

Vectors

$$\vec{v} = [a_1, a_2, \dots, a_n]$$

$$\text{zero vector: } \vec{0} = [0, 0, \dots, 0]$$

parallel vector: $\vec{v} \parallel \vec{w}$ (\vec{v} & \vec{w} should be non-zero vectors), if $\vec{v} = r\vec{w}$ for some non-zero real number r

$$\text{transpose } \vec{v}^T \quad [a, b, c]^T = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \quad \text{column vector}$$

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix}^T = [a, b, c] \quad \text{row vector}$$

$$\text{magnitude } \|\vec{u}\| = \sqrt{u_1^2 + u_2^2 + \dots + u_n^2}$$

span $\text{sp}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n) =$ the set of all linear combinations of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$

$$\text{dot product } \vec{v} = [v_1, v_2, \dots, v_n] \quad \vec{w} = [w_1, w_2, \dots, w_n]$$

$$\vec{v} \cdot \vec{w} = v_1 w_1 + v_2 w_2 + \dots + v_n w_n$$

> 2 inequalities: 1° triangle inequality: $\|\vec{v} + \vec{w}\| \leq \|\vec{v}\| + \|\vec{w}\|$

2° Cauchy-Schwarz inequality: $|\vec{v} \cdot \vec{w}| \leq \|\vec{v}\| \|\vec{w}\|$

$$> \langle \vec{v}, \vec{w} \rangle = \arccos \frac{\vec{v} \cdot \vec{w}}{\|\vec{v}\| \|\vec{w}\|}$$

$$\text{perpendicular/orthogonal} \Leftrightarrow \vec{v} \cdot \vec{w} = 0$$

$$\frac{\vec{v} \cdot \vec{w}}{\|\vec{v}\| \|\vec{w}\|} \quad \text{duality!}$$

projection

$$\vec{p} = \text{proj}_{\vec{a}} \vec{b}$$

$$\vec{p} = k\vec{a}$$

$$k=0 \Leftrightarrow \vec{b} = \vec{0} \text{ or } \vec{b} \perp \vec{a}$$

$$k = \frac{\vec{b} \cdot \vec{a}}{\|\vec{a}\|^2} \quad \vec{p} = \frac{\vec{b} \cdot \vec{a}}{\|\vec{a}\|^2} \cdot \vec{a}$$

Matrices

An $m \times n$ matrix A :

$M_{m \times n}(\mathbb{R})$

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

$m=n$: square matrix

all entries are 0: $O_{m \times n}$ zero matrix

For a square matrix:

(1) $\forall i \neq j, a_{ij} = 0$: diagonal matrix

(2) $a_{ij} = \begin{cases} 0, & \forall i \neq j \\ 1, & \forall i = j \end{cases}$: identity matrix

(3) $a_{ij} = 0, \forall i > j$: upper triangular matrix

(4) $a_{ij} = 0, \forall i < j$: lower triangular matrix

Transpose A & A^T

symmetric matrix: $A = A^T$

skew symmetric matrix: $A = -A^T$

$$(A + A^T)^T = A + A^T$$

$$\vec{a} \cdot \vec{b} = \vec{a}^T \vec{b}$$

$$(AB)^T = B^T A^T$$

Multiplication $(A: m \times n)(B: n \times k) = (C: m \times k)$

$$(AB)_{ij} = (i^{\text{th}} \text{ row of } A) (j^{\text{th}} \text{ col of } B) = C_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

$$ACB + C = AB + AC \quad (A+B)C = AC + BC$$

Trace $A \in M_{m,n}(R)$

$$\text{tr}(A) = \sum_{i=1}^n a_{ii}$$

$$\text{tr}(AB) = \text{tr}(BA)$$

Linear System of Equations

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

$$\underset{A}{\phantom{\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}}} \quad \underset{\vec{x}}{\phantom{\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}}} = \underset{\vec{b}}{\phantom{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}}}$$

A : coefficient matrix

$[A|b]$: augmented/partitioned matrix

$A\vec{x} = \vec{b}$ has solution(s) iff b is in the span of the col of A

Elementary Row Operation

$$\left. \begin{array}{l} \text{row interchange } R_i \leftrightarrow R_j \\ \text{row scaling } R_i \rightarrow aR_i \quad a \neq 0 \\ \text{row addition } R_i \rightarrow R_i + sR_j \end{array} \right\} \begin{array}{l} A \sim B \\ \text{row equivalent} \end{array}$$

