

Optimization Services 2.4 User's Manual

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Abstract

This is the User's Manual for the Optimization Services (OS) project. The objective of OS is to provide a general framework consisting of a set of standards for representing optimization instances, results, solver options, and communication between clients and solvers in a distributed environment using Web Services. This COIN-OR project provides C++ and Java source code for libraries and executable programs that implement OS standards. The OS library includes a robust solver and modeling language interface (API) for linear, nonlinear and other types of optimization problems. Also included is the C++ source code for a command line executable `OSSolverService` for reading problem instances (OSiL format, nl format, MPS format) and calling a solver either locally or on a remote server. Finally, both Java source code and a Java `war` file are provided for users who wish to set up a solver service on a server running Apache Tomcat. See the Optimization Services home page <http://www.optimizationservices.org> and the COIN-OR Trac page <http://projects.coin-or.org/OS> for more information.

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1 The Optimization Services (OS) Project

The objective of Optimization Services (OS) is to provide a general framework consisting of a set of standards for representing optimization instances, results, solver options, and communication between clients and solvers in a distributed environment using Web Services. This COIN-OR project provides source code for libraries and executable programs that implement OS standards. See the COIN-OR Trac page <http://projects.coin-or.org/OS> or the Optimization Services Home Page <http://www.optimizationservices.org> for more information.

Like other COIN-OR projects, OS has a versioning system that ensures end users some degree of stability and a stable upgrade path as project development continues. The current stable version of OS is 2.4, and the current stable release is 2.4.0, based on trunk version 4340.

The OS project provides the following:

1. A set of XML based standards for representing optimization instances (OSiL), optimization results (OSrL), and optimization solver options (OSoL). There are other standards, but these are the main ones. The schemas for these standards are described in Section 6.
2. Open source libraries that support and implement many of the standards.
3. A robust solver and modeling language interface (API) for linear and nonlinear optimization problems. Corresponding to the OSiL problem instance representation there is an in-memory object, `OSInstance`, along with a collection of `get()`, `set()`, and `calculate()` methods for accessing and creating problem instances. This is a very general API for linear, integer, and nonlinear programs. Extensions for other major types of optimization problems are also in the works. Any modeling language that can produce OSiL can easily communicate with any solver that uses the `OSInstance` API. The `OSInstance` object is described in more detail in Section 7. The nonlinear part of the API is based on the COIN-OR project CppAD by Brad Bell (<http://projects.coin-or.org/CppAD>) but is written in a very general manner and could be used with other algorithmic differentiation packages. More detail on algorithmic differentiation is provided in Section ??.
4. A command line executable `OSSolverService` for reading problem instances (OSiL format, AMPL nl format, MPS format) and calling a solver either locally or on a remote server. This is described in Section 4.
5. Utilities that convert AMPL nl files and MPS files into the OSiL XML format. This is described in Section ??.
6. Standards that facilitate the communication between clients and optimization solvers using Web Services. In Section ?? we describe the `OSAgent` part of the OS library that is used to create Web Services SOAP packages with OSiL instances and contact a server for solution.
7. An executable program `OSAmplClient` that is designed to work with the AMPL modeling language. The `OSAmplClient` appears as a “solver” to AMPL and, based on options given in AMPL, contacts solvers either remotely or locally to solve instances created in AMPL. This is described in Section 5.1.
8. Server software that works with Apache Tomcat and Apache Axis. This software uses Web Services technology and acts as middleware between the client that creates the instance and the solver on the server that optimizes the instance and returns the result. This is illustrated in Section ??.

9. A lightweight version of the project, **OSCommon**, for modeling language and solver developers who want to use OS API, readers and writers, without the overhead of other COIN-OR projects or any third-party software. For information on how to download **OSCommon** see Section ??.

2 Quick Roadmap

If you want to:

- Download the OS source code or binaries – see Section ??.
- Download just the OS API, readers and writers – see Section ??.
- Build the OS project from the source code – see Section ??.
- Use the OS library to build model instances or use solver APIs – see Sections ??, ?? and 7.
- Use the `OSSolverService` to read files in nl, OSiL, or MPS format and call a solver locally or remotely – see Section 4.
- Use AMPL to solve problems either locally or remotely with a COIN-OR solver, Cplex, GLPK, or LINDO – see Section 5.1.
- Use GAMS to solve problems either locally or remotely – see Section 5.2.
- Build a remote solver service using Apache Tomcat – see Section ??.
- Use MATLAB to generate problem instances in OSiL format and call a solver either remotely or locally – see Section 5.3.
- Use the OS library for algorithmic differentiation (in conjunction with COIN-OR CppAD) – see Section ??.
- Use modeling languages to generate model instances in OSiL format – see Section 5.

3 Downloading the OS Binaries

The OS project is an open-source project with source code under the Common Public License (CPL). See <http://www.ibm.com/developerworks/library/os-cpl.html>. This project was initially created by Robert Fourer, Jun Ma, and Kipp Martin. The code has been written primarily by Horand Gassmann, Jun Ma, and Kipp Martin. Horand Gassmann, Jun Ma, and Kipp Martin are the COIN-OR project leaders and active developers for the OS project. Most users will only be interested in obtaining the binaries, which we describe next. It is also possible to obtain the source code for the project, which will be of interest mostly to developers. If binaries are not provided for a particular operating system, it may be possible to build them from the source. For details it is best to start reading the OS web page at <http://projects.coin-or.org/OS/>.

3.1 Obtaining the Binaries

If the user does not wish to compile source code, the OS library, OSSolverService executable and Tomcat server software configuration are available in binary format for some operating systems. The repository is at <http://www.coin-or.org/download/binary/OS/>. Unlike the source code described in Section ??, the binary files are not subject to version control and can be downloaded using an ordinary browser. If binaries are not provided for a particular operating system, it may be possible to build them from the source code. Since the source is under version control, this requires svn. (See Sections ??, ?? and ??).

The binary distribution for the OS library and executables follows the following naming convention:

`OS-version_number-platform-compiler-build_options.tgz (zip)`

For example, OS Release 2.1.0 compiled with the Intel 9.1 compiler on an Intel 32-bit Linux system is:

`OS-2.1.0-linux-x86-icc9.1.tgz`

For more detail on the naming convention and examples see:

<https://projects.coin-or.org/CoinBinary/wiki/ArchiveNamingConventions>

After unpacking the `tgz` or `zip` archives, the following folders are available.

bin – this directory has the executables `OSSolverService` and `OSAmplClient`.

include – the header files that are necessary in order to link against the OS library.

lib – the libraries that are necessary for creating applications that use the OS library.

share – license and author information for all the projects used by the OS project.

Files are also provided for an Apache Tomcat Web server along with the associated Web service that can read SOAP envelopes with model instances in OSiL format and/or options in OSoL format, call the `OSSolverService`, and return the optimization result in OSrL format. The naming convention for the server binary is

`OS-server-version_number.tgz (.zip)`

For example, the files associated with OS server release 2.0.0 are in the binary distribution

`OS-server-2.0.0.tgz`

There is no platform information given since the server and related binaries were written in Java. The details and use of this distribution are described in Section ??.

Finally for Windows users we provide Visual Studio project files (and supporting libraries and header files) for building projects based on the OS library and libraries used by the OS project. The binary for this is named

`OS-version_number-VisualStudio.zip`

For example, the necessary files associated with OS stable 2.4 are in the binary distribution

`OS-2.1-VisualStudio.zip`

The binaries provided are based on Visual Studio Express 2008. See Section ?? for more detail.

4 The OSSolverService

The `OSSolverService` is a command line executable designed to pass problem instances in either OSiL, AMPL nl, or MPS format to solvers and get the optimization result back to be displayed either to standard output or a specified browser. The `OSSolverService` can be used to invoke a solver locally or on a remote server. It can communicate with a remote solver both synchronously and asynchronously. At present six service methods are implemented, `solve`, `send`, `retrieve`, `getJobID`, `knock` and `kill`. These methods are explained in more detail in Section 4.4. Only the `solve` method is available locally.

There are two ways to use the `OSSolverService` executable. The first way is to use the interactive shell. The interactive shell is invoked by either double clicking on the icon for the `OSSolverService` executable, or by opening a command window, connecting to the directory holding the executable, and then typing in `OSSolverService` with no arguments. Using the interactive shell is fairly intuitive and we do not discuss in detail. The second way to use the `OSSolverService` executable is to provide arguments at the command line. This is discussed next. The command line arguments are also valid for the interactive shell.

4.1 OSSolverService Input Parameters

At present, the `OSSolverService` takes the following parameters. The order of the parameters is irrelevant. Not all the parameters are required.

osil xxx.osil This is the path information and name of the file that contains the optimization instance in OSiL format. It is assumed that this file is available on the machine that is running `OSSolverService`. This option can be omitted, as there are other ways to specify an optimization instance.

osol xxx.osol This is the path information and name of the file that contains the solver options. It is assumed that this file is available on the machine that is running `OSSolverService`. It is not necessary to specify this option.

osrl xxx.osrl This is the path information and name of the file that contains the solver solution. A valid file path must be given on the machine that is running `OSSolverService`. It is not necessary to specify this option. If this option is not specified then the solver solution is displayed to the screen.

osplInput xxx.ospl The name of an input file in the OS Process Language (OSpL); this is used as input to the `knock` method.

osplOutput xxx.ospl The name of an output file in the OS Process Language (OSpL); this is the output string from the `knock` and `kill` method.

serviceLocation url This is the URL of the solver service. It is not required, and if not specified it is assumed that the problem is solved locally.

serviceMethod methodName This is the method on the solver service to be invoked. The options are `solve`, `send`, `kill`, `knock`, `getJobID`, and `retrieve`. The use of these options is illustrated in the examples below. This option is not required, and the default value is `solve`.

mps xxx.mps This is the path information and name of the MPS file if the problem instance is in MPS format. It is assumed that this file is available on the machine that is running `OSSolverService`. The default file format is OSiL so this option is not required.

Table 1: Solver configurations

	binaries (Section 3.1)	UNIX build (Section ??)	MSVS build (Section ??)
Bonmin	x	x ¹	x ^{1,2}
Cbc	x	x	x
Clp	x	x	x
Couenne	x	x ¹	—
DyLP	x	x	—
Ilopt	x	x ¹	x ^{1,2}
SYMPHONY	x	x	x
Vol	x	x	x

Explanations:

¹Requires third-party software to be downloaded

²Requires Fortran compiler (see Section ??)

Table 2: Default solvers

Problem type	Default solver
Linear, continuous	Clp
Linear, integer	Cbc
Nonlinear, continuous	Ilopt
Nonlinear, integer	Bonmin

nl xxx.nl This is the path information and name of the AMPL nl file if the problem instance is in AMPL nl format. It is assumed that this file is available on the machine that is running `OSSolverService`. The default file format is OSiL so this option is not required.

solver solverName Possible values of this parameter depend on the installation. The default configurations can be read off from Table 1. Other solvers supported (if the necessary libraries are present) are `cplex` (Cplex through COIN-OR Osi), `glpk` (GLPK through COIN-OR Osi) and `lindo` (LINDO). If no value is specified for this parameter, then a default value is used for the `solve` or `send` service method. The default solver depends on the problem type and can be read off from table 2.

browser browserName This parameter is a path to the browser on the local machine. If this optional parameter is specified then the solver result in OSrL format is transformed using XSLT into HTML and displayed in the browser.

config pathToConfigureFile This optional parameter specifies a path on the local machine to a text file containing values for the input parameters. This is convenient for the user not wishing to constantly retype parameter values.

