

Задача трёх тел

Вариант описания 1



$$\begin{cases} x_1(t) & v_{x1}(t) & y_1(t) & v_{y1}(t) \\ x_2(t) & v_{x2}(t) & y_2(t) & v_{y2}(t) \\ x_3(t) & v_{x3}(t) & y_3(t) & v_{y3}(t) \end{cases}$$

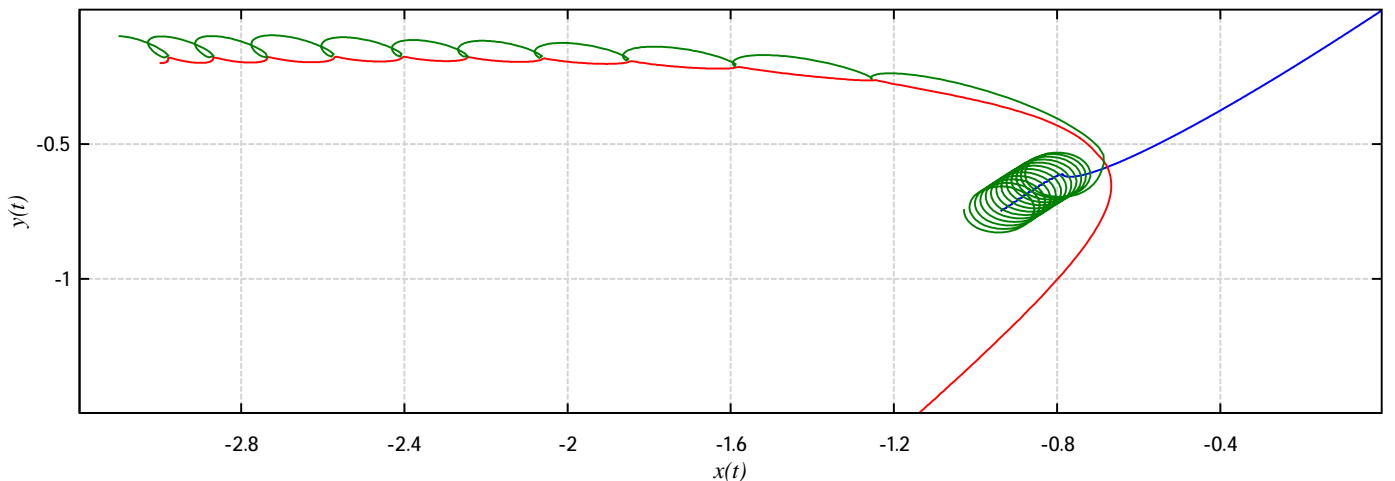
appVersion(4) = "1.2.9018.0"