IF $[A|b] \sim [H|a]$, THEN $A\vec{x} = \vec{b}$ and $H\vec{x} = \vec{a}$ have the same soln set

> Row Echelon Form REF

Reduced Row Echelon Form RREF (unique)

> Solve linear equations: Gauss reduction with back substitution method
Gauss-Jordan method

$\left\{ \begin{array}{l} \text{consistent solution: have soln} \\ \text{inconsistent solution: do not have soln} \end{array} \right.$

> Elementary Matrix

Inverse $A \begin{cases} \text{invertible: if } \exists C \text{ s.t. } AC = CA = I \\ \text{singular} \end{cases}$

$$(A^{-1})^T = (A^T)^{-1} \quad (AB)^{-1} = B^{-1}A^{-1} \quad (A+B)^{-1} \& A^{-1}+B^{-1} \text{ are not necessarily the same}$$

> A is invertible iff RREF of $[A|I]$ is $[I|C]$

A is invertible iff $|A| \neq 0$

A is invertible iff col vectors of A form a basis for \mathbb{R}^n
 iff $A\vec{x} = \vec{b}$ has a soln for all $\vec{b} \in \mathbb{R}^n$
 iff A can be expressed as a product of elementary matrices
 iff $\text{span}(\text{row}(A))$ or $\text{span}(\text{col}(A))$ is \mathbb{R}^n

Homogeneous System: $A\vec{x} = \vec{0}$

consistent and has a trivial soln $\vec{0}$

> null space: $\text{null}(A) = \{\vec{x} \in \mathbb{R}^n \mid A\vec{x} = \vec{0}\}$

row/col space: $\text{row}(A)$ $\text{col}(A)$

> linearly independent: $[\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_n] \vec{x} = \vec{0}$ only has the trivial soln

Dimension

Subspace $W \subseteq \mathbb{R}^n$, W is a subspace of \mathbb{R}^n if

1° W is nonempty

2° if $\vec{u}, \vec{v} \in W$, then $\vec{u} + \vec{v} \in W$ (closure under vector addition)

3° if $\vec{u} \in W, r \in \mathbb{R}$, then $r\vec{u} \in W$ (closure under scalar multiplication)

B is a Basis for W , if 1° $W = \text{sp}(B)$

2° $\forall \vec{w} \in W, B\vec{x} = \vec{w}$ has a unique soln

Dimension of W : $\dim(W)$ is the # of elements in a basis for W

$\text{rank}(A) = \dim(\text{col}(A)) = \dim(\text{row}(A))$

$\text{nullity}(A) = \dim(\text{null}(A))$

★ for $A: m \times n$ $A \sim H$

$\text{rank}(A) + \text{nullity}(A) = n$

of pivots in H

of col in H without pivots

Linear Transformation

$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ ① $T(\vec{u} + \vec{v}) = T(\vec{u}) + T(\vec{v})$

② $T(r\vec{v}) = rT(\vec{v})$

lines remain lines; origin does not move

\mathbb{R}^n : domain \mathbb{R}^m : codomain

$W \subseteq \mathbb{R}^n$, the image of W under T : $T[W] = \{T(\vec{w}) \mid \vec{w} \in W\}$

$= \{\vec{y} \in \mathbb{R}^m \mid \exists \vec{u} \in W, T(\vec{u}) = \vec{y}\}$

$W' \subseteq \mathbb{R}^m$, the inverse image of W' under T is $T^{-1}[W'] = \{\vec{v} \in \mathbb{R}^n \mid T(\vec{v}) \in W'\}$

range of T : $\text{range}(T) = \{T(\vec{v}) \mid \vec{v} \in \mathbb{R}^n\}$

kernel of T : $\ker(T) = \{\vec{v} \in \mathbb{R}^n \mid T(\vec{v}) = \vec{0}\}$

$\forall \vec{x} \in \mathbb{R}^n \quad T(\vec{x}) = A\vec{x}$, A is the standard matrix representation of T

one-to-one: $T(\vec{v}) = T(\vec{u}) \rightarrow \vec{v} = \vec{u}$ $\text{null}(A) = \{\vec{0}\}$

onto: $\text{range}(T) = \mathbb{R}^m$ $\text{rank}(A) = m$

isomorphism: one-to-one and onto

Determinant

determinant: $1 \times 1 \quad \det(A) = |a| = a$

$2 \times 2 \quad \det(A) = \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} = a_1 b_2 - b_1 a_2$

