

# Crteria for Bayesian hypothesis testing in two-sample problems

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## Introduction to Bayesian testing



- To much dismay of scientists (and our students),
   p-values aren't probabilities of hypotheses being
   true given the data.
- Bayesian testing allows us to find them by
  - Specifying (prior) **probabilities** to anything we don't know, including competing hypotheses.
  - When we gather data, we condition on it and find probabilities of hypotheses given the data.

#### Problem solved?

## Not really...



- Bayesian answers in testing can depend strongly on prior probability specifications.
- If we're not careful, our Bayes decisions can be catastrophic.
- As a consequence, there is a vast literature discussing prior choice in testing, dating since (at least) Jeffreys' work at the beginning of the 20th century.

#### Strategy:

- List desirable properties that Bayes decisions should satisfy, usually by taking limits or looking at extreme cases.
- Determine which priors satisfy them, and which don't.

For example, we arguably want...

• **Consistency:** If one of our hypotheses is true and we have infinite data, the posterior probability of the truth should converge to 1.

For other criteria, see Bayarri et al. (2012).

## Today



- I'll propose 2 new properties that (I believe) two-sample tests should satisfy.
- Alternatives to limit consistency, which was proposed recently.
- Application: so far, normal means; there is much yet to be explored!



## Limit consistency



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- **Limit consistency** was introduced in Chapter 6 of Ly (2017).
- Context: Testing if rates of two homogeneous Poisson processes are equal  $(H_0)$  or different  $(H_1)$ .
- **Idea:** If there is infinite data for one of the groups but the data for the other group is fixed, there is no decisive evidence in favor of  $H_0$  or  $H_1$ .

• Independent samples from groups A and B:

$$y_{iA} \stackrel{\text{iid}}{\sim} P_{\theta_A}, \ y_{jB} \stackrel{\text{iid}}{\sim} P_{\theta_B},$$

where the parameters  $\theta_A$  and  $\theta_B$  are unknown.

- **Test:**  $H_0: P_{\theta_A} = P_{\theta_B}$  against  $H_1: P_{\theta_A} \neq P_{\theta_B}$ .
- In Bayesian hypothesis tests, all unknowns are modeled probabilistically.
- We don't know which hypothesis is true and we don't know the parameters, so we specify **priors** on them.

## Bayes factor



- Let the conditional densities of the data  $\mathcal{D}$  given  $\theta_{A,B}$  under  $H_0$  and  $H_1$  be  $p(\mathcal{D} \mid \theta_{A,B}, H_0)$  and  $p(\mathcal{D} \mid \theta_{A,B}, H_1)$ , respectively.
- Let  $\pi_0(d\theta_{A,B})$  and  $\pi_1(d\theta_{A,B})$  be the prior measures on  $\theta_{A,B}$  under  $H_0$  and  $H_1$ .
- The Bayes factor of  $H_1$  to  $H_0$  is defined as

$$B_{10} = \frac{\int p(\mathcal{D} \mid \theta_{A,B}, H_1) \pi_1(\mathrm{d}\theta_{A,B})}{\int p(\mathcal{D} \mid \theta_{A,B}, H_0) \pi_0(\mathrm{d}\theta_{A,B})} = \frac{p(\mathcal{D} \mid H_1)}{p(\mathcal{D} \mid H_0)}.$$

• If  $B_{10}$  is large, the data support  $H_1$ . If  $B_{10}$  is near 0, the data support  $H_0$ .



### Limit consistency



#### Definition

Let the data from group *A* be fixed and assume that the sample size of group *B* goes to infinity.

Then,  $B_{10}$  is **limit consistent** if  $\lim B_{10} = \ell$  with  $0 < \ell < \infty$ .



#### **Problems**



There are 2 things I don't like about the definition.

- It only applies to Bayes factors. What about Bayes decisions in general, or non-Bayesian approaches?
- **2** It isn't "ambitious enough." I would like to converge to a one-sample problem where  $\theta_B$  is known.

For that reason, I propose an alternative criterion: **limit compatibility**.



## Limit compatibility



## Limit compatibility

#### Definition

Consider the hypothesis tests:

- One-sample test:  $H_{01}: P_{\theta_A} = P_{\theta_B^*}$  against  $H_{11}: P_{\theta_A} \neq P_{\theta_B^*}$  with  $P_{\theta_A}$  unknown and  $P_{\theta_B^*}$  known.
- **2** Two-sample test:  $H_{02}: P_{\theta_A} = P_{\theta_B}$  against  $H_{12}: P_{\theta_A} \neq P_{\theta_B}$  with  $\theta_A$  and  $\theta_B$  unknown.

