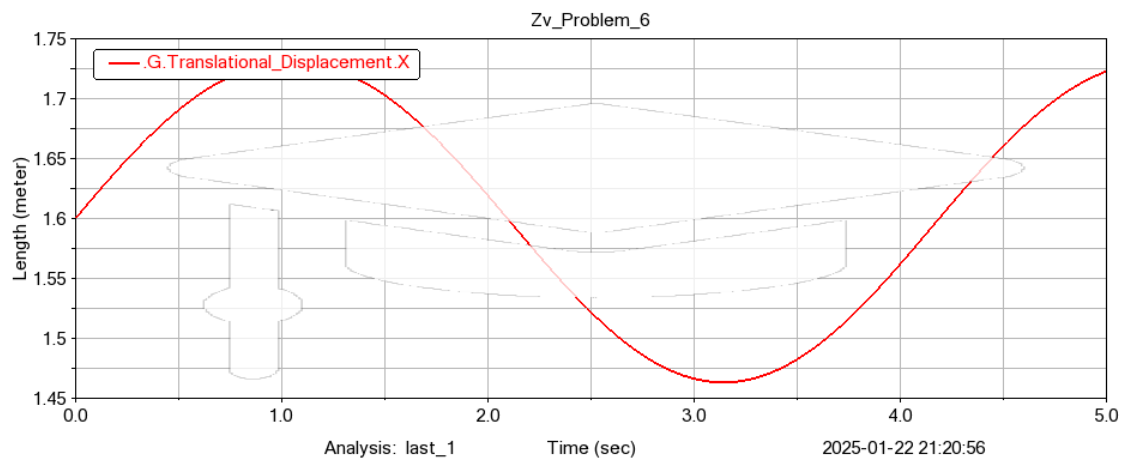
Point G = 8

position

Matlab

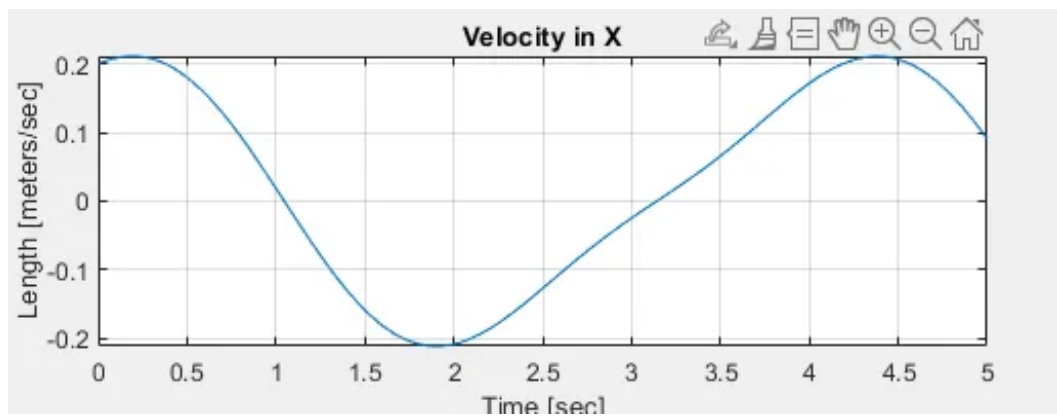


