

# 树莓派 移动检测物体检测

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## 1. 使用命令

sudo apt-get install motion 安装motion

```
pi@raspberrypi-wt ~ $ sudo apt-get install motion
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following extra packages will be installed:
  ffmpeg libav-tools libavdevice53 libavfilter2 libavfilter3 libavresample1
  libmysqlclient18 libopencv-core2.3 libopencv-imgproc2.3 libpq5 mysql-common
Suggested packages:
  frei0r-plugins mysql-client postgresql-client
The following NEW packages will be installed:
  ffmpeg libav-tools libavdevice53 libavfilter2 libavfilter3 libavresample1
  libmysqlclient18 libopencv-core2.3 libopencv-imgproc2.3 libpq5 motion
  mysql-common
0 upgraded, 12 newly installed, 0 to remove and 3 not upgraded.
Need to get 6,249 kB of archives.
After this operation, 18.0 MB of additional disk space will be used.
Do you want to continue [Y/n]? y
Get:1 http://mirrors.zju.edu.cn/raspbian/raspbian/ wheezy/main libopencv-core2.3
  armhf 2.3.1-11 [707 kB]
Get:2 http://mirrors.zju.edu.cn/raspbian/raspbian/ wheezy/main libopencv-imgproc
  2.3 armhf 2.3.1-11 [672 kB]
```

## 2. 查看摄像头设备是否已经安装好了

ls /dev

```
pi@raspberrypi-wt: ~ — ssh — 80x24
autofs      loop6       ram13       tty1        tty30       tty51       vchiq
block       loop7       ram14       tty10       tty31       tty52       vcio
btrfs-control loop-control ram15       tty11       tty32       tty53       vc-mem
bus         MAKEDEV    ram2        tty12       tty33       tty54       vcs
cachefiles  mapper     ram3        tty13       tty34       tty55       vcs1
char        media0     ram4        tty14       tty35       tty56       vcs2
console     mem        ram5        tty15       tty36       tty57       vcs3
cpu_dma_latency memory_bandwidth ram6        tty16       tty37       tty58       vcs4
cuse        mncblk0    ram7        tty17       tty38       tty59       vcs5
disk        mncblk0p1 ram8        tty18       tty39       tty6        vcs6
fb0         mncblk0p2 ram9        tty19       tty4        tty60       vcsa
fd          net        random      tty2        tty40       tty61       vcsa1
full        network_latency raw          tty20       tty41       tty62       vcsa2
fuse        network_throughput rfkill      tty21       tty42       tty63       vcsa3
input       null       root        tty22       tty43       tty7        vcsa4
kmsg        ppp        shm         tty23       tty44       tty8        vcsa5
log         ptmx       snd         tty24       tty45       tty9        vcsa6
loop0       pts        sndstat     tty25       tty46       ttyAMA0     vcsa
loop1       ram0       stderr      tty26       tty47       ttyprintk   vchi
loop2       ram1       stdin       tty27       tty48       uinput      video0
loop3       ram10      stdout      tty28       tty49       urandom     xconsole
loop4       ram11     tty         tty29       tty5        v4l         zero
loop5       ram12     tty0        tty3        tty50       vc-cma
```

发现我们已经找到了video0，说明设备已经被识别了

### 3. 更改motion配置

```
# Start in daemon (background) mode and release terminal (default: off)
daemon on
```

修改/etc/motion/motion.conf文件，将守护进程开启

```
GNU nano 2.2.6          File: motion.conf          Modified

# Restrict webcam connections to localhost only (default: on)
webcam_localhost off

# Limits the number of images per connection (default: 0 = unlimited)
# Number can be defined by multiplying actual webcam rate by desired number of $
# Actual webcam rate is the smallest of the numbers framerate and webcam_maxrate
webcam_limit 0
```

不仅仅是本地服务器

```
# set to 'yes' to enable the motion daemon
start_motion_daemon=yes
```

```
~
~
```

将/etc/default/motion中的守护改为开启

```
313 # Set to 'preview' will only draw a box in preview_shot pictures.
314 locate on
315
```

设置成为检测到物体运动，就用框框住

### 4. 开启服务

sudo service motion start

然后如下

在浏览器中输入

192.168.1.182:8081

可以得到下图



的确检测到了图像，同时运动检测到了运动；

至此，运动检测服务器搭建完成