-help This parameter prints out the list of available options (in essence, this list). Synonyms for **-help** are **-h** and **-?**.

-version This parameter prints version and licence information. **-v** is an acceptable synonym.

The input parameters to the `OSSolverService` may be given entirely in the command line or in a configuration file. We first illustrate giving all the parameters in the command line. The following command will invoke the `Clp` solver on the local machine to solve the problem instance `parincLinear.osil`. When invoking the commands below involving `OSSolverService` we assume that 1) the user is connected to the directory where the `OSSolverService` executable is located, and 2) that `../data/osilFiles` is a valid path to `COIN-OS/data/osilFiles`. If the OS project was built successfully, then there is a copy of `OSSolverService` in `COIN-OS/OS/src`. The user may wish to execute `OSSolverService` from this `src` directory so that all that follows is correct in terms of path definitions.

```
./OSSolverService solver clp osil ../data/osilFiles/parincLinear.osil
```

Alternatively, these parameters can be put into a configuration file. Assume that the configuration file of interest is `testlocalclp.config`. It would contain the two lines of information

```
osil ../data/osilFiles/parincLinear.osil
solver clp
```

Then the command line is

```
./OSSolverService config ../data/configFiles/testlocalclp.config
```

Windows users should **note** that the folder separator is always the forward slash (`/`) instead of the customary backslash (`\`).

Parameters specified in the configure file are overridden by parameters specified at the command line. This is convenient if a user has a base configure file and wishes to override only a few options. For example,

```
./OSSolverService config ../data/configFiles/testlocalclp.config solver lindo
```

or

```
./OSSolverService solver lindo config ../data/configFiles/testlocalclp.config
```

will result in the LINDO solver being used even though `Clp` is specified in the `testlocalclp` configure file.

Some things to note:

1. The default `serviceMethod` is `solve` if another service method is not specified. The service method cannot be specified in the OSoL options file.
2. The command line parameters are intended to only influence the behavior of the local `OSSolverService`. In particular, only the service method is transmitted to a remote location. Any communication with a remote solver other than setting the service method **must** take place through an OSoL options file.
3. Only the `solve()` method is available for local calls to `OSSolverService`.
4. If the options `send`, `kill`, `knock`, `getJobID`, or `retrieve` are specified, a `serviceLocation` must be specified.
5. When using the `send()` or `solve()` methods a problem instance must be specified.

4.2 The Command Line Parser

The top layer of the local `OSSolverService` is a command line parser that parses the command line and the config file (if one is specified) and passes the information on to a local solver or a remote solver service, depending on whether a `serviceLocation` was specified. If a `serviceLocation` is specified a call is made to a remote solver service, otherwise a local solver is called.

If a local solve is indicated, we pass to a solver in the `OSLibrary` two things: an `OSoL` file if one has been specified and a problem instance. The problem instance is the instance in the `OSiL` file specified by the `osil` option. If there is no `OSiL` file, then it is the instance specified in the `nl` file. If there is no `nl` file, it is the instance in the `mps` file. If no `OSiL`, `nl` or `mps` file is specified, an error is thrown.

The `OSoL` file is simply passed on to the `OSLibrary`; it is not parsed at this point. The `OSoL` file elements `<solverToInvoke>` and `instanceLocation` cannot be used for local calls. One can specify which solver to use in the `OSLibrary` through the `solver` option. If this option is empty, a default solver is selected (see Table 2).

If the `serviceLocation` parameter is used, a call is placed to the remote solver service specified in the `serviceLocation` parameter. Two strings are passed to the remote solver service: a string which is the `OSoL` file if one has been specified, or the empty string otherwise, and a string containing an instance if one has been specified. The instance can be specified using the `osil`, `-nl`, or `-mps` option. If an `OSiL` file is specified in the `osil` option, it is used. If there is no `OSiL` file, then the instance specified in the `nl` file is used. If there is no `nl` file, the `mps` file is used. If no file is given, an empty string is sent.

For remote calls, the solver can only be set in the `osol` file, using the element `<solverToInvoke>`; the `solver` option has no effect.

4.3 Solving Problems Locally

Generally, when solving a problem locally the user will use the `solve` service method. The `solve` method is invoked synchronously and waits for the solver to return the result. This is illustrated in Figure 1. As illustrated, the `OSSolverService` reads a file on the hard drive with the optimization instance, usually in `OSiL` format. The optimization instance is parsed into a string which is passed to the `OSLibrary` (see ??), which is linked with various solvers. Similarly an option file in `OSoL` format is parsed into a string and passed to the `OSLibrary`. *No interpretation of the options is done at this stage*, so that any `<solverToInvoke>` or `<instanceLocation>` directives in the `OSoL` file will be ignored for local solves. The result of the optimization is passed back to the `OSSolverService` as a string in `OSrL` format.

Here is an example of using a configure file, `testlocal.config`, to invoke `Ipopt` locally using the `solve` command.

```
osil ../data/osilFiles/parincQuadratic.osil
solver ipopt
serviceMethod solve
browser /Applications/Firefox.app/Contents/MacOS/firefox
osrl /Users/kmartin/temp/test.osrl
```

The first line of `testlocal.config` gives the local location of the `OSiL` file, `parincQuadratic.osil`, that contains the problem instance. The second parameter, `solver ipopt`, is the solver to be invoked, in this case COIN-OR `Ipopt`. The third parameter `serviceMethod solve` is not really

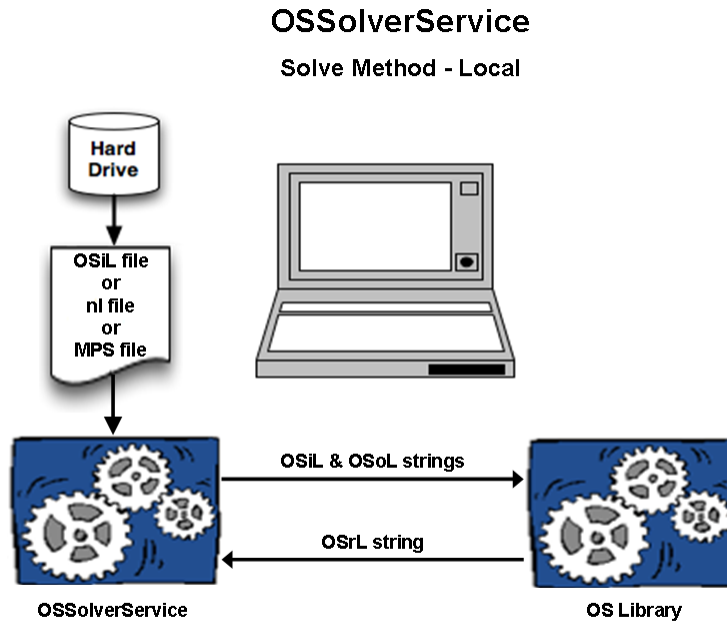


Figure 1: A local call to solve.

needed, since the default solver service is `solve`. It is included only for illustration. The fourth parameter is the location of the browser on the local machine. The fifth parameter is `osr1`. The value of this parameter, `/Users/kmartin/temp/test.osr1`, specifies the location on the local machine where the OSrL result file will get written.

Parameters may also be contained in an XML-file in OSoL format. In the configuration file `testlocalosol.config` we illustrate specifying the instance location in an OSoL file.

```
osol ../data/osolFiles/demo.osol
solver clp
```

The file `demo.osol` is

```
<?xml version="1.0" encoding="UTF-8"?>
<osol xmlns="os.optimizationservices.org"
      xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:schemaLocation="os.optimizationservices.org
      http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
    <instanceLocation locationType="local">
      ../data/osilFiles/parincLinear.osil
    </instanceLocation>
  </general>
</osol>
```

4.4 Solving Problems Remotely with Web Services

In many cases the client machine may be a “weak client” and using a more powerful machine to solve a hard optimization instance is required. Indeed, one of the major purposes of Optimization Services is to facilitate optimization in a distributed environment. We now provide examples that illustrate using the `OSSolverService` executable to call a remote solver service. By remote solver service we mean a solver service that is called using Web Services. The OS implementation of the solver service uses Apache Tomcat. See tomcat.apache.org. The Web Service running on the server is a Java program based on Apache Axis. See ws.apache.org/axis. This is described in greater detail in Section ???. This Web Service is called `OSSolverService.jws`. It is not necessary to use the Tomcat/Axis combination.

See Figure 2 for an illustration of this process. The client machine uses `OSSolverService` executable to call one of the six service methods, e.g., `solve`. The information such as the problem instance in OSiL format and solver options in OSoL format are packaged into a SOAP envelope and sent to the server. The server is running the Java Web Service `OSSolverService.jws`. This Java program running in the Tomcat Java Servlet container implements the six service methods. If a `solve` or `send` request is sent to the server from the client, an optimization problem must be solved. The Java solver service solves the optimization instance by calling the `OSSolverService` on the server. So there is an `OSSolverService` on the client that calls the Web Service `OSSolverService.jws` that in turn calls the executable `OSSolverService` on the server. The Java solver service passes options to the local `OSSolverService` in form of two strings, an osil string representing the instance and an osol string representing the options (if any).

For remote calls the instance location can be specified either as a command parameter (on the command line or in a config file) or through the `<instanceLocation>` element in the OSoL options file. OSiL files specified in the `<instanceLocation>` element must be converted to an osil string by the solver service. If two instance files are specified in this way — one through the local command interface, the other in an options file — the solver service is free to pick which one to choose.

In the following sections we illustrate each of the six service methods.

4.4.1 The solve Service Method

First we illustrate a simple call to `OSSolverService.jws`. The call on the client machine is

```
./OSSolverService config ../data/configFiles/testremote.config
```

where the `testremote.config` file is

```
osil ../data/osilFiles/parincLinear.osil
serviceLocation http://kipp.chicagobooth.edu/os/OSSolverService.jws
```

No solver is specified and by default the Clp solver is used by the `OSSolverService`, since the problem is a continuous linear program. If, for example, the user wished to solve the problem with the SYMPHONY solver then this is accomplished either by using the `solver` option on the command line

```
./OSSolverService config ../data/configFiles/testremote.config solver symphony
```

or by adding the line

```
solver symphony
```

OSSolverService

Solve Method

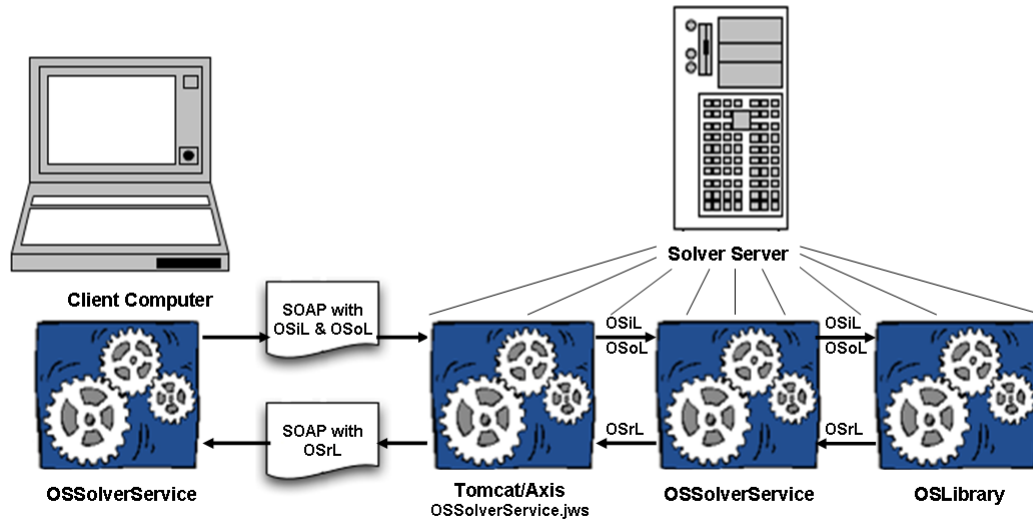


Figure 2: A remote call to solve.

to the `testremote.config` file.

