MODULE-1 SYSTEM OF LINEAR EQUATIONS

MAT3004 APPLIED LINEAR ALGEBRA VIT

Topics to be discussed

System of Linear Equations:

- Gaussian elimination
- Gauss Jordan methods
- Elementary matrices
- Permutation matrix
- Inverse matrices
- System of linear equations
- LU factorizations
- LDU factorizations

List of Definition and terms

- Linear equation (LE)
- System of linear equation (SLE)
- Matrix representation of a SLE (AX = B)
- Homogeneous and nonhomogeneous system
- Solution, Trivial solution, Unique solution, Infinite solution, No solution
- Consistency and Inconsistency of a system
- Augmented matrix, variable matrix, solution matrix
- Pivot element or key element

- Rows and Columns of a matrix, Elimination and reduction of a rows and columns
- 10. Forward and backward elimination
- 11. Row equivalent, Row reduction of 1st, 2nd, 3rd kinds
- ECHELON FORM of a matrix
- Triangular form of a matrix (Upper and Lower triangular form)
- Elementary matrix, Permutation matrix
- Block matrix, submatrix
- Inverse of a matrix, left and right inverse, invertible, non-singular, singular

Some problem types

- 1. Solve the following (given) system of equations using
 - Gauss Elimination method
 - Gauss Jordan Elimination method
 - Matrix inversion method
 - LU factorization method
 - LDU factorization method
- 2. Find the conditions for the consistency of a (given) system AX = B.
- 3. Find the values of a, b for which a (given) system AX = B has infinite solutions, no solution, unique solution.
- 4. Reduce the matrix (given) to Echelon form.
- 5. Find the inverse of a (given) matrix by Gauss Jordan method.
- 6. Find the LU and LDU decomposition of a given matrix.
- 7. Find the elementary matrices in I_n .
- 8. Write the matrix A as a product of elementary matrices.

Some Theorems

- 1. If a $n \times n$ square matrix A has a left inverse B and a right inverse C, then B and C are equal i.e.B = C. **Proof required.**
- 2. The product of invertible matrices is also invertible, whose inverse is the product of the individual inverses in reversed order i.e. $_{(AB)^{-1}} = B^{-1}A^{-1}$. 3. Let A be a $n \times n$ matrix. The following are equivalent: **Proof required.**
- - a) A has a left inverse;
 - b) $AX = \mathbf{0}$ has only the trivial solution $X = \mathbf{0}$;
 - c) A is row equivalent to I_n ;
 - d) A is a product of elementary matrices;
 - A is invertible;
 - A has a right inverse.

Proof required.

4. A triangular matrix is invertible if and only if it has no zero diagonal entry.

Statement only without proof.

Livour equation: Consider the equation $a_1x_1 + a_2x_2 + \dots a_nx_n = b$ where $a_1, a_2, \ldots a_n$ and b are constants is called livear equation. system of liver ignation: - (Group of liver equations) ix general system of m linear equations unknowns can be written as an x + an x2 + an x3 + ... an x = b1 agi xi + age x2 + agg x3 + aguxn=ba amixi+ amaxa+amixxx+...

whose $x_1, x_2, \dots x_n$ are the unknowns, an ap, ann one the oxyliciants of the system and by, by,.... but are the constant toins. The system @ is said to be homogonous Hall the constant tours one zono, i.e. b1=b2=...bm=0 othowise @ is known as non-homognous. Every hemogenous tel has trivial solution.

3x-5y=0=) x=0, y=0=) 0=0

In general, a linear system may have in any one of three possible ways: i) The system has a single (unique) solution. ii) The system has infinitely many solution: iii) The system has no elution.

The system is @ is said to be consistent if it has atlant the solution and inconsistent if it has no solution.

The system @ an he expressed as

where
$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \end{bmatrix}$$

$$A = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_n \end{bmatrix}$$

$$A = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_n \end{bmatrix}$$

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ a_{31} & a_{32} & \cdots & a_{3n} \\ a_{32} & a_{33} & \cdots & a_{3n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ a_{31} & a_{32} & \cdots & a_{3n} \\ a_{32} & a_{33} & \cdots & a_{3n} \\ a_{31} & a_{32} & \cdots & a_{3n} \\ a_{32} & \cdots & a_{3n} \\ a_{31} & \cdots & a_{3n} \\ a_{32} & \cdots & a_{3n} \\ a_{31} & \cdots & a_{3n} \\ a_{32} & \cdots & a_{3n} \\ a_{32} & \cdots & a_{3n} \\ a_{33} & \cdots & a_{3n} \\ a_{34} & \cdots & a_{3n} \\ a_{34} & \cdots & a_{3n} \\ a_{35}$$

is called argumented matrix.

Elementary operations:

matrix (system of linear equations) one allod demonstrary operations

- i.e. Ri ← Ri (li ← lj)
- ii) Multiply a non-zous constant throughout a row (an equation)
- iii) Add a constant multiple of an equation to

i.e. Ri -> ORI+R; (ON) Rj -> ORj+Ri

Row-echelon form of a matrix: - (Gours Dimination mother

of matrix is said to be in now-echelon four if it satisfies the following: (i) The 2000 nows, if they count, come last in the ordered ent. (ii) The fout non-zono entries, in the non-zono news are 1, called lading ences (iii) In each column containing a loading non-zono element, the entries below that leading non-zono

element are D.

