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数码管骰子实验

实验要求

使用实验板实现一个数码管筛子,数字筛子的基本要求是数码管(只需要一个数字)快速在1-8之间循环跳动,当按下按键时,数码管定格在当前的数字上,不再跳动。

实验器材

硬件

- 实验板一块;
- 5V/1A电源一个;
- microUSB线一根;
- USB-TTL串口线一根(FT232RL芯片或PL2303芯片)。
- 七段数码管
- 相关外围期间
- 以下为自备(可选)器材:
- PC (Windows/Mac OS/Linux) 一台;
- 以太网线一根(可能还需要路由器等)。

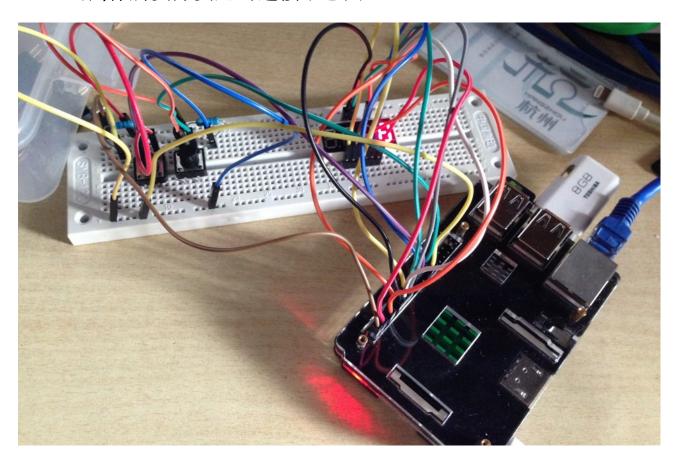
软件

- PC上的USB-TTL串口线配套的驱动程序;
- PC上的串口终端软件,如minicom、picocom、putty等;
- PC上的SSH软件,如putty等。

自选扩展内容

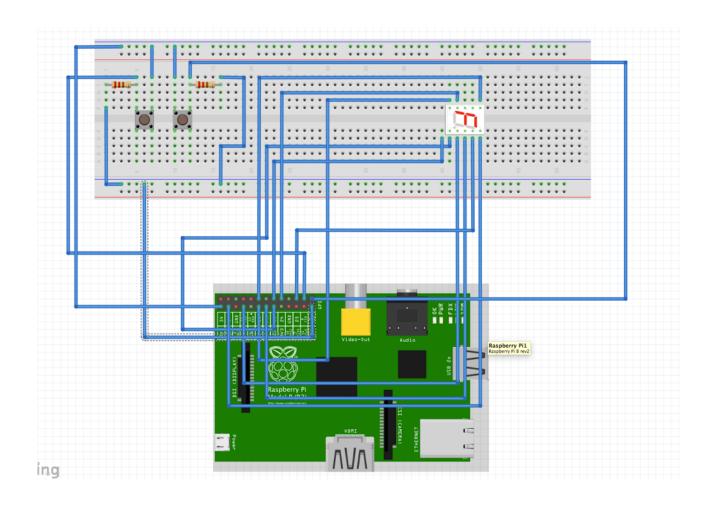
1 用不同的输出方式。

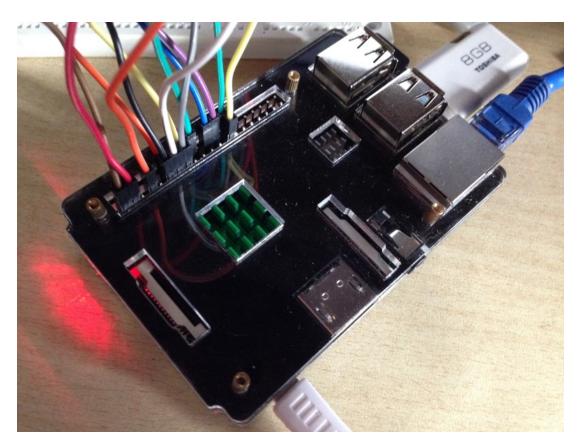
1 画出你所实际实施的连接示意图;