Next we illustrate a call to the remote SolverService and specify an OSiL instance that is actually residing on the remote machine that is hosting the OSSolverService and not on the client machine.

```
./OSSolverService osol ../data/osolFiles/remoteSolve1.osol
serviceLocation http://kipp.chicagobooth.edu/os/OSSolverService.jws
```

where the `remoteSolve1.osol` file is

```
<?xml version="1.0" encoding="UTF-8"?>
<osol xmlns="os.optimizationservices.org"
      xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:schemaLocation="os.optimizationservices.org
      http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
    <instanceLocation locationType="local">c:\parincLinear.osil</instanceLocation>
    <contact transportType="smtp">kipp.martin@chicagogsb.edu</contact>
    <solverToInvoke>ipopt</solverToInvoke>
  </general>
</osol>
```

If we were to change the `locationType` attribute in the `<instanceLocation>` element to `http` then we could specify the instance location on yet another machine. This is illustrated below for `remoteSolve2.osol`. The scenario is depicted in Figure 3. The OSiL string passed from the client to the solver service is empty. However, the OSoL element `<instanceLocation>` has an attribute

OSSolverService

Solve Method

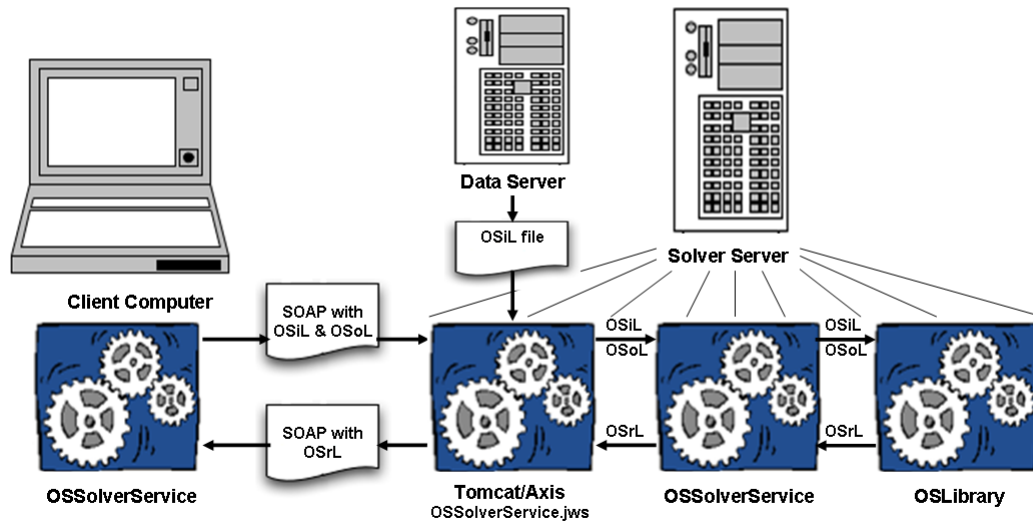


Figure 3: Downloading the instance from a remote source.

locationType equal to http. In this case, the text of the `<instanceLocation>` element contains the URL of a third machine which has the problem instance `parincLinear.osil`. The solver service will contact the machine with URL `http://www.coin-or.org/OS/parincLinear.osil` and download this test problem. So the OSSolverService is running on the server `kipp.chicagobooth.edu` which contacts the server `www.coin-or.org` for the model instance.

```
<?xml version="1.0" encoding="UTF-8"?>
<osol xmlns="os.optimizationservices.org"
      xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:schemaLocation="os.optimizationservices.org
      http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
    <instanceLocation locationType="http">
      http://www.coin-or.org/OS/parincLinear.osil
    </instanceLocation>
    <solverToInvoke>ipopt</solverToInvoke>
  </general>
</osol>
```

Note: The `solve` method communicates synchronously with the remote solver service and once started, these jobs cannot be killed. This may not be desirable for large problems when the user does not want to wait for a response or when there is a possibility for the solver to enter an infinite loop. The `send` service method should be used when asynchronous communication is desired.

4.4.2 The send Service Method

When the `solve` service method is used, then the `OSSolverService` does not finish execution until the solution is returned from the remote solver service. When the `send` method is used, the instance is communicated to the remote service and the `OSSolverService` terminates after submission. An example of this is

```
./OSSolverService config ../data/configFiles/testremoteSend.config
```

where the `testremoteSend.config` file is

```
-nl ../data/amplFiles/hs71.nl
serviceLocation http://kipp.chicagobooth.edu/os/OSSolverService.jws
serviceMethod send
```

In this example the COIN-OR Ipopt solver is specified. The input file `hs71.nl` is in AMPL nl format. Before sending this to the remote solver service the `OSSolverService` executable converts the nl format into the OSiL XML format and packages this into the SOAP envelope used by Web Services.

Since the `send` method involves asynchronous communication the remote solver service must keep track of jobs. The `send` method requires a `JobID`. In the above example no `JobID` was specified. When no `JobID` is specified the `OSSolverService` method first invokes the `getJobID` service method to get a `JobID`, puts this information into an OSoL file it creates, and sends the information to the server. More information on the `getJobID` service method is provided in Section 4.4.4. The `OSSolverService` prints the OSoL file to standard output before termination. This is illustrated below,

```
<?xml version="1.0" encoding="UTF-8"?>
<osol xmlns="os.optimizationservices.org"
      xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:schemaLocation="os.optimizationservices.org
      http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
    <jobID>
      gsbrkm4__127.0.0.1__2007-06-16T15.46.46.075-05.00149771253
    </jobID>
    <solverToInvoke>ipopt</solverToInvoke>
  </general>
</osol>
```

The `JobID` is one that is randomly generated by the server and passed back to the `OSSolverService`. The user can also provide a `JobID` in their OSoL file. For example, below is a user-provided OSoL file that could be specified in a configuration file or on the command line.

```
<?xml version="1.0" encoding="UTF-8"?>
<osol xmlns="os.optimizationservices.org"
      xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:schemaLocation="os.optimizationservices.org
      http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
```

```

    <jobID>123456abcd</jobID>
    <solverToInvoke>ipopt</solverToInvoke>
  </general>
</osol>

```

The same JobID cannot be used twice, so if 123456abcd was used earlier, the result of `send` will be `false`.

In order to be of any use, it is necessary to get the result of the optimization. This is described in Section 4.4.3. Before proceeding to this section, we describe two ways for knowing when the optimization is complete. One feature of the standard OS remote SolverService is the ability to send an email when the job is complete. Below is an example of the OSoL that uses the email feature.

```

<?xml version="1.0" encoding="UTF-8"?>
<osol xmlns="os.optimizationservices.org"
      xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:schemaLocation="os.optimizationservices.org
      http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
    <jobID>123456abcd</jobID>
    <contact transportType="smtp">
      kipp.martin@chicagogsb.edu
    </contact>
    <solverToInvoke>ipopt</solverToInvoke>
  </general>
</osol>

```

The remote Solver Service will send an email to the above address when the job is complete. A second option for knowing when a job is complete is to use the `knock` method. (See Section 4.4.5.)

Note that in all of these examples we provided a value for the `<solverToInvoke>` element. A default solver is used (see Table 2 if another solver is not specified).

4.4.3 The retrieve Service Method

The `retrieve` method is used to get information about the instance solution. This method has a single string argument which is an OSoL instance. Here is an example of using the `retrieve` method with `OSSolverService`.

```
./OSSolverService config ../data/configFiles/testremoteRetrieve.config
```

The `testremoteRetrieve.config` file is

```

serviceLocation http://kipp.chicagobooth.edu/os/OSSolverService.jws
osol ../data/osolFiles/retrieve.osol
serviceMethod retrieve
osrl /home/kmartin/temp/test.osrl

```

and the `retrieve.osol` file is


```
<?xml version="1.0" encoding="UTF-8"?>
<osol xmlns="os.optimizationservices.org"
      xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:schemaLocation="os.optimizationservices.org
      http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
    <jobID>123456abcd</jobID>
  </general>
</osol>
```

The OSoL file `retrieve.osol` contains a tag `<jobID>` that is communicated to the remote service. The remote service locates the result and returns it as a string. The `<jobID>` should reflect a `<jobID>` that was previously submitted using a `send()` command. The result is returned as a string in OSrL format. The user must modify the line

```
osrl /home/kmartin/temp/test.osrl
```

to reflect a valid path for their own machine. (It is also possible to delete the line in which case the result will be displayed on the screen instead of being saved to the file indicated in the `osrl` option.)

4.4.4 The getJobID Service Method

Before submitting a job with the `send` method a JobID is required. The `OSSolverService` can get a JobID with the following options.

```
serviceLocation http://kipp.chicagobooth.edu/os/OSSolverService.jws
serviceMethod getJobID
```

Note that no OSoL input file is specified. In this case, the `OSSolverService` sends an empty string. A string is returned with the JobID. This JobID is then put into a `<jobID>` element in an OSoL string that would be used by the `send` method.

4.4.5 The knock Service Method

The `OSSolverService` terminates after executing the `send` method. Therefore, it is necessary to know when the job is completed on the remote server. One way is to include an email address in the `<contact>` element with the attribute `transportType` set to `smtp`. This was illustrated in Section 4.4.1. A second way to check on the status of a job is to use the `knock` service method. For example, assume a user wants to know if the job with JobID 123456abcd is complete. A user would make the request

```
./OSSolverService config ../data/configFiles/testRemoteKnock.config
```

where the `testRemoteKnock.config` file is

```
serviceLocation http://kipp.chicagobooth.edu/os/OSSolverService.jws
osplInput ../data/osolFiles/demo.ospl
osol ../data/osolFiles/retrieve.osol
serviceMethod knock
```

the `demo.ospl` file is

```
<?xml version="1.0" encoding="UTF-8"?>
<ospl xmlns="os.optimizationservices.org">
  <processHeader>
    <request action="getAll"/>
  </processHeader>
  <processData/>
</ospl>
```

and the retrieve.osol file is

```
<?xml version="1.0" encoding="UTF-8"?>
<osol xmlns="os.optimizationservices.org"
      xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:schemaLocation="os.optimizationservices.org
      http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
    <jobID>123456abcd</jobID>
  </general>
</osol>
```

The result of this request is a string in OSPL format, with the data contained in its `processData` section. The result is displayed on the screen; if the user desires it to be redirected to a file, a command should be added to the `testRemoteKnock.config` file with a valid path name on the local system, e.g.,

```
osplOutput ./result.ospl
```

Part of the return format is illustrated below.

```
<?xml version="1.0" encoding="UTF-8"?>
<ospl xmlns="os.optimizationservices.org">
  <processHeader>
    <serviceURI>http://localhost:8080/os/ossolver/CGSolverService.jws</serviceURI>
    <serviceName>CGSolverService</serviceName>
    <time>2006-05-10T15:49:26.7509413-05:00</time>
  </processHeader>
  <processData>
    <statistics>
      <currentState>idle</currentState>
      <availableDiskSpace>23440343040</availableDiskSpace>
      <availableMemory>70128</availableMemory>
      <currentJobCount>0</currentJobCount>
      <totalJobsSoFar>1</totalJobsSoFar>
      <timeServiceStarted>2006-05-10T10:49:24.9700000-05:00</timeServiceStarted>
      <serviceUtilization>0.1</serviceUtilization>
    </statistics>
    <jobs>
      <job jobID="123456abcd">
        <state>finished</state>
        <serviceURI>http://kipp.chicagobooth.edu/ipopt/IPOPTSolverService.jws</serviceURI>
        <submitTime>2007-06-16T14:57:36.678-05:00</submitTime>
```

```

        <startTime>2007-06-16T14:57:36.678-05:00</startTime>
        <endTime>2007-06-16T14:57:39.404-05:00</endTime>
        <duration>2.726</duration>
    </job>
</jobs>
</statistics>
</processData>
</ospl>

```

Notice that the `<state>` element in `<job jobID="123456abcd">` indicates that the job is finished.