Let  $\delta_1$  and  $\delta_2$  be the decision rules for the one- and two-sample test, respectively.

If the data from group A are fixed and the sample size of group B goes to infinity,  $\delta_1$  and  $\delta_2$  are **limit-compatible** if  $\delta_2 \rightarrow \delta_*$  such that  $\delta_* = H_{h2} \Leftrightarrow \delta_1 = H_{h1}$  for  $h \in \{0, 1\}$ .

## Application: Independent normal means



• **Data:** Independent normal samples of sizes  $n_A$  and  $n_B$  from groups A and B, respectively:

$$y_{iA} \stackrel{\text{iid}}{\sim} N(\mu_A, \sigma^2), \ y_{jB} \stackrel{\text{iid}}{\sim} N(\mu_B, \sigma^2),$$

where  $\sigma^2$  is known. Group means are denoted  $\overline{y}_A$  and  $\overline{y}_B$  and the overall mean is  $\overline{y}$ .

• **Goal:** Compare limits of decision rules for two-sample test  $H_{02}$ :  $\mu_A = \mu_B$  against  $H_{12}$ :  $\mu_A \neq \mu_B$  to decisions for analogous one-sample test where  $\mu_B = \mu_B^*$  is known.

- One- and two-sample *z*-tests are limit-compatible.
- Indeed, let  $Z_n = \sqrt{\kappa}(\overline{y}_A \overline{y}_B)/\sigma$ ,  $Z_* = \sqrt{n_A}(\overline{y}_A \mu_B^*)/\sigma$ ,  $z_\alpha/2$  be the  $(1 \alpha/2)\%$  quantile of a N(0, 1).
- Then, the decision rules

$$\delta_2 = H_{02} \mathbb{1}\{|Z_n| \le |z_{\alpha/2}|\} + H_{12} \mathbb{1}\{|Z_n| > |z_{\alpha/2}|\}$$
  
$$\delta_1 = H_{01} \mathbb{1}\{|Z_*| \le |z_{\alpha/2}|\} + H_{11} \mathbb{1}\{|Z_*| > |z_{\alpha/2}|\}$$

are limit-compatible as  $n_B \to \infty$  because  $|Z_n| \to_d |Z_*|$  and the indicators converge.

## Bayesian framework



• Losses  $L_1$  and  $L_2$  for one- and two-sample tests of the type:

$$L_{j}(\mu_{A}, \mu_{B}, H_{0j}) = \mathbb{1}(\mu_{A} \neq \mu_{B})\gamma_{1}f(|\mu_{A} - \mu_{B}|)$$
  
$$L_{j}(\mu_{A}, \mu_{B}, H_{1j}) = \mathbb{1}(\mu_{A} = \mu_{B})\gamma_{0},$$

where  $\gamma_0, \gamma_1, f(|\mu_A - \mu_B|) > 0$ .

- Priors of hypotheses are  $\mathbb{P}(H_{01}) = \mathbb{P}(H_{02}) = \pi_0$ .
- Includes decisions under {0,1}-loss by letting  $\gamma_0 = \gamma_1$  and  $f(|\mu_A \mu_B|) = 1$ .
- Other loss functions are possible, such as adaptations of the ones in Robert and Casella (1994) or Robert (1996).

## Bayes decisions



- Let the data be  $\mathcal{D}$  and  $\overline{f}_i = \mathbb{E}_i[f(|\mu_A \mu_B|) | H_{1i}, \mathcal{D}].$
- Given this framework, the Bayes decisions are

$$\delta_j^{\pi} = \begin{cases} H_{0j} & \text{if } \mathbb{P}_j(H_{0j} \mid \mathcal{D}) \ge \frac{\gamma_1 \overline{f}_j}{\gamma_0 + \gamma_1 \overline{f}_j} \\ H_{1j} & \text{otherwise,} \end{cases}$$

where

$$\mathbb{P}_{j}(H_{0j} \mid \mathcal{D}) = \left[1 + \frac{1 - \pi_{0}}{\pi_{0}} B_{10,j}\right]^{-1}.$$

• Bayes decisions depend on  $\mathcal{D}$  only through the Bayes factor  $B_{10,i}$  and  $\overline{f}_i$ .