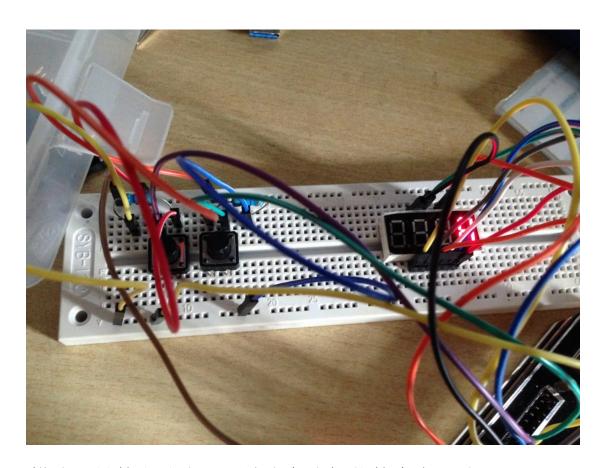


- 2 给出所用的器材的列表;
- pcDuino v2板一块;
- 5V/1A电源一个;
- microUSB线一根;
- 面包板一块;
- 两位7段数码管(共阳)一颗;
- 8段LED柱状显示器一颗;
- 360Ω 1/8W电阻8颗;
- 10k 1/8W电阻2颗;
- 按钮两个;
- 面包线若干。
- PC (Windows/Mac OS/Linux) 一台
- 以太网线一根(可能还需要路由器等);

3用Fritzing画出外部设备的连线图,附实物照片;







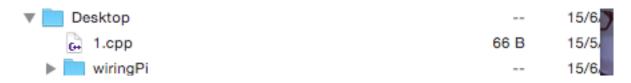
4 描述所做的实验步骤,给出各步操作的命令和结果;

1、安装wiringPi

成熟的库如wiringPi可以用来控制树莓派的GPIO接口。安装过程如下:输入命令: git clone git://git.drogon.net/wiringPi

```
PrinceMacbook:~ Prince$ git clone git://git.drogon.net/wiringPi
Cloning into 'wiringPi'...
remote: Counting objects: 742, done.
remote: Compressing objects: 100% (676/676), done.
remote: Total 742 (delta 537), reused 94 (delta 58)
Receiving objects: 100% (742/742), 262.96 KiB | 68.00 KiB/s, done.
Resolving deltas: 100% (537/537), done.
Checking connectivity... done.
```

通过sftp放到树莓派上



移动到系统临时文件夹/tmp

```
pi@raspberrypi /tmp $ mv ~/Desktop/wiringPi/ /tmp/
pi@raspberrypi /tmp $ ls
wiringPi
pi@raspberrypi /tmp $ [
```

cd wiringPi
sudo ./build

```
pieraspberrypi /tmp $ cd wiringPi/
pieraspberrypi /tmp/wiringPi $ sudo ./build
wiringPi Build script

WiringPi Library

[UnInstall]

[Compile] wiringPi.c

[Compile] piHiPri.c

[Compile] wiringSerial.c

[Compile] wiringShift.c

[Compile] wiringShift.c

[Compile] wiringPiSPI.c

[Compile] wiringPiSPI.c

[Compile] wiringPiI2C.c

[Compile] softPwm.c

[Compile] softTone.c
```