When making a `knock` request, the OSoL string can be empty. In this example, if the OSoL string had been empty the status of all jobs kept in the file `ospl.xml` is reported. In our default solver service implementation, there is a configuration file `OSParameter` that has a parameter `MAX_JOBIDS_TO_KEEP`. The current default setting is 100. In a large-scale or commercial implementation it might be wise to keep problem results and statistics in a database. Also, there are values other than `getAll` (i.e., get all process information related to the jobs) for the OSpL `action` attribute in the `<request>` tag. For example, the `action` can be set to a value of `ping` if the user just wants to check if the remote solver service is up and running. For details, check the OSpL schema.

4.4.6 The kill Service Method

If the user submits a job that is taking too long or is a mistake, it is possible to kill the job on the remote server using the `kill` service method. For example, to kill job 123456abcd, at the command line type

```
./OSSolverService config ../data/configFiles/kill.config
```

where the configure file `kill.config` is

```
osol ../data/osolFiles/kill.osol
serviceLocation http://kipp.chicagobooth.edu/os/OSSolverService.jws
serviceMethod kill
```

and the `kill.osol` file is

```

<?xml version="1.0" encoding="UTF-8"?>
<osol xmlns="os.optimizationservices.org"
      xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
      xsi:schemaLocation="os.optimizationservices.org
      http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
    <jobID>123456abcd</jobID>
  </general>
</osol>

```

The result is returned in OSpL format.

4.4.7 Summary and description of the API

The six service methods just described are also available as callable routines. Below is a summary of the inputs and outputs of the six methods. See also Figure 4. A test program illustrating the use of the methods is described in Section ??.

- `solve(osil, osol)`:
 - Inputs: a string with the instance in OSiL format and an optional string with the solver options in OSoL format
 - Returns: a string with the solver solution in OSrL format
 - Synchronous call, blocking request/response
- `send(osil, osol)`:
 - Inputs: a string with the instance in OSiL format and a string with the solver options in OSoL format (same as in `solve`)
 - Returns: a boolean, true if the problem was successfully submitted, false otherwise
 - Has the same signature as `solve`
 - Asynchronous (server side), non-blocking call
 - The `osol` string should have a `JobID` in the `<jobID>` element
- `getJobID(osol)`:
 - Inputs: a string with the solver options in OSoL format (in this case, the string may be empty because no options are required to get the `JobID`)
 - Returns: a string which is the unique job id generated by the solver service
 - Used to maintain session and state on a distributed system
- `knock(osp1, osol)`:
 - Inputs: a string in OSpL format and an optional string with the solver options in OSoL format
 - Returns: process and job status information from the remote server in OSpL format
- `retrieve(osol)`:
 - Inputs: a string with the solver options in OSoL format
 - Returns: a string with the solver solution in OSrL format
 - The `osol` string should have a `JobID` in the `<jobID>` element
- `kill(osol)`:
 - Inputs: a string with the solver options in OSoL format
 - Returns: process and job status information from the remote server in OSpL format
 - Critical in long running optimization jobs

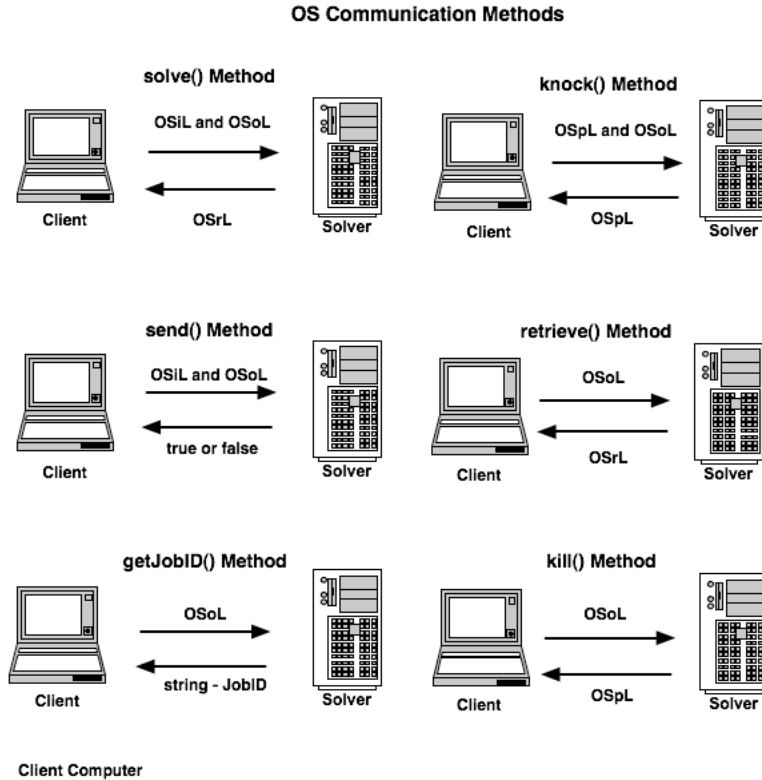


Figure 4: The OS Communication Methods

4.5 Passing Options to Solvers

The OSoL (Optimization Services option Language) protocol is used to pass options to solvers. When using the `OSSolverService` executable this will typically be done through an OSoL XML file by specifying the `osol` option followed by the location of the file. However, it is also possible to write a custom application that links to the OS library and to build an `OSOption` object in memory and then pass this to a solver. We next describe the feature of the OSoL protocol that will be the most useful to the typical user.

In the OSoL protocol there is an element `<solverOptions>` that can have any number of `<solverOption>` children. (See the file `parsertest.osol` in `OS/data/osolFiles`.) Each `<solverOption>` child can have six attributes, all of which except one are optional. These attributes are:

- **name:** this is the only required attribute and is the option name. It should be unique.
- **value:** the value of the option.
- **solver:** the name of the solver associated with the option. At present the values recognized by this attribute are "ipopt", "bonmin", "couenne", "cbc", and "osi". The last option is used for all solvers that are accessed through the Osi interface, which are `clp`, `DyLP`, `SYMPHONY` and `Vol`, in addition to `Glpk` and `Cplex`, if the latter are included in the particular build of `OSSolverService`.
- **type:** this will usually be a data type (such as integer, string, double, etc.) but this is not necessary.

- **category:** the same solver option may apply in more than one context (and with different meaning) so it may be necessary to specify a category to remove ambiguities. For example, in LINDO an option can apply to a specific model or to every model in an environment. Hence we might have

```
<solverOption name="LS_IPARAM_LP_PRINTLEVEL"
  solver="lindo" category="model" type="integer" value="0"/>
<solverOption name="LS_IPARAM_LP_PRINTLEVEL"
  solver="lindo" category="environment" type="integer" value="1"/>
```

where we specify the print level for a specific model or the entire environment. The category attribute should be separated by a colon (':') if there is more than one category or additional subcategories, as in the following hypothetical example.

```
<solverOption name="hypothetical"
  solver="SOLVER" category="cat1:subcat2:subsubcat3"
  type="string" value="illustration"/>
```

- **description:** a description of the option; typically this would not get passed to the solver.

As of trunk version 2164 the reading of an OSoL file is implemented in the `OSCoinSolver`, `OSBonmin` and `OSIpopt` solver interfaces. The `OSBonmin`, and `OSIpopt` solvers have particularly easy interfaces. They have methods for integer, string, and numeric data types and then take options in form of (name, value) pairs. Below is an example of options for `Ipopt`.

```
<solverOption name="mu_strategy" solver="ipopt"
  type="string" value="adaptive"/>
<solverOption name="tol" solver="ipopt"
  type="numeric" value="1.e-9"/>
<solverOption name="print_level" solver="ipopt"
  type="integer" value="5"/>
<solverOption name="max_iter" solver="ipopt"
  type="integer" value="2000"/>
```

We have also implemented the `OSOption` class for the `OSCoinSolver` interface. This can be done in two ways. First, options can be set through the Osi Solver interface (the `OSCoinSolver` interface wraps around the Osi Solver interface). We have implemented all of the options listed in `OsiSolverParameters.hpp` in Osi trunk version 1316. In the Osi solver interface, in addition to string, double, and integer types there is a type called `HintParam` and a type called `OsiHintParam`. The value of the `OsiHintParam` is an `OsiHintStrength` type, which may be confusing. For example, to have the following Osi method called

```
setHintParam(OsiDoReducePrint, true, hintStrength);
```

the user should set the following `<solverOption>` tags:

```
<solverOption name="OsiDoReducePrint" solver="osi"
  type="OsiHintParam" value="true" />
<solverOption name="OsiHintIgnore" solver="osi"
  type="OsiHintStrength" />
```

There should be only one `<solverOption>` with type `OsiHintStrength` and if there are more than one in the OSOL file (string) the last one is the one implemented.

In addition to setting options using the Osi Solver interface, it is possible to pass options directly to the Cbc solver. By default the following options are sent to the Cbc solver,

```
-log=0 -solve
```

The option `-log=0` will keep the branch-and-bound output to a minimum. Default options are overridden by putting into the OSOL file at least one `<solverOption>` tag with the `solver` attribute set to `cbc`. For example, the following sequence of options will limit the search to 100 nodes, cut generation turned off.

```
<solverOption name="maxN" solver="cbc" value="100" />
<solverOption name="cuts" solver="cbc" value="off" />
<solverOption name="solve" solver="cbc" />
```

Any option that Cbc accepts at the command line can be put into a `<solverOption>` tag. We list those below.

