

# Consensus-Based Optimization Beyond Finite-Time Analysis

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# Objective

## Problem

$$\min_{x \in \mathbb{R}^d} f(x)$$

with  $f$  a **non-convex** with **unknown gradient** function, and with one unique minimizer  $x_*$ .

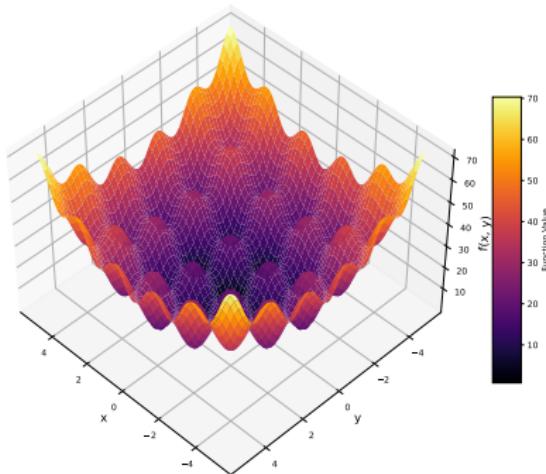


Figure: Example of function  $f$

# Solutions

**Algorithm:** Generate particles to reach the minimizer of  $f$ .

- Simulated Annealing Pelletier 1998.
- Genetic and Evolutionary Algorithms Holland 1975.
- Bayesian Optimization Hastings 1970.
- Particle Swarm Optimization (PSO) Kennedy and Eberhart 1995.

**Applications:** Machine learning, Signal processing, ...

**Problem:** Lack of theoretical results for these algorithms.

# PSO Kennedy and Eberhart 1995

**Idea:** At time step  $k + 1$ , we want all particles  $(X_{k+1}^i)_{i \leq n}$  to move closer to the best particle among all previous positions  $(X_j^i)_{j \leq k, i \leq n}$ .

- **Personal best:**  $p_k^i := \arg \min_{x \in \{X_0^i, \dots, X_k^i\}} f(x)$
- **Global best:**  $g_k := \arg \min_{p \in \{p_k^1, \dots, p_k^n\}} f(p)$

## Vanilla PSO Algorithm

$$\begin{aligned} v_{k+1}^i &= v_k^i + \eta_1 (r_1 (p_k^i - X_k^i) + r_2 (g_k - X_k^i)), \\ X_{k+1}^i &= X_k^i + \eta_2 v_{k+1}^i, \end{aligned}$$

where  $r_1, r_2 \sim \mathcal{U}(0, 1)$  are independent random coefficients.

### Problem:

- Heuristic algorithm with few theoretical guarantees.
- We know how to analyze particle systems of the form

$$X_{k+1}^i = F(X_k^1, \dots, X_k^n),$$

but the PSO update rule does not directly fit into this framework.



# CBO: a simplification of PSO

$X_k^1, \dots, X_k^n$ : particles generated at time  $k$ .

At time  $k + 1$ , we want each particle to move closer to the best particle at time  $k$ .

$$\left\{ \begin{array}{l} X_{k+1}^1 = X_k^1 + \eta \left( \underset{x \in \{X_k^1, \dots, X_k^n\}}{\arg \min} f(x) - X_k^1 \right) \\ \vdots \\ X_{k+1}^n = X_k^n + \eta \left( \underset{x \in \{X_k^1, \dots, X_k^n\}}{\arg \min} f(x) - X_k^n \right) \end{array} \right.$$

**Problem:** The operator  $\arg \min$  is irregular.

## Laplace principle

$$C_\alpha^n := \frac{\sum_{i=1}^n X_k^i \exp(-\alpha f(X_k^i))}{\sum_{i=1}^n \exp(-\alpha f(X_k^i))} \xrightarrow{\alpha \rightarrow \infty} \underset{x \in \{X_k^1, \dots, X_k^n\}}{\arg \min} f(x)$$

Consensus-Based Optimization algorithm (CBO) (Pinna et al. 2017):

$$\forall i \leq n, \quad X_{k+1}^i = X_k^i + \eta (C_\alpha^n - X_k^i) + \underbrace{\sqrt{\eta} \sigma_k \xi_k^i}_{\text{noise for exploration}}$$

