实验目的

- 1. 学习 uC/OS II 的应用程序编写:
- 2. 理解如何直接操纵 GPIO, 体会与 Linux 的不同;
- 3. 学习单总线设备的访问方式;
- 4. 学习7段数码管的时分复用驱动方式。

实验器材

硬件

- pcDuino v2 板一块;
- 5V/1A 电源一个;
- microUSB 线一根;
- 面包板一块;
- 两位7段数码管(共阳)一颗;
- 360 Ω 1/8W 电阻 1 颗;
- DHT-11 温湿度传感器 1 个;
- 面包线若干。

以下为自备(可选)器材:

- PC (Windows/Mac OS/Linux) 一台;
- USB-TTL 串口线一根(FT232RL 芯片或 PL2303 芯片):

软件

- 编译软件;
- Fritzing.

实验要求

- 1. 设计输出方案, 画连线示意图;
- 2. 在面包板上连线,完成外部电路;
- 3. 编写 C/C++程序,测试程序和电路;
 - a. 测试、实现 uC/OS II 对 GPIO 的访问;
 - b. 实现 DHT-11 数据的读;
 - c. 实现以时分复用方式在四位 7 段数码管上依次显示 0000-9999 的数字;

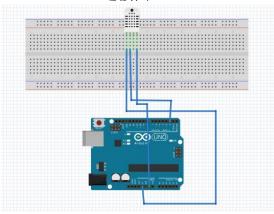
d. 用两个 uc/0S II 任务,一个定时读 DHT-11 数据,一个轮流驱动数码管,一秒一次显示当 前温度和湿度。注意处理 好两个任务之间的数据共享。

实验报告要求

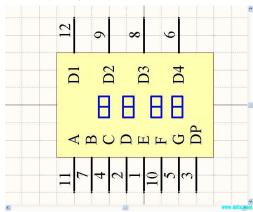
- 1. 画出你所实际实施的连接示意图;
- 2. 给出所用的器材的列表;
- 3. 用 Fritzing 画出外部设备的连线图, 附实物照片;
- 4. 描述所做的实验步骤,给出各步操作的命令和结果;
- 5. 给出代码并解释;
- 6. 将所做作品拍摄视频上传到优酷,给出优酷的视频网址;
- 7. 说明其他所做的扩展内容的情况。

实验步骤

1. 设计输出方案, 画连线示意图; DHT11 连接图:



数码管原理图:



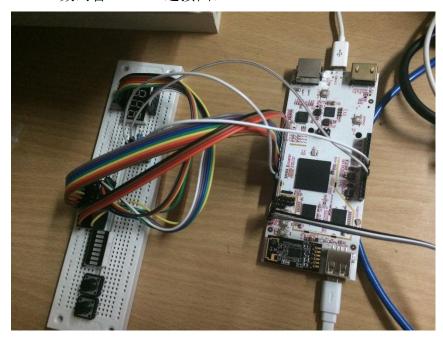
2. 在面包板上连线,完成外部电路; 实际 DHT11 连接图:



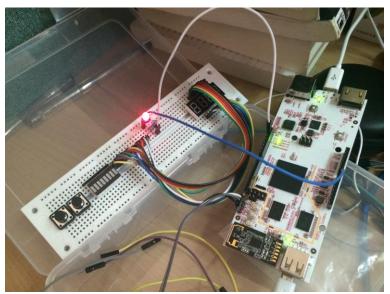
数码管连接图:



数码管 DHT11 连接图:



- 3. 编写 C/C++程序,测试程序和电路;
- 3.1. 测试、实现 uC/OS II 对 GPIO 的访问;
 - a) 参考网络教程——在 pcDuino 上学习 μC/OS II: http://www.oschina.net/question/1425530_144141
 - b) 使用 LED 灯进行测试,闪烁效果如下:



c) 关键代码如下: 使用 digitalwrite 进行 IO 的 LOW、HIGH 控制。

```
void MyTask(void*p_arg )
char* sTaskName = (char*)p_arg;
static flag1 =1;
#if OS_CRITICAL_METHOD ==3
     OS_CPU_SR
                    cpu_sr =0;
#endif
     while(1)
          OS_ENTER_CRITICAL();
          printf("Name: %s\n", sTaskName );
if(!strcmp(sTaskName,"Task 1"))
               if(flag1 ==1)
                    flag1 =0;
                    printf("HIGH\n");
                    digitalWrite(led_pin, 1);
                    flag1 =1;
                    printf("LOW\n");
                    digitalWrite(led_pin, 0);
          OS_EXIT_CRITICAL();
          OSTimeDly(50);
```