Double parameters:

```
dualB(ound) dualT(olerance) primalT(olerance) primalW(eight)
```

Branch and Cut double parameters:

```
allow(ableGap) cuto(ff) inc(rement) inf(easibilityWeight) integerT(olerance)
preT(olerance) ratio(Gap) sec(onds)
```

Integer parameters:

```
cpp(Generate) force(Solution) idiot(Crash) maxF(actor) maxIt(erations)
output(Format) slog(Level) sprint(Crash)
```

Branch and Cut integer parameters:

```
cutD(epth) log(Level) maxN(odes) maxS(olutions) passC(uts)
passF(easibilityPump) passT(reeCuts) pumpT(une) strat(egy) strong(Branching)
trust(PseudoCosts)
```

Keyword parameters:

```
chol(esky) crash cross(over) direction dualP(ivot)
error(sAllowed) keepN(ames) mess(ages) perturb(ation) presolve
primalP(ivot) printi(ngOptions) scal(ing)
```

Branch and Cut keyword parameters:

```
clique(Cuts) combine(Solutions) cost(Strategy) cuts(OnOff) Dins
DivingS(ome) DivingC(oefficient) DivingF(ractional) DivingG(uided) DivingL(ineSearch)
DivingP(seudoCost) DivingV(ectorLength) feas(ibilityPump) flow(CoverCuts) gomory(Cuts)
greedy(Heuristic) heur(isticsOnOff) knapsack(Cuts) lift(AndProjectCuts) local(TreeSearch)
mixed(IntegerRoundingCuts) node(Strategy) pivot(AndFix) preprocess probing(Cuts)
rand(omizedRounding) reduce(AndSplitCuts) residual(CapacityCuts) Rens Rins
round(ingHeuristic) sos(Options) two(MirCuts)
```

Actions or string parameters:

```
allS(lack) barr(ier) basisI(n) basisO(ut) directory
dirSample dirNetlib dirMiplib dualS(implex) either(Simplex)
end exit export help import
initialS(olve) max(imize) min(imize) netlib netlibD(ual)
netlibP(rimal) netlibT(une) primalS(implex) printM(ask) quit
restore(Model) saveM(odel) saveS(olution) solu(tion) stat(istics)
stop unitTest userClp
```

Branch and Cut actions:

```
branch(AndCut) doH(euristic) miplib prio(rityIn) solv(e)
strengthen userCbc
```

The user may also wish to specify an initial starting solution. This is particularly useful with interior point methods. This is accomplished by using the `<initialVariableValues>` tag. Below we illustrate how to set the initial values for variables with an index of 0, 1, and 3.

```
<initialVariableValues numberOfVar="3">
  <var idx="0" value="1"/>
  <var idx="1" value="4.742999643577776" />
  <var idx="3" value="1.379408293215363"/>
</initialVariableValues>
```

As of trunk version 2164 the initial values for variables can be passed to the `Bonmin` and `Ipopt` solvers.

When implementing solver options in-memory, the typical calling sequence is:

```
solver->buildSolverInstance();
solver->setSolverOptions();
solver->solve();
```

5 OS Support for Modeling Languages, Spreadsheets and Numerical Computing Software

Algebraic modeling languages can be used to generate model instances as input to an OS compliant solver. We describe two such hook-ups, `OSAmplClient` for AMPL, and `CoinOS` for GAMS (version 23.3 and above).

5.1 AMPL Client: Hooking AMPL to Solvers

It is possible to call all of the COIN-OR solvers listed in Table 1 (p.8) directly from the AMPL (see <http://www.ampl.com>) modeling language. In this discussion we assume the user has already obtained and installed AMPL. Both the binary download described in Section 3.1 and the unix and Windows builds (Section ?? and ??, respectively) contain an executable, `OSAmplClient.exe`, that is linked to all of the COIN-OR solvers listed in Table 1. From the perspective of AMPL, the `OSAmplClient` acts like an AMPL “solver”. The `OSAmplClient.exe` can be used to solve problems either locally or remotely.

5.1.1 Using OSAmplClient for a Local Solver

In the following discussion we assume that the AMPL executable `ampl.exe`, the `OSAmplClient`, and the test problem `eastborne.mod` are all in the same directory.

The problem instance `eastborne.mod` is an AMPL model file included in the OS distribution in the `amplFiles` directory. To solve this problem locally by calling `OSAmplClient.exe` from AMPL, first start AMPL and then open the `eastborne.mod` file inside AMPL. The test model `eastborne.mod` is a linear integer program.

```
# take in sample integer linear problem
# assume the problem is in the AMPL directory
model eastborne.mod;
```

The next step is to tell AMPL that the solver it is going to use is `OSAmplClient.exe`. Do this by issuing the following command inside AMPL.


```
# tell AMPL that the solver is OSAmplClient
option solver OSAmplClient;
```

It is not necessary to provide the `OSAmplclient.exe` solver with any options. You can just issue the `solve` command in AMPL as illustrated below.

```
# solve the problem
solve;
```

Of the six methods described in Section 4 only the `solve` method has been implemented to date.

If no options are specified, the default solver is used, depending on the problem characteristics (see Table 2). If you wish to specify a specific solver, use the `solver` option. For example, since the test problem `eastborne.mod` is a linear integer program, `Cbc` is used by default. If instead you want to use `SYMPHONY`, then you would pass a `solver` option to the `OSAmplclient.exe` solver as follows.

```
# now tell OSAmplClient to use SYMPHONY instead of Cbc
option OSAmplClient_options "solver symphony";
```

Valid values for the `solver` option are installation-dependent. The solver name in the `solver` option is case insensitive.

5.1.2 Using OSAmplClient to Invoke an OS Solver Server

Next, assume that you have a large problem you want to solve on a remote solver. It is necessary to specify the location of the server solver as an option to `OSAmplClient`. The `serviceLocation` option is used to specify the location of a solver server. In this case, the string of options for `OSAmplClient_options` is:

```
serviceLocation http://xxx/OSServer/services/OSSolverService
```

where `xxx` is the URL for the server. This string is used to replace the string ‘`solver symphony`’ in the previous example. We will omit the other parts (i.e., the AMPL instruction

```
option OSAmplClient_options
```

the double quotes and the trailing semicolon) in this and the remaining examples. The `serviceLocation` option will send the problem to the solver server at location `http://xxx`.

Each call

```
option OSAmplClient_options
```

is memoryless. That is, the options set in the last call will overwrite any options set in previous calls and cause them to be discarded. For instance, the sequence of option calls

```
option OSAmplClient_options "solver symphony";
option OSAmplClient_options "serviceLocation
    http://xxx/OSServer/services/OSSolverService";
solve;
```

will result in the default solver being called.

Finally, the user may wish to pass options to the individual solver. This is done by providing an options file. A sample options file, `solveroptions.osol` is provided with this distribution. The name of the options file is the value of the `osol` option. The string of options to `OSAmplClient_options` is now

```
serviceLocation http://xxx/OSServer/services/OSSolverService
osol solveroptions.osol
```

This `solveroptions.osol` file contains four solver options; two for `Cbc`, one for `Ilopt`, and one for `SYMPHONY`. You can have any number of options. Note the format for specifying an option:

```
<solverOption name="maxN" solver="cbc" value="5" />
```

The attribute `name` specifies that the option name is `maxN` which is the maximum number of nodes allowed in the branch-and-bound tree, the `solver` attribute specifies the name of the solver that the option should be applied to, and the `value` attribute specifies the value of the option. As a second example, consider the specification

```
<solverOption name="max_iter" solver="ipopt" type="integer" value="2000"/>
```

In this example we are specifying an iteration limit for `Ilopt`. Note the additional attribute `type` that has value `integer`. The `Ilopt` solver requires specifying the data type (string, integer, or numeric) for its options. Different solvers have different options, and we recommend that the user look at the documentation for the solver of interest in order to see which options are available. A good summary of options for COIN-OR solvers is <http://www.coin-or.org/GAMSlinks/gamscoin.pdf>.

If you examine the file `solveroptions.osol` you will see that there is an XML tag with the name `<solverToInvoke>` and that the solver given is `symphony`. This has no effect on a local solve. However, if this option file is paired with

```
serviceLocation http://xxx/OSServer/services/OSSolverService
osol solveroptions.osol
```

then in our reference implementation the remote solver service will parse the file `solveroptions.osol`, find the `<solverToInvoke>` tag and then pass the `symphony` solver option to the `OSSolverService` on the remote server.

5.1.3 AMPL Summary

1. Tell AMPL to use the `OSAmplClient` as the solver:

```
option solver OSAmplClient;
```

2. Specify options to the `OSAmplClient` solver by using the AMPL command `OSAmplClient_options`.
3. There are three possible options to specify:
 - the location of the options file using the `osol` option;
 - the location of the remote server using the `serviceLocation` option;
 - the name of the solver using the `solver` option; valid values for this option are installation-dependent. For details, see Table 1 on page 8 and the discussion in Section 4.1.

These three options behave *exactly like* the `solver`, `serviceLocation`, and `osol` options used by the `OSSolverService` described in Section 4.2. Note that the `solver` option only has an affect with a local solve; if the user wants to invoke a specific solver with a remote solve, then this must be done in the OSoL file using the `<solverToInvoke>` element.

4. The options given to `OSAmplClient_options` can be given in any order.
5. If no options are specified using `OSAmplClient_options`, the default solver is used. (For details see Table 2). All solvers are invoked locally.
6. A remote solver is called if and only if the `serviceLocation` option is specified.

5.2 GAMS and Optimization Services

This section pertains to GAMS version 23.3 (and above) that now includes support for OS. Here we describe the GAMS implementation of Optimization Services. We assume that the user has installed GAMS.

There are two ways to access an OS Solver Service from GAMS, on the local machine or on a remote server. The difference between the two approaches is explained in the next two sections.

5.2.1 Using GAMS to Invoke the Local OS Solver Service CoinOS

In GAMS, OS is implemented through the `CoinOS` solver that is packaged with GAMS. The GAMS `CoinOS` solver is really a *solver interface* and is linked through the OS library to the following COIN-OR solvers: `Bonmin`, `Cbc`, `Clp`, `Glpk`, and `Ipopt`. Think of `CoinOS` as a *metasolver*. As an example (we assume a Windows operating system and use the .exe extension), consider:

```
gams.exe eastborne.gms MIP=CoinOS
```

The solver name `CoinOS` is not case sensitive and

```
gams.exe eastborne.gms MIP=coinos
```

will also work. In addition, if

```
Option MIP = CoinOS ;
```

is present in the GAMS file, then writing `MIP=CoinOS` on the command line is unnecessary. Since `Option MIP = CoinOS;` is present in the GAMS model file `eastborne.gms`, we will not specify it explicitly on the command line in the ensuing discussion. To summarize,

```
gams.exe eastborne.gms
```

is equivalent to the two versions of the command given previously. Executing any of the commands will result in the model being solved on the local machine using the COIN-OR solver `Cbc`, the default solver for mixed-integer linear models (MIP).

It is possible to control which solver is selected by `CoinOS`. This is done by providing an *options file* to GAMS. Since the solver is named `CoinOS`, the options file should be named `CoinOS.opt` (the file name is not case sensitive) and the command line call is

```
gams.exe eastborne.gms optfile 1
```

Calling multiple GAMS options files uses the convention

```
optfile=1 corresponds to Coin0S.opt
optfile=2 corresponds to Coin0S.op2
...
optfile=99 corresponds to Coin0S.o99
```

We now explain the valid options that can go into a GAMS option file when using the Coin0S solver. They are:

solver (string): Specifies the solver that is used to solve an instance. Valid values are **clp**, **cbc**, **glpk**, **ipopt**, and **bonmin**. If a solver name is specified that is not recognized, the default solver for the problem type is used. The value for the solver option is case insensitive. For example, if the file **Coin0S.opt** contains a single line

```
solver glpk
```

then executing

```
gams.exe eastborne.gms optfile 1
```

will result in using **Glpk** to solve the problem.

writeosil (string): If this option is used, GAMS will write the optimization instance to file (string) in OSiL format.

writeosrl (string): If this option is used, GAMS will write the result of the optimization to file (string) in OSrL format.

The options just described are options for the GAMS modeling language. It is also possible to pass options directly to the COIN-OR solvers by using the OS interface. This is done by passing the name of an options file that conforms to the OSoL standard. The option

readosol (string) specifies the name of an OS option file in OSoL format that is given to the solver. Note: The file **Coin0S.opt** is an option file for GAMS but the GAMS option **readosol** in the GAMS options file is specifying the name of an OS options file.

