

Introduction to Computer Vision

GENERATIVE ADVERSARIAL NETs

2014, Ian J. Good et al.

*Presented by **Nguyen Quang Huy***

Faculty of Information Technology, Ton Duc Thang University

Email: 523h0140@student.tdtu.edu.vn

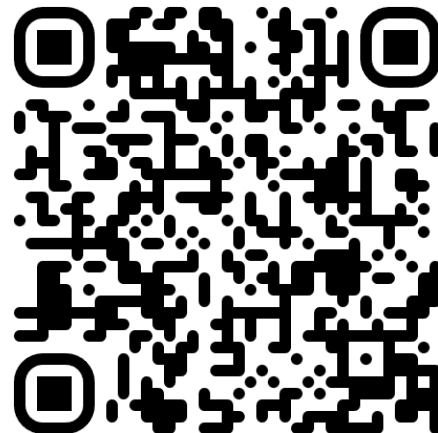
QR Code



Presentation slide



GAN Implementation



Github Resources

Outline

1. Introduction & General Idea
2. Architecture
3. Challenges & improvements
4. Applications
5. Demo / Visualization

1. Introduction & General Idea



Ian Goodfellow (1987) source: [Wikipedia](#)

- B.S & M.S at Stanford
- Ph.D at Montreal
- Google Brain
- OpenAI
- Google Research
- Apple
- Google Deepmind

1. Introduction & General Idea

Stage 1 Feature learning

- Image processing
- SVM / KNN, CNN

Stage 2 Detection & Segmentation



- Object detection: 2 - Stage Detector (R-CNN), 1 - Stage Detector (YOLO)
- Image segmentation: Semantic, Instance Segmentation

Stage 3 Tracking & Attention

- Object tracking
- Object Recognition (SORT, DeepSORT)
- Attention Mechanism & VisionTransformer

1. Introduction & General Idea

Why we need Generative Models ?

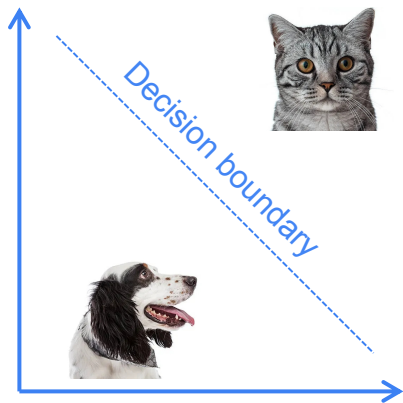
- Discriminative models $P(\text{Class} | \text{Image})$

- Generative models $P(\text{Image})$


1. Introduction & General Idea

Discriminative AI vs Generative AI

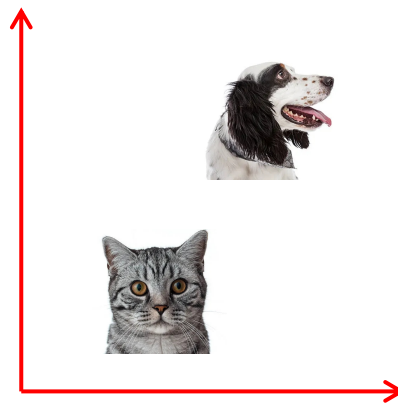
Discriminative

Classify or labeling data points
as cat or dog

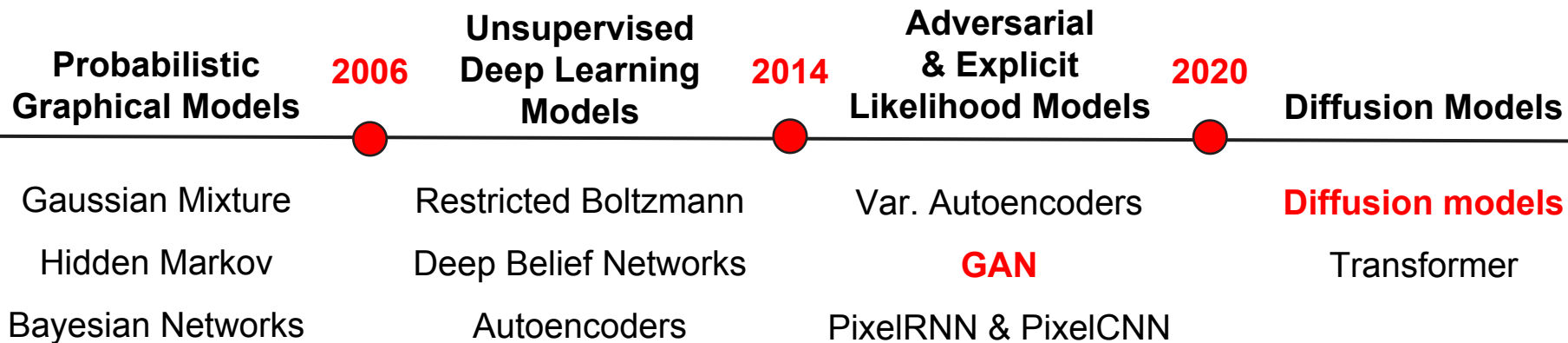


Generative

Produce a new data points
that looks like dog or cat



1. Introduction & General Idea



2. Architecture

Adversarial Learning

D/G try to maximize/minimize

value of objective function

$$\boxed{\min_G \max_D V(D, G)} = \boxed{\mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})]} + \boxed{\mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))]}$$