输入以下命令验证wiringPi是否安装成功:

gpio -v

```
pi@raspberrypi ~/gpiolab/lab7 $ gpio -v
gpio version: 2.26
Copyright (c) 2012-2015 Gordon Henderson
This is free software with ABSOLUTELY NO WARRANTY.
For details type: gpio -warranty

Raspberry Pi Details:
   Type: Model 2, Revision: 1.1, Memory: 1024MB, Maker: Sony
```

gpio readall

pi@raspberrypi	~/gpiolab/lab7 \$	gpio readall

				LDi	2	+				
wPi	Name			Physical				Name	wPi	ВСМ
	3.3v	 	i	1	2	i	 	5v		
8	SDA.1	OUT	1	і з і	j 4	i	i	5V	i	i
9	SCL.1	IN	1	5 j	6	İ	İ	0v	İ	İ
7	GPI0. 7	OUT	1	7	8	1	ALT0	TxD	15	14
	0 v			9	10	1	ALT0	RxD	16	15
0	GPIO. 0	OUT	0	11	12	0	OUT	GPIO. 1	1	18
2	GPIO. 2	OUT	0	13	14	l		0v		l
3	GPIO. 3	OUT	0	15	16	0	OUT	GPIO. 4	4	23
	3.3v			17	18	0	OUT	GPIO. 5	5	24
12	MOSI	IN	0	19	20	l		0v		l
13	MISO	IN	0	21	22	0	OUT	GPIO. 6	6	25
14	SCLK	IN	0	23	24	0	IN	CE0	10	8
	0 v			25	26	0	IN	CE1	11	7
30	SDA.0	IN	1	27	28	1	IN	SCL.0	31	1
21	GPI0.21	IN.	1	29	30	l		0v		l
22	GPI0.22	IN	1	31	32	0	IN	GPI0.26	26	12
23	GPI0.23	IN	0	33	34	l		0v		l
24	GPI0.24	IN	0	35	36	0	IN	GPI0.27	27	16
25		IN	0	37	38	0	IN	GPI0.28	28	20
	0v	l 		39	40	0	IN	GPI0.29	29	21
wPi			•	-		•				ВСМ
	8 9 7 0 2 3 12 13 14 30 21 22 23 24 25	3.3v 8 SDA.1 9 SCL.1 7 GPIO. 7 0v 0 GPIO. 0 2 GPIO. 2 3 GPIO. 3 3.3v 12 MOSI 13 MISO 14 SCLK 0v 30 SDA.0 21 GPIO.21 22 GPIO.22 23 GPIO.22 23 GPIO.23 24 GPIO.24 25 GPIO.25 0v	3.3v 8 SDA.1 OUT 9 SCL.1 IN 7 GPIO. 7 OUT 0v 0 GPIO. 0 OUT 2 GPIO. 2 OUT 3 GPIO. 3 OUT 3.3v 12 MOSI IN 13 MISO IN 14 SCLK IN 0v 30 SDA.0 IN 21 GPIO.21 IN 22 GPIO.22 IN 23 GPIO.23 IN 24 GPIO.24 IN 25 GPIO.25 IN 0v	3.3v	3.3v 1 3 8 SDA.1 OUT 1 3 9 SCL.1 IN 1 5 7 GPIO. 7 OUT 1 7	3.3v 1 2 8 SDA.1 OUT 1 3 4 9 SCL.1 IN 1 5 6 7 GPIO. 7 OUT 1 7 8 0v 9 10 0 GPIO. 0 OUT 0 11 12 2 GPIO. 2 OUT 0 13 14 3 GPIO. 3 OUT 0 15 16 3.3v 17 18 12 MOSI IN 0 19 20 13 MISO IN 0 21 22 14 SCLK IN 0 23 24 0v 25 26 30 SDA.0 IN 1 27 28 21 GPIO.21 IN 1 29 30 22 GPIO.22 IN 1 31 32 23 GPIO.23 IN 0 33 34 24 GPIO.24 IN 0 35 36 25 GPIO.25 IN 0 37 38 0v 39 40	3.3v 1 1 2 8 SDA.1 OUT 1 3 4 9 SCL.1 IN 1 5 6 7 GPIO. 7 OUT 1 7 8 1 0v 9 10 1 0 GPIO. 0 OUT 0 11 12 0 2 GPIO. 2 OUT 0 13 14 3 GPIO. 3 OUT 0 15 16 0 3.3v 17 18 0 12 MOSI IN 0 19 20 13 MISO IN 0 21 22 0 14 SCLK IN 0 23 24 0 0v 25 26 0 30 SDA.0 IN 1 27 28 1 21 GPIO.21 IN 1 29 30 22 GPIO.22 IN 1 31 32 0 23 GPIO.23 IN 0 33 34 24 GPIO.24 IN 0 35 36 0 25 GPIO.25 IN 0 37 38 0 0v 39 40 0 WPi Name Mode V Physical V	3.3v 1 2	3.3v	3.3v 1 1 2 5v 8 SDA.1 OUT 1 3 4 5V 9 SCL.1 IN 1 5 6 0v 7 GPIO. 7 OUT 1 7 8 1 ALT0 TxD 15