The reduced sear-echelon form of an argumented matrix is q the form:

(iv) Above each leading is a column of zords in addition to the your-echelon form

Gauss - climination method: The gauss-elimination algorithm is as follows: (1) Write the argumented matrix of the system of linear equations. (ii) Find an echolon form of the argumented matrix using elementary sow operation. (iii) White the system of equations coronesponding to the echelen form. (iv) use back substitution to get the solution. dement:

The left mest new-zono entries in the

Example: Solve the system of linear equations 2y+4z=2, x+2y+2z=3, 3x+4y+6z=-1 and write The system of linear equations 0.x+2y+42=2 x+2y+2z=3 3x+4y+6x=-1 Augumented matorix [A;B]=[1

[Back substitution method]

From equation 3, we have [z=-a]

· sub z--2 in equation (2), we get

Substitute y=5, z=-2 in equation 0, we get

1. Selve the following system of equations by goursian elimination. What are the pivots

(i) -xty+27=0, 3x+4y+2=0,2x+5y+3z=0

(ii) 2y-z=1,4x-loy+3z=5, 3x-3y=6

(ii) W+ I+y= 3, -3W-17x+y+2x=1,4W-17x+8y-5x=1,

(iv) $x_1 + 2x_2 + 3x_3 + 2x_4 = -1$, $-x_1 - 2x_2 - 2x_3 + 2x_4 = 2$, $2x_1 + 4x_2 + 8x_3 + 12x_4 = 4$

(i) Sel:- The system of equations
$$-x+y+zz=0$$

$$3x+4y+z=0$$

$$3x+5y+3z=0$$
Argumented matrix $[A:B] = \begin{bmatrix} -1 & 1 & 2 & 0 \\ 3 & 4 & 1 & 0 \\ 2 & 5 & 3 & 0 \end{bmatrix} \underset{R \to R \times F}{R \to R} \times F)$

$$-\begin{bmatrix} 1 & -1 & -2 & 0 \\ 3 & 4 & 1 & 0 \\ 2 & 5 & 3 & 0 \end{bmatrix} \underset{R \to R}{R \to R} \times F_3 - 2R_1$$

$$-\begin{bmatrix} 1 & -1 & -2 & 0 \\ 0 & 7 & 7 & 0 \\ 0 & 7 & 7 & 0 \end{bmatrix} \underset{R \to R}{R \to R} \times F_3 - R_2$$

$$-\begin{bmatrix} 1 & -1 & -2 & 0 \\ 0 & 7 & 7 & 0 \\ 0 & 7 & 7 & 0 \end{bmatrix} \underset{R \to R}{R \to R} \times F_3 - R_2$$

2. Détermine the condition on bi. so that the following system has a solution.

(i)
$$x + 2y + 6z = b_1$$
, $2x - 3y - 2z = b_2$, $3x - y + 4z = b_3$

(ii)
$$x+3y-2z=b_1$$
, $3x-y+3z=b_2$, $4x+3y+z=b_3$

(i) Set: The system of equations
$$2x-3y-2z=b_2$$
 $3x-y+4z-b_3$

Assumented matrix
$$[A;B] = \begin{bmatrix} 1 & 2 & 6 & 61 \\ 2 & -3 & -2 & 62 \\ 3 & -1 & 4 & 63 \end{bmatrix}$$

$$R_{2} \rightarrow R_{2} - 2R$$

$$R_{3} \rightarrow R_{3} - 3R$$

Since
$$P(A) = 2$$
, $P(A|B) = 2$ if $b_3 - b_2 - b_1 = 0$
 $P(A) = 2 = P(A|B) < no of volubles (3)$
The given system has an infinite no of solution when $b_3 - b_1 - b_2 = 0$

(ii) Sol: The system of equations
$$x+3y-2z=b_1$$
 $2x-y+3z=b_2$ $4x+2y+z=b_3$
Argumented matrix $[A|B] = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

Argumented matrix
$$[A \mid B] = \begin{bmatrix} 1 & 3 & -2 & b_1 \\ 2 & -1 & 3 & b_2 \\ 4 & 2 & 1 & b_3 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - 2R$$

$$\sim \begin{bmatrix} 1 & 3 & -2 & b_1 \\ 0 & -7 & 7 & b_2 - 2b_1 \\ 0 & -10 & 9 & b_3 - 4b_1 \end{bmatrix}$$

$$R_3 \rightarrow R_2 / 2$$

. The given system has an unique solution

1. (ii) St.: The system of squations
$$3y-x=1$$

$$4x-10y+3x=5$$

$$3x-3y=6$$
Argumental matrix [A | B] =
$$\begin{bmatrix} 0 & 2 & -1 & 1 \\ 4 & -10 & 3 & 5 \\ 3 & -3 & 0 & 6 \end{bmatrix} P_3 \rightarrow P_3/3$$

$$\sim \begin{bmatrix} 0 & 2 & -1 & 1 \\ 4 & -10 & 3 & 5 \\ 1 & -1 & 0 & 2 \end{bmatrix} P_4 \leftrightarrow P_3$$

$$\sim \begin{bmatrix} 1 & -1 & 0 & 2 \\ 4 & -10 & 3 & 5 \\ 0 & 2 & -1 & 1 \end{bmatrix} P_9 \rightarrow P_3 - 4P_1$$

det [z=t] substitute in equation (3)