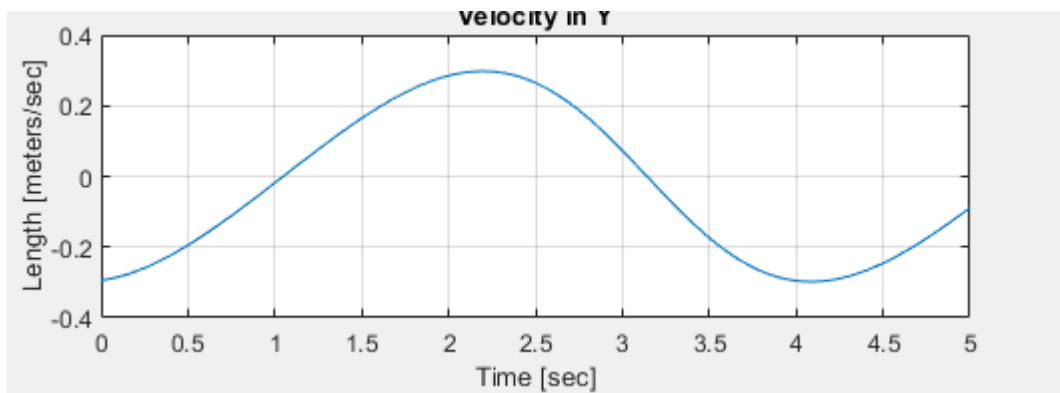
Adams



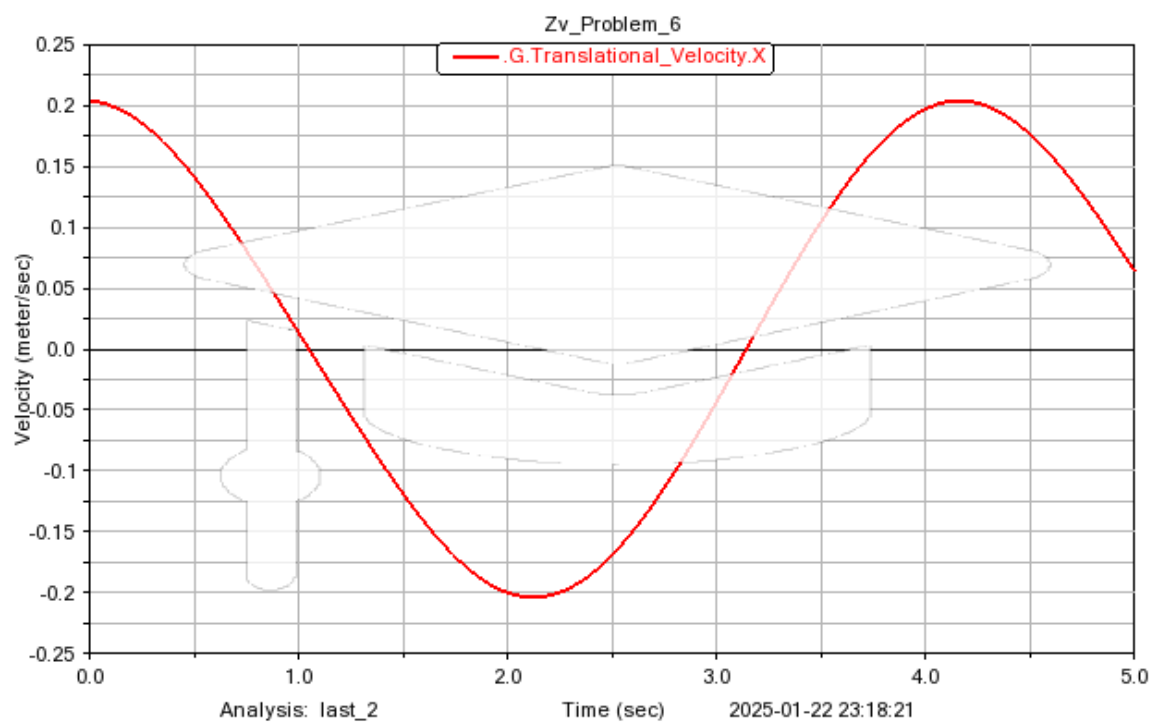
Velocity