Expected on real dataset

Expected on noise distribution

$D(x) \in [0, 1]$ the probability that the D believes the sample x is real

$G(z)$ generated image from the z noise

$x \sim p_{\text{data}}(x)$ random variable x taken according to real data distribution

2. Architecture

Adversarial Learning

Discriminator (D)

$$\max V(D, G)$$

Real: $D(x) \rightarrow 1, x \sim P_{data}(x)$
 $\log D(x) \rightarrow 0^+$

Fake: $D(G(z)) \rightarrow 0, z \sim P_z(z)$
 $\log(1 - D(G(z))) \rightarrow 0^+$

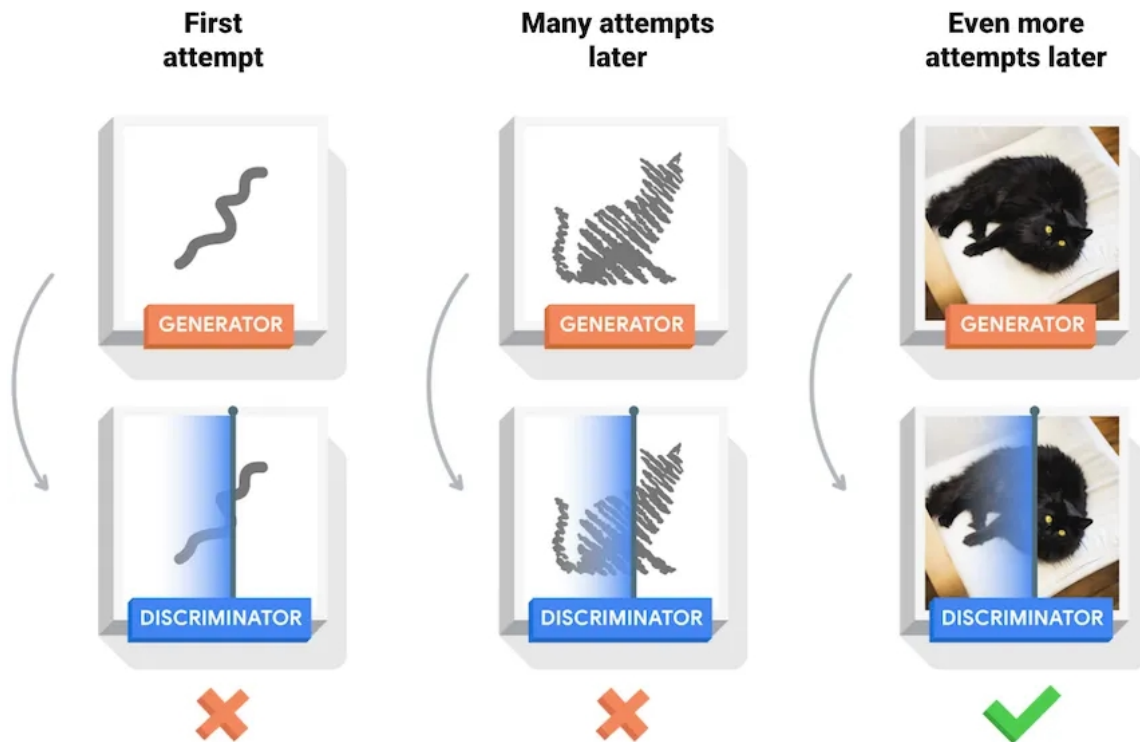
Generator (G)

$$\min V(D, G)$$

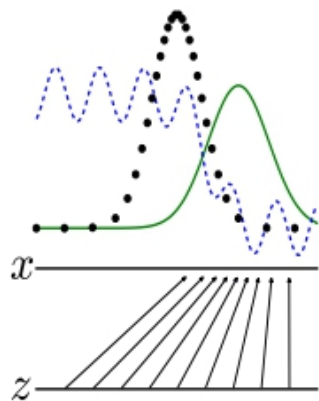
Fake: $D(G(z)) \rightarrow 1, z \sim P_z(z)$
 $\log(1 - D(G(z))) \rightarrow -\infty$

2. Architecture

Adversarial Learning

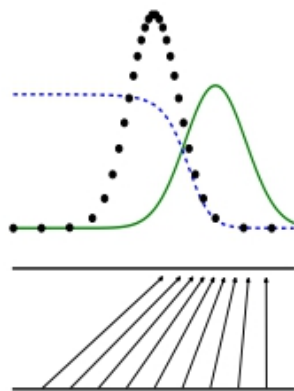


2. Architecture



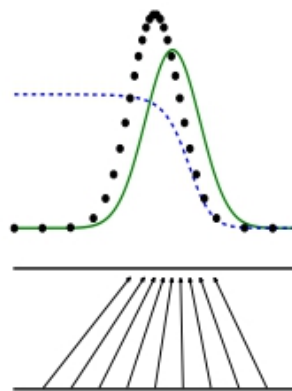
(a)