 $G := 1$ $m_1 := 30$ $m_2 := 2$ $m_3 := 0.5$ $t_{end} := 1$

funvec

$$\begin{cases} x_1(0) = 0 & x_2(0) = -3 & x_3(0) = -3.1 & y_1(0) = 0 & y_2(0) = -0.2 & y_3(0) = -0.1 \\ v_{x1}(0) = -1 & v_{x2}(0) = 1 & v_{x3}(0) = 2 & v_{y1}(0) = -1 & v_{y2}(0) = 0 & v_{y3}(0) = 0 \\ \frac{d}{dt} x_1(t) = v_{x1}(t) & \frac{d}{dt} v_{x1}(t) = \frac{G \cdot m_2 \cdot (x_2(t) - x_1(t))}{\sqrt{(x_2(t) - x_1(t))^2 + (y_2(t) - y_1(t))^2}^3} + \frac{G \cdot m_3 \cdot (x_3(t) - x_1(t))}{\sqrt{(x_3(t) - x_1(t))^2 + (y_3(t) - y_1(t))^2}^3} \\ \frac{d}{dt} y_1(t) = v_{y1}(t) & \frac{d}{dt} v_{y1}(t) = \frac{G \cdot m_2 \cdot (y_2(t) - y_1(t))}{\sqrt{(x_2(t) - x_1(t))^2 + (y_2(t) - y_1(t))^2}^3} + \frac{G \cdot m_3 \cdot (y_3(t) - y_1(t))}{\sqrt{(x_3(t) - x_1(t))^2 + (y_3(t) - y_1(t))^2}^3} \\ \frac{d}{dt} x_2(t) = v_{x2}(t) & \frac{d}{dt} v_{x2}(t) = \frac{G \cdot m_1 \cdot (x_1(t) - x_2(t))}{\sqrt{(x_2(t) - x_1(t))^2 + (y_2(t) - y_1(t))^2}^3} + \frac{G \cdot m_3 \cdot (x_3(t) - x_2(t))}{\sqrt{(x_3(t) - x_2(t))^2 + (y_3(t) - y_2(t))^2}^3} \\ \frac{d}{dt} y_2(t) = v_{y2}(t) & \frac{d}{dt} v_{y2}(t) = \frac{G \cdot m_1 \cdot (y_1(t) - y_2(t))}{\sqrt{(x_2(t) - x_1(t))^2 + (y_2(t) - y_1(t))^2}^3} + \frac{G \cdot m_3 \cdot (y_3(t) - y_2(t))}{\sqrt{(x_3(t) - x_2(t))^2 + (y_3(t) - y_2(t))^2}^3} \\ \frac{d}{dt} x_3(t) = v_{x3}(t) & \frac{d}{dt} v_{x3}(t) = \frac{G \cdot m_1 \cdot (x_1(t) - x_3(t))}{\sqrt{(x_3(t) - x_1(t))^2 + (y_3(t) - y_1(t))^2}^3} + \frac{G \cdot m_2 \cdot (x_2(t) - x_3(t))}{\sqrt{(x_3(t) - x_2(t))^2 + (y_3(t) - y_2(t))^2}^3} \\ \frac{d}{dt} y_3(t) = v_{y3}(t) & \frac{d}{dt} v_{y3}(t) = \frac{G \cdot m_1 \cdot (y_1(t) - y_3(t))}{\sqrt{(x_3(t) - x_1(t))^2 + (y_3(t) - y_1(t))^2}^3} + \frac{G \cdot m_2 \cdot (y_2(t) - y_3(t))}{\sqrt{(x_3(t) - x_2(t))^2 + (y_3(t) - y_2(t))^2}^3} \end{cases}$$

M := Rkadapt (funvec, t_end, 1100)



Вариант описания 2

ClearAll(1)=1

$\left\{ \begin{array}{l} x1(t) \quad y1(t) \\ x2(t) \quad y2(t) \\ x3(t) \quad y3(t) \end{array} \right.$

$G := 1$

$m_1 := 30$

$m_2 := 2$

$m_3 := 0.5$

$t_{end} := 1$

funvec

$x1(0) = 0 \quad x1'(0) = -1 \quad x2(0) = -3 \quad x2'(0) = 1 \quad x3(0) = -3.1 \quad x3'(0) = 2$

$y1(0) = 0 \quad y1'(0) = -1 \quad y2(0) = -0.2 \quad y2'(0) = 0 \quad y3(0) = -0.1 \quad y3'(0) = 0$

$$x1''(t) = \frac{G \cdot m_2 \cdot (x2(t) - x1(t))}{\sqrt{(x2(t) - x1(t))^2 + (y2(t) - y1(t))^2}^3} + \frac{G \cdot m_3 \cdot (x3(t) - x1(t))}{\sqrt{(x3(t) - x1(t))^2 + (y3(t) - y1(t))^2}^3}$$

$$y1''(t) = \frac{G \cdot m_2 \cdot (y2(t) - y1(t))}{\sqrt{(x2(t) - x1(t))^2 + (y2(t) - y1(t))^2}^3} + \frac{G \cdot m_3 \cdot (y3(t) - y1(t))}{\sqrt{(x3(t) - x1(t))^2 + (y3(t) - y1(t))^2}^3}$$