Matlab





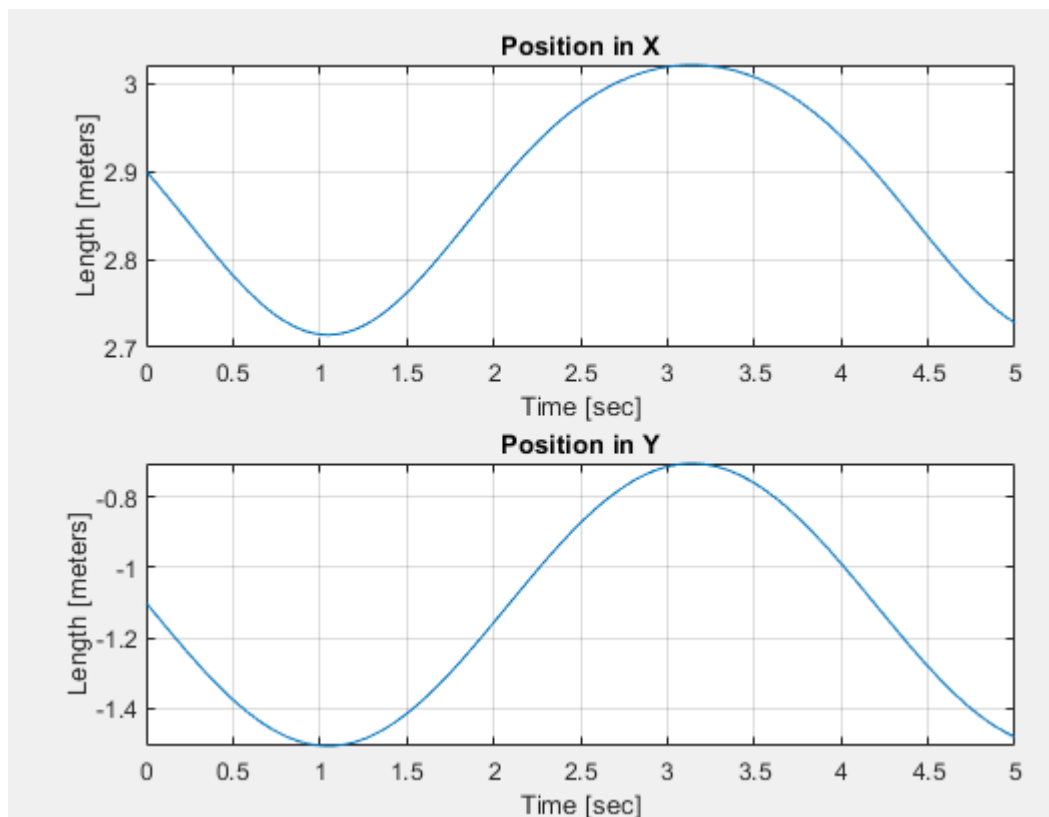
Adams



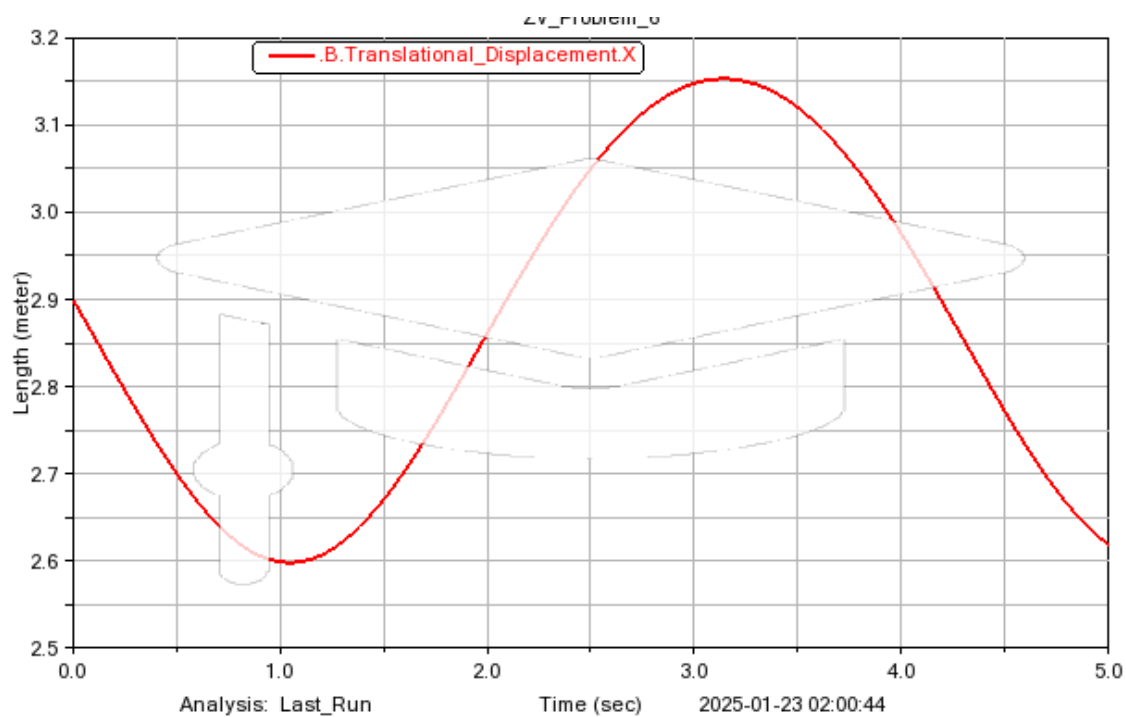