Start training



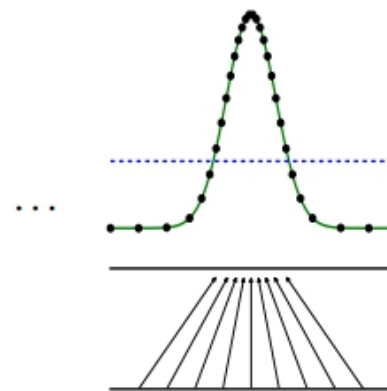
(b)

After few steps



(c)

Update G



(d)

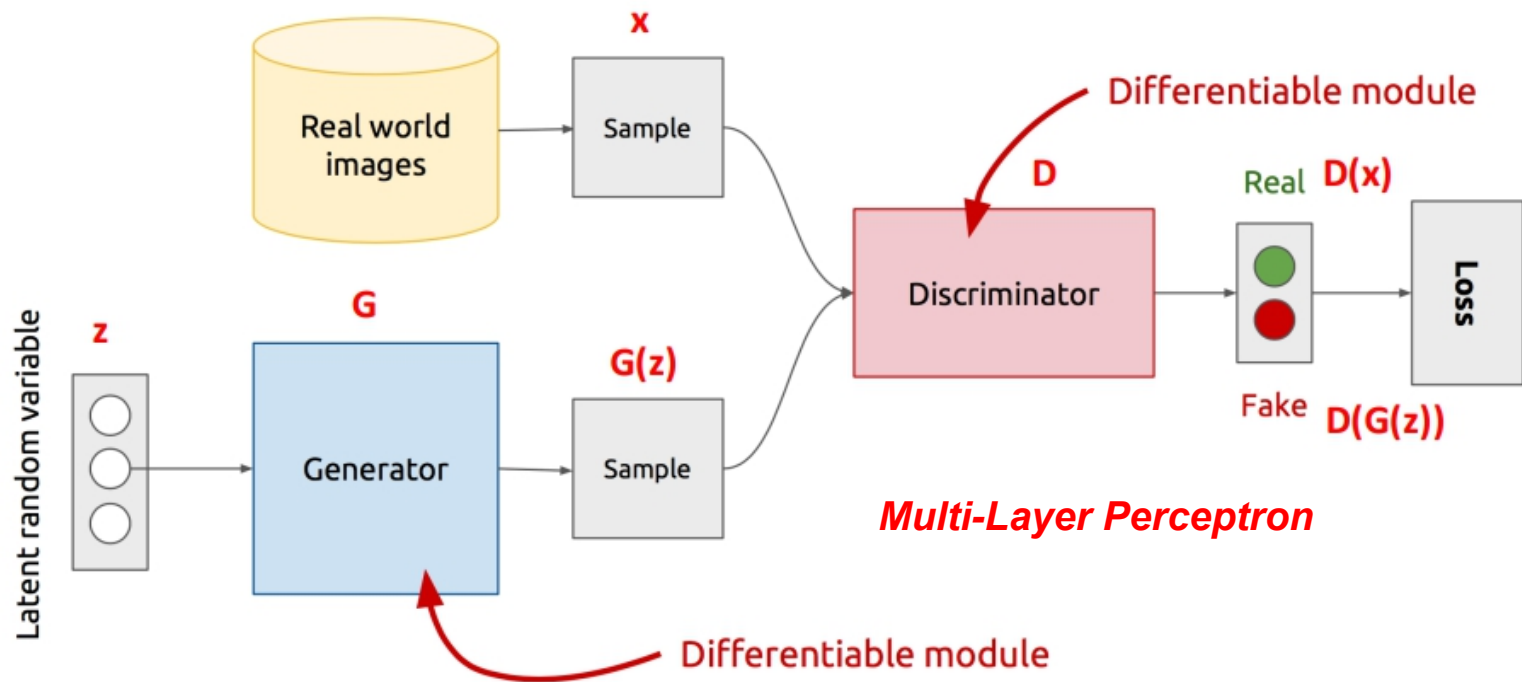
Nash Equilibrium