Ret y= 1tt 2, 2=t substitute in equation 1

Angumated matrix
$$[A \mid B] = \begin{bmatrix} 1 & 2 & 3 & 2 & -1 \\ -1 & -2 & -2 & 1 & 2 \\ 2 & 4 & 8 & 12 & 4 \end{bmatrix} R_3 \rightarrow R_3/2$$

$$\sim \begin{bmatrix} 1 & 2 & 3 & 2 & -1 \\ -1 & -2 & -2 & 1 & 2 \\ 1 & 2 & 4 & 6 & 2 \end{bmatrix} R_3 \rightarrow R_3 + R_4$$

$$\sim \begin{bmatrix} 1 & 2 & 3 & 2 & -1 \\ 0 & 0 & 1 & 3 & 1 \\ 0 & 0 & 1 & 4 & 3 \end{bmatrix} R_3 \rightarrow R_3 - R_2$$

$$\sim \begin{bmatrix} 1 & 2 & 3 & 2 & -1 \\ 0 & 0 & 1 & 3 & 1 \\ 0 & 0 & 0 & 1 & 2 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 2 & 3 & 2 & -1 \\ 0 & 0 & 1 & 3 & 1 \\ 0 & 0 & 0 & 1 & 2 \end{bmatrix}$$

=)
$$x_1 + 2x_2 + 3x_3 + 2x_4 = -1$$
 $x_3 + 3x_4 = 1$
3

Substitute $x_4 = 2$ in equation (2)

 $x_3 + 6 = 1$
 $x_3 = -5$

Substitute $x_3 = -5$, $x_4 = 2$ in equation (1)

 $x_4 + 2x_3 + 15 + 4 = -1$
 $x_4 + 2x_3 = +10$

Let $x_3 = t$
 $x_4 + 2t = 10$
 $x_4 = 10 - 2t$

(i)syp(A) = p(A | B) = number of vociables, then the system. has a unique solution. (ii) of P(A) = P(A ! B) < number of vocables, then the system has an infinite member of solutions (ii) If P(A) ≠ P(A; B), then the system has no solution 1. Détermine all values of bi that make the Jellowing system x+y-z=b1, 2y+z=b2, y-z=b3 consistent 2. Determine the condition of so that the following system has no solution 2x +y17x=b1, 6x-2y+11x=b2,

2x-y+3x= b3

3. Which of the following system has a non-trivial solution

- (i) xt&y+3x=0 x+2y+32=0
- (ii) 2x +y-2=0 x-2y-3z=0

4. For which values of "a" does each of the following system have no solution, exactly one solution or infinitely many solution

(i) x+2y-3x=4, 3x-y+5x=2, 4x+y+(a=14)x=a+2

Argumented matrix
$$[A \mid B] = \begin{bmatrix} 1 & 2 & -3 & 4 \\ 3 & -1 & 5 & 2 \\ 4 & 1 & 2 & -14 & 242 \end{bmatrix}$$

$$R_{2} \rightarrow R_{2} \rightarrow R_{3} \rightarrow R_{3} \rightarrow R_{3} \rightarrow R_{4}$$

$$\sim \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & -7 & 14 & -10 \\ 0 & -7 & 2 & 2 & 2 & 2 \end{bmatrix}$$

$$R_{3} \rightarrow R_{3} \rightarrow R_{3} \rightarrow R_{2}$$

$$\sim \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & -7 & 14 & -10 \\ 0 & 0 & 2 & 16 & 2 & 4 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & 1 & -2 & 194 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & 1 & -2 & 194 \end{bmatrix}$$

i) 9/ a-16=0 and a-4=0 than ((A)=2, ((A;B)=2 i.e a=±4 then the given system has an injurite number of solutions [: (A)=2= ((A;B)×3] ii) 94 a2-16 =0 and a-4 =0 than P(A)=3, P(A/B)=3 i.e a # 14 then the given system has an_ unique selution (: P(A)=3=P(A|B)=no of unknown) iii) If a=-4, then the given system has no relution

+** Gaus - Jordan dimination:

(i) Write the argumented matrix for the given existen of linear equations.

(ii) Donive the modured new-scholen form for the conjuncted matrix by using elementary new operations (iii) Write the system of aquations corresponding to the modured new-echelen form. This system gives the solution.

gaun jordan dimination.