#### **Parametrizations**



- It turns out that, in this problem, parametrizations matter... a lot.
- We'll consider 3 parametrizations:
  - **1 Independent means:**  $\mu_A$  and  $\mu_B$  separately.
  - **2** Effect-size:  $\mu_A = \mu \delta/2$  and  $\mu_B = \mu + \delta/2$ .
  - **3** Baseline:  $\mu_A = \mu_A$  and  $\mu_B = \mu_A + \alpha$ .

## Independent priors



Test  $H_{02}$ :  $\mu_A = \mu_B = \mu$  against  $H_{12}$ :  $\mu_A \neq \mu_B$  with priors

$$\begin{split} \mu \mid H_{02} \sim N \big( 0, \sigma^2 / \omega \big) \\ \mu_A, \mu_B \mid H_{12} \sim N \big( \mu_A \mid 0, \sigma^2 / \omega_A \big) \, N \big( \mu_B \mid 0, \sigma^2 / \omega_B \big). \end{split}$$

The Bayes factor of  $H_{12}$  to  $H_{02}$  is

$$B_{10,2} = \left[ \frac{\omega_A \omega_B (\omega + n)}{(\omega_A + n_A)(\omega_B + n_B) \omega} \right]^{1/2} \exp\left\{ \frac{Q}{2} \right\}.$$

$$\sigma^2 Q = \frac{n_A^2 \overline{y}_A^2}{n_A + \omega_A} + \frac{n_B^2 \overline{y}_B^2}{n_B + \omega_B} - \frac{n^2 \overline{y}^2}{n + \omega}$$

## Independent priors



As  $n_B \to \infty$ ,

$$B_{10,2} \rightarrow_d B_l = \left(\frac{\omega}{\omega_B} + \frac{\omega n_A}{\omega_A \omega_B}\right)^{-1/2} \exp\left\{\frac{Q_*}{2}\right\}$$

$$Q_* = Z_*^2 + \frac{(\omega - \omega_B)(\mu_B^*)^2}{\sigma^2} - \frac{n_A \omega_A \overline{y}_A^2}{\sigma^2(n_A + \omega_A)}.$$

Non-vanishing dependence on prior for  $\mu_B$  unless  $\omega_B = \omega!$ 

#### Question



- Is there **any** prior specification for the one-sample test where  $\mu_B^*$  is known that yields  $B_l$  as a Bayes factor?
- That is, is there any limit-compatible prior?

• In the one-sample test  $H_{11}: \mu_A \neq \mu_B^*$  against  $H_{01}: \mu_A = \mu_B^*$ , the Bayes factor of  $H_{11}$  to  $H_{01}$  can be written as

$$B_{10,1} = \frac{\int N(\overline{y}_A \mid \mu_A, \sigma^2/n_A) \pi_1(\mu_A \mid H_{11}) d\mu_A}{N(\overline{y}_A \mid \mu_B^*, \sigma^2/n_A)}.$$

The integral of the numerator with respect to  $\overline{y}_A$  must be equal to 1

• If  $B_l$  were to be  $B_{10,1}$ , the numerator should be

$$\left(\frac{\omega}{\omega_B}\right)^{-1/2} \exp\left\{\frac{(\omega-\omega_B)(\mu_B^*)^2}{2\sigma^2}\right\} N\left(\overline{y}_A \mid 0, \frac{\sigma^2(n_A+\omega_A)}{n_A\omega_A}\right).$$

• There are only 2 choices of  $\omega$ ,  $\omega_B > 0$  so that the integral wrt  $\overline{y}_A$  is equal to 1:  $\omega = \omega_B$ , and another one where the values of  $\omega$  depend on  $\mu_B^*$  (which is cheating).

## Independent priors



- The choice  $\omega = \omega_B$  converges to a Bayes factor the one-sample problem  $H_{01}: \mu_A = \mu_B^*$  against  $H_{11}: \mu_A \neq \mu_B^*$  with  $\mu_B^*$  known.
- The prior for the one-sample problem is  $\mu_A \mid H_{11} \sim N(0, \sigma^2/\omega_A)$ .
- Hard to justify as a default choice unless  $\mu_B^* = 0$ , since it assumes a preference of values of  $\mu_A$  near 0 whenever  $\mu_A \neq \mu_B^*$ .
- For example, the value of  $\overline{y}_A$  that minimizes  $B_{10,1}$  is  $\overline{y}_A = (1 + \omega/n_A)\mu_B^*$  instead of  $\overline{y}_A = \mu_B^*$ .