**discriminative distribution
(D, blue, dashed line)**

**data generating distribution
(black, dotted line)**

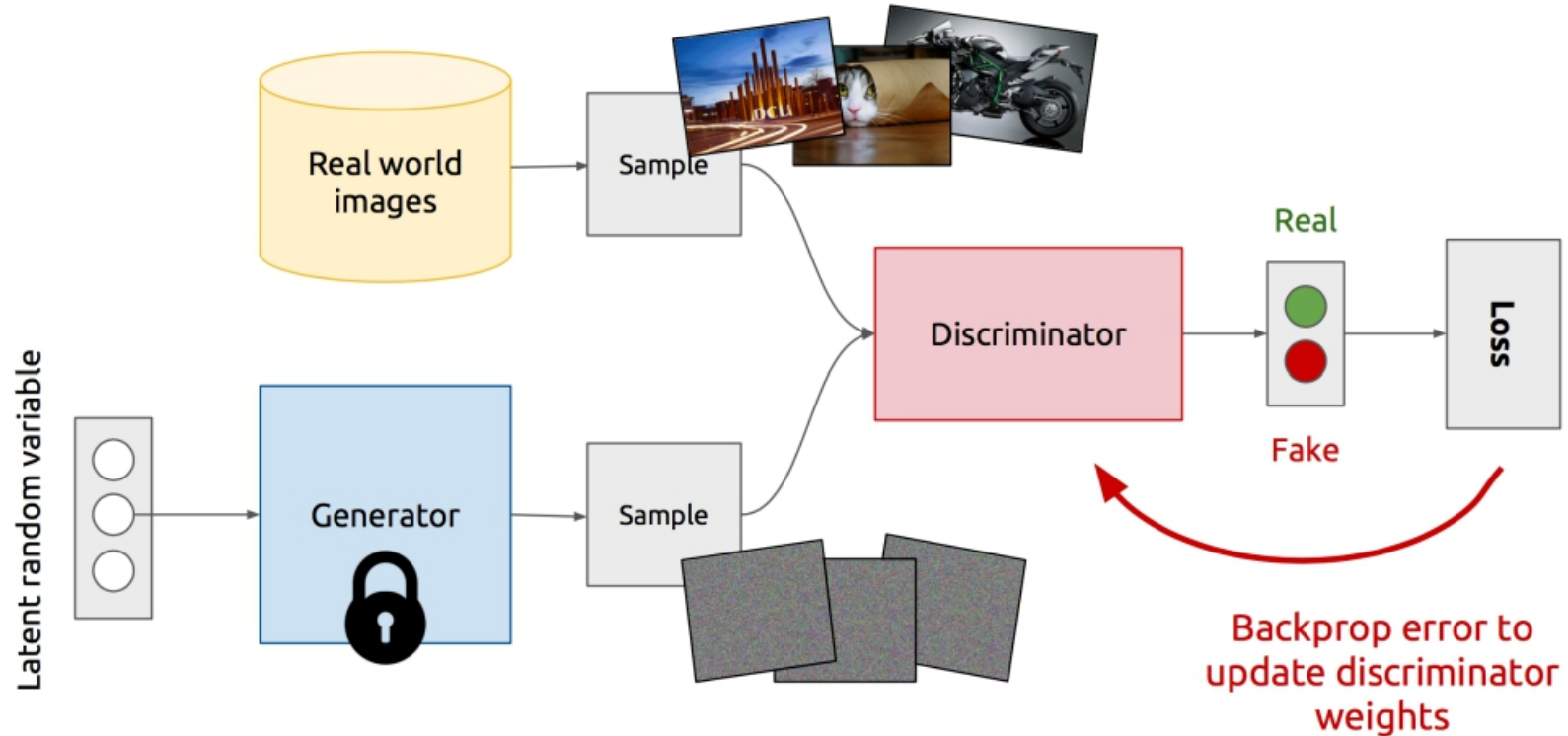
**generative distribution
(green, solid line)**