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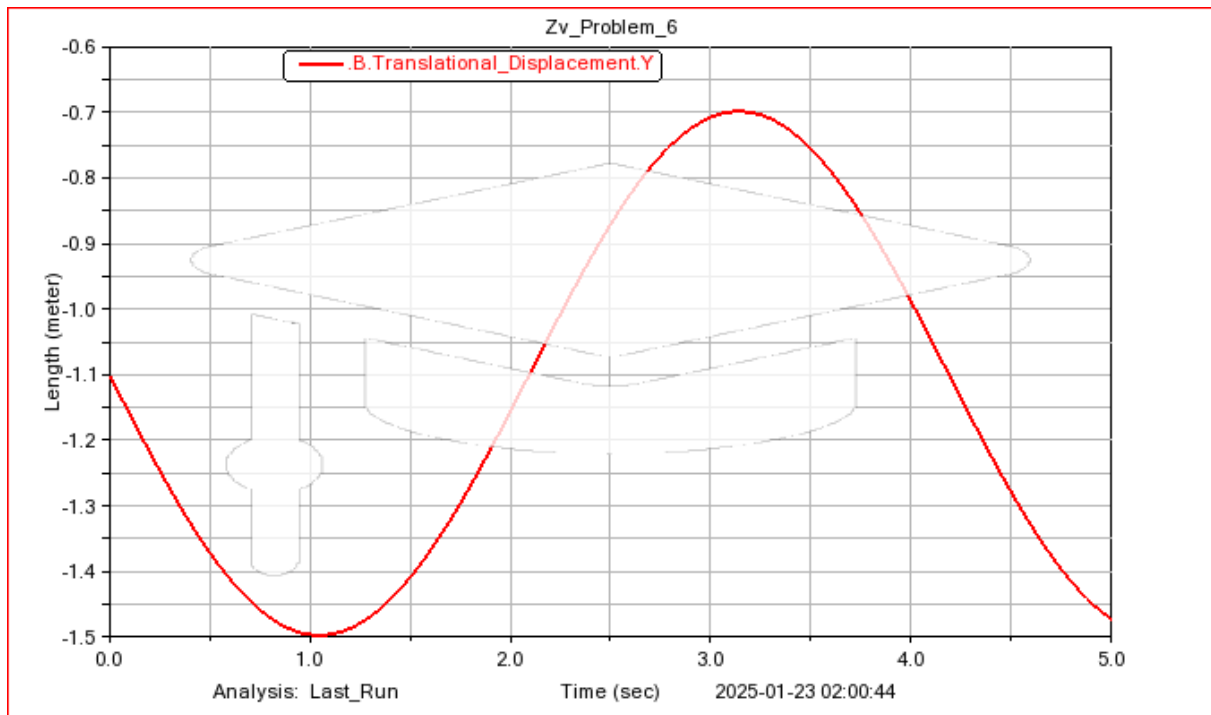
Position