The file **solveroptions.osol** is contained in the OS distribution in the **osolFiles** directory in the **data** directory. This file contains four solver options; two for **Cbc**, one for **Ipopt**, and one for **SYMPHONY** (which is available for remote server calls, but not locally). You can have any number of options. Note the format for specifying an option:

```
<solverOption name="maxN" solver="cbc" value="5" />
```

The attribute **name** specifies that the option name is **maxN** which is the maximum number of nodes allowed in the branch-and-bound tree, the **solver** attribute specifies the name of the solver to which the option should be applied, and the **value** attribute specifies the value of the option.

As a second example, consider the specification

```
<solverOption name="max_iter" solver="ipopt" type="integer" value="2000"/>
```

In this example we are specifying an iteration limit for **Ipopt**. Note the additional attribute **type** that has value **integer**. The **Ipopt** solver requires specifying the data type (string, integer, or numeric) for its options. For a list of options that solvers take, see the file

docs/solvers/coin.pdf

inside the GAMS directory. An up-to-date online version of this list is available at <http://www.coin-or.org/GAMSLinks/gamscoin.pdf>.

5.2.2 Using GAMS to Invoke a Remote OS Solver Service

We now describe how to call a remote OS solver service using the GAMS `CoinOS`. Before proceeding, it is important to emphasize that when calling a remote OS solver service, the remote service may be a different implementation of OS than the GAMS implementation in `CoinOS`. For example, the remote implementation may also provide access to solvers such as `SYMPHONY`, `Couenne`, and `DyLP`. There are several reason why you might wish to use a remote OS solver service.

- Have access to a faster machine.
- Be able to submit jobs to run in asynchronous mode – submit your job, turn off your laptop, and check later to see if the job ran.
- Call several additional solvers (`SYMPHONY`, `Couenne` and `DyLP`).

In order to use the COIN-OR solver service it is necessary to specify the service URL. This is done using the `service` option.

`service (string)`: Specifes the URL of the COIN-OR solver service

Use the following value for this option.

`service http://webdss.ise.ufl.edu:2646/OSServer/services/OSSolverService`

Default solver values are present, depending on the problem for characteristics. For more details, consult Table 2 (p.8). In order to control the solver used, it is necessary to specify the name of the solver inside the XML tag `<solverToInvoke>`. The example `solveroptions.osol` file contains the XML tag

```
<solverToInvoke>symphony</solverToInvoke>
```

If, for example, the `CoinOS.opt` file is

```
solver ipopt
service http://webdss.ise.ufl.edu:2646/OSServer/services/OSSolverService
readosol solveroptions.osol
writeosrl temp.osrl
```

then `Ipopt` is ignored as a solver option and the remote server uses the `SYMPHONY` solver. Valid values for the remote solver service specified in the `<solverToInvoke>` tag are `clp`, `cbc`, `dylp`, `glpk`, `ipopt`, `bonmin`, `couenne`, `symphony`, and `vol`. If the problem is solved using a remote solver service the value specified by the GAMS `solver` option is irrelevant and ignored.

The GAMS `CoinOS` solver behaves differently from other implementations of OS in the following way. Although it is possible to put the address of the remote server in the OS options file, it is not read by the GAMS `CoinOS` solver. The only way to specify a remote solver is through the GAMS `service` option.

By default, the call to the server is a *synchronous* call. The GAMS process will wait for the result and then display the result. This may not be desirable when solving large optimization

models. The user may wish to submit a job, turn off his or her computer, and then check at a later date to see if the job is finished. In order to use the remote solver service in this fashion, i.e., *asynchronously*, it is necessary to use the **service_method** option.

service_method (string) specifies the method to execute on a server. Valid values for this option are **solve**, **getJobID**, **send**, **knock**, **retrieve**, and **kill**. We explain how to use each of these.

The default value of **service_method** is **solve**. A **solve** invokes the remote service in synchronous mode. When using the **solve** method you can optionally specify a set of solver options in an OSol file by using the **readosol** option. The remaining values for the **service_method** option are used for an asynchronous call. We illustrate them in the order in which they would most logically be executed.

service_method getJobID: When working in asynchronous mode, the server needs to uniquely identify each job. The **getJobID** service method will result in the server returning a unique job id. For example if the following **CoinOS.opt** file is used

```
service http://webdss.ise.ufl.edu:2646/OSServer/services/OSSolverService
service_method getJobID
```

with the command

```
gams.exe eastborne.gms optfile=1
```

the user will see a rather long job id returned to the screen as output. Assume that the job id returned is **coinor12345xyz**. This job id is used to submit a job to the server with the **send** method. Any job id can be sent to the server as long as it has not been used before.

service_method send: When working in asynchronous mode, use the **send** service method to submit a job. When using the **send** service method option an option is required and the options file must specify a job id that has not been used before. Assume that in the **CoinOS.opt** we specify the options:

```
service http://webdss.ise.ufl.edu:2646/OSServer/services/OSSolverService
service_method send
readosol sendWithJobID.osol
```

The **sendWithJobID.osol** options file is identical to the **solveroptions.osol** options file except that it has an additional XML tag:

```
<jobID>coinor12345xyz</jobID>
```

We then execute

```
gams.exe eastborne.gms optfile=1
```

If all goes well, the response to the above command should be: "Problem instance successfully sent to OS service". At this point the server will schedule the job and work on it. It is possible to turn off the user computer at this point. At some point the user will want to know if the job is finished. This is accomplished using the **knock** service method.

service_method knock: When working in asynchronous mode, this is used to check the status of a job. Consider the following **CoinOS.opt** file:

```

service http://webdss.ise.ufl.edu:2646/OSServer/services/OSSolverService
service_method knock
readosol sendWithJobID.osol
readospl knock.ospl
writeospl knockResult.ospl

```

The `knock` service method requires two inputs. The first input is the name of an options file, in this case `sendWithJobID.osol`, specified through the `readosol` option. In addition, a file in OSPL format is required. You can use the `knock.ospl` file provided in the binary distribution. This file name is specified using the `readospl` option. If no job id is specified in the OSOL file then the status of all jobs on the server will be returned in the file specified by the `writeospl` option. If a job id is specified in the OSOL file, then only information on the specified job id is returned in the file specified by the `writeospl` option. In this case the file name is `knockResult.ospl`. We then execute

```
gams.exe eastborne.gms optfile=1
```

The file `knockResult.ospl` will contain the information

```

<job jobID="coinor12345xyz">
<state>finished</state>
<serviceURI>http://192.168.0.219:8443/os/OSSolverService.jws</serviceURI>
<submitTime>2009-11-10T02:13:11.245-06:00</submitTime>
<startTime>2009-11-10T02:13:11.245-06:00</startTime>
<endTime>2009-11-10T02:13:12.605-06:00</endTime>
<duration>1.36</duration>
</job>

```

Note that the job is complete as indicated in the `<state>` tag. It is now time to actually retrieve the job solution. This is done with the `retrieve` method.

service_method retrieve: When working in asynchronous mode, this method is used to retrieve the job solution. It is necessary when using `retrieve` to specify an options file and in that options file specify a job id. Consider the following `CoinOS.opt` file:

```

service http://webdss.ise.ufl.edu:2646/OSServer/services/OSSolverService
service_method retrieve
readosol sendWithJobID.osol
writeosrl answer.osrl

```

When we then execute

```
gams.exe eastborne.gms optfile=1
```

the result is written to the file `answer.osrl`.

Finally there is a `kill` service method which is used to kill a job that was submitted by mistake or is running too long on the server.

service_method kill: When working in asynchronous mode, this method is used to terminate a job. You should specify an OSOL file containing the JobID by using the `readosol` option.

5.2.3 GAMS Summary:

1. In order to use OS with GAMS you can either specify CoinOS as an option to GAMS at the command line,

```
gams eastborne.gms MIP=CoinOS
```

or you can place the statement `Option ProblemType = CoinOS;` somewhere in the model *before* the `Solve` statement in the GAMS file.

2. If no options are given, then the model will be solved locally using the default solver (see Table 2 on p.8).
3. In order to control behavior (for example, whether a local or remote solver is used) an options file, `CoinOS.opt`, must be used as follows

```
gams.exe eastborne.gms optfile=1
```

4. The `CoinOS.opt` file is used to specify *eight potential options*:

- `service (string)`: using the COIN-OR solver server; this is done by giving the option

```
service http://webdss.ise.ufl.edu:2646/OSServer/services/OSSolverService
```

- `readosol (string)`: whether or not to send the solver an options file; this is done by giving the option

```
readosol solveroptions.osol
```

- `solver (string)`: if a local solve is being done, a specific solver is specified by the option

```
solver solver_name
```

Valid values are `clp`, `cbc`, `glpk`, `ipopt` and `bonmin`. When the COIN-OR solver service is being used, the only way to specify the solver to use is through the `<solverToInvoke>` tag in an OSoL file. In this case the valid values for the solver are `clp`, `cbc`, `dylp`, `glpk`, `ipopt`, `bonmin`, `couenne`, `symphony` and `vol`.

- `writeosrl (string)`: the solution result can be put into an OSrL file by specifying the option

```
writeosrl osrl_file_name
```

- `writeosil (string)`: the optimization instance can be put into an OSiL file by specifying the option

```
writeosil osil_file_name
```

- `writeospl (string)`: Specifies the name of an OSpL file in which the answer from the knock or kill method is written, e.g.,

```
writeospl write_ospl_file_name
```


- `readospl (string)`: Specifies the name of an OSPL file that the `knock` method sends to the server

`readospl read_ospl_file_name`
 - `service_method (string)`: Specifies the method to execute on a server. Valid values for this option are `solve`, `getJobID`, `send`, `knock`, `retrieve`, and `kill`.
5. If an OS options file is passed to the GAMS `CoinOS` solver using the GAMS `CoinOS` option `readosol`, then GAMS does not interpret or act on any options in this file. The options in the OS options file are passed directly to either: i) the default local solver, ii) the local solver specified by the GAMS `CoinOS` option `solver`, or iii) to the remote OS solver service if one is specified by the GAMS `CoinOS` option `service`.

5.3 MATLAB: Using MATLAB to Build and Run OSiL Model Instances

MATLAB has powerful matrix generation and manipulation routines. This section is for users who wish to use MATLAB to generate the matrix coefficients for linear or quadratic programs and use the OS library to call a solver and get the result back. Using MATLAB with OS requires the user compile a file `OSMatlabSolverMex.cpp` into a MATLAB executable file (these files will have a `.mex` extension) after compilation. This executable file is linked to the OS library and works through the MATLAB API to communicate with the OS library.

The OS MATLAB application differs from the other applications in the `OS/applications` folder in that makefiles are not used. The file

`OS/applications/matlab/OSMatlabSolverMex.cpp`

must be compiled inside the MATLAB command window. Building the OS MATLAB application requires the following steps.

Step 1: The MATLAB installation contains a file `mexopts.sh` (UNIX) or `mexopts.bat` (Windows) that must be edited. This file typically resides in the `bin` directory of the MATLAB application. This file contains compile and link options that must be properly set. Appropriate paths to header files and libraries must be set. This discussion is based on the assumption that the user has either done a `make install` for the OS project or has downloaded a binary archive of the OS project. In either case there will be an `include` directory with the necessary header files and a `lib` directory with the necessary libraries for linking.