$3 \times 3 \quad \det(A) = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$

$> n \times n$: $A = [A_{ij}] \quad n \times n$

minor matrix A_{ij} is a $(n-1) \times (n-1)$ matrix obtained by removing the i^{th} row and j^{th} col of A

cofactor of a_{ij} of A is $a'_{ij} = (-1)^{i+j} |A_{ij}|$ A'

$\det(A) = \sum_{i=1}^n a_{ij}' a_{ij}$ or $\sum_{j=1}^n a_{ij}' a_{ij} = |A|$

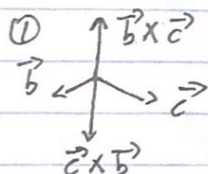
Cross Product

$\vec{a} = [a_1, a_2, a_3], \vec{b} = [b_1, b_2, b_3] \in \mathbb{R}^3$

$\vec{c} = \vec{a} \times \vec{b} = \begin{bmatrix} |a_2 & a_3| \\ |b_2 & b_3| \end{bmatrix}, -|a_1 & a_3|, |a_1 & a_2|$

$\vec{c} \perp \vec{a} \quad \vec{c} \perp \vec{b}$

$\vec{b} \times \vec{c} = -\vec{c} \times \vec{b}$



②. $\vec{a} \times (\vec{b} \times \vec{c})$ not as $(\vec{a} \times \vec{b}) \times \vec{c}$

$\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c}$

$\vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$

③. area of a parallelogram: $|\vec{a} \times \vec{b}|$

volume of a parallelepiped: $|\vec{a} \cdot (\vec{b} \times \vec{c})| = |(\vec{a} \times \vec{b}) \cdot \vec{c}|$

①. $A R_i \leftrightarrow R_j B \quad |B| = -|A|$

$A R_j \rightarrow r R_j B \quad |B| = r|A|$

$A R_i \rightarrow R_i + r R_j B \quad |B| = |A|$

②. $|A| = |A^T| \quad |A| |A^{-1}| = 1$

③. $|rA| = r^n |A| \quad |\text{adj}(A)| = |A|^{n-1}$

④. if A is a triangular matrix, then

$|A| = \prod_{i=1}^n a_{ii}$



adjacent matrix: $\text{adj}(A) = (A')^T$

$$> \text{adj}(A)A = A\text{adj}(A) = |A|I$$

$$A^{-1} = \frac{\text{adj}(A)}{\det(A)} \quad (|A| \neq 0)$$

Cramer's Rule

$A\vec{x} = \vec{b}$ $|A| \neq 0$ n equations with n unknowns

then, $\vec{x} = [x_1, x_2, \dots, x_n]$ is of the form $x_k = \frac{|B_k|}{|A|}$

(B_k is A with the k^{th} col replaced by \vec{b})

Eigenvalues & Eigenvectors

if \exists a non-zero vector \vec{v} , s.t. $A\vec{v} = \lambda\vec{v}$

λ : eigenvalue

\vec{v} : eigenvector

characteristic polynomial: $p(\lambda) = |\lambda I - A|$ algebraic multiplicity \geq geometric multiplicity: $\dim(E_{\lambda_i})$

characteristic equation: $|\lambda I - A| = 0$ (the soln are the eigenvalues of A)

eigenspace of λ : $E_{\lambda} = \{\vec{x} \in \mathbb{R}^n \mid A\vec{x} = \lambda\vec{x}\} (= \text{null}(A - \lambda I))$

> for A and λ , (1) λ^k is an eigenvalue of A^k , and \vec{v} is an eigenvector of A ($k \in \mathbb{N}$)

(2) $\lambda = 0$ is not an eigenvalue of $A \iff A$ is invertible

(3) $\frac{1}{\lambda}$ is an eigenvalue of A^{-1} , and \vec{v} is an eigenvector of A (A is invertible)

Diagonalizable Matrix: if \exists invertible matrix P s.t. $P^{-1}AP$ is diagonal then A is a diagonalizable matrix

A and B are similar matrices if \exists invertible matrix s.t. $B = P^{-1}AP$

(1) the matrix A has n eigenvalues (including each according to its algebraic multiplicity)

> A has n distinct eigenvalues $\Rightarrow \vec{v}_1, \dots, \vec{v}_n$ are linearly independent