Matlab



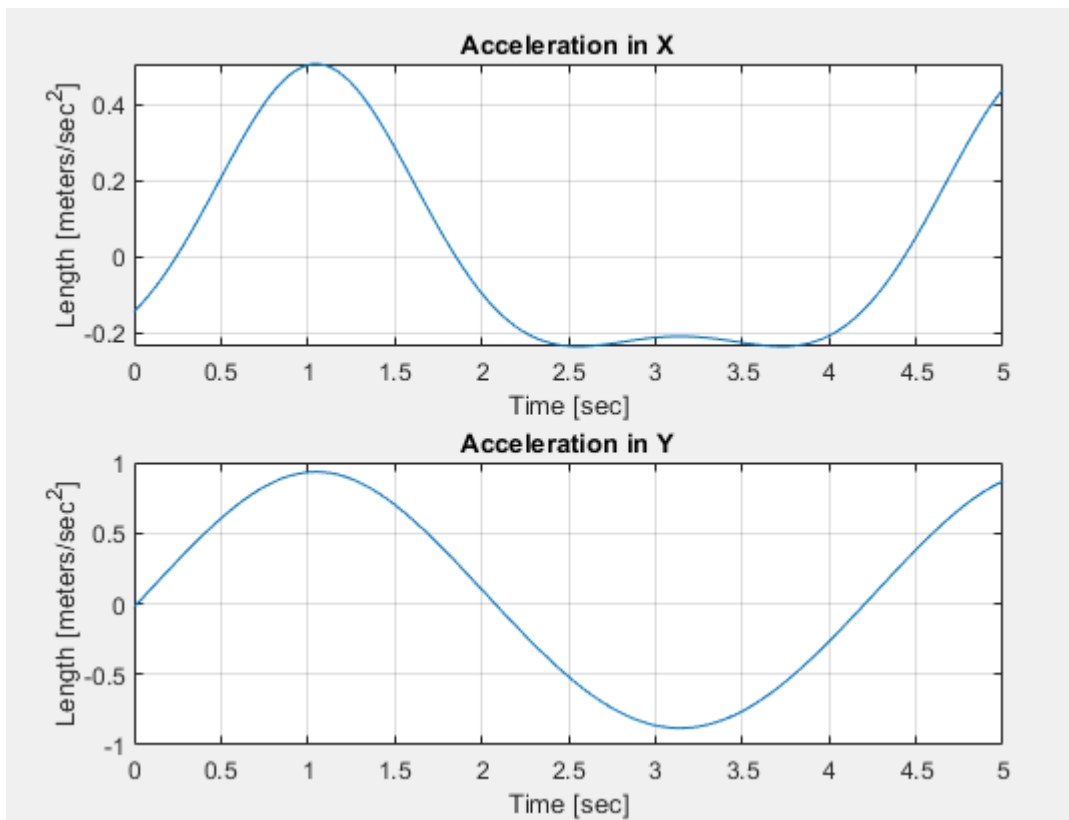
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