## Independent priors



- **Recall:** Limit compatibility requires convergence of Bayes factors and **posterior expectations.**
- For any  $\omega_B > 0$ , the posterior of  $\mu_B$  collapses to a point mass at  $\mu_B^*$  and the posterior of  $\mu_A$  doesn't change.
- The posterior is compatible with the prior  $\mu_A \mid H_{11} \sim N(0, \sigma^2/\omega_A)$  for the one-sample test.
- **NB:** Unlike with the Bayes factor, compatibility doesn't depend on the value of  $\omega_B$ .

## Summary



- With independent priors, limit compatibility does not hold unless  $\omega_B = \omega$ .
- Even then, the compatible prior isn't entirely satisfactory: it is centered at 0 instead of μ<sub>B</sub><sup>\*</sup>.

- Let  $\mu_A = \mu \delta/2$  and  $\mu_B = \mu + \delta/2$ .
- $\delta$  is the effect size  $\delta = \mu_B \mu_A$ .
- Two-sample test becomes  $H_{02}$ :  $\delta = 0$  against  $H_{12}$ :  $\delta \neq 0$ .
- Prior specification:  $\mu \sim N(0, \sigma^2/\lambda)$  independent of  $\delta \mid H_{12} \sim N(0, \sigma^2/\omega)$ .

As 
$$n_R \to \infty$$
,

$$B_{10,2}^{\delta} \rightarrow_{d} B_{l} = (1 + \kappa_{l}/\omega)^{-1/2} \exp\left\{\frac{\kappa_{l}}{2(\kappa_{l} + \omega)} Z_{l}^{2}\right\}$$

$$\kappa_{l} = \lambda/4 + n_{A}$$

$$Z_{l} = \frac{n_{A}(\mu_{B}^{*} - \overline{y}_{A})}{\sigma\sqrt{\kappa_{l}}} + \frac{\lambda\mu_{B}^{*}}{2\sigma\sqrt{\kappa_{l}}}.$$



- Only two values of  $\eta = 1 + \lambda/(4\omega)$  have compatible Bayes factors wrt the one-sample problem.
  - $\eta=1$ , which comprises the uninteresting case  $\omega\to\infty$  (the prior for  $\delta$  is point mass at 0) and  $\lambda\to0$ , which corresponds to a flat prior on the common parameter.
  - 2 Root of  $4\omega(\mu_B^*)^2(\eta-1)^2/\sigma^2 = \eta \log \eta$  greater than 1, which depends on  $\mu_B^*$ .
- If  $\lambda = 0$ , we converge to the Bayes factor under the **desirable** prior  $\mu_A \mid H_{11} \sim N(\mu_B^*, \sigma^2/\omega_A)$ , centered at hypothesized value under  $H_{01}$ .

- The posterior of  $\mu_A = \mu \delta/2$  converges weakly to  $N(n_A \overline{y}_A + (\omega \lambda/4)\mu_B^*)/(n_A + \lambda/4 + \omega), \sigma^2/(n_A + \lambda/4 + \omega))$ .
- There are compatible posteriors if  $\lambda = 0$  or  $\lambda = 4\omega$ .
- If  $\lambda = 4\omega$ , the compatible prior is  $\mu_A \sim N(0, \sigma^2/(2\omega))$ , which is centered at 0 (not  $\mu_B^*$ ). For this choice of  $\lambda$  there is no compatible Bayes factor.



## Summary



- Putting a flat prior on common parameter is the only possibility that yields limit compatibility.
- The compatible prior is **reasonable**: a normal prior on  $\mu_A$  under the alternative, centered at  $\mu_B^*$ .
- Flat priors on common parameters are recommended in the related literature (see e.g. Bayarri et al. (2012)). This can be seen as another justification.



- Suppose we parametrize the problem so that the mean of group A is  $\mu_A$  and the mean of group B is  $\mu_A + \alpha$ .
- The test becomes  $H_{02}$ :  $\alpha = 0$  against  $H_{12}$ :  $\alpha \neq 0$ .
- Priors:  $\mu_A \sim N_1(0, \sigma^2/\lambda)$  independent of  $\alpha \mid H_{12} \sim N_1(0, \sigma^2/\omega)$ .