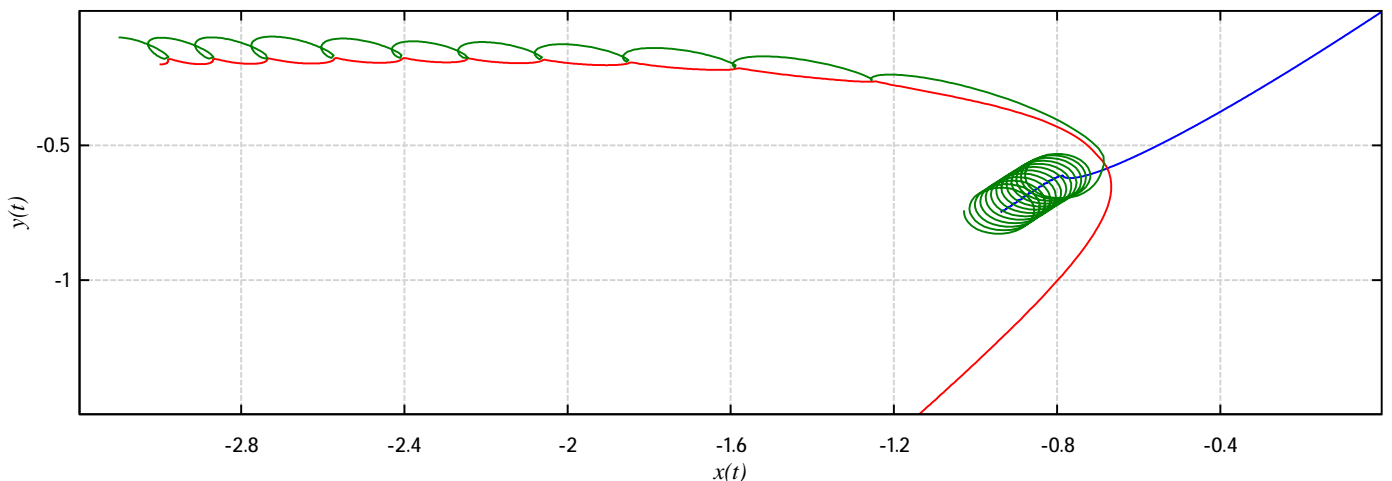
$$x2''(t) = \frac{G \cdot m_1 \cdot (x1(t) - x2(t))}{\sqrt{(x2(t) - x1(t))^2 + (y2(t) - y1(t))^2}^3} + \frac{G \cdot m_3 \cdot (x3(t) - x2(t))}{\sqrt{(x3(t) - x2(t))^2 + (y3(t) - y2(t))^2}^3}$$

$$y2''(t) = \frac{G \cdot m_1 \cdot (y1(t) - y2(t))}{\sqrt{(x2(t) - x1(t))^2 + (y2(t) - y1(t))^2}^3} + \frac{G \cdot m_3 \cdot (y3(t) - y2(t))}{\sqrt{(x3(t) - x2(t))^2 + (y3(t) - y2(t))^2}^3}$$

$$x3''(t) = \frac{G \cdot m_1 \cdot (x1(t) - x3(t))}{\sqrt{(x3(t) - x1(t))^2 + (y3(t) - y1(t))^2}^3} + \frac{G \cdot m_2 \cdot (x2(t) - x3(t))}{\sqrt{(x3(t) - x2(t))^2 + (y3(t) - y2(t))^2}^3}$$

$$y3''(t) = \frac{G \cdot m_1 \cdot (y1(t) - y3(t))}{\sqrt{(x3(t) - x1(t))^2 + (y3(t) - y1(t))^2}^3} + \frac{G \cdot m_2 \cdot (y2(t) - y3(t))}{\sqrt{(x3(t) - x2(t))^2 + (y3(t) - y2(t))^2}^3}$$