\Updownarrow
 A is diagonalizable

(2) the sum of the n eigenvalues of $A = \text{tr}(A)$

the product of $A = \det(A)$

(3) For $p(\lambda) = \lambda^n + c_{n-1}\lambda^{n-1} + \dots + c_1\lambda + c_0$

1° $c_{n-1} = -\text{tr}(A)$ $c_0 = (-1)^n |A|$

2° The Cayley-Hamilton Thm: $p(A) = A^n + c_{n-1}A^{n-1} + \dots + c_1A + c_0I = 0$

$$> A^{-1} = -\frac{1}{c_0} (A^{n-1} + c_{n-1}A^{n-2} + \dots + c_1I)$$

(4) symmetric matrices are diagonalizable

Diagonalization Process

$A: n \times n$

1. $p(\lambda) = \det(A - \lambda I_n)$

2. $p(\lambda) = (\lambda - \lambda_1)^{n_1} \cdot (\lambda - \lambda_2)^{n_2} \dots (\lambda - \lambda_k)^{n_k}$

[when $p(\lambda)$ cannot be written as the form above, A is not diagonalizable]

3. from $(A - \lambda_i I) \vec{x} = \vec{0}$, find $E_{\lambda_i} = \text{null}(\lambda - \lambda_i I_n)$ $i = 1, \dots, k$

4. $\vec{x} = s_1 \vec{b}_1 + s_2 \vec{b}_2 + \dots + s_m \vec{b}_m$ $\{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_{m_i}\}$

If the algebraic multiplicity of $\lambda_i = 1$ or the geometric multiplicity of λ_i , then A is diagonalizable [else not diagonalizable]

5. the col position of b_j in P is the col position $P^{-1}AP = D$ of its associated eigenvalue on the diagonal of D

Linear Recurrence:

Fib seq: 1 1 2 3 5 8 13 ...

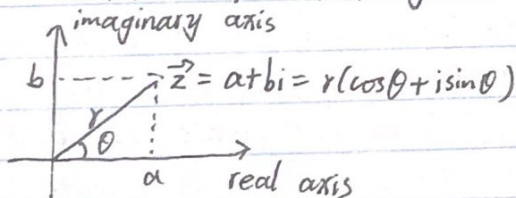
$$\begin{cases} x_{k+1} = x_{k+1} \\ x_k + x_{k+1} = x_{k+2} \end{cases} \Rightarrow \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_k \\ x_{k+1} \end{bmatrix} = \begin{bmatrix} x_{k+1} \\ x_{k+2} \end{bmatrix}$$

Complex Scalars

complex num: $z = x + iy$ $x, y \in \mathbb{R}$

$z \in \mathbb{C}$ $i^2 = -1/\sqrt{-1} = i$ $\text{Re } z = x$ $\text{Im } z = y$

absolute value/modules/magnitude of $z: |z| = \sqrt{x^2 + y^2}$



θ : argument of z

if $-\pi < \theta \leq \pi$, θ is the principle argument of z or $\text{Arg}(z)$

$r(\cos \theta + i \sin \theta)$: the polar form of z

①. $z_1 z_2 = |z_1| |z_2| [\cos(\text{Arg}(z_1) + \text{Arg}(z_2)) + i \sin(\text{Arg}(z_1) + \text{Arg}(z_2))]$

$z_1/z_2 = \frac{|z_1|}{|z_2|} [\cos(\text{Arg}(z_1) - \text{Arg}(z_2)) + i \sin(\text{Arg}(z_1) - \text{Arg}(z_2))]$

$\text{Arg}(z^n) = n\theta$

②. Conjugate: $\overline{a+ib} = a-ib$

$(a+ib)(\overline{a+ib}) = a^2 + b^2$

real & non-negative

$|z|^2 = z \bar{z} = a^2 + b^2$

$\overline{z_1 z_2} = \bar{z}_1 \bar{z}_2$

$z^{-1} = \frac{\bar{z}}{|z|^2}$

$|z_1 + z_2| \leq |z_1| + |z_2|$

If $z = r(\cos \theta + i \sin \theta) \in \mathbb{C}$, then

①. $z^n = r^n (\cos(n\theta) + i \sin(n\theta))$

②. the n^{th} roots of z are $r^{\frac{1}{n}} (\cos(\frac{\theta}{n} + \frac{2k\pi}{n}) + i \sin(\frac{\theta}{n} + \frac{2k\pi}{n}))$ $k = 0, 1, 2, \dots, n-1$