**Without taking any limits**, the Bayes factor of  $H_{12}$  to  $H_{02}$  is

$$B_{10,2}^{\alpha} = (1 + \kappa_{\alpha}/\omega)^{-1/2} \exp\left\{\frac{\kappa_{\alpha} Z_{\alpha}^{2}}{2(\kappa_{\alpha} + \omega)}\right\}$$

$$\kappa_{\alpha} = \frac{\lambda n_{B} + n_{A} n_{B}}{n + \lambda}$$

$$Z_{\alpha} = \frac{n_{B} n_{A} (\overline{y}_{B} - \overline{y}_{A}) + \lambda n_{B} \overline{y}_{B}}{\sigma \sqrt{\kappa_{\alpha}} (n + \lambda)}.$$

It depends the choice of baseline unless  $\lambda = 0!$ 



## Summary



- As with the effect-size parametrization, there is no realistic Bayes factor that is compatible for the one-sample test unless  $\lambda = 0$ .
- In the case  $\lambda = 0$ , the baseline and effect-size parametrization yield identical Bayes factors and posteriors on  $\mu_A$ ,  $\mu_B$ .



# Conditional compatibility



#### Another criterion



- In a Bayesian two-sample test, conditioning on  $\mu_B = \mu_B^*$  should yield a Bayes decision that arises under a prior specification the one-sample problem where  $\mu_B^*$  is known.
- Ideally, conditioning on  $\mu_B = \mu_B^*$  should also be the same as taking the limit as  $n_B \to \infty$ .
- Surprisingly, conditioning and taking limits aren't always the same.



# Cond'l compatibility

#### Definition

Consider the Bayesian hypothesis tests:

- $H_{01}: P_{\theta_A} = P_{\theta_B^*}$  against  $H_{11}: P_{\theta_A} \neq P_{\theta_B^*}$  with  $P_{\theta_A}$  unknown and  $P_{\theta_B^*}$  known, with prior specification  $\pi_1$ .
- **2**  $H_{02}: P_{\theta_A} = P_{\theta_B}$  against  $H_{12}: P_{\theta_A} \neq P_{\theta_B}$  with  $\theta_A$  and  $\theta_B$  unknown, with prior specification  $\pi_2$ .

Let  $\delta_1$  be the Bayes decision for the one-sample test and  $\delta_*$  be the conditional Bayes decision for the two-sample test upon conditioning on  $\theta_B = \theta_B^*$ .

The decision rules  $\delta_1$  and  $\delta_*$  are **conditionally compatible** if  $\delta_* = H_{h2} \Leftrightarrow \delta_1 = H_{h1}$  for  $h \in \{0, 1\}$ .

# Summary



- With independent priors or effect-size and baseline parametrizations with proper priors, everything breaks down.
- With baseline or effect-size parametrization and flat priors on "common parameter", everything is fine.



- Parametrize  $\mu_B = \mu_A + \alpha$  and work with priors  $\mu_A \sim N(0, \sigma^2/\lambda)$  and  $\alpha \mid H_{12} \sim N(0, \sigma^2/\omega)$ .
- After conditioning on  $\mu_B = \mu_B^*$ , the prior is

$$\mu_A \mid \mu_B = \mu_B^*, H_{21} \sim N \left[ \frac{\omega}{\lambda + \omega} \, \mu_B^*, \frac{\sigma^2}{\lambda + \omega} \right]$$

Not centered at  $\mu_B^*$  unless  $\lambda = 0$ .

The ratio of the limiting Bayes factor as  $n_B \to \infty$  to the conditional Bayes factor is

$$\frac{B_l}{B_{\text{cond}}} = (1 + \lambda/\omega)^{-1/2} \exp\left\{\frac{\lambda(\mu_B^*)^2}{2\sigma^2(\lambda + \omega)}\right\}$$

- In general, not equal to 1 unless  $\lambda = 0$ .
- If  $\mu_B^* = 0$ , we have  $B_l < B_{\rm cond}$ . If  $\mu_B^* \neq 0$ , generally  $B_l > B_{\rm cond}$  unless  $\mu^*/\sigma$  is very small.

- Similar story as with baseline parametrization.
- Let  $\mu_A = \mu \delta/2$  and  $\mu_B = \mu + \delta/2$ .
- Priors  $\mu \sim N(0, \sigma^2/\lambda)$  and  $\delta \mid H_{12} \sim N(0, \sigma^2/\omega)$ .
- Ratio "limit /conditional:"

$$\frac{B_l}{B_{\text{cond}}} = \left[1 + \lambda/(4\omega)\right]^{-1/2} \exp\left\{\frac{\lambda(\mu_B^*)^2}{2\sigma^2(\lambda + 4\omega)}\right\}$$

### **Beyond normal priors**



### Non-local priors



- What are they? Consider the hypothesis test  $H_0: \theta \in \Theta_0$  against  $H_1: \theta \in \Theta_1$ . A prior for  $\theta \mid H_1$  is said to be non-local if it vanishes as  $\theta$  approaches  $\Theta_0$  (Johnson and Rossell, 2010).
- Bayes factors under non-local priors have been seen to attain faster rates of convergence to the "truth" under the null hypothesis (Johnson and Rossell, 2010, 2012)



#### Local vs non-local



- As noted in Consonni et al. (2013), Bayes decisions under non-local priors and {0,1}-loss are equivalent to Bayes decisions under local priors with respect to loss functions that involve parameters.
- The results I showed you (sort of) include this case.
- **Result:** Non-local priors proposed in the literature have the same behavior as local priors.