21+3x2-2x2-3, 2x1+6x2-2x3+4x4-18, x2+x3+3x4-10

Arramented metaix
$$[A \mid B] = \begin{bmatrix} 1 & 3 & -2 & 0 & 3 \\ 2 & 6 & -2 & 4 & 18 \\ 0 & 1 & 1 & 3 & 10 \end{bmatrix}_{R_3 + R_3 - 2R_1}$$

$$\sim \begin{bmatrix} 1 & 3 & -2 & 0 & 3 \\ 0 & 0 & 2 & 4 & 12 \\ 0 & 1 & 1 & 3 & 10 \\ 0 & 0 & 2 & 4 & 12 \end{bmatrix}_{R_3 \to R_3/2}$$

$$\sim \begin{bmatrix} 1 & 3 & -2 & 0 & 3 \\ 0 & 1 & 1 & 3 & 10 \\ 0 & 0 & 2 & 4 & 12 \end{bmatrix}_{R_3 \to R_3/2}$$

$$\sim \begin{bmatrix} 1 & 3 & -2 & 0 & 3 \\ 0 & 1 & 1 & 3 & 10 \\ 0 & 0 & 1 & 2 & 6 \end{bmatrix}_{R_1 \to R_1 - 3R_3}$$

chiese xyst

Form Egu @, we have x1 = 3-t from equ 6), we have ==4-t From equ (6), we have x3=6-st x1=3-t x2-4-t 5-3-6-at x40t tER

3 . The the fillewing system of linear equation by

(1) 3x-3y-8, 4x-5y+x-15, 3x+42-1

(ii) $x_1 + x_2 + x_3 - x_4 = -3$, $2x_1 - x_2 + x_3 + x_4 = 0$, $3x_1 + 2x_2 - x_3 - x_4 = 1$, $x_1 + x_2 + 3x_3 - 3x_4 = -8$

. Argumented matrix
$$[A \mid B] = \begin{bmatrix} 1 & 1 & -1 & b_1 \\ 0 & 2 & 1 & b_2 \\ 0 & 1 & -1 & b_3 \end{bmatrix} R_3 \Rightarrow 3R_3 - R_2$$

$$\sim \begin{bmatrix} 1 & 1 & -1 & b_1 \\ 0 & 2 & 1 & b_2 \\ 0 & 0 & -3 & 2b_3 - b_2 \end{bmatrix} R_3 \Rightarrow R_3 / 2$$
:

$$y + \frac{1}{3}z = \frac{1}{3}$$

$$y + \frac{1}{3}z = \frac{1}{3}$$

$$y + b_{3}b_{3} = 2b_{3}$$

$$y = b_{3}+b_{3}$$

$$y = b_{3}+b_{3}$$
Sub
$$y = b_{3}+b_{3}$$
,
$$x = b_{3}-ab_{3}$$
 in equal
$$x + b_{3}+b_{3} - b_{3}+ab_{3} = b_{1}$$

$$x + b_{3}+b_{3}-b_{3}+ab_{3} = b_{1}$$

$$x + ab_{3} = b_{1}$$

$$x + ab_{3} = b_{1}$$

$$x + ab_{3} = b_{1}$$

2. Argumented matrix
$$[A \mid B] = \begin{bmatrix} 2 & 1 & 7 & b_1 \\ b & -2 & 11 & b_2 \\ 2 & -1 & 3 & b_3 \end{bmatrix} R_1 \Rightarrow R_1 \Rightarrow R_2 \Rightarrow R_2 \Rightarrow R_3 \Rightarrow R_4 \Rightarrow R_3 \Rightarrow R_4 \Rightarrow R_5 \Rightarrow R_5$$

$$\begin{bmatrix}
 1 & 1 & 1 \\
 2 & 1 & 1 \\
 0 & 1 & 2 & -\frac{b_3 + 3b_1}{5} \\
 0 & 1 & 2 & -\frac{b_3 + b_1}{2} \\
 0 & 1 & 2 & -\frac{b_3 + b_1}{2} \\
 R_3 = R_3 - R_2$$

. The given system has no solution.

3.(1) Argunanted matrix
$$[A|B] = \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 2 & 2 & 0 \\ 1 & 2 & 3 & 0 \end{bmatrix} R_2 = R_3 \Rightarrow R_3 - R_3 \Rightarrow R_3 \Rightarrow R_3 - R_3 \Rightarrow R_3 \Rightarrow$$

(ii) Argumented matrix
$$[A \mid B] = \begin{bmatrix} 2 & 1 & -1 & 0 \\ 1 & -2 & -3 & 0 \\ 3 & 1 & -2 & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & -2 & -3 & 0 \\ 2 & 1 & -1 & 0 \\ 3 & 1 & -2 & 0 \end{bmatrix} \xrightarrow{R_3 \Rightarrow R_3 - 2R_3} \xrightarrow{R_3 \Rightarrow R_3 - 3R_3} \xrightarrow{R_3 \Rightarrow R_3 \neq R_3 + 2R_3} \xrightarrow{R_3 \Rightarrow R_3 \neq R$$

21ii) Argumented matrix
$$[A \mid B] = \begin{bmatrix} 1 & 1 & 1 & -1 & -2 \\ 2 & -1 & 1 & 1 & 0 \\ 3 & 2 & -1 & -1 & 1 \\ 1 & 1 & 3 & -3 & -8 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 1 & 1 & -1 & -2 \\ 0 & -3 & -1 & 3 & 4 \\ 0 & -1 & -4 & 2 & 7 \\ 0 & 0 & 2 & -2 & -6 \\ 0 & -1 & -4 & 2 & 7 \\ 0 & 0 & 2 & -2 & -6 \\ 0 & -1 & -4 & 2 & 7 \\ 0 & -3 & -1 & 3 & 4 \end{bmatrix} R_{2} \Rightarrow R_{2}/2$$

$$R_{4} \Rightarrow R_{4} - 3R_{3}$$

21) Assumented materix
$$[A;B] = \begin{bmatrix} 2 & -3 & 0 & 8 \\ 4 & -5 & 1 & 15 \\ 2 & 0 & 4 & 1 \end{bmatrix} R_1 \leftrightarrow R_3$$

Towerse maloure -

the uxu square matrix A is said to be invertible on new-singular if there exists a square matrix B of the same size such that

AB-In-BA

Such that a material B is called the inverse of A, and is denoted by A-1

Note: i) of matrix '1' is raid to be singular if it is not invertible.