First edit the `CXXFLAGS` option to point to the header files in the `cppad` directory and the `include` directory in the project root. For example, it should look like:

```
CXXFLAGS='-fno-common -no-cpp-precomp -fexceptions
-I/Users/kmartin/Documents/files/code/cpp/OScpp/COIN-OS/
-I/Users/kmartin/Documents/files/code/cpp/OScpp/COIN-OS/include'
```

Next edit the `CXXLIBS` flag so that the OS and supporting libraries are included. For example, it should look like the following on a MacIntosh:

```
CXXLIBS="$MLIBS -lstdc++ -L/Users/kmartin/coin/os-trunk/vpath/lib
-lOS -lbonmin -lIpopt -l0siCbc -l0siClp -l0siSym -l0siVol
-l0siDyld -lCbc -lCgl -l0si -lClp -lSym -lVol -lDyld
-lCoinUtils -lCbcSolver -lcoinmumps -ldl -lpthread
/usr/local/lib/libgfortran.dylib -lgcc_s.10.5 -lgcc_ext.10.5 -lSystem -lm
```

Important: It has been the authors' experience that setting the necessary MATLAB compiler and linker options to build the `mex` can be tricky. We include in

`OS/applications/matlab/macOSXscript.txt`

the exact options that work on a 64 bit Mac with MATLAB release R2009b.

Step 2: Build the MATLAB executable file. Start MATLAB and in the MATLAB command window connect to the directory `OS/examples/matlab` which contains the file `OSmatlabSolver.cpp`. Execute the command:

```
mex -v OSMatlabSolver.cpp
```

On a 64 bit machine the command should be

```
mex -v -largeArrayDims OSMatlabSolver.cpp
```

On an Intel MAC OS X 64 bit chip the resulting executable will be named `OSmatlabSolver.mexmaci64`. On the Windows system the file is named `OSmatlabSolver.mexw32`.

Step 3: Set the MATLAB path to include the directory `OS/applications/matlab` (or more generally, the directory with the `mex` executable).

Step 4: In the MATLAB command window, connect to the directory `OS/data/matlabFiles`. Run either of the MATLAB files `markowitz.m` or `parincLinear.m`. The result should be displayed in the MATLAB browser window.

To use the `OSmatlabSolver` it is necessary to put the coefficients from a linear, integer, or quadratic problem into MATLAB arrays. We illustrate for the linear program:

$$\begin{aligned}
 \text{Minimize} \quad & 10x_1 + 9x_2 & (1) \\
 \text{Subject to} \quad & .7x_1 + x_2 \leq 630 & (2) \\
 & .5x_1 + (5/6)x_2 \leq 600 & (3) \\
 & x_1 + (2/3)x_2 \leq 708 & (4) \\
 & .1x_1 + .25x_2 \leq 135 & (5) \\
 & x_1, x_2 \geq 0 & (6)
 \end{aligned}$$

The MATLAB representation of this problem in MATLAB arrays is

```

% the number of constraints
numCon = 4;
% the number of variables
numVar = 2;
% variable types
VarType='CC';
% constraint types
A = [.7  1; .5  5/6; 1  2/3  ; .1  .25];
BU = [630 600  708  135];
BL = [];
OBJ = [10  9];
VL = [-inf -inf];
VU = [];
ObjType = 1;
% leave Q empty if there are no quadratic terms
Q = [];
prob_name = 'ParInc Example'
password = '';
%
%
%the solver
solverName = 'ipopt';
%the remote service address
%if left empty we solve locally -- must solve locally for now
serviceAddress='';
% now solve
callMatlabSolver( numVar, numCon, A, BL, BU, OBJ, VL, VU, ObjType, ...
    VarType, Q, prob_name, password, solverName, serviceAddress)

```

This example m-file is in the `data` directory and is file `parincLinear.m`. Note that in addition to the problem formulation we can specify which solver to use through the `solverName` variable. If solution with a remote solver is desired this can be specified with the `serviceAddress` variable. If the `serviceAddress` is left empty, i.e.,

```
serviceAddress='';
```

then a local solver is used. In this case it is crucial that the appropriate solver is linked in with the `matlabSolver` executable using the `CXXLIBS` option.

The `data` directory also contains the m-file `template.m` which contains extensive comments about how to formulate the problems in MATLAB. The user can edit `template.m` as necessary and create a new instance.

A second example which is a quadratic problem is given in Section 5.3. The appropriate MATLAB m-file is `markowitz.m` in the `data/matlabFiles` directory. The problem consists in investing in a number of stocks. The expected returns and risks (covariances) of the stocks are known. Assume that the decision variables x_i represent the fraction of wealth invested in stock i and that no stock can have more than 75% of the total wealth. The problem then is to minimize the total risk subject to a budget constraint and a lower bound on the expected portfolio return.

Assume that there are three stocks (variables) and two constraints (not counting the upper limit of .75 on the investment variables).

```
% the number of constraints
numCon = 2;
% the number of variables
numVar = 3;
```

All the variables are continuous:

```
VarType='CCC';
```

Next define the constraint upper and lower bounds. There are two constraints, an equality constraint (an =) and a lower bound on portfolio return of .15 (a \geq). These two constraints are expressed as

```
BL = [1    .15];
BU = [1    inf];
```

The variables are nonnegative and have upper limits of .75 (no stock can comprise more than 75% of the portfolio). This is written as

```
VL = [];
VU = [.75 .75 .75];
```

There are no nonzero linear coefficients in the objective function, but the objective function vector must always be defined and the number of components of this vector is the number of variables.

```
OBJ = [0 0 0 ]
```

Now the linear constraints. In the model the two linear constraints are

$$\begin{aligned} x_1 + x_2 + x_3 &= 1 \\ 0.3221x_1 + 0.0963x_2 + 0.1187x_3 &\geq .15 \end{aligned}$$

These are expressed as

```
A = [ 1 1 1 ;
      0.3221 0.0963 0.1187 ];
```

Now for the quadratic terms. The only quadratic terms are in the objective function. The objective function is

$$\begin{aligned} \min & 0.425349694x_1^2 + 0.445784443x_2^2 + 0.231430983x_3^2 + 2 \times 0.185218694x_1x_2 \\ & + 2 \times 0.139312545x_1x_3 + 2 \times 0.13881692x_2x_3 \end{aligned}$$

To represent quadratic terms MATLAB uses an array, here denoted Q , which has four rows, and a column for each quadratic term. In this example there are six quadratic terms. The first row of Q is the row index where the terms appear. By convention, the objective function has index -1, and constraints are counted starting at 0. The first row of Q is

-1 -1 -1 -1 -1 -1

The second row of Q is the index of the first variable in the quadratic term. We use zero based counting. Variable x_1 has index 0, variable x_2 has index 1, and variable x_3 has index 2. Therefore, the second row of Q is

0 1 2 0 0 1

The third row of Q is the index of the second variable in the quadratic term. Therefore, the third row of Q is

0 1 2 1 2 2

Note that terms such as x_1^2 are treated as $x_1 * x_1$ and that mixed terms such as $x_2 x_3$ could be given in either order.

The last (fourth) row is the coefficient. Therefore, the fourth row reads

.425349654 .445784443 .231430983 .370437388 .27862509 .27763384

The full array is

```
Q = [ -1 -1 -1 -1 -1 -1;
      0 1 2 0 0 1 ;
      0 1 2 1 2 2;
      .425349654 .445784443 .231430983 .370437388 .27862509 .27763384
    ];
```

Finally, name the problem, specify the solver (in this case `ipopt`), the service address (and password if required by the service), and call the solver.

```
% replace Template with the name of your problem
prob_name = 'Markowitz Example from Anderson, Sweeney, Williams, and Martin';
password = '';
%
%the solver
solverName = 'ipopt';
%the remote service service address
%if left empty we solve locally -- must solve locally for now
serviceAddress='';
% now solve
OSCallMatlabSolver( numVar, numCon, A, BL, BU, OBJ, VL, VU, ObjType, VarType, ...
    Q, prob_name, password, solverName, serviceAddress)
```

6 OS Protocols

The objective of OS is to provide a set of standards for representing optimization instances, results, solver options, and communication between clients and solvers in a distributed environment using Web Services. These standards are specified by W3C XSD schemas. The schemas for the OS project are contained in the `schemas` folder under the OS root. There are numerous schemas in this directory that are part of the OS standard. For a full description of all the schemas see Ma [4]. We briefly discuss the standards most relevant to the current version of the OS project.

6.1 OSiL (Optimization Services instance Language)

OSiL is an XML-based language for representing instances of large-scale optimization problems including linear programs, mixed-integer programs, quadratic programs, and very general nonlinear programs.

OSiL stores optimization problem instances as XML files. Consider the following problem instance, which is a modification of an example of Rosenbrock [5]:

$$\text{Minimize } (1 - x_0)^2 + 100(x_1 - x_0^2)^2 + 9x_1 \quad (7)$$

$$\text{s.t. } x_0 + 10.5x_0^2 + 11.7x_1^2 + 3x_0x_1 \leq 25 \quad (8)$$

$$\ln(x_0x_1) + 7.5x_0 + 5.25x_1 \geq 10 \quad (9)$$

$$x_0, x_1 \geq 0 \quad (10)$$

There are two continuous variables, x_0 and x_1 , in this instance, each with a lower bound of 0. Figure 5 shows how we represent this information in an XML-based OSiL file. Like all XML files, this is a text file that contains both *markup* and *data*. In this case there are two types of markup, *elements* (or *tags*) and *attributes* that describe the elements. Specifically, there are a `<variables>` element and two `<var>` elements. Each `<var>` element has attributes `lb`, `name`, and `type` that describe properties of a decision variable: its lower bound, “name”, and domain type (continuous, binary, general integer).

To be useful for communication between solvers and modeling languages, OSiL instance files must conform to a standard. An XML-based representation standard is imposed through the use of a *W3C XML Schema*. The W3C, or World Wide Web Consortium (www.w3.org), promotes standards for the evolution of the web and for interoperability between web products. XML Schema (www.w3.org/XML/Schema) is one such standard. A schema specifies the elements and attributes that define a specific XML vocabulary. The W3C XML Schema is thus a schema for schemas; it specifies the elements and attributes for a schema that in turn specifies elements and attributes for an XML vocabulary such as OSiL. An XML file that conforms to a schema is called *valid* for that schema.

By analogy to object-oriented programming, a schema is akin to a header file in C++ that defines the members and methods in a class. Just as a class in C++ very explicitly describes member and method names and properties, a schema explicitly describes element and attribute names and properties.

Figure 6 is a piece of our schema for OSiL. In W3C XML Schema jargon, it defines a *complexType*, whose purpose is to specify elements and attributes that are allowed to appear in a valid XML instance file such as the one excerpted in Figure 5. In particular, Figure 6 defines the complexType named `Variables`, which comprises an element named `<var>` and an attribute named `numberOfVariables`. The `numberOfVariables` attribute is of a standard type `positiveInteger`, whereas the `<var>` element is a user-defined complexType named `Variable`. Thus the complex-

```
<variables numberOfVariables="2">
  <var lb="0" name="x0" type="C"/>
  <var lb="0" name="x1" type="C"/>
</variables>
```

Figure 5: The `<variables>` element for the example (1)–(4).

Type **Variables** contains a sequence of `<var>` elements that are of complexType **Variable**. OSiL's schema must also provide a specification for the **Variable** complexType, which is shown in Figure 7.