2. Architecture



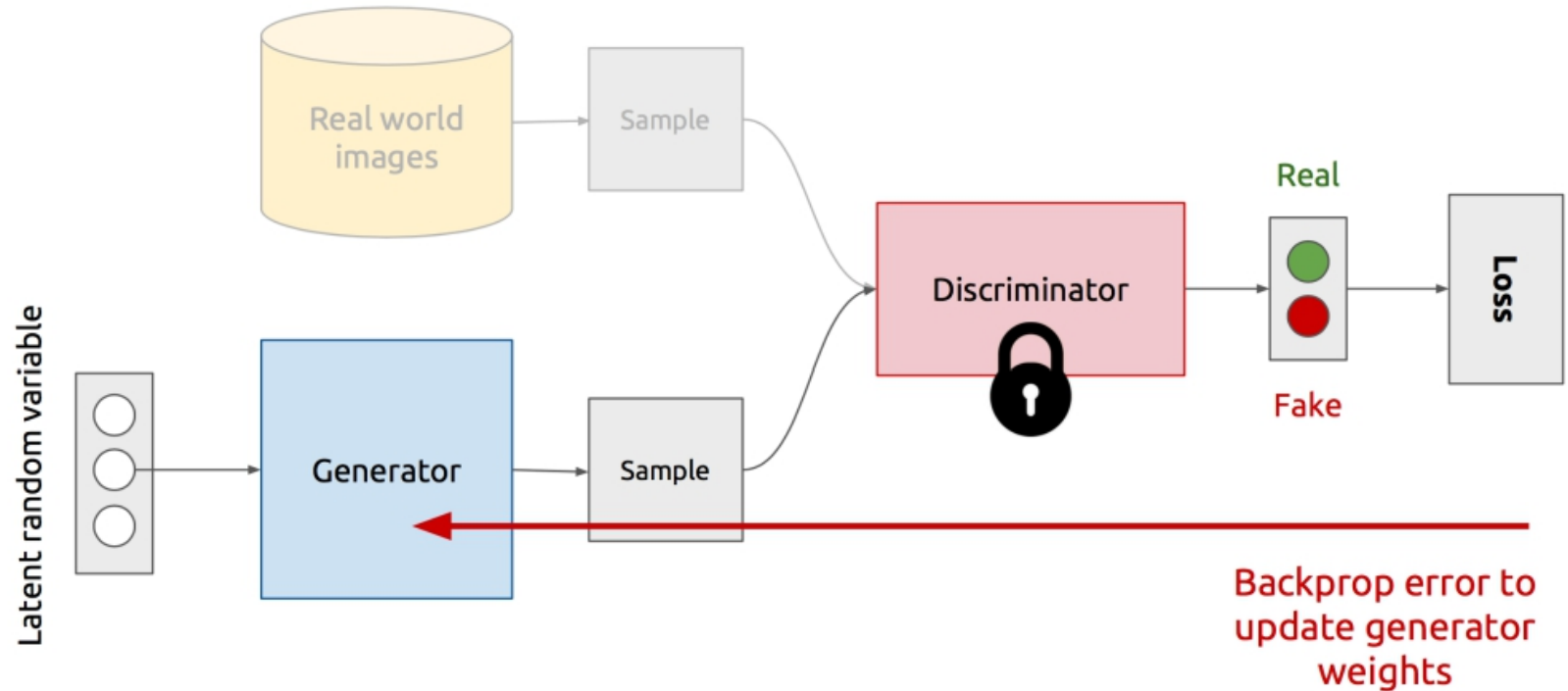
2. Architecture

Discriminator training



2. Architecture

Generator training



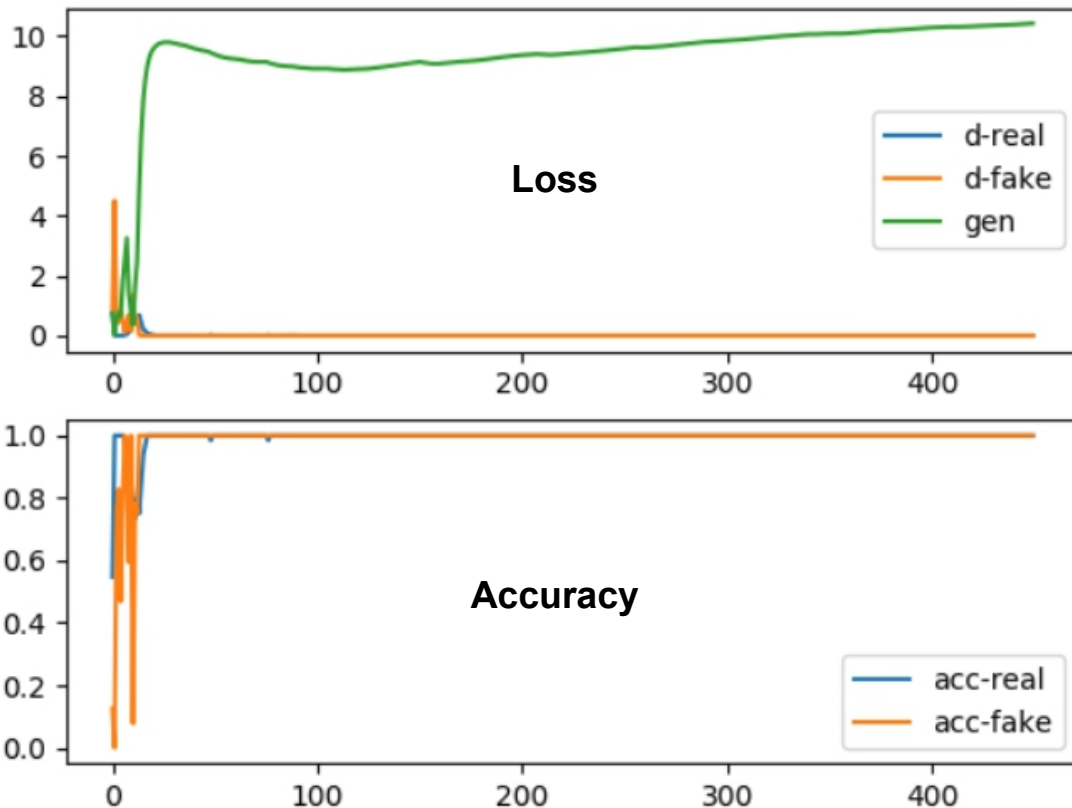
3. Challenges & Improvements

Non-convergence

In GANs architecture:

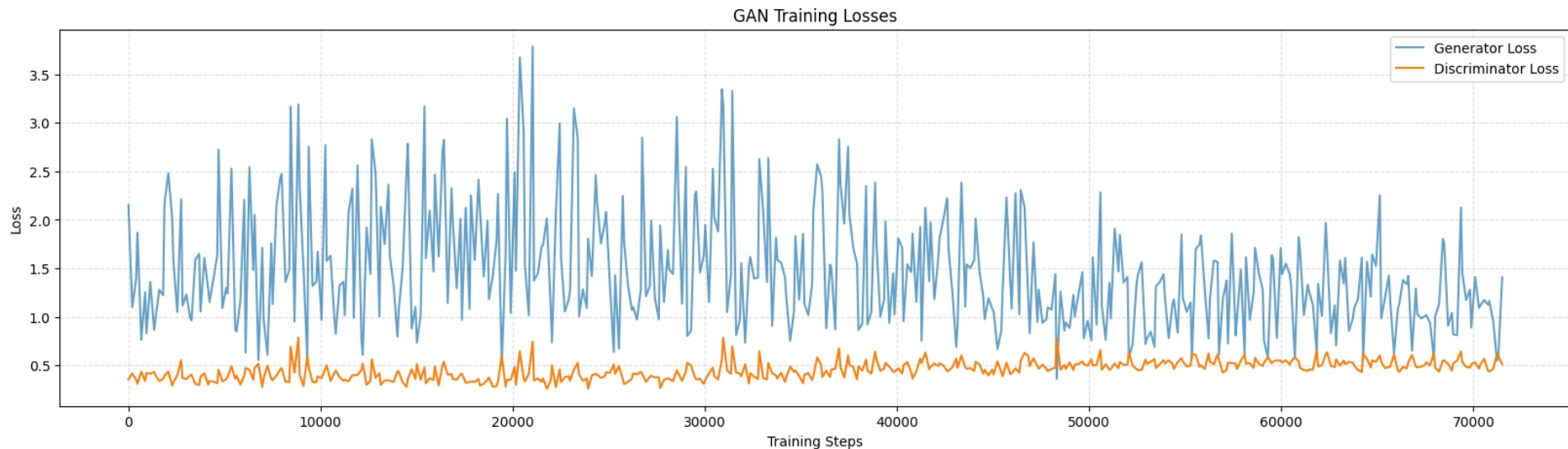
- The D tries to minimize a cross-entropy while the G tries to maximize it.
- When D confidence is high and starts to reject the samples that are produced by G leads to G's gradient vanishes.