5 说明所用的GPIO库的来源; git://git.drogon.net/wiringPi wiringPi.h

wiringPi的接口映射(来自https://projects.drogon.net/raspberry-pi/wiringpi/pins/):

```
6给出代码并解释;
#include <wiringPi.h>
#include <stdio.h>
#include <stdlib.h>
#define DIGIT0 8
#define DIGIT1 9
#define BTN0 10
#define BTN1 11
char digit[10][8] = //The increasing number
  {
     \{0,0,0,0,0,0,1,1\}, //0
     \{1,0,0,1,1,1,1,1\}, //1
     \{0,0,1,0,0,1,0,1\}, //2
     \{0,0,0,0,1,1,0,1\}, //3
     {1,0,0,1,1,0,0,1},//4
     {0,1,0,0,1,0,0,1},//5
     {0,1,0,0,0,0,0,1},//6
     \{0,0,0,1,1,1,1,1,1\}, //7
     \{0,0,0,0,0,0,0,1\}, //8
     {0,0,0,0,1,0,0,1} //9
  };
char loop[10][8] = //the loop-running bar in the left windows
     \{0,1,1,1,1,1,1,1,1\},\
     \{1,1,0,1,1,1,1,1\},\
     \{1,1,1,0,1,1,1,1\},\
     \{1,1,1,1,0,1,1,1\},\
     \{1,1,1,1,1,0,1,1\},\
  };
void main()
{
  int pin;
  int m = 0, n = 0;
  int flag = 1;
//display numbers when flag is 1 and cycle light when flag is 0
```

```
int run = 0;
unsigned int time0 = 0, time1 = 0;
if (wiringPiSetup () == -1) //test the install status of wiringPi
{
  exit (1);
}
for (pin = 0; pin < 8; ++pin)
  pinMode (pin, OUTPUT) ;
 digitalWrite(pin, HIGH);
}
pinMode(DIGITO, OUTPUT); //The left number
//pinMode(DIGIT1, OUTPUT); //The right number
pinMode(BTN0, INPUT); //The start button
pinMode(BTN1, INPUT); //The stop button
while (1)
{
  time1 = millis();
  if (digitalRead(BTN0) && run == 0)
  {
    puts("Start!");
             //change the running state
    run = 1;
    m = 0;
    n = 0;
    time0 = millis();
  else if (digitalRead(BTN1) && run == 1)
  {
    puts("Stop!");
    run = 0;
  }
```

```
if (time1 - time0 >= 50 \&\& run == 1)
    {
      time0 = time1;
      printf("%d\n", n);
                                  //shell outputs
      m = ++m \% 6;
      n = ++n \% 8;
    }
    for (pin = 0; pin < 8; pin++)
      digitalWrite(pin, flag ? digit[n+1][pin] : loop[m][pin]);//write pins
    digitalWrite(DIGIT0, 1);
    //digitalWrite(DIGIT1, flag);
    delay(150);
  }
}
     将所做作品拍摄视频上传到优酷,给出优酷的视频网址;
 7
运行视频:
     审核已通过
    http://v.youku.com/v_show/id_XMTI1OTk1OTQ1Ng==.html
```

8 说明其他所做的扩展内容的情况。