What A be an invertible matrix and K be any new-zero rador, then @ A^{\dagger} is invertible and $(A^{-1})^{-1}A$.

(b) the matrix KA is invertible and $(KA)^{-1} = \frac{1}{K}A^{-1}$

@ AT is investible and (AT) -1-(A-1)T.

@ AA-1-AA-1

annet be invertible.

in the product of involved matrices is also involved where involved in the product of the individual involves in revoval order i.e (AB) - B'A-1

Tiero exercitare (Gaus-Jerdan Diminaline):-

Let A be an nxn matrix, then

1) write the matrix [A | In]

ii) ampute the reduced earden form of [A!In] (iii) If the neduced scholon form is of the type [In 18], then B is the invoice of A. Find the inverse of $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 5 \end{bmatrix}$ by using Gauss - Jordan dimindion. (Ex Censider [A!]3x3] = 2 3 5 1010

$$\begin{bmatrix} I_{n} & B \\ B & -6 & 4 & -1 \\ -1 & 1 & -1 \\ 3 & -2 & 1 \end{bmatrix}$$
i.e. $A^{-1} = B = \begin{bmatrix} -6 & 4 & -1 \\ -1 & 1 & -1 \\ 3 & -2 & 1 \end{bmatrix}$

1. Find the invoice of the following matrices

i)
$$A = \begin{bmatrix} 1 & -1 & 2 \\ 2 & -3 & -5 \\ -1 & 3 & 5 \end{bmatrix}$$

(fi)
$$A = \begin{bmatrix} 1 & 0 & 2 \\ 2 & -1 & 3 \\ 4 & 1 & 8 \end{bmatrix}$$

Gusider
$$[A : I_{3\times3}] = \begin{bmatrix} 1 & 1 & 5 & 1 & 1 & 0 & 0 \\ 1 & 2 & 7 & 1 & 0 & 1 & 0 \\ 2 & -1 & 4 & 1 & 0 & 0 & 1 \end{bmatrix} \underset{R_3 \to R_3 = R_4}{R_3 \to R_3 = R_4}$$

(iii) Consider
$$[A1]_{3\times 2}$$
 = $\begin{bmatrix} 1 & 0 & 2 & 1 & 1 & 0 & 0 \\ 2 & -1 & 3 & 1 & 0 & 1 & 0 \\ 4 & 1 & 8 & 1 & 0 & 0 & 1 \\ R_{2} + R_{2} + R_{3} + R_{4} + R_{5} + R_{5}$

ii) Causider
$$[A|\tilde{I}_{3\times3}] = \begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 2 & 3 & 1 & 0 & 1 \\ 5 & 5 & 1 & 1 & 0 & 0 \end{bmatrix} R_{3} + R_{5} + S_{5} + S_{5$$

Black Mobilia: -

It sub matrice "" is a matrice oftained from A by deleting contain news and/or columns of A. Consider a material $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \end{bmatrix}$ divided the four blocks (sub matrices) of by the detted lines shown.

Nece, if we write $A_{11} = \begin{bmatrix} a_{11} & a_{12} & a_{33} \\ a_{21} & a_{22} & a_{23} \end{bmatrix}$, $A_{12} \begin{bmatrix} a_{14} \\ a_{24} \end{bmatrix}$ A21 = [a3, a32 a33], A22 = [a34] than A can be written as $A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}$ called a block matrix.

Broduct of block materices: 91 A = $\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{32} \end{bmatrix}$ and $B = \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix}$ are block natrices and the number of columns in Aix is equal to the number of news in Bkj, then AB = [A11 B1 + A12 B2] A11 B12 + A12 B22]
A21 B11 + A22 B21 A21 B12 + A22 B22 Example: Compute AB using block multiplication whose $A = \begin{bmatrix} 1 & 2 & | & 1 & 0 \\ -3 & 4 & | & 0 & | \\ \hline 0 & 0 & | & 2 & -1 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 & | & 2 \\ 0 & 1 & | & 3 \\ \hline 2 & 3 & | & 4 \\ \hline 3 & -2 & 1 \end{bmatrix}.$

awider
$$A_{11} = \begin{bmatrix} 1 & 2 \\ -3 & 4 \end{bmatrix}$$
 $A_{12} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ $A_{21} = \begin{bmatrix} 0 & 0 \end{bmatrix}$ $A_{22} = \begin{bmatrix} 0 & 1 \\ 3 \end{bmatrix}$ $A_{21} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ $A_{21} = \begin{bmatrix} 1 & 2 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 3 & -2 \end{bmatrix}$ $A_{11}B_{11} = \begin{bmatrix} 1 & 2 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 3 & -2 \end{bmatrix}$ $A_{12}B_{21} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 3 & 3 \\ 3 & -2 \end{bmatrix}$ $A_{12}B_{21} = \begin{bmatrix} 2 & 3 & 3 \\ 3 & -2 \end{bmatrix}$ $A_{13}B_{12} = \begin{bmatrix} 1 & 2 \\ 3 & -2 \end{bmatrix}$ $A_{13}B_{12} = \begin{bmatrix} 1 & 2 \\ 3 & -2 \end{bmatrix}$ $A_{13}B_{12} = \begin{bmatrix} 1 & 2 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix}$