# Behavior of CBO

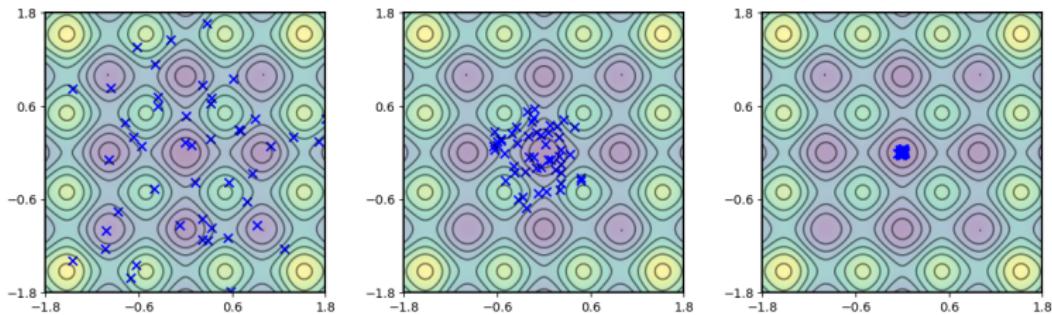


Figure: Demonstration of CBO with  $N = 50$  particles on a 2D function.

# Literature review

- 1995–today: Development of the PSO algorithm and its variants [Kennedy and Eberhart 1995](#).
- 2013: PSO where the memory is discarded (almost CBO) [Askari-Sichani and Jalili 2013](#).
- 2017: Introduction of the CBO algorithm with smooth  $\arg \min$  [Pinna et al. 2017](#).
- 2018: First convergence proof of the CBO algorithm in the infinite-particle regime ( $n := \text{Number of Particles} \rightarrow \infty$ ) under restrictive assumptions [Carrillo et al. 2018](#).
- 2021–2023: Extension of Carrillo et al.'s result to the finite-particle regime ( $n < \infty$ ) [Hu et al. 2021](#); [Gerber, Hoffmann, and Vaes 2023](#).
- 2024: New convergence proof in the infinite-particle regime that relaxes Carrillo et al.'s assumptions [Fornasier, Klock, and Riedl 2024](#).
- 2024–today: Further improvements of Fornasier et al.'s results.
- 2017–today: Development of CBO variants for various tasks, such as sampling, saddle-point search, and constrained optimization.

# The CBO algorithm of Fornasier, Klock, and Riedl 2024

## Algorithm Fornasier, Klock, and Riedl 2024

$$\forall i \leq n, \quad X_{k+1}^i = X_k^i + \eta (C_\alpha^n - X_k^i) + \sqrt{\eta} \|C_\alpha^n - X_k^i\| \xi_k^i.$$

In the population limit ( $n \rightarrow \infty$ ), particles  $X_k^1, \dots, X_k^n$  are i.i.d.:

$$C_\alpha^n = \frac{\sum_{i=1}^n X_k^i \exp(-\alpha f(X_k^i))}{\sum_{i=1}^n \exp(-\alpha f(X_k^i))} \xrightarrow{n \rightarrow \infty} \underbrace{\frac{\mathbb{E}(X_k^1 e^{-\alpha f(X_k^1)})}{\mathbb{E}(e^{-\alpha f(X_k^1)})}}_{\text{Law of large number}} =: C_\alpha(\text{Law}(X_k^1)).$$

## Mean field Equation ( $\eta \rightarrow 0, n \rightarrow \infty$ )

$$dX_t = (C_\alpha(\text{Law}(X_t)) - X_t)dt + \|C_\alpha(\text{Law}(X_t)) - X_t\| dB_t$$

$B_t$ : Brownian motion

# Result of Fornasier, Klock, and Riedl 2024

$$x_* := \arg \min f.$$

Result in the mean field limit (Fornasier, Klock, and Riedl 2024)

For some  $t \leq T(\alpha)$ :

$$W_2(\text{Law}(X_t), \delta_{x_*}) \leq e^{-Ct} W_2(\text{Law}(X_0), \delta_{x_*}).$$

Choosing  $\alpha$  large s. t.  $e^{-CT(\alpha)} \leq \frac{\varepsilon}{W_2(\text{Law}(X_0), \delta_{x_*})}$ , we reach an  $\varepsilon$  precision.

Result of the finite particle regime (Fornasier, Klock, and Riedl 2024)

$n$ : number of particles

For  $k \leq \min(K(\alpha), \log n)$  and :

$$W_2(\text{Law}(X_k^i), \delta_{x_*}) \leq e^{-Ck} W_2(\text{Law}(X_0^i), \delta_{x_*}).$$

**Problem:** In the finite particles regime, the **number of iterations is bounded** by a quantity depending on  $\alpha$  and  $n$ .