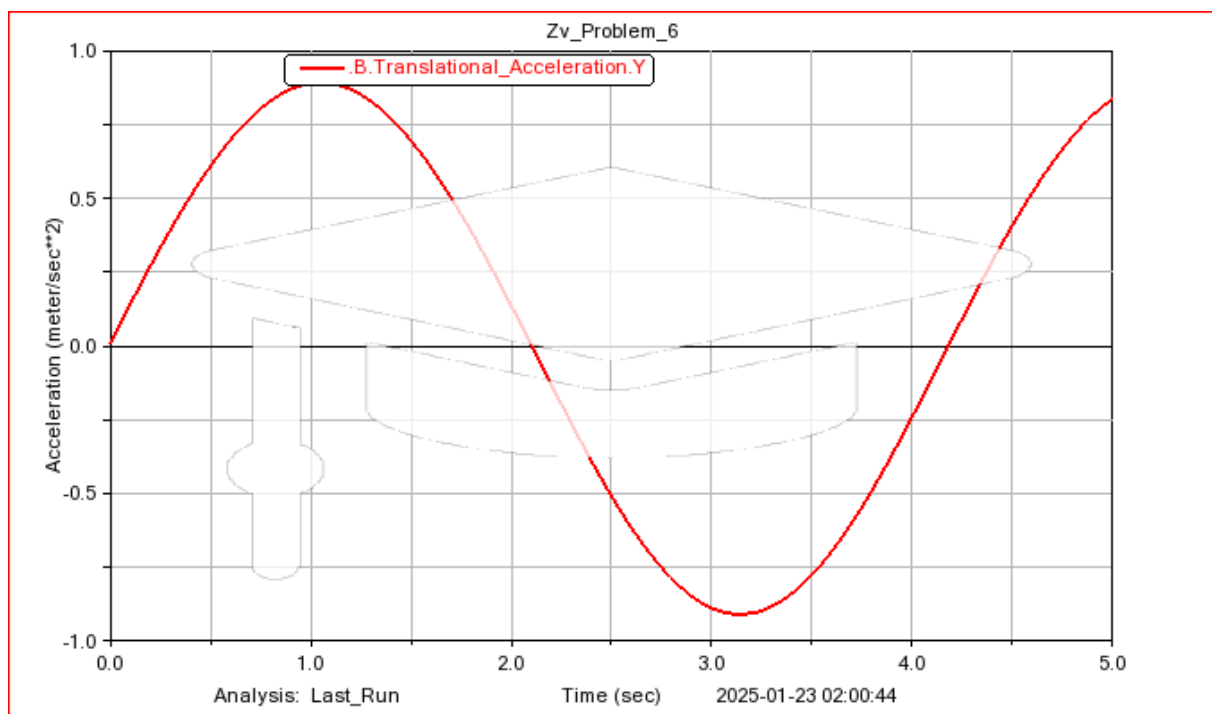
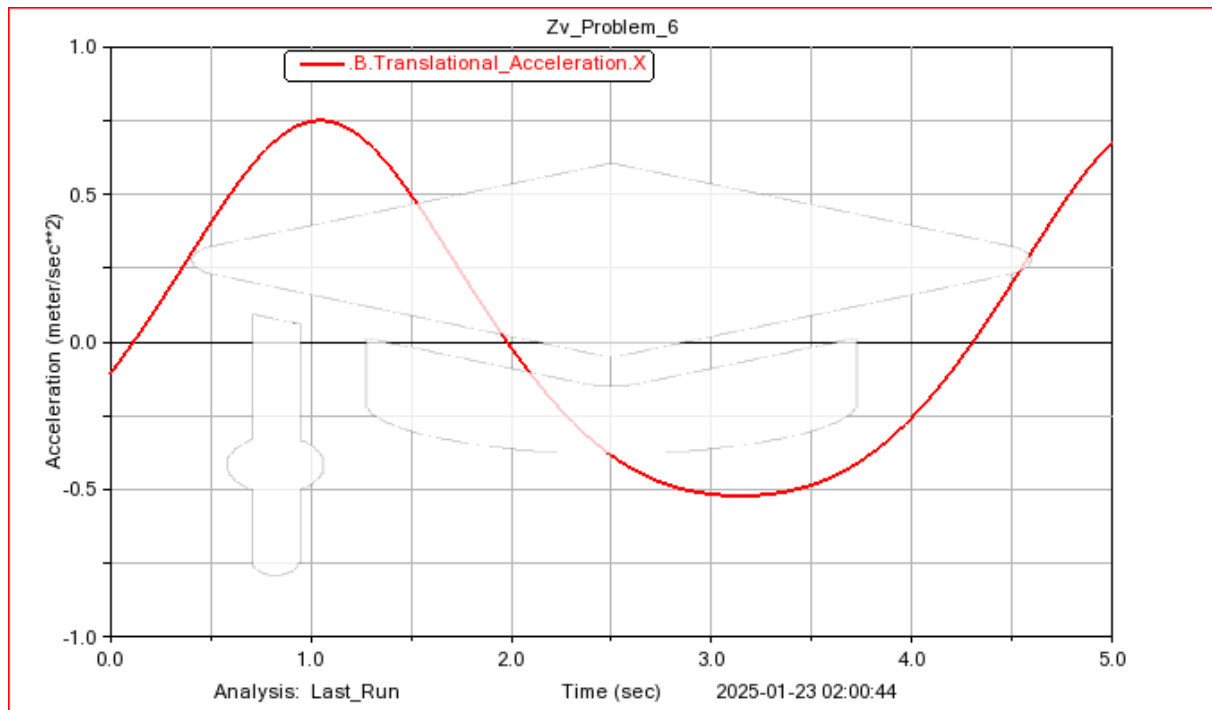