$$A_{11}B_{12} = \begin{bmatrix} 8 \\ 6 \end{bmatrix}$$

$$A_{12}B_{22} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

$$A_{21}B_{11} = \begin{bmatrix} 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \end{bmatrix}$$

$$A_{22}B_{21} = \begin{bmatrix} 2 & -1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 3 & -2 \end{bmatrix}$$

$$A_{22}B_{21} = \begin{bmatrix} 1 & 18 \end{bmatrix}$$

$$A_{22}B_{21} = \begin{bmatrix} 1 & 18 \end{bmatrix}$$

$$\begin{cases}
A_{21} B_{12} = \begin{bmatrix} 0 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} \\
-[0]
\end{cases}$$

$$A_{22} B_{22} = \begin{bmatrix} 2 & -1 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

$$-[7]$$

$$A_{8} = \begin{bmatrix} 3 & 5 & 18 \\ 0 & 2 & 7 \\ 1 & 8 & 7 \end{bmatrix}$$

Elementary matrix: -

oh elementary matrix is a matrix, which is obtained from the identity matrix In by executing only one elementary now operation.

Ros Ru

Buporties:-

1) If E denotes an elementary materia and E'(E-1) denotes the elementary matrix acrossponding to the invove elementary new operation on E, then,

ii) of E multiplies a row by c+0, than E' multiplies the now by &

iii) If E interchanges two soms, then E'

interchanges them again

iv) If E adds a multiple of the sun to another, then E' subtracte it from the same new.

v) Evory domentary matrix is involible and inverse matrix E'=E' is also an abmentary matrix.

Example: -

1. 94
$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & C & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 then $E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{C} & 0 \\ 0 & 0 & 1 \end{bmatrix}$

2. 95 $E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}$ then $E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}$

3. 96 $E = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ then $E^{-1} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

$$N$$
 $A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 3 & 8 \\ -3 & -1 & 2 \end{bmatrix}$

i)
$$A = \begin{bmatrix} 1 & -3 \\ -2 & 4 \end{bmatrix} R_2 \rightarrow R_2 + 2R_1$$

$$\sim \begin{bmatrix} 1 & -3 \\ 0 & -2 \end{bmatrix} R_2 \rightarrow R_2 / -2$$

Since
$$R_2 \rightarrow R_2 - 2R_1$$
.
 $S_1^{-1} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$

Since
$$R_2 \rightarrow -2R_2$$

$$E_2^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}$$

State
$$R_1 \rightarrow R_1 + 3R_2$$
 State $R_1 \rightarrow R_1 - 3R_2$

$$E_3 = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \qquad E_3^{-1} = \begin{bmatrix} 1 & -3 \\ 0 & 1 \end{bmatrix}$$

$$A = E_1 \cdot E_2 \cdot E_3$$

$$\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 3 \end{bmatrix}$$

$$\begin{bmatrix}
1 & 0 \\
2 & 1
\end{bmatrix}
\begin{bmatrix}
1 & 0 \\
0 & 2
\end{bmatrix}
\begin{bmatrix}
1 & 3 \\
0 & 1
\end{bmatrix}$$

$$\begin{bmatrix}
1 & 3 \\
0 & 1
\end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 2 & -\frac{1}{3} \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & -5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{array}{c} \text{in)} \ A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 3 & 8 \\ -3 & -1 & 2 \end{bmatrix} \\ R_{2} \rightarrow R_{2} - 2R_{1} \\ R_{3} \rightarrow R_{3} + 3R_{1} \end{array}$$

$$\sim \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 4 \\ 0 & 3 & 8 \end{bmatrix} \\ R_{3} \rightarrow R_{3} - 3R_{2} \end{array}$$

The materia A Council be expressed as the preduct of elementary matrices since the third new

के उटक

Pounutations; -

A permutation matrix is a square matrix obtained from the identity matrix if permuting < changing the order > the news

Example

[1 0 0] is not a pomutation matrix.

i) Every permitation matrix is a alamentary matrix but every elementary matrix need not be a

permetation matrix ii) The product of any two promutation matrices is again a pourutation matrix

The transperse of a parametrition matrix is alio a pourutation materia

iv) Every poundation matrix P is involtible and

V) A parametation matrix is the product of a finite number of elementary matrices and of which corresponds to the new interchanging elementary some

11)
$$A = \begin{bmatrix} 1 & 0 \\ 5 & 2 \end{bmatrix} R_2 \rightarrow R_2 - 5R_1$$

$$\sim \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2/2}$$

$$E_1^{-1} = \begin{bmatrix} 1 & 0 \\ 5 & 1 \end{bmatrix}$$

$$E_{a}^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

$$=\begin{bmatrix}1 & 0\\5 & 1\end{bmatrix}\begin{bmatrix}1 & 0\\0 & 2\end{bmatrix}$$