$M := \text{Rkadapt}(\text{funvec}, t_{end}, 1100)$



Вариант описания 3

ClearAll (1)=1

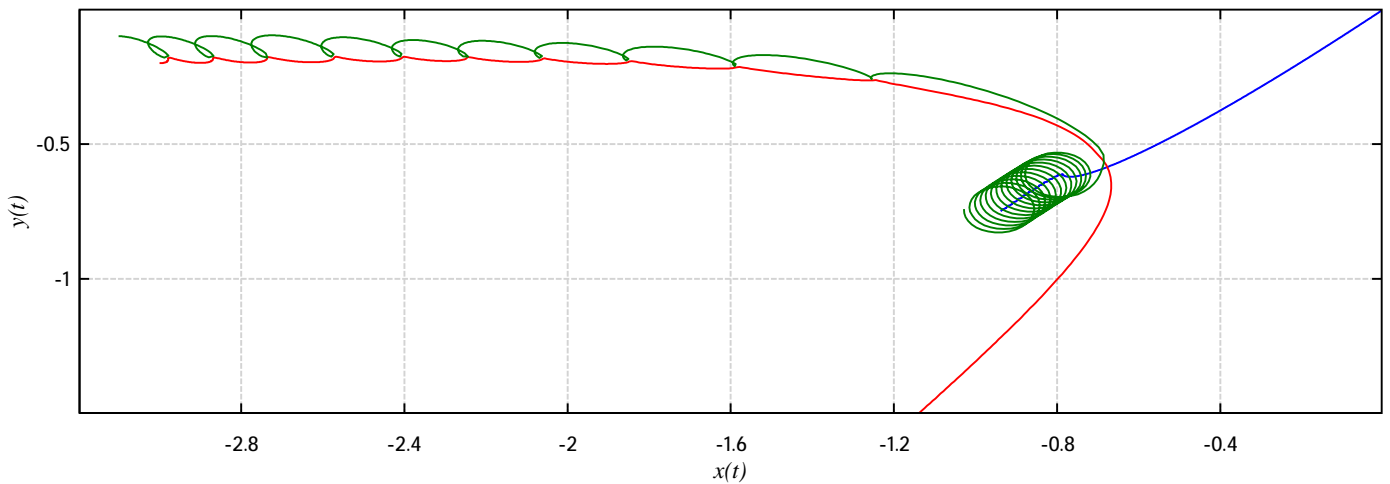
$$\left\{ \begin{array}{l} x1(t) \quad y1(t) \\ x2(t) \quad y2(t) \\ x3(t) \quad y3(t) \end{array} \right. \quad \begin{array}{l} G := 1 \quad m_1 := 30 \quad m_2 := 2 \quad m_3 := 0.5 \quad t_{end} := 1 \\ \Delta x_{21} := x2(t) - x1(t) \quad \Delta x_{12} := -\Delta x_{21} \quad \Delta y_{21} := y2(t) - y1(t) \quad \Delta y_{12} := -\Delta y_{21} \\ \Delta x_{31} := x3(t) - x1(t) \quad \Delta x_{13} := -\Delta x_{31} \quad \Delta y_{31} := y3(t) - y1(t) \quad \Delta y_{13} := -\Delta y_{31} \\ \Delta x_{32} := x3(t) - x2(t) \quad \Delta x_{23} := -\Delta x_{32} \quad \Delta y_{32} := y3(t) - y2(t) \quad \Delta y_{23} := -\Delta y_{32} \end{array}$$

funvec

$$r_{21} := \sqrt{\Delta x_{21}^2 + \Delta y_{21}^2} \quad r_{31} := \sqrt{\Delta x_{31}^2 + \Delta y_{31}^2} \quad r_{32} := \sqrt{\Delta x_{32}^2 + \Delta y_{32}^2}$$

$$\left\{ \begin{array}{l} x1(0) = 0 \quad x1'(0) = -1 \quad x2(0) = -3 \quad x2'(0) = 1 \quad x3(0) = -3.1 \quad x3'(0) = 2 \\ y1(0) = 0 \quad y1'(0) = -1 \quad y2(0) = -0.2 \quad y2'(0) = 0 \quad y3(0) = -0.1 \quad y3'(0) = 0 \\ x1''(t) = \frac{G \cdot m_2 \cdot \Delta x_{21}}{r_{21}^3} + \frac{G \cdot m_3 \cdot \Delta x_{31}}{r_{31}^3} \quad y1''(t) = \frac{G \cdot m_2 \cdot \Delta y_{21}}{r_{21}^3} + \frac{G \cdot m_3 \cdot \Delta y_{31}}{r_{31}^3} \\ x2''(t) = \frac{G \cdot m_1 \cdot \Delta x_{12}}{r_{21}^3} + \frac{G \cdot m_3 \cdot \Delta x_{32}}{r_{32}^3} \quad y2''(t) = \frac{G \cdot m_1 \cdot \Delta y_{12}}{r_{21}^3} + \frac{G \cdot m_3 \cdot \Delta y_{32}}{r_{32}^3} \\ x3''(t) = \frac{G \cdot m_1 \cdot \Delta x_{13}}{r_{31}^3} + \frac{G \cdot m_2 \cdot \Delta x_{23}}{r_{32}^3} \quad y3''(t) = \frac{G \cdot m_1 \cdot \Delta y_{13}}{r_{31}^3} + \frac{G \cdot m_2 \cdot \Delta y_{23}}{r_{32}^3} \end{array} \right.$$

M := Rkadapt (funvec, t_end, 1100)