Acceleration

Matlab

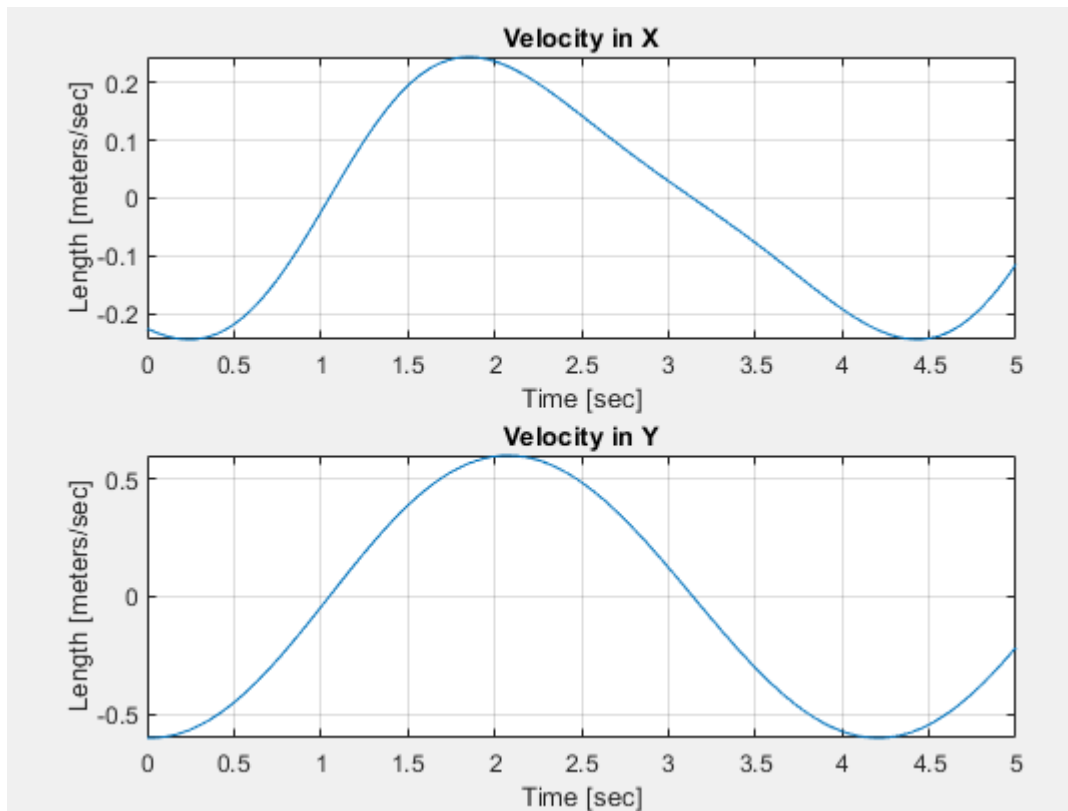


Adams



Velocity

Matlab



Adams

