看门狗

配置内核中的硬件看门狗,使得一定时间内不喂狗就重启 Acadia 或 RPi 或 WRTnode,写一个程序或脚本保持一定频率的喂狗,当关闭这 个程序或脚本时形成重启。实验报告要记录和表现出重启。

实现目的

- 1. 掌握看门狗的概念;
- 2. 掌握 Acadia 或 RPi 或 WRTnode 上编写看门狗程序的方法。

实验器材

硬件

- Acadia 或 RPi 或 WRTnode 板一块;
- 5V/1A 电源一个;
- microUSB 线一根;
- USB-TTL 串口线一根(FT232RL 芯片或 PL2303 芯片)。

以下为自备(可选)器材:

- PC (Windows/Mac OS/Linux) 一台;
- 以太网线一根(可能还需要路由器等)。

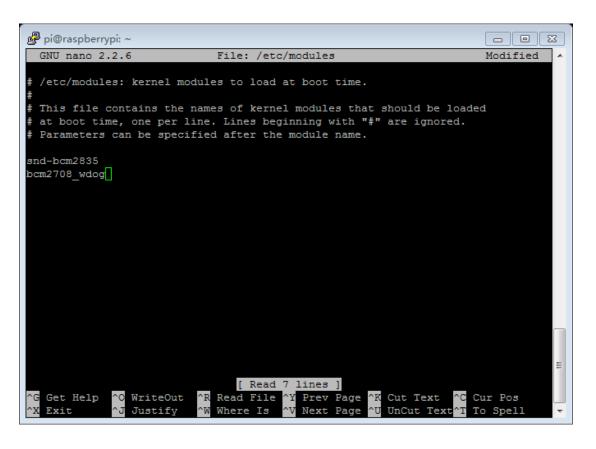
软件

- PC 上的 USB-TTL 串口线配套的驱动程序;
- PC上的串口终端软件,如minicom、picocom、putty等;
- PC 上的 SSH 软件,如 putty 等。

实验步骤

1. 编写看门狗程序并编译;

加载模块



```
💋 pi@raspberrypi: ~
                                   implies --force-modversions and
                                    --force-vermagic
                                   Ignore module's version
           --force-modversion
           --force-vermagic
                                   Ignore module's version magic
Query Options:
       -D, --show-depends
                                   Only print module dependencies and exit
        -c, --showconfig
                                   Print out known configuration and exit
       -c, --show-config
                                   Same as --showconfig
           --show-modversions
                                   Dump module symbol version and exit
           --dump-modversions
                                   Same as --show-modversions
General Options:
       -n, --dry-run
-n, --show
                                   Do not execute operations, just print out
                                   Same as --dry-run
       -C, --config=FILE
                                   Use FILE instead of default search paths
       -d, --dirname=DIR
                                   Use DIR as filesystem root for /lib/modules
        -s, --syslog
                                   print to syslog, not stderr
       -q, --quiet
                                   disable messages
        -v, --verbose
                                   enables more messages
       -V, --version
-h, --help
                                   show version
                                   show this help
pi@raspberrypi ~ $ sudo modprobe watch dog
FATAL: Module watch_dog not found.
pi@raspberrypi ~ $ sudo modprobe bcm2708_wdog
pi@raspberrypi ~ $ sudo nano /etc/modules
pi@raspberrypi ~ $ 🗍
```

```
COM4 - PuTTY
                                                                             GNU nano 2.2.6
                               File: watch dog.c
                                                                             Modified ^
      printf("open error\n");
      exit(EXIT_FAILURE);
  while(1)
      printf("feeding!\n");
      a = write(fd, "a", 1);
      if (a != 1)
         break;
      sleep(5);
   close(fd);
                            ^R Read File ^Y Prev Page ^K Cut Text ^C Cur Pos ^W Where Is ^V Next Page ^U UnCut Text^T To Spell
  Get Help
              ^O WriteOut
                 Justify
```

2. 运行程序:

```
while(1)
{
    printf("feeding!\n");
    a = write(fd, "a", 1);
    if (a != 1)
    {
        a = -1;
        break;
    }
    sleep(5);
}

close(fd);

[ Wrote 32 lines ]

pi@raspberrypi:~$ ls

Desktop objdump.o shairport watch_dog.c

objdump.c python_games this_is_pi.txt
pi@raspberrypi:~$ gcc watch_dog.c -o watch_dog
pi@raspberrypi:~$ ]
```

3. 对程序进行验证。

```
[ "watchdog" is a device file ]

pi@raspberrypi:/dev$ cd /home/pi
pi@raspberrypi:/$ is

Desktop objdump.o shairport watch_dog
objdump.c python_games this_is_pi.txt watch_dog.c
pi@raspberrypi:/$ sudo root
sudo: root: command not found
pi@raspberrypi:/s sudo su
root@raspberrypi:/home/pi$ ./watch_dog
feeding!
feeding!
feeding!
feeding!
```

```
COM4 - PuTTY
                                                                                                                                 - • X
                                    [ "watchdog" is a device file ]
pi@raspberrypi:/dev$ cd /home/pi
pi@raspberrypi:~$ ls
Desktop objdump.o shairport watch_dog objdump.c python_games this_is_pi.txt watch_dog.c pi@raspberrypi:~$ sudo root
sudo: root: command not found
pi@raspberrypi:~$ sudo su
root@raspberrypi:/home/pi# ./watch_dog
feeding!
                                                                                                                                                 ш
feeding!
feeding!
feeding!
feeding!
feeding!
[1]+ Stopped
                                            ./watch_dog
 root@raspberrypi:/home/pi# Uncompressing Linux... done, booting the kernel.
       0.000000] Booting Linux on physical CPU 0x0
0.000000] Initializing cgroup subsys cpu
[ 0.000000] Initializing cgroup subsys cpuacct
[ 0.000000] Linux version 3.18.7+ (dc4@dc4-XPS13-9333) (gcc version 4.8.3 20140303 (prereleas
e) (crosstool-NG linaro-1.13.1+bzr2650 - Linaro GCC 2014.03) ) #755 PREEMPT Thu Feb 12 17:14:31
GMT 2015
       0.000000] CPU: ARMv6-compatible processor [410fb767] revision 7 (ARMv7), cr=00c5387d 0.000000] CPU: PIPT / VIPT nonaliasing data cache, VIPT nonaliasing instruction cache
```

5 秒钟左右后自动重新启动。