Вариант описания 4

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ClearAll(1)=1
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$$\Delta x_{21} := x_2(t) - x_1(t) \quad \Delta x_{12} := -\Delta x_{21} \quad \Delta y_{21} := y_2(t) - y_1(t) \quad \Delta y_{12} := -\Delta y_{21}$$

$$\Delta x_{31} := x_3(t) - x_1(t) \quad \Delta x_{13} := -\Delta x_{31} \quad \Delta y_{31} := y_3(t) - y_1(t) \quad \Delta y_{13} := -\Delta y_{31}$$

$$\Delta x_{32} := x_3(t) - x_2(t) \quad \Delta x_{23} := -\Delta x_{32} \quad \Delta y_{32} := y_3(t) - y_2(t) \quad \Delta y_{23} := -\Delta y_{32}$$

$$F(n\#, u\#, v\#) := \begin{cases} s := \text{var2str} \left(\frac{G \cdot m_u \cdot \Delta n_{uv}}{\sqrt{\Delta x_{uv}^2 + \Delta y_{uv}^2}^3} \right) \\ s := \text{strrep}(s, \text{num2str}(u), \text{num2str}(u\#)) \\ s := \text{strrep}(s, \text{num2str}(v), \text{num2str}(v\#)) \\ \text{str2num}(\text{strrep}(s, \text{num2str}(n), \text{num2str}(n\#))) \end{cases} \quad \begin{cases} x_1(t) & y_1(t) \\ x_2(t) & y_2(t) \\ x_3(t) & y_3(t) \end{cases} \quad \text{funvec}$$

$$G := 1$$

$$m_1 := 30$$

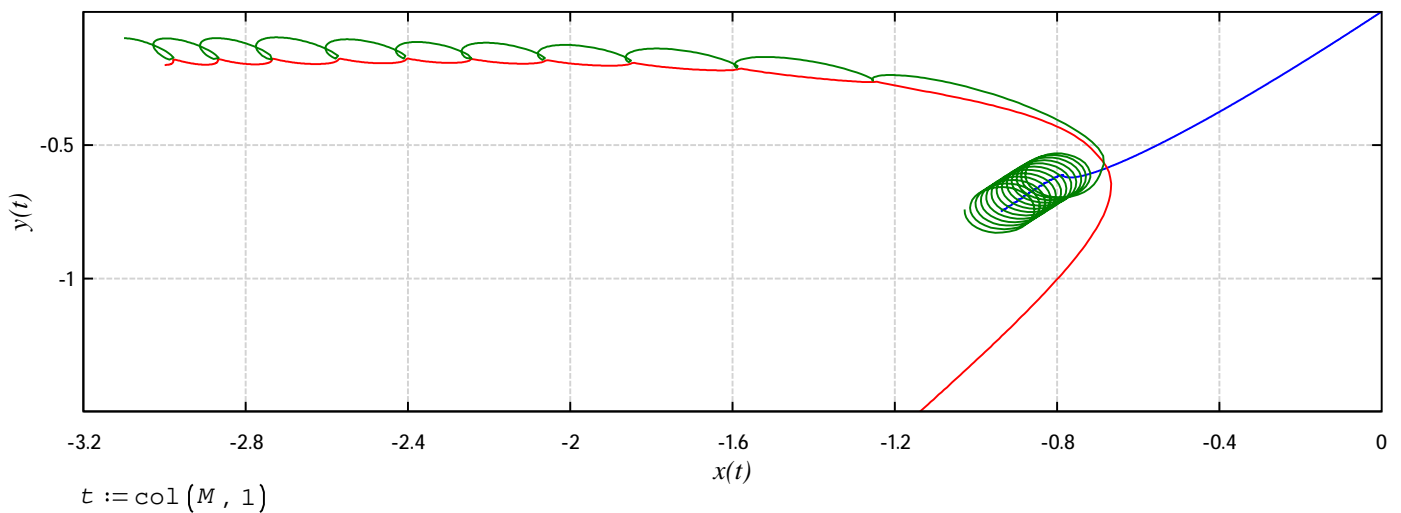
$$m_2 := 2$$

$$m_3 := 0.5$$

$$t_{\text{end}} := 1$$

$$\begin{cases} x_1(0) = 0 & x_1'(0) = -1 & x_2(0) = -3 & x_2'(0) = 1 & x_3(0) = -3.1 & x_3'(0) = 2 \\ y_1(0) = 0 & y_1'(0) = -1 & y_2(0) = -0.2 & y_2'(0) = 0 & y_3(0) = -0.1 & y_3'(0) = 0 \\ x_1''(t) = F(x, 2, 1) + F(x, 3, 1) & y_1''(t) = F(y, 2, 1) + F(y, 3, 1) \\ x_2''(t) = F(x, 1, 2) + F(x, 3, 2) & y_2''(t) = F(y, 1, 2) + F(y, 3, 2) \\ x_3''(t) = F(x, 1, 3) + F(x, 2, 3) & y_3''(t) = F(y, 1, 3) + F(y, 2, 3) \end{cases}$$