- d) 完整代码请参考附件 ledcs.c
- 3.2. 实现 DHT-11 数据的读;
 - a) 改写 DHT-11 的库, 使得该库适合 C 运行;

```
int f_read(int pin)
    // BUFFER TO RECEIVE
    uint8_t bits[5];
    uint8_{t} cnt = 7;
    uint8 t idx = 0;
    int i=0;
    // ACKNOWLEDGE or TIMEOUT
    unsigned int loopCnt = TIMEOUTLIMIT;
    unsigned long t;
    uint8 t sum;
    // EMPTY BUFFER
    for (i=0; i<5; i++) bits[i] = 0;
    // REQUEST SAMPLE
    pinMode(pin, OUTPUT);
    digitalWrite(pin, LOW);
    delay(12);
    digitalWrite(pin, HIGH);
    delayMicroseconds(40);
    pinMode(pin, INPUT);
    // printf("1\n");
    loopCnt = TIMEOUTLIMIT;
    while(digitalRead(pin) == LOW)
         if (loopCnt-- == 0) return DHTLIB_ERROR_TIMEOUT;
    // printf("2\n");
    loopCnt = TIMEOUTLIMIT;
    while(digitalRead(pin) == HIGH)
         if (loopCnt-- == 0) return DHTLIB_ERROR_TIMEOUT;
    // READ OUTPUT - 40 BITS => 5 BYTES or TIMEOUT
    for (i=0; i<40; i++)
         // printf("%d-1\n",i);
         loopCnt = TIMEOUTLIMIT;
         while(digitalRead(pin) == LOW)
             if (loopCnt-- == 0) return DHTLIB_ERROR_TIMEOUT;
         t = micros();
         // printf("%d-2\n",i);
         loopCnt = TIMEOUTLIMIT;
         while(digitalRead(pin) == HIGH)
             if (loopCnt-- == 0) return DHTLIB_ERROR_TIMEOUT;
         // printf("%d-3\n",i);
```

e) 重新编译 ucosII, 生成可运行文件: ucos-sample

```
P
                                                                               COM3 - PuTTY
Name: Task 1
Read sensor: OKTemperature (oC): 31.000000Humidity (%): 32.000000Name: Task
Read sensor: OKTemperature (oC): 31.000000Humidity (%): 32.000000Name: Task 1
Read sensor: OKTemperature (oC): 31.000000Humidity (%): 32.000000Name: Task 1
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Read sensor: OKTemperature (oC): 31.000000Humidity (%): 32.000000Name: Task 1
Read sensor: OKTemperature (oC): 31.000000Humidity (%): 32.000000Name: Task 1
ý
root@ubuntu:/home/ubuntu/ucos2# make
make: Warning: File `config.mk' has modification time 1.3e+08 s in the future
make[1]: Entering directory `/home/ubuntu/ucos2/ucos'
make[1]: Warning: File `/home/ubuntu/ucos2/config.mk' has modification time 1.3e
+08 s in the future
make[2]: Entering directory `/home/ubuntu/ucos2/ucos/port'
make[2]: Warning: File `/home/ubuntu/ucos2/config.mk' has modification time 1.3e
+08 s in the future
  [CC] /home/ubuntu/ucos2/build/os cpu c.o
  [LD] /home/ubuntu/ucos2/build/port.o
make[2]: warning: Clock skew detected. Your build may be incomplete.
make[2]: Leaving directory `/home/ubuntu/ucos2/ucos/port'
  [CC] /home/ubuntu/ucos2/build/os_core.o
  [CC] /home/ubuntu/ucos2/build/os dbg r.o
```

f) 运行进行程序测试:

```
Cemperature (oC): 31.000000 Humidity (%): 36.000000
Read sensor: OK
Temperature (oC): 31.000000 Humidity (%): 35.000000
Read sensor: OK
Temperature (oC): 31.000000 Humidity (%): 35.000000
Read sensor: OK
Temperature (oC): 31.000000 Humidity (%): 35.000000
Read sensor: OK
Temperature (oC): 31.000000 Humidity (%): 39.000000
Read sensor: OK
Temperature (oC): 31.000000 Humidity (%): 39.000000
Read sensor: OK
Temperature (oC): 31.000000 Humidity (%): 39.000000
Read sensor: OK
Temperature (oC): 31.000000 Humidity (%): 39.000000
Read sensor: OK
Temperature (oC): 31.000000 Humidity (%): 38.000000
```

- g) 完整代码请参考 DHT11.c
- 3.3. 实现以时分复用方式在四位7段数码管上依次显示0000-9999的数字;
 - a) 关键代码展示:

首先定义为 Task 2, n 用来累加,由于累加过快,采用除以 10 的方式使得变化速度能够接受:

```
if(!strcmp(sTaskName,"Task 2"))
{
    n++;
    if(n>99999)
        n=0;
    Cacul();
}
```

b) 数码管显示:

```
void Cacul(){
    // int h=time_s;
    // n=888888;
    // printf("%d\n",n);
    clearLEDs();
    pickDigit(1);
    pickNumber((n/x/1000)%10);
    delayMicroseconds(del);
```

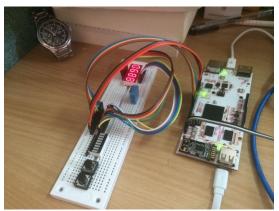
c) 分时复用显示数码管:

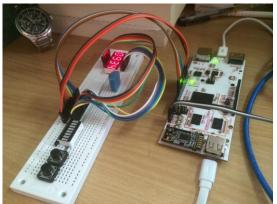
```
void pickDigit(int x) //定义pickDigit(x),其作用是开启dx端口
{
  digitalWrite(d1, LOW);
  digitalWrite(d2, LOW);
  digitalWrite(d3, LOW);
  digitalWrite(d4, LOW);
  switch(x)
  case 1:
    digitalWrite(d1, HIGH);
   break;
    digitalWrite(d2, HIGH);
    break;
    digitalWrite(d3, HIGH);
    break;
   digitalWrite(d4, HIGH);
    break;
```

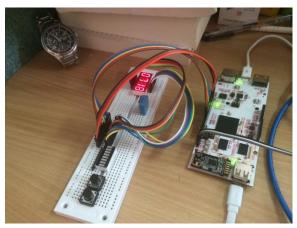
d) 八段数码管代码:

```
void one() //定义数字1时阴极那些管脚开关
{
    digitalWrite(a, HIGH);
    digitalWrite(b,LOW);
    digitalWrite(c,LOW);
    digitalWrite(d, HIGH);
    digitalWrite(e, HIGH);
    digitalWrite(f, HIGH);
    digitalWrite(g, HIGH);
}
```

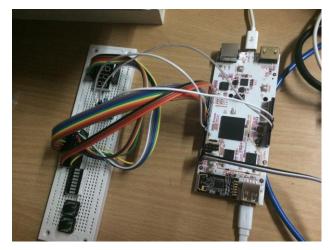
e) 实际运行展示:







- f) 完整代码参见附件。
- 3.4. 用两个 uc/OS II 任务,一个定时读 DHT-11 数据,一个轮流驱动数码管,一秒一次显示当 前温度和湿度。注意处理 好两个任务之间的数据共享。
 - a) 实际连接图:



b) 关键代码: 创建两个任务,能够并行运行:

```
hardware_init();

OSTaskCreate( MyTask, sTask1, (void*)Stk1, 4);

OSTaskCreate( MyTask, sTask2, (void*)Stk2, 5);
```

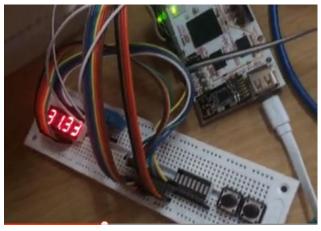
设置温度湿度为全局变量,实现数据共享:

```
int T_read(int pin);
int humidity;
int temperature;

//设置阴极接口
int a = 4:
```

c) 运行效果:

PCDuino 上:



PC端:

```
emperature (oC): 31.000000 Humidity (%): 32.000000
Read sensor: OK
Cemperature (oC): 31.000000 Humidity (%): 32.000000
Read sensor: Time out error
Temperature (oC): 31.000000 Humidity (%): 32.000000
Read sensor: OK
Temperature (oC): 31.000000 Humidity (%): 32.000000
Read sensor: OK
Cemperature (oC): 31.000000 Humidity (%): 32.000000
Read sensor: OK
emperature (oC): 31.000000 Humidity (%): 32.000000
ead sensor: Time out error
emperature (oC): 31.000000 Humidity (%): 32.000000
Read sensor: OK

Temperature (oC): 31.000000 Humidity (%): 32.000000

Read sensor: Time out error
Temperature (oC): 31.000000 Humidity (%): 32.000000
Read sensor: OK
emperature (oC): 31.000000 Humidity (%): 32.000000
   perature (oC): 31.000000 Humidity (%): 32.000000
```

- d) 完整代码请看附件。
- 4. 拍摄的视频优酷地址:

PCduino 室温计 ucos 应用

http://v.youku.com/v_show/id_XNzIzOTAzODgw.html PCduino 室温计 ucos 应用 文字清晰版

http://v.youku.com/v_show/id_XNzIzOTA2MDIw.html