#### Local vs non-local



• **Framework:** Losses  $L_1$  and  $L_2$  for one- and two-sample tests of the type:

$$L_{j}(\mu_{A}, \mu_{B}, H_{0j}) = \mathbb{1}(\mu_{A} \neq \mu_{B})\gamma f(|\mu_{A} - \mu_{B}|)$$
  

$$L_{j}(\mu_{A}, \mu_{B}, H_{1j}) = \mathbb{1}(\mu_{A} = \mu_{B})\gamma,$$

where 
$$\gamma$$
,  $f(|\mu_A - \mu_B|) > 0$ .

• Decisions with non-local priors and  $f(|\mu_A - \mu_B|) = 1$  are equivalent to decisions with local priors and choices of f which depend on  $|\mu_A - \mu_B|$ .



#### Local vs non-local



• Let  $\delta = |\mu_A - \mu_B|$  and consider the "penalty" functions

$$f_{M}(\delta) = \omega \delta^{2}/\sigma^{2}$$

$$f_{E}(\delta) = \exp\left\{\sqrt{2} - \frac{\sigma^{2}}{\omega \delta^{2}}\right\}$$

$$f_{I}(\delta) = \frac{\sqrt{2}\sigma^{2}}{\omega \delta^{2}} \exp\left\{-\frac{\sigma^{2}}{\omega \delta^{2}} + \frac{\omega \delta^{2}}{2\sigma^{2}}\right\}$$

• Decisions with normal priors and  $f_M$ ,  $f_E$ , and  $f_I$  are equivalent to decisions with non-local moment, exponential, and inverse-moment priors and  $f(\delta) = 1$ , respectively.

- Let's work with the baseline parametrization where  $\mu_B = \mu_A + \alpha$  and  $\pi(\mu_A) \propto 1$ .
- In this context, Zellner's *g*-prior (after centering the design matrix) is  $\alpha \mid H_{12} \sim N(0, gn\sigma^2/(n_A n_B))$  which yields

$$B_{10,2} = (g+1)^{-1/2} \exp\left\{ \frac{gZ_n^2}{2(g+1)} \right\}.$$

• A common choice is g = n, but that implies  $B_{10,2} \rightarrow 0$  as  $n_B \rightarrow \infty$  (it isn't conditionally compatible, either...)



- An alternative to g = n is  $g = n_A n_B/n$ .
- As  $n_B \to \infty$ , g behaves like  $n_A$  and yields compatible Bayes factors with unit information priors for the one-sample problem.
- As both  $n_A$ ,  $n_B \to \infty$ ,  $n_A n_B / n$  acts as the usual polynomial model complexity penalty in local Bayes factors.
- Note that g constant isn't desirable because  $B_{10,2}$  wouldn't be consistent under  $H_{02}$ .



### Thicker-tailed priors



 Preliminary results with mixtures of normals show identical behavior as with normal priors.



## **HPD** regions



 Some people like avoiding Bayes factors and like making decisions by checking whether high posterior density regions include the hypothesized value under the null.



- **Indep. priors:** Compatibility with prior on  $\mu_A$  centered at 0.
- **Effect-size:** Flat prior on common parameter is compatible with prior on  $\mu_A$  centered at  $\mu_B^*$ . Non-flat priors on common parameter aren't compatible with any prior unless  $\lambda = 4\omega$ , which is compatible with a prior on  $\mu_A$  centered at 0.
- **Baseline:** Flat prior on grand mean is OK; any other choice isn't compatible.



#### Conclusions and future work



#### Conclusions



- Proposed new criteria to defend or propose prior choice in two-sample problems.
- In testing normal means, they strongly recommend parametrizations with common parameters, and flat priors on them.
- Have to be careful in how we specify the prior scale of the prior.



#### Future work



- Normal means: More than 2 groups.
- Beyond normal means: testing 2 proportions, nonparametric tests of equality of distributions, etc.
- Suggestions?



Thanks!



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