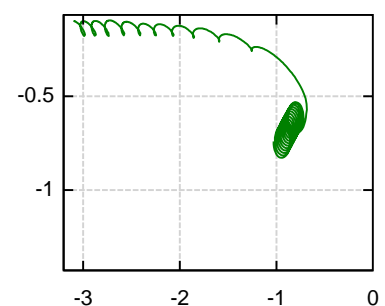
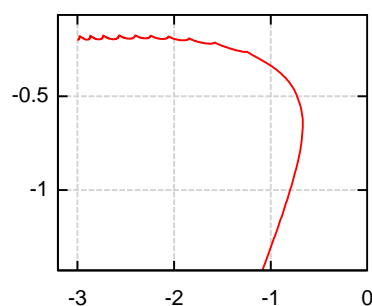
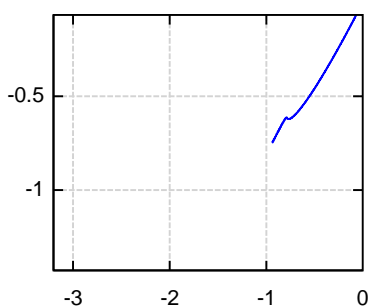
$$M := \text{Rkadapt}(\text{funvec}, t_{\text{end}}, 1100)$$



$$m_1 = 30$$

$$m_2 = 2$$

$$m_3 = 0.5$$



$$\begin{bmatrix} x_1(t) \\ y_1(t) \end{bmatrix}$$

$$\begin{bmatrix} x_2(t) \\ y_2(t) \end{bmatrix}$$

$$\begin{bmatrix} x_3(t) \\ y_3(t) \end{bmatrix}$$

Вариант описания 5

```
ClearAll(1)=1
```

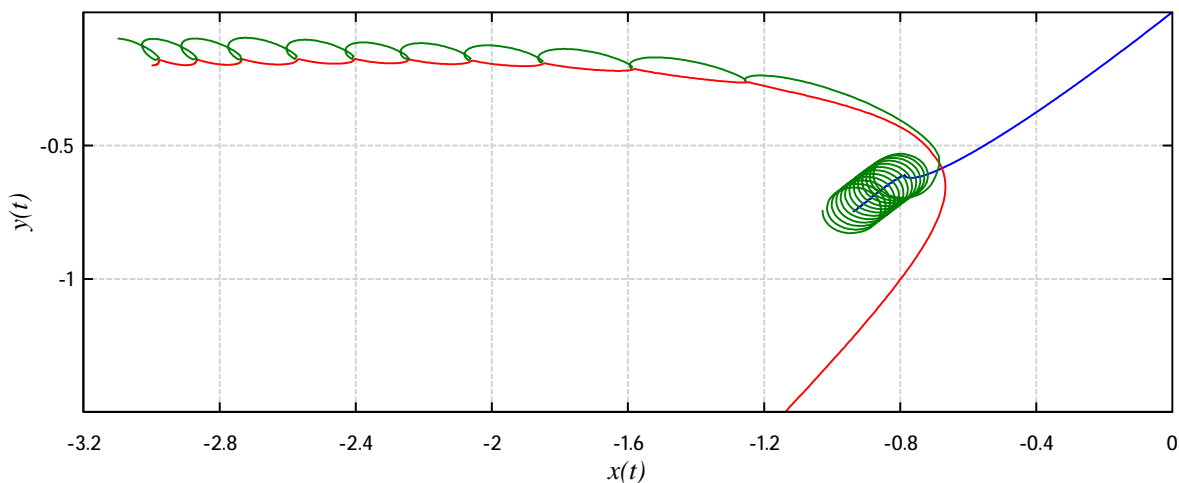
$$\left\{ \begin{array}{l} x1(t) \quad x2(t) \quad x3(t) \\ y1(t) \quad y2(t) \quad y3(t) \end{array} \right\} \left| \begin{array}{l} x := R \quad [1..3] \\ y := R \quad [4..6] \end{array} \right. \quad A(R, i, j) := \frac{G \cdot M_i \cdot (R_i - R_j)}{\text{norme} \left(\left[\begin{array}{l} x_i \quad y_i \end{array} \right] - \left[\begin{array}{l} x_j \quad y_j \end{array} \right] \right)^3}$$

