

# Introduction to Probability

## CST Part IA Paper 1

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### 1 Prerequisites and Introduction

#### 1. Combinatorics:

Counting tasks on $n$ objects			
Permutations (sort objects)		Combinations (choose $r$ objects)	
Distinct	Indistinct	Distinct 1 group	Distinct $k$ groups
$n!$	$\frac{n!}{n_1!n_2!\cdots n_r!}$	$\binom{n}{r} = \frac{n!}{r!(n-r)!}$	$\binom{n}{n_1, n_2, \dots, n_k} = \frac{n!}{n_1!n_2!\cdots n_k!}$

Pascal's identity:  $\binom{n}{r} = \binom{n-1}{r-1} + \binom{n-1}{r} \quad (1 \leq r \leq n)$

Binomial theorem:  $(x+y)^n = \sum_{r=0}^n \binom{n}{r} x^r y^{n-r}$

#### 2. Probability axioms:

Axiom 1: For any event  $E$ ,  $0 \leq \mathbb{P}[E] \leq 1$

Axiom 2: Probability of the sample space  $S$  is  $\mathbb{P}[S] = 1$

Axiom 3: If  $E$  and  $F$  are mutually exclusive (i.e.,  $E \cap F = \emptyset$ ), then  $\mathbb{P}[E \cup F] = \mathbb{P}[E] + \mathbb{P}[F]$

In general, for all mutually exclusive events  $E_1, E_2, \dots$ ,

$$\mathbb{P}\left[\bigcup_{i=1}^{\infty} E_i\right] = \sum_{i=1}^{\infty} \mathbb{P}[E_i]$$

3. General inclusion-exclusion principle:  $\mathbb{P}\left[\bigcup_{i=1}^n E_i\right] = \sum_{r=1}^n (-1)^{r+1} \left( \sum_{i_1 < \dots < i_r} \mathbb{P}[E_{i_1} \cap \dots \cap E_{i_r}] \right)$

Case  $n = 2$ :  $\mathbb{P}[E \cup F] = \mathbb{P}[E] + \mathbb{P}[F] - \mathbb{P}[E \cap F]$

#### 4. Union bound (Boole's inequality): For any events $E_1, E_2, \dots, E_n$ ,

$$\mathbb{P}\left[\bigcup_{i=1}^n E_i\right] \leq \sum_{i=1}^n \mathbb{P}[E_i]$$

#### 5. Conditional probability (original and conditioning on event $G$ ):

Chain rule:

$$\mathbb{P}[EF] = \mathbb{P}[E|F]\mathbb{P}[F]$$

$$\mathbb{P}[EF|G] = \mathbb{P}[E|FG]\mathbb{P}[F|G]$$

Multiplication rule:

$$\mathbb{P}[E_1 E_2 \cdots E_n] = \mathbb{P}[E_1] \mathbb{P}[E_2|E_1] \cdots \mathbb{P}[E_n|E_1 \cdots E_{n-1}]$$

$$\mathbb{P}[E_1 E_2 \cdots E_n | G] = \mathbb{P}[E_1|G] \mathbb{P}[E_2|E_1 G] \cdots \mathbb{P}[E_n|E_1 \cdots E_{n-1} G]$$

Independence of  $E$  and  $F$ :

$$\mathbb{P}[EF] = \mathbb{P}[E]\mathbb{P}[F]$$

$$\mathbb{P}[E|F] = \mathbb{P}[E]$$

$$\mathbb{P}[EF|G] = \mathbb{P}[E|G]\mathbb{P}[F|G]$$

$$\mathbb{P}[E|FG] = \mathbb{P}[E|G]$$

Law of total probability:

$$\begin{aligned}\mathbb{P}[E] &= \mathbb{P}[EF] + \mathbb{P}[EF^c] = \mathbb{P}[E|F]\mathbb{P}[F] + \mathbb{P}[E|F^c]\mathbb{P}[F^c] \\ \mathbb{P}[E|G] &= \mathbb{P}[EF|G] + \mathbb{P}[EF^c|G] = \mathbb{P}[E|FG]\mathbb{P}[F|G] + \mathbb{P}[E|F^cG]\mathbb{P}[F^c|G]\end{aligned}$$