Cause Gradient Vanishing



3. Challenges & Improvements

Non-convergence

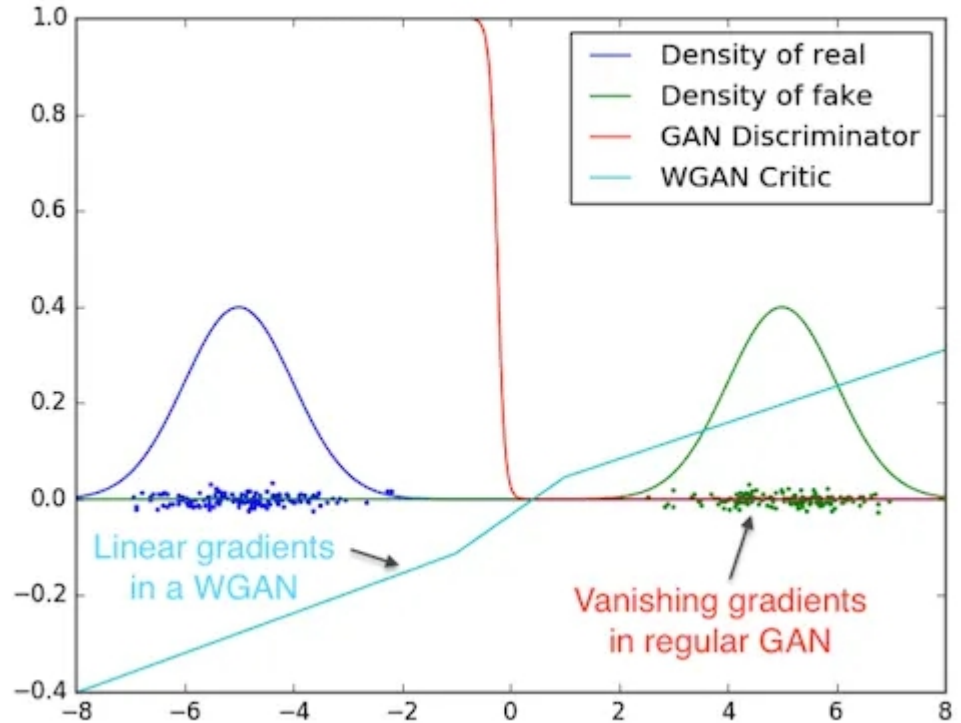


3. Challenges & Improvements

Non-convergence

WGAN Improvement

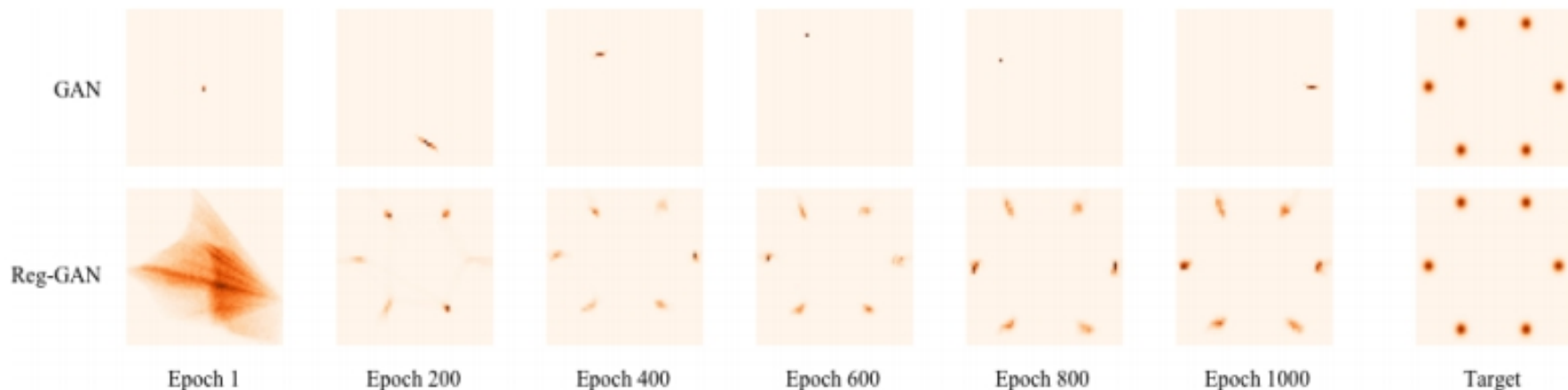
- Use the Earth Mover distance.
- Provides meaningful and continuous gradients even when the real and generated distributions do not overlap.
- Removes the need for carefully balanced updates between G and D.
- **Overall**, it provides smoother convergence and a clearer measure of training progress through the critic loss.



3. Challenges & Improvements

Mode collapse

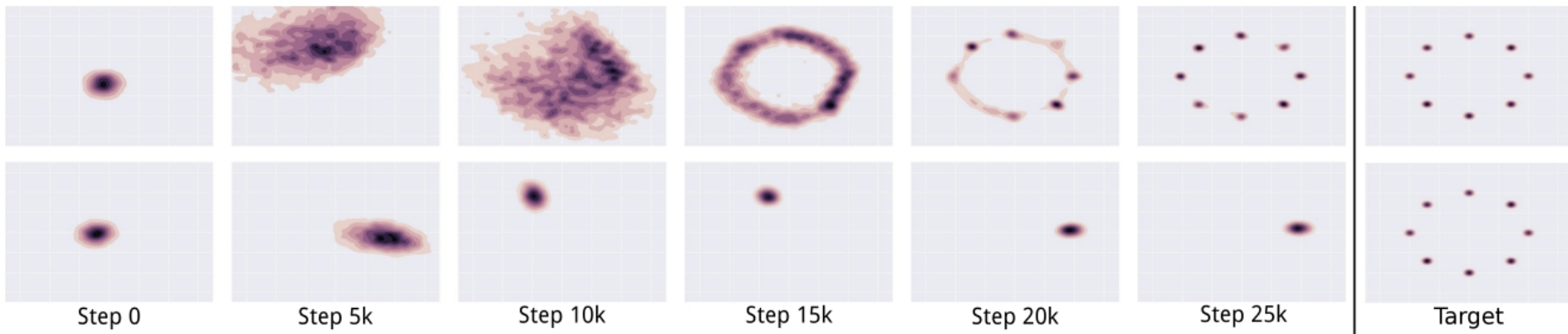
GANs can sometimes suffer from the limitation of generating samples with little representative of the population, which means that, for example, after training a GAN on the MNIST dataset, it may happen that our Generator is unable to generate digits different from digit 0.



3. Challenges & Improvements

Mode collapse Unrolled GAN

- Anticipating how the discriminator would respond to the generator's updates: before updating the generator, they “unroll” several discriminator optimization steps.
- This gives the generator a clearer, more global view of the loss landscape and discourages it from collapsing onto a single mode.



3. Challenges & Improvements

Evaluation Difficulty

- There is no ground truth reference for generated samples: No MSE, RMSE, F1, ...
- Metrics must assess both image quality and diversity, yet common losses do not directly correlate with visual realism.