R

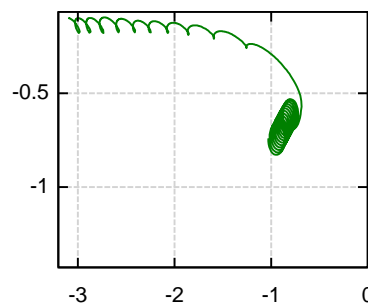
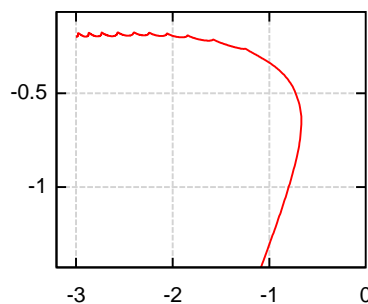
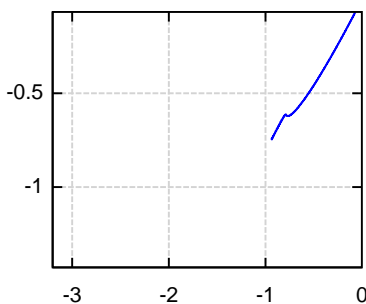
```
G:=1      m1:=30      m2:=2      m3:=0.5      tend:=1      M:=eval(stack(m1, m2, m3))
```

$$\left\{ \begin{array}{l} x1''(t) = A(x, 2, 1) + A(x, 3, 1) \\ x2''(t) = A(x, 1, 2) + A(x, 3, 2) \\ x3''(t) = A(x, 1, 3) + A(x, 2, 3) \\ y1''(t) = A(y, 2, 1) + A(y, 3, 1) \\ y2''(t) = A(y, 1, 2) + A(y, 3, 2) \\ y3''(t) = A(y, 1, 3) + A(y, 2, 3) \end{array} \right. \quad \begin{array}{l} x1(0) = 0 \quad x1'(0) = -1 \\ x2(0) = -3 \quad x2'(0) = 1 \\ x3(0) = -3.1 \quad x3'(0) = 2 \\ y1(0) = 0 \quad y1'(0) = -1 \\ y2(0) = -0.2 \quad y2'(0) = 0 \\ y3(0) = -0.1 \quad y3'(0) = 0 \end{array}$$

```
M:=Rkadapt(R, tend, 1100)
```



```
t:=col(M, 1)
```

 $m_1 = 30$
 $m_2 = 2$
 $m_3 = 0.5$

 $\begin{bmatrix} x1(t) \\ y1(t) \end{bmatrix}$
 $\begin{bmatrix} x2(t) \\ y2(t) \end{bmatrix}$
 $\begin{bmatrix} x3(t) \\ y3(t) \end{bmatrix}$

```
var2str([[x1(t)],[y1(t)]])="mat(x1(~t),y1(~t),2,1)"
```