In general, for disjoint events  $F_1, F_2, \dots, F_n$  such that  $F_1 \cup \dots \cup F_n = S$ ,

$$\mathbb{P}[E] = \sum_{i=1}^n \mathbb{P}[E|F_i]\mathbb{P}[F_i] \qquad \mathbb{P}[E|G] = \sum_{i=1}^n \mathbb{P}[E|F_iG]\mathbb{P}[F_i|G]$$

Bayes' theorem:

$$\mathbb{P}[F|E] = \frac{\mathbb{P}[E|F]\mathbb{P}[F]}{\mathbb{P}[E]} \qquad \mathbb{P}[F|EG] = \frac{\mathbb{P}[E|FG]\mathbb{P}[F|G]}{\mathbb{P}[E|G]}$$

6. Confusion matrix:

		Actual condition	
		Positive $F$	Negative $F^c$
Predicted condition	Positive $E$	True positive $\mathbb{P}[E F]$	False positive $\mathbb{P}[E F^c]$
	Negative $E^c$	False negative $\mathbb{P}[E^c F]$	True negative $\mathbb{P}[E^c F^c]$

## 2 Random Variables

1. Probability distribution functions:

Discrete random variable  $X$ :

- Probability mass function (PMF):  $p(x)$
- Compute probability:

$$\begin{aligned}\mathbb{P}[X = a] &= p(a) \\ \mathbb{P}[a \leq X \leq b] &= \sum_{x=a}^b p(x)\end{aligned}$$

- Cumulative distribution function (CDF):

$$F_X(a) = \mathbb{P}[X \leq a] = \sum_{x \leq a} p(x)$$

Continuous random variable  $X$ :

- Probability density function (PDF):  $f(x)$
- Compute probability:

$$\begin{aligned}\mathbb{P}[X = a] &= 0 \\ \mathbb{P}[a \leq X \leq b] &= \int_a^b f(x)dx\end{aligned}$$

- Cumulative distribution function (CDF):

$$F_X(a) = \mathbb{P}[X \leq a] = \int_{-\infty}^a f(x)dx$$

2. Expectation:

Discrete random variable  $X$ :

$$\begin{aligned}\mathbb{E}[X] &= \sum_x xp(x) \\ \mathbb{E}[g(X)] &= \sum_x g(x)p(x)\end{aligned}$$

Continuous random variable  $X$ :

$$\begin{aligned}\mathbb{E}[X] &= \int_{-\infty}^{\infty} xf(x)dx \\ \mathbb{E}[g(X)] &= \int_{-\infty}^{\infty} g(x)f(x)dx\end{aligned}$$

Linearity of expectation:  $\mathbb{E}[aX + b] = a\mathbb{E}[X] + b$

Additivity of expectation:  $\mathbb{E}[X + Y] = \mathbb{E}[X] + \mathbb{E}[Y]$

3. Variance:  $\mathbb{V}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2] = \mathbb{E}[X^2] - \mathbb{E}[X]^2$

Scaling of variance:  $\mathbb{V}[aX + b] = a^2\mathbb{V}[X]$

Standard deviation:  $\mathbb{SD}[X] = \sqrt{\mathbb{V}[X]}$

Scaling of standard deviation:  $\mathbb{SD}[aX + b] = |a|\mathbb{SD}[X]$

#### 4. Discrete distributions:

Bernoulli  $\text{Ber}(p)$ : 1 experiment with success probability  $p$

$$\mathbb{P}[X = 1] = p \quad \mathbb{E}[X] = p \quad \mathbb{V}[X] = p(1 - p)$$

Binomial  $\text{Bin}(n, p)$ :  $n$  independent trials with success probability  $p$

$$\mathbb{P}[X = k] = \binom{n}{k} p^k (1 - p)^{n-k} \quad \mathbb{E}[X] = np \quad \mathbb{V}[X] = np(1 - p)$$

Poisson  $\text{Pois}(\lambda)$ : # successes over experiment duration, with success rate  $\lambda = np$

$$\mathbb{P}[X = k] = \frac{\lambda^k}{k!} e^{-\lambda} \quad \mathbb{E}[X] = \lambda \quad \mathbb{V}[X] = \lambda$$