3. Challenges & Improvements

Evaluation Difficulty

Improvement

- Inception Score: [Pros and Cons of GAN Evaluation Measures](#)
- **Fréchet Inception Distance:** [Pros and Cons of GAN Evaluation Measures](#)
- Kernel Maximum Mean Discrepancy: [An empirical study on evaluation metrics of gans](#)
- 1-Nearest Neighbor: [An empirical study on evaluation metrics of gans](#)
- CrossLID: [Quality Evaluation of GANs Using Cross Local Intrinsic Dimensionality](#)
- Duality Gap: [A Domain Agnostic Measure for Monitoring and Evaluating GANs](#)
- Based on 3rd Models: [On the Evaluation of GANs By Discriminative Models](#)

3. Challenges & Improvements

Fréchet Inception Distance

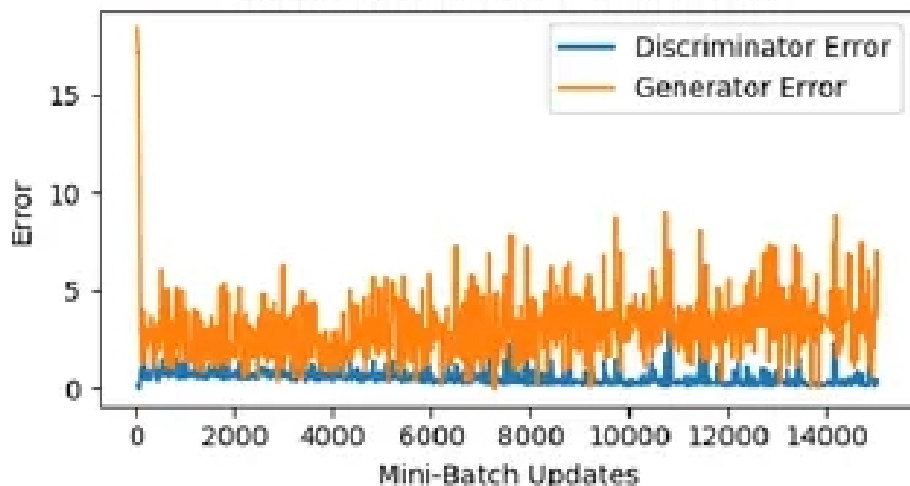
$$FID(P_r, P_g) = ||\mu_r - \mu_g||_2^2 + Tr(\Sigma_r + \Sigma_g - 2(\Sigma_r \Sigma_g)^{1/2})$$

- Where $(\Sigma_r \Sigma_g)^{1/2}$ denotes the matrix square root of the product.
- Compares the distribution of real images and distribution of generated images by a pretrained network (commonly Inception-V3).
- Approximates each distribution by a multivariate Gaussian and computes the Fréchet (Wasserstein-2) distance between the two Gaussians.
- **Lower FID → generated set is closer to the real set in feature statistics (both mean and covariance).**

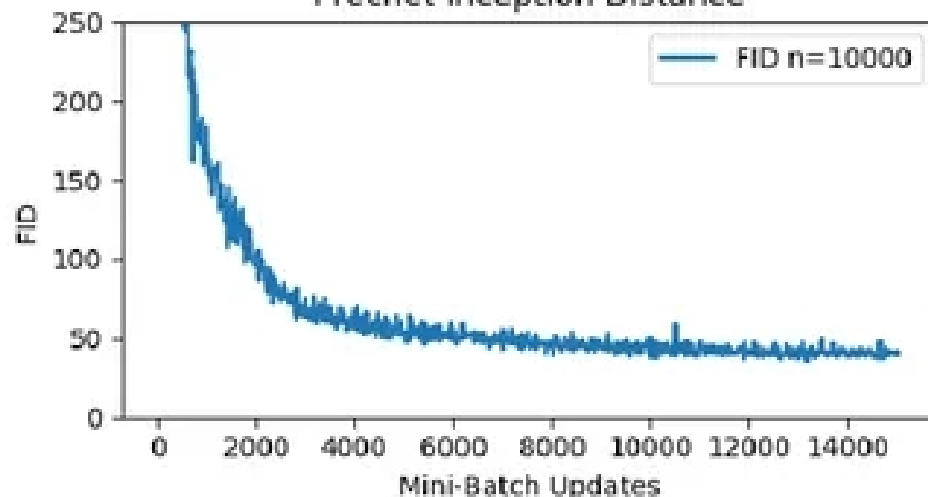
3. Challenges & Improvements

Fréchet Inception Distance

Generator and Discriminator Error



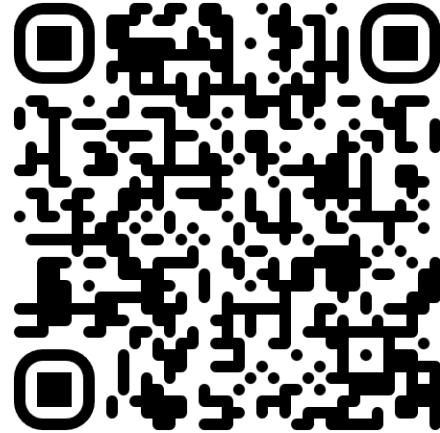
Frechet Inception Distance



5. Demo / Visualization



GAN Implementation



Github Resources

References

- [PyTorch implementations of GANs](#)
- [A list of all named GANs](#)
- [Vanilla GANs paper](#)
- [WGAN paper](#)
- [Fréchet Inception Distance](#)
- [A mix of GAN implementations including progressive growing](#)
- [GAN-play](#)
- [Style GAN](#)