# Literature's gap

Convergence of CBO:

	<b>Low value of <math>k</math></b>	<b>Large value of <math>k</math></b>
$n = \infty$	Fornasier, Klock, and Riedl 2024	Carrillo et al. 2018
$n < \infty$	Fornasier, Klock, and Riedl 2024	Our result

- In the case  $n = \infty$  with large  $k$ , the result of Carrillo et al. 2018 holds under **restrictive conditions** on the initial distribution.
- In the case  $n < \infty$  and for small  $k$ , convergence is guaranteed only when  $k \ll n$  and  $k \leq K(\alpha)$ .

# Limitation of Fornasier, Klock, and Riedl 2024

Mean field:  $dX_t = (C_\alpha(\text{Law}(X_t)) - X_t)dt + \|C_\alpha(\text{Law}(X_t)) - X_t\| dB_t$

Assume that  $\mathbb{P}(\|X_t - x_*\| \leq \varepsilon) > c$ :

$$C_\alpha(\text{Law}(X_t)) = \frac{\mathbb{E}(X_t e^{-f(X_t)})}{\mathbb{E}(e^{-\alpha f(X_t)})} \simeq \frac{x_* e^{-\alpha f(x_*)} \mathbb{P}(\|X_t - x_*\| \leq \varepsilon) + e^{-\alpha(f(x_*) + \tilde{\varepsilon})}}{e^{-\alpha f(x_*)} \mathbb{P}(\|X_t - x_*\| \leq \varepsilon)} \rightarrow x_*$$

Under,  $\mathbb{P}(\|X_t - x_*\| \leq \varepsilon) > c$ :

$$dX_t \simeq (x_* - X_t)dt + \|x_* - X_t\| dB_t, \quad (1)$$

which means  $\text{Law}(X_t) \rightarrow \delta_{x_*}$ .

## Problem

- $\mathbb{P}(\|X_t - x_*\| \leq \varepsilon) > c$ : true when  $X_t$  has a density with large enough variance.
- $\|C_\alpha(\text{Law}(X_t)) - X_t\| \rightarrow 0 \implies$  the variance of  $X_t$  decreases.
- At some time  $T$ ,  $\mathbb{P}(\|X_t - x_*\| \leq \varepsilon) < c$  and the approximation Eq. (1) does not hold.

# Our version of CBO

We want a long-time result on CBO.

## Idea

We solve the issue raised in Fornasier, Klock, and Riedl 2024 by using fixed-variance noise.

- Noise with excessively large variance  $\implies$  particles are likely to be too far from  $x_*$ .
- Variance need to be large enough :  $\gamma > \gamma_0$ .

## Our algorithm

For every  $i \leq n$ :

$$X_{k+1}^i = X_k^i + \eta (C_\alpha^n - X_k^i) + \underbrace{\sqrt{2\eta \frac{\gamma}{\alpha}} \xi_k^i}_{\text{fix variance}}$$

# Main result

$\alpha \gg 1$  : parameter of algorithm (needed for the Laplace principle).

## Our result

$$\mathbb{E} \|X_k^i - x_*\| \leq C \left( \frac{1}{\sqrt{n}} + \sqrt{\eta} + (1 + c)^{-k} \right)$$

- A similar result holds in the Mean Field regime.
- $\gamma > \gamma_0$ : the noise has a variance large enough.

# Solution of the Mean Field equation

## Mean Field Equation

$$dX_t = (C_\alpha(\text{Law}(X_t)) - X_t)dt + \sqrt{2\frac{\gamma}{\alpha}}dB_t$$

It is an Ornstein–Uhlenbeck equation with the solution

$$X_t = x_t + \mathcal{N}\left(0, \frac{\gamma}{\alpha} I_d\right) + \underbrace{X_0 e^{-t}}_{\text{small when } t \gg 1}$$

with

$$\dot{x}_t = C_\alpha(\text{Law}(X_t)) - x_t.$$

For large  $t$ ,  $\text{Law}(X_t) \simeq \mathcal{N}(x_t, \frac{\gamma}{\alpha} I_d)$  and by the Laplace principle:

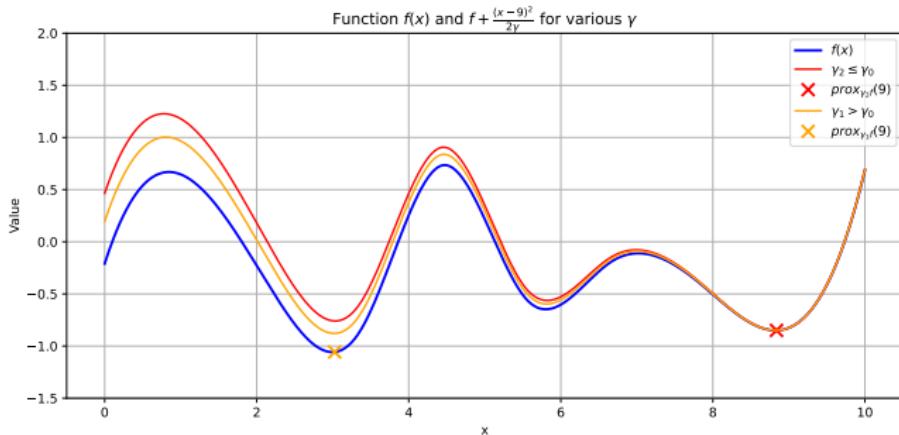
$$C_\alpha(\text{Law}(X_t)) \simeq \frac{\int x e^{-\alpha \left(f(x) + \frac{\|x - x_t\|^2}{2\gamma}\right)} dx}{\int e^{-\alpha \left(f(x) + \frac{\|x - x_t\|^2}{2\gamma}\right)} dx} \xrightarrow{\alpha \rightarrow \infty} \underbrace{\arg \min_{x \in \mathbb{R}^d} \left(f(x) + \frac{\|x - x_t\|^2}{2\gamma}\right)}_{\text{prox}_{\gamma f}(x_t)}$$

With  $\mathbb{E} \|\varepsilon_t\| \ll 1$ :

$$\dot{x}_t = (\text{prox}_{\gamma f}(x_t) - x_t) + \varepsilon_t$$

# The proximal operator

**Problem:**  $\text{prox}_{\gamma f}(x) := \arg \min \{f + \|\cdot - x\|^2 / 2\gamma\}$  requires  $f$  convex.



- For  $\gamma$  large enough,  $\text{prox}_{\gamma f}(x)$  is sufficiently close to  $x_*$ .
- The function  $f$  is convex in a neighborhood of  $x_*$ .
- For  $\gamma$  large enough,  $\text{prox}_{\gamma f}(x)$  lies within the convex region of  $f$ .
- Conclusion: There exists a convex function  $\bar{f}$  such that  $\bar{f} = f$  in a neighborhood of  $x_*$  and  $\text{prox}_{\gamma f} = \text{prox}_{\gamma \bar{f}}$  for large enough  $\gamma$ .

Alternative point of view: The noise must be sufficiently large to escape local minima.

# Convergence of Mean field Equation

The ODE:

$$\dot{x}_t = \text{prox}_{\gamma \bar{f}}(x_t) - x_t + \varepsilon_t,$$

is a continuous version of the [Proximal Point Method](#):

$$x_{k+1} = \text{prox}_{\gamma \bar{f}}(x_k) \Leftrightarrow x_{k+1} - x_k = \text{prox}_{\gamma \bar{f}}(x_k) - x_k.$$

$\bar{f}$  is convex then

$$\|x_t - x_*\| \leq \|x_0 - x_*\| e^{-Ct} + \underbrace{\sup_s \mathbb{E} \|\varepsilon_s\|}_{s}$$

Recall:  $X_t = \mathcal{N}(x_t, \frac{\gamma}{\alpha} I_d)$

## Convergence of the Mean Field equation

$$\mathbb{E} \|X_t - \mathcal{N}(x_*, \frac{\gamma}{\alpha} I_d)\| \leq \mathbb{E} \|X_0 - \mathcal{N}(x_*, \frac{\gamma}{\alpha} I_d)\| e^{-Ct} + \underbrace{\sup_s \mathbb{E} \|\varepsilon_s\|}_{\frac{C}{\sqrt{\alpha}}}$$

or

$$\mathbb{E} \|X_t - x_*\| \leq \frac{C}{\sqrt{\alpha}} + e^{-Ct} \mathbb{E} \|X_0 - x_*\|,$$



# The finite particle error

## The finite particle algorithm

$$\forall i \leq n \quad dX_t^i = (C_\alpha^n - X_t^i)dt + \sqrt{2\frac{\gamma}{\alpha}}dB_t^i.$$

## The Mean Field equation

$$dX_t = (C_\alpha(\text{Law}(X_t) - X_t)dt + \sqrt{2\frac{\gamma}{\alpha}}dB_t.$$