Вариант описания 6

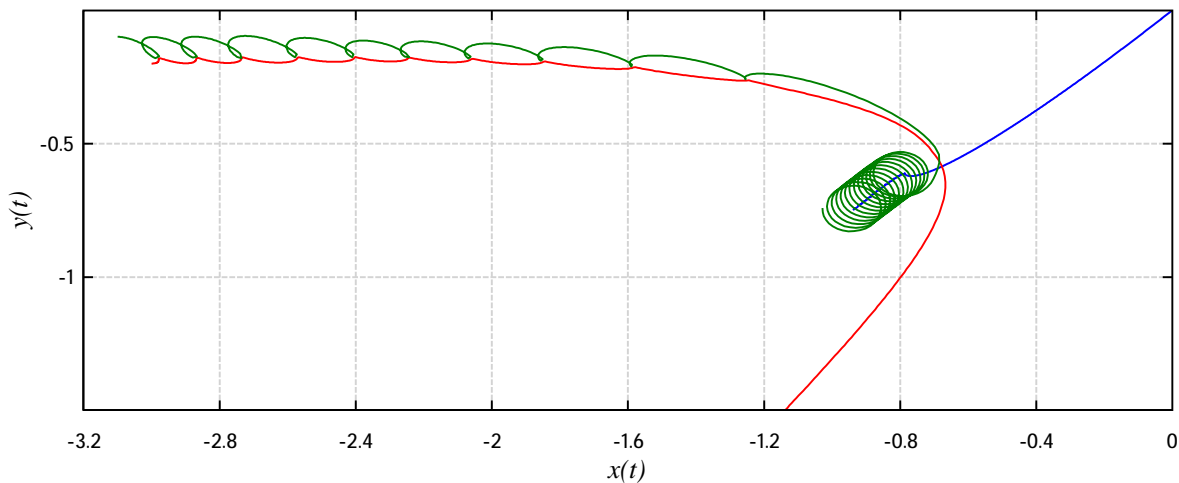
ClearAll(1)=1

$$\left\{ \begin{array}{l} x1(t) \quad x2(t) \quad x3(t) \\ y1(t) \quad y2(t) \quad y3(t) \end{array} \right| \begin{array}{l} x := R[1..3] \\ y := R[4..6] \end{array} \quad a(p, i, j) := \frac{G \cdot M_i \cdot (p_i - p_j)}{\text{norme} \left(\left[\begin{array}{l} x_i \quad y_i \end{array} \right] - \left[\begin{array}{l} x_j \quad y_j \end{array} \right] \right)^3} \quad \Sigma a(p, j) := \text{for } i \in [1 \ 2 \ 3] \\ a_i := a(p, i, j) \\ \sum a$$

$G := 1$ $m_1 := 30$ $m_2 := 2$ $m_3 := 0.5$ $t_{\text{end}} := 1$ $M := \text{stack}(m_1, m_2, m_3)$

$$\left\{ \begin{array}{l} x1''(t) = \Sigma a(x, 1) \quad x1(0) = 0 \quad x1'(0) = -1 \\ x2''(t) = \Sigma a(x, 2) \quad x2(0) = -3 \quad x2'(0) = 1 \\ x3''(t) = \Sigma a(x, 3) \quad x3(0) = -3.1 \quad x3'(0) = 2 \\ y1''(t) = \Sigma a(y, 1) \quad y1(0) = 0 \quad y1'(0) = -1 \\ y2''(t) = \Sigma a(y, 2) \quad y2(0) = -0.2 \quad y2'(0) = 0 \\ y3''(t) = \Sigma a(y, 3) \quad y3(0) = -0.1 \quad y3'(0) = 0 \end{array} \right.$$

$M := \text{Rkadapt}(R, t_{\text{end}}, 1100)$

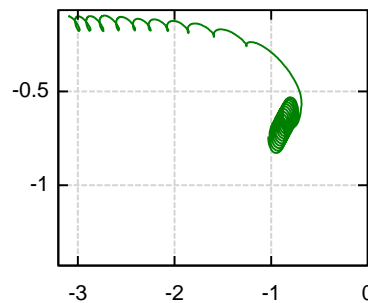
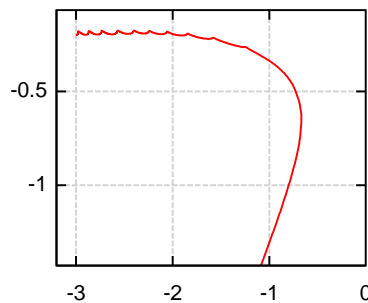
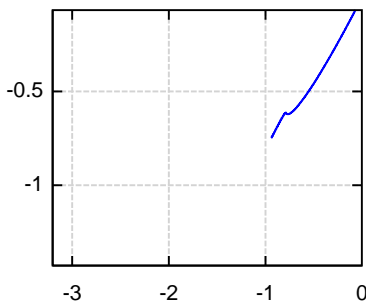


$t := \text{col}(M, 1)$

$m_1 = 30$

$m_2 = 2$

$m_3 = 0.5$



$$\begin{bmatrix} x1(t) \\ y1(t) \end{bmatrix}$$

$$\begin{bmatrix} x2(t) \\ y2(t) \end{bmatrix}$$

$$\begin{bmatrix} x3(t) \\ y3(t) \end{bmatrix}$$

$\text{var2str} \left(\begin{bmatrix} x1(t) \\ y1(t) \end{bmatrix} \right) = \text{"mat}(x1(\sim t), y1(\sim t), 2, 1) \text{"}$