Geometric  $\text{Geo}(p)$ : # independent trials until first success, with success probability  $p$

$$\mathbb{P}[X = n] = (1 - p)^{n-1} p \quad \mathbb{E}[X] = \frac{1}{p} \quad \mathbb{V}[X] = \frac{1 - p}{p^2}$$

Negative binomial  $\text{NegBin}(r, p)$ : # independent trials until  $r$  success, with success probability  $p$

$$\mathbb{P}[X = n] = \binom{n-1}{r-1} (1 - p)^{n-r} p^r \quad \mathbb{E}[X] = \frac{r}{p} \quad \mathbb{V}[X] = \frac{r(1 - p)}{p^2}$$

Hypergeometric  $\text{Hyp}(N, n, m)$ : # objects with a feature in a sample of size  $n$  (without replacement) from a population of size  $N$  that contains  $m$  items with the feature

$$\mathbb{P}[X = n] = \frac{\binom{m}{i} \binom{N-m}{n-i}}{\binom{N}{n}} \quad \mathbb{E}[X] = n \frac{m}{N} \quad \mathbb{V}[X] = n \frac{m}{N} \left(1 - \frac{m}{N}\right) \left(1 - \frac{n-1}{N-1}\right)$$

#### 5. Continuous distributions:

Uniform  $\text{Uni}(\alpha, \beta)$ : equal probability within range  $[\alpha, \beta]$

$$\begin{aligned} \text{PDF: } f(x) &= \begin{cases} \frac{1}{\beta - \alpha} & \text{when } \alpha \leq x \leq \beta \\ 0 & \text{otherwise} \end{cases} & \text{CDF: } F(x) &= \begin{cases} 0 & \text{when } x < \alpha \\ \frac{x - \alpha}{\beta - \alpha} & \text{when } \alpha \leq x \leq \beta \\ 1 & \text{when } x > \beta \end{cases} \\ \mathbb{E}[X] &= \frac{\alpha + \beta}{2} & \mathbb{V}[X] &= \frac{(\beta - \alpha)^2}{12} \end{aligned}$$

Exponential  $\text{Exp}(\lambda)$ : time until first success occurs, with success rate  $\lambda$

$$\begin{aligned} \text{PDF: } f(x) &= \begin{cases} \lambda e^{-\lambda x} & \text{when } x \geq 0 \\ 0 & \text{otherwise} \end{cases} & \text{CDF: } F(x) &= 1 - e^{-\lambda x} \\ \mathbb{E}[X] &= \frac{1}{\lambda} & \mathbb{V}[X] &= \frac{1}{\lambda^2} \end{aligned}$$

Normal (Gaussian)  $\mathcal{N}(\mu, \sigma^2)$ : mean  $\mu$ , variance  $\sigma^2$

$$\begin{aligned} \text{PDF: } f(x) &= \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} & \text{CDF: } F(x) &= \Phi\left(\frac{x - \mu}{\sigma}\right) \\ \mathbb{E}[X] &= \mu & \mathbb{V}[X] &= \sigma^2 \\ X \sim \mathcal{N}(\mu, \sigma^2) &\implies aX + b \sim \mathcal{N}(a\mu + b, a^2\sigma^2) \\ X \sim \mathcal{N}(\mu_X, \sigma_X^2), Y \sim \mathcal{N}(\mu_Y, \sigma_Y^2) &\implies X + Y \sim \mathcal{N}(\mu_X + \mu_Y, \sigma_X^2 + \sigma_Y^2) \end{aligned}$$

6. Continuity correction:

Discrete		Continuous
$\mathbb{P}[X = a]$	$\approx$	$\mathbb{P}[a - 0.5 \leq X \leq a + 0.5]$
$\mathbb{P}[X > a]$	$\approx$	$\mathbb{P}[X \geq a + 0.5]$
$\mathbb{P}[X \geq a]$	$\approx$	$\mathbb{P}[X \geq a - 0.5]$
$\mathbb{P}[X < a]$	$\approx$	$\mathbb{P}[X \leq a - 0.5]$
$\mathbb{P}[X \leq a]$	$\approx$	$\mathbb{P}[X \leq a + 0.5]$