In OSiL the linear part of the problem is stored in the `<linearConstraintCoefficients>` element, which stores the coefficient matrix using three arrays as proposed in the earlier LPFML schema [2]. There is a child element of `<linearConstraintCoefficients>` to represent each array: `<value>` for an array of nonzero coefficients, `<rowIdx>` or `<colIdx>` for a corresponding array of row indices or column indices, and `<start>` for an array that indicates where each row or column begins in the previous two arrays. This is shown in Figure 8.

The quadratic part of the problem is represented in Figure 9.

The nonlinear part of the problem is given in Figure 10.

The complete OSiL representation can be found in the Appendix (Section ??).

6.2 OSrL (Optimization Services result Language)

OSrL is an XML-based language for representing the solution of large-scale optimization problems including linear programs, mixed-integer programs, quadratic programs, and very general nonlinear programs. An example solution (for the problem given in (7)–(10)) in OSrL format is given below.

```
<?xml version="1.0" encoding="UTF-8"?>
```

```
<xs:complexType name="Variables">
  <xs:sequence>
    <xs:element name="var" type="Variable" maxOccurs="unbounded"/>
  </xs:sequence>
  <xs:attribute name="numberOfVariables"
    type="xs:positiveInteger" use="required"/>
</xs:complexType>
```

Figure 6: The **Variables** complexType in the OSiL schema.

```
<xs:complexType name="Variable">
  <xs:attribute name="name" type="xs:string" use="optional"/>
  <xs:attribute name="init" type="xs:string" use="optional"/>
  <xs:attribute name="type" use="optional" default="C">
    <xs:simpleType>
      <xs:restriction base="xs:string">
        <xs:enumeration value="C"/>
        <xs:enumeration value="B"/>
        <xs:enumeration value="I"/>
        <xs:enumeration value="S"/>
      </xs:restriction>
    </xs:simpleType>
  </xs:attribute>
  <xs:attribute name="lb" type="xs:double" use="optional" default="0"/>
  <xs:attribute name="ub" type="xs:double" use="optional" default="INF"/>
</xs:complexType>
```

Figure 7: The **Variable** complexType in the OSiL schema.

```

<linearConstraintCoefficients numberOfValues="3">
  <start>
    <el>0</el><el>2</el><el>3</el>
  </start>
  <rowIdx>
    <el>0</el><el>1</el><el>1</el>
  </rowIdx>
  <value>
    <el>1.</el><el>7.5</el><el>5.25</el>
  </value>
</linearConstraintCoefficients>

```

Figure 8: The `<linearConstraintCoefficients>` element for constraints (8) and (9).

```

<quadraticCoefficients numberOfQuadraticTerms="3">
  <qTerm idx="0" idxOne="0" idxTwo="0" coef="10.5"/>
  <qTerm idx="0" idxOne="1" idxTwo="1" coef="11.7"/>
  <qTerm idx="0" idxOne="0" idxTwo="1" coef="3."/>
</quadraticCoefficients>

```

Figure 9: The `<quadraticCoefficients>` element for constraint (8).

```

<?xml-stylesheet type = "text/xsl"
  href = "/Users/kmartin/Documents/files/code/cpp/OScpp/COIN-OSX/OS/stylesheets/OSrL.xslt"?>
<osrl xmlns="os.optimizationservices.org"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="os.optimizationservices.org
  http://www.optimizationservices.org/schemas/2.0/OSiL.xsd">
  <general>
    <generalStatus type="normal"/>
    <serviceName>Solved using a LINDO service</serviceName>
    <instanceName>Modified Rosenbrock</instanceName>
  </general>
  <optimization numberOfSolutions="1" numberOfVariables="2" numberOfConstraints="2"
    numberOfObjectives="1">
    <solution targetObjectiveIdx="-1">
      <status type="optimal"/>
      <variables>
        <values numberOfVar="2">
          <var idx="0">0.87243</var>
          <var idx="1">0.741417</var>
        </values>
        <other numberOfVar="2" name="reduced costs" description="the variable reduced costs">
          <var idx="0">-4.06909e-08</var>
          <var idx="1">0</var>
        </other>
      </variables>
      <objectives>
        <values numberOfObj="1">

```



```

<nl idx="-1">
  <plus>
    <power>
      <minus>
        <number value="1.0"/>
        <variable coef="1.0" idx="0"/>
      </minus>
      <number value="2.0"/>
    </power>
    <times>
      <power>
        <minus>
          <variable coef="1.0" idx="0"/>
          <power>
            <variable coef="1.0" idx="1"/>
            <number value="2.0"/>
          </power>
        </minus>
        <number value="2.0"/>
      </power>
      <number value="100"/>
    </times>
  </plus>
</nl>

```

Figure 10: The `<nl>` element for the nonlinear part of the objective (7).

```

    <obj idx="-1">6.7279</obj>
  </values>
</objectives>
<constraints>
  <dualValues numberOfCon="2">
    <con idx="0">0</con>
    <con idx="1">0.766294</con>
  </dualValues>
</constraints>
</solution>
</optimization>

```

6.3 OSoL (Optimization Services option Language)

OSoL is an XML-based language for representing options that get passed to an optimization solver or a hosted optimization solver Web service. It contains both standard options for generic services and extendable option tags for solver-specific directives. Several examples of files in OSoL format are presented in Section 4.4.

6.4 OSnL (Optimization Services nonlinear Language)

The OSnL schema is imported by the OSiL schema and is used to represent the nonlinear part of an optimization instance. This is explained in greater detail in Section ???. Also refer to Figure 10

for an illustration of elements from the OSnL standard. This figure represents the nonlinear part of the objective in equation (7), that is,

$$(1 - x_0)^2 + 100(x_1 - x_0^2)^2.$$

6.5 OSpL (Optimization Services process Language)

This is a standard used to enquire about dynamic process information that is kept by the Optimization Services registry. The string passed to the `knock` method is in the OSpL format. See the example given in Section 4.4.5.

7 The OSInstance API

The OSInstance API can be used to:

- get information about model parameters, or convert the `OSExpressionTree` into a prefix or postfix representation through a collection of `get()` methods,
- modify, or even create an instance from scratch, using a number of `set()` methods,
- provide information to solvers that require function evaluations, Jacobian and Hessian sparsity patterns, function gradient evaluations, and Hessian evaluations.

7.1 Get Methods

The `get()` methods are used by other classes to access data in an existing `OSInstance` object or get an expression tree representation of an instance in postfix or prefix format. Assume `osinstance` is an object in the `OSInstance` class created as illustrated in Figure ?? . Then, for example,

```
osinstance->getVariableNumber();
```

will return an integer which is the number of variables in the problem,

```
osinstance->getVariableTypes();
```

will return a `char` pointer to the variable types (C for continuous, B for binary, and I for general integer),

```
getVariableLowerBounds();
```

will return a `double` pointer to the lower bound on each variable. There are similar `get()` methods for the constraints. There are numerous `get()` methods for the data in the `<linearConstraintCoefficients>` element, the `<quadraticCoefficients>` element, and the `<nonlinearExpressions>` element.

When an `osinstance` object is created, it is stored as an expression tree in an `OSExpressionTree` object. However, some solver APIs (e.g., LINDO) may take the data in a different format such as postfix and prefix. There are methods to return the data in either postfix or prefix format.

First define a `vector` of pointers to `OSnLNode` objects.

```
std::vector<OSnLNode*> postfixVec;
```

then get the expression tree for the objective function (index = -1) as a postfix vector of nodes.

```
postfixVec = osinstance->getNonlinearExpressionTreeInPostfix( -1);
```

If, for example, the `osinstance` object was the in-memory representation of the instance illustrated in Section ?? and Figure ?? then the code

```
for (i = 0 ; i < n; i++){  
    cout << postfixVec[i]->snodeName << endl;  
}
```

will produce

```
number  
variable  
minus  
number  
power  
number  
variable  
variable  
number  
power  
minus  
number  
power  
times  
plus
```

This postfix traversal of the expression tree in Figure ?? lists all the nodes by recursively processing all subtrees, followed by the root node. The method `processNonlinearExpressions()` in the `LindoSolver` class in the `OSSolverInterfaces` library component illustrates the use of a postfix vector of `OSnLNode` objects to build a Lindo model instance.

7.2 Set Methods

The `set()` methods can be used to build an in-memory `OSInstance` object. A code example of how to do this is in Section ??.

7.3 Calculate Methods

The `calculate()` methods are described in Section ??.

7.4 Modifying an OSInstance Object

The `OSInstance` API is designed to be used to either build an in-memory `OSInstance` object or provide information about the in-memory object (e.g., the number of variables). This interface is not designed for problem modification. We plan on later providing an `OSModification` object for this task. However, by directly accessing an `OSInstance` object it is possible to modify parameters in the following classes:

- Variables
- Objectives

- **Constraints**
- **LinearConstraintCoefficients**

For example, to modify the first nonzero objective function coefficient of the first objective function to 10.7 the user would write,

```
osinstance->instanceData->objectives->obj[0]->coef[0]->value = 10.7;
```

If the user wanted to modify the actual number of nonzero coefficients as declared by

```
osinstance->instanceData->objectives->obj[0]->numberOfObjCoef;
```

then the only safe course of action would be to delete the current **OSInstance** object and build a new one with the modified coefficients. It is strongly recommend that no changes are made involving allocated memory – i.e., any kind of **numberOf*****. Modifying an objective function coefficient is illustrated in the **OSModDemo** example. See Section ??.

After modifying an **OSInstance** object, it is necessary to set certain boolean variables to true in order for these changes to get reflected in the OS solver interfaces.

- **Variables** – if any changes are made to a parameter in this class set

```
osinstance->bVariablesModified = true;
```

- **Objectives** – if any changes are made to a parameter in this class set

```
osinstance->bObjectivesModified = true;
```

- **Constraints** – if any changes are made to a parameter in this class set

```
osinstance->bConstraintsModified = true;
```

- **LinearConstraintCoefficients** – if any changes are made to a parameter in this class set

```
osinstance->bAMatrixModified = true;
```

At this point, if the user desires to modify an **OSInstance** object that contains nonlinear terms, the only safe strategy is to delete the object and build a new object that contains the modifications.

7.5 Printing a Model for Debugging

The **OSiL** representation for the test problem **rosenbrockmod.osil** is given in Appendix ??. Many users will not find the **OSiL** representation useful for model debugging purposes. For users who wish to see a model in a standard infix representation we provide a method **printModel()**. Assume that we have an **osinstance** object in the **OSInstance** class that represents the model of interest. The call

```
osinstance->printModel( -1)
```

will result in printing the (first) objective function indexed by -1. In order to print constraint k use

```
osinstance->printModel( k)
```

In order to print the entire model use

```
osinstance->printModel( )
```

Below we give the result of `osinstance->printModel()` for the problem `rosenbrockmod.osil`.

Objectives:

```
min 9*x_1 + (((1 - x_0) ^ 2) + (100*((x_1 - (x_0 ^ 2)) ^ 2)))
```

Constraints:

```
(((((10.5*x_0)*x_0) + ((11.7*x_1)*x_1)) + ((3*x_0)*x_1)) + x_0) <= 25  
10 <= ((ln( x_0*x_1)) + (7.5*x_0)) + (5.25*x_1))
```

Variables:

```
x_0 Type = C Lower Bound = 0 Upper Bound = 1.7976931348623157e308  
x_1 Type = C Lower Bound = 0 Upper Bound = 1.7976931348623157e308
```

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