If  $\text{Law}(X_0) = \text{Law}(X_0^i)$ :

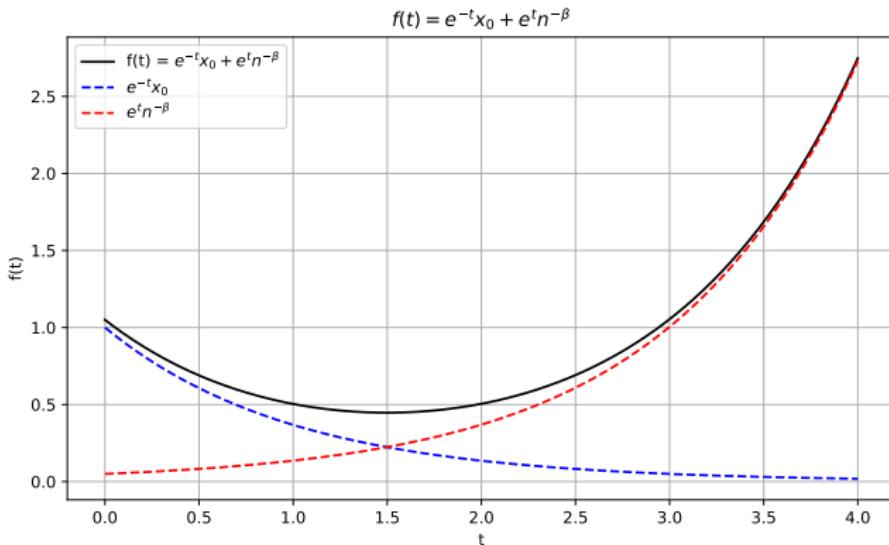
$$W_2(\text{Law}(X_t), \text{Law}(X_t^i)) \leq \frac{e^{Ct}}{\sqrt{n}}.$$

This is a classical issue arising from the use of **Grönwall's lemma**.

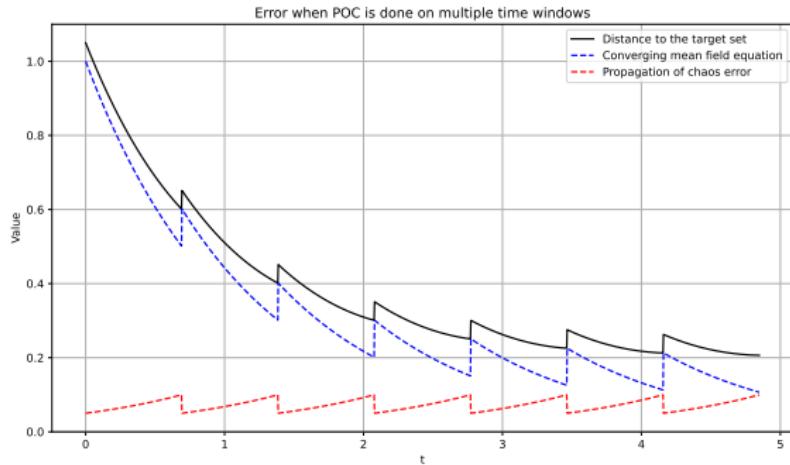
# Putting the results together

$$W_2(\text{Law}(X_t^i), \mathcal{N}_\alpha) \leq \underbrace{e^{-Ct} W_2(\text{Law}(X_0^i), \mathcal{N}_\alpha)}_{\text{Mean Field Equation}} + \underbrace{\frac{e^{Ct}}{\sqrt{n}}}_{\text{finite particle error}}.$$

**Problem:** The exponential term in red diverge as  $t \rightarrow \infty$ .



# Iterating over multiple time intervals



For  $T$  large enough, for any  $t \geq 0$ ,

$$W_2(\text{Law}(X_{t+T}^i), \mathcal{N}_\alpha) \leq \frac{1}{2} W_2(\text{Law}(X_t^i), \mathcal{N}_\alpha) + \frac{e^{CT}}{\sqrt{n}}.$$

Repeat this over  $N$  time intervals of width  $T$ :  $[0, T], \dots, [(N-1)T, NT]$ .

# Conclusion

- By using noise with fixed variance, we address an **open question regarding the long-time convergence** of the CBO algorithm.
- A **convergence proof that does not rely on the mean-field equation** would provide deeper insight. At this stage, we cannot claim that CBO offers a **clear advantage over a simple random search**.