LU Factorization:

det A be a equare matrix that can be factorized into the form A= LU, where L is a lever triangular matrix & U is an upper triangular matrix. This factorization is alled an LU factorization er Lu decomposition of A

Note: i) Evory matrix has an LU factoringation and

when it exists, It is not unique. ii) If the matrix A is invertible 2 if the

permitation materix P is fixed then the materix PA has a unique LDU factorization untom ex linear equation

PA has a unique Selving method for a given system of linear equations Let AX=B be a system of "n" linear equations in by LU factorization: i) Find the LU facemposition of n "n" unknowns than ii) selve LY=B by forward substitution iii) Selve UX=Y by back substituition 1. Salve the following system of equations using LU decomposition 2x1+x2+3x3--1 4x1+ x2+7x3=5 -6x1-2x2-12x35-2

The given rystow of linear equations can be expressed as AX-B, where

$$A = \begin{bmatrix} 2 & 1 & 3 \\ 4 & 1 & 7 \\ -6 & -2 & -12 \end{bmatrix}, \quad X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad B = \begin{bmatrix} -1 \\ 5 \\ -2 \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 1 & 3 \\ 4 & 1 & 7 \\ -6 & -9 & -12 \end{bmatrix} \xrightarrow{R_2 \to R_3 + 3R_1} \xrightarrow{R_3 \to R_3 + 3R_1}$$

$$\sim \begin{bmatrix} 2 & 1 & 3 \\ 0 & -1 & 1 \\ 0 & 1 & -3 \end{bmatrix} \underset{R_3 \to R_3 + R_3}{|} R_{3} R_{3}$$

$$\sim \begin{bmatrix}
 2 & 1 & 3 \\
 0 & -1 & 1 \\
 0 & 0 & -2
 \end{bmatrix} = U$$

The invoice elementary matrices that obacsponds

to the new operation

$$E_1^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 $F_3 \rightarrow F_2 + 2F_1$

$$E_3^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \quad R_3 \rightarrow R_5 R_2$$

$$L = E_{1}^{-1} E_{2}^{-1} E_{3}^{-1}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & -1 & 1 \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -3 & -1 & 1 \end{bmatrix}$$

$$A = LU$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -3 & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 3 \\ 0 & -1 & 1 \\ 0 & 0 & -2 \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 1 & 3 \\ 4 & 1 & 4 \\ -6 & -2 & -12 \end{bmatrix}$$

Consider LY = B

$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -3 & -1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix}$$

$$= \frac{y_1 - 1}{2y_1 + y_2 - 5} - 2$$

$$= \frac{3y_1 + y_2 - 5}{-3y_1 - y_2 + y_3 - 2} - 2$$

Sub
$$y_1 - 1$$
, $y_2 = 7$ in equ (9)
 $3 - 7 + 4y_3 = -2$
 $-4 + 4y_3 = -2$
 $y_3 = 2$
 $y_1 = -1$, $y_2 = 7$, $y_3 = 2$
Since $0x = y$

$$\begin{bmatrix} 2 & 1 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 7 \\ 2 \end{bmatrix}$$

$$2x_1 + x_2 + 3x_3 = -1$$

$$-2x_3 = 2$$

$$-2x_3 = 2$$

(3=)
$$x_3=-1$$

Sub $x_3=-1$ in squ (3)
 $-x_2-1=7$
 $x_2=-8$
Sub $x_3=-8$, $x_3=-1$ in equ (1)
 $2x_1-8-3=-1$
 $2x_1-11=-1$
 $2x_1=10$
 $x_1=5$
 $x_1=5$

matrices

i)
$$A = \begin{bmatrix} 2 & 1 \\ 8 & 7 \end{bmatrix} R_3 \rightarrow R_3 - 4R_4$$

$$- \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix} - U$$

$$E_1^{-1} = \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix}$$

$$L = E^{-1} = \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1/2 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1/2 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1/2 \\ 0 & 1 \end{bmatrix}$$

ii)
$$A = \begin{bmatrix} 1 & 5 \\ 8 & 1 \end{bmatrix} R_2 \rightarrow R_2 - 8R_1$$

$$\sim \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} = 0$$
Since $R_2 \rightarrow R_2 - 8R_1$

$$E_1^{-1} = \begin{bmatrix} 1 & 0 \\ 8 & 1 \end{bmatrix}$$

$$L=E^{-1}=\begin{bmatrix}1 & 0\\ 8 & 1\end{bmatrix}$$

$$A = L U$$

$$= \begin{bmatrix} 1 & 0 \\ 8 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 8 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = LDU$$

$$A = LDU$$

$$A = LDU$$

$$A = LDU$$

I= [0 1]

Ro-Ro+8R1

white the express PA as LDU factorization

$$PA = \begin{bmatrix} 0 & 0 & 1 & 2 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{bmatrix}$$

$$PA = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 2 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{bmatrix}$$

$$PA = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{bmatrix}$$

$$PA = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{bmatrix}$$

$$PA = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{bmatrix}$$

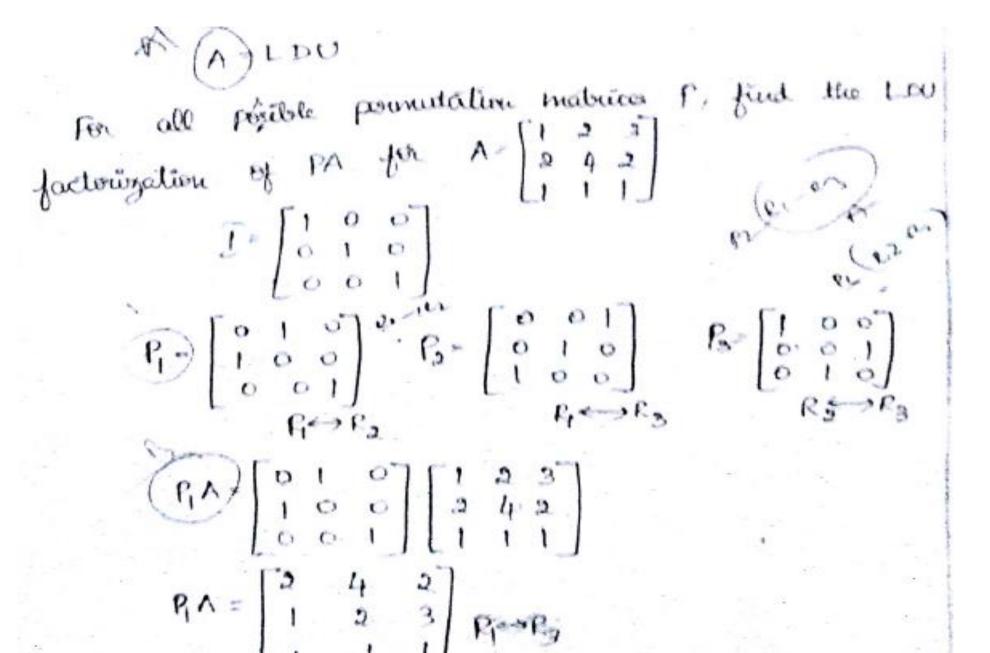
$$PA = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{bmatrix}$$

$$PA = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{bmatrix}$$

$$PA = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{bmatrix}$$

$$PA = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{bmatrix}$$

$$PA = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$



$$\sim \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 2 & 4 & 2 \end{bmatrix} R_3 = R_3 - R_3$$

$$\sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 2 & 0 \end{bmatrix} R_3 = R_3 - 3R_3$$

$$\sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & -4 \end{bmatrix} = V$$

$$R_1 \leftrightarrow R_3$$

$$E_{1}^{-1} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

$$R_{2} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$R_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{array}{l}
P_{A} = LU \\
= \begin{bmatrix} 2 & 2 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & -4 \end{bmatrix} \\
= \begin{bmatrix} 2 & 2 & 1 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \\
P_{A} = LDU \\
P_{A} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 1 \\ a & 4 & 2 \\ 1 & 2 & 3 \end{bmatrix} R_{3} \Rightarrow R_{3} - 3R_{4}$$

$$\sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 0 \\ 0 & 1 & 2 \end{bmatrix} R_{3} \Rightarrow R_{3} - 3R_{4}$$

$$\sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & -4 \end{bmatrix} R_{3} \Rightarrow R_{3} - 3R_{4}$$

$$= \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & -4 \end{bmatrix} = U$$

$$= \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$F_{3}^{=}) R_{3}^{-} R_{1}$$

$$F_{3}^{-} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$R_{3}^{(0)} R_{2}^{(0)} R_{3}^{-} R_{2}^{-}$$

$$R_{3}^{(0)} R_{3}^{-} R_{2}^{-}$$

$$R_{3}^{(0)} R_{3}^{-} R_{2}^{-}$$

$$E_{4}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$$

$$E_{4}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$$

$$E_{4}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$$

$$E_{4}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$$

$$\begin{array}{l} P_{3}A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 2 \\ 1 & 1 & 1 \end{bmatrix} \\ = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 1 & 1 \\ 2 & 4 & 2 \end{bmatrix} \begin{bmatrix} R_{2} = 1 & R_{2} - R_{1} \\ R_{3} = 1 & R_{3} - 2 & R_{1} \end{bmatrix} \\ \sim \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & -4 \end{bmatrix} = U \\ \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & -4 \end{bmatrix} = V \\ \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} \\ \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 0 & 1 \end{bmatrix}$$

4. ii)
$$x-y+z=1$$
, $x+3y+az=3$, $2x+ay+3z=3$

$$\begin{bmatrix} A \mid B \end{bmatrix} = \begin{bmatrix} 1 & -1 & 1 & 1 \\ 1 & 3 & a & a \\ a & a & 3 & 3 \end{bmatrix} R_3 > R_3$$

i) If
$$a\neq 3$$
, $a\neq 2$
 $e(A) = e(A, B) = no ef unknown$
It has unique relation
 $a\neq -3$, $a=2$
 $e(A) = e(A, B) \neq no ef unknowns$
 $e(A) = e(A, B) \neq no ef unknowns$
It has injunte no ef relations
 $e(A) \neq e(A, B)$
 $e(A) \neq e(A, B)$