7. Joint probability mass function (for discrete RVs):  $p_{X,Y}(a, b) = \mathbb{P}[X = a, Y = b]$

Joint distribution function (for discrete or continuous RVs):  $F_{X,Y}(a, b) = \mathbb{P}[X \leq a, Y \leq b]$

Joint probability density  $f$  and joint continuous distribution  $F$  (for continuous RVs):

$$F(a, b) = \int_{-\infty}^a \int_{-\infty}^b f(x, y) dx dy \quad f(x, y) = \frac{\partial^2}{\partial x \partial y} F(x, y)$$

$$\mathbb{P}[a_1 \leq X \leq b_1, a_2 \leq Y \leq b_2] = \int_{a_1}^{b_1} \int_{a_2}^{b_2} f(x, y) dx dy$$

Marginal distribution:  $F_X(a) = \mathbb{P}[X \leq a] = \lim_{b \rightarrow \infty} F_{X,Y}(a, b)$

8. Covariance:  $\text{Cov}[X, Y] = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y]$

Covariance of linear combinations:

$$\begin{aligned} \text{Cov}[X, a] &= 0 & \text{Cov}[X, X] &= \mathbb{V}[X] \\ \text{Cov}[aX, bY] &= ab\text{Cov}[X, Y] & \text{Cov}[X + a, Y + b] &= \text{Cov}[X, Y] \end{aligned}$$

Variance of sum:  $\mathbb{V}[X + Y] = \mathbb{V}[X] + \mathbb{V}[Y] + 2\text{Cov}[X, Y]$

In general, for any random variables  $X_1, X_2, \dots, X_n$ :

$$\mathbb{V}\left[\sum_{i=1}^n X_i\right] = \sum_{i=1}^n \mathbb{V}[X_i] + 2 \sum_{i=1}^{n-1} \sum_{j=i+1}^n \text{Cov}[X_i, X_j]$$

Correlation coefficient:  $\rho(X, Y) = \frac{\text{Cov}[X, Y]}{\sqrt{\mathbb{V}[X]\mathbb{V}[Y]}} \in [-1, 1]$  ( $\rho(X, Y) = 0$  if  $\mathbb{V}[X] = 0$  or  $\mathbb{V}[Y] = 0$ )

Scaling-invariance of correlation coefficient:  $\rho(aX, bY) = \rho(X, Y)$

### 3 Moments and Limit Theorems

1. Markov's inequality: for any non-negative random variable  $X$  with finite  $\mathbb{E}[X]$ , for any  $a > 0$ ,

$$\mathbb{P}[X \geq a] \leq \frac{\mathbb{E}[X]}{a}$$

Let  $a = \delta \cdot \mathbb{E}[X]$  (where  $\delta > 0$ ), then the inequality can be rewritten as

$$\mathbb{P}[X \geq \delta \cdot \mathbb{E}[X]] \leq \frac{1}{\delta}$$

2. Chebyshev's inequality: for any random variable  $X$  with finite  $\mathbb{E}[X]$  and  $\mathbb{V}[X]$ , for any  $a > 0$ ,

$$\mathbb{P}[|X - \mathbb{E}[X]| \geq a] \leq \frac{\mathbb{V}[X]}{a^2}$$

Let  $a = \sqrt{\delta \cdot \mathbb{V}[X]}$  (where  $\delta > 0$ ), then the inequality can be rewritten as

$$\mathbb{P}\left[|X - \mathbb{E}[X]| \geq \sqrt{\delta \cdot \mathbb{V}[X]}\right] \leq \frac{1}{\delta}$$

3. Weak law of large numbers: let  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$ , where  $X_i$ 's are independent and identically distributed (i.i.d.) with finite expectation  $\mu$  and finite variance  $\sigma^2$ . Then, for any  $\epsilon > 0$ ,

$$\lim_{n \rightarrow \infty} \mathbb{P} [|\bar{X}_n - \mu| > \epsilon] = 0$$

Strong law of large numbers:

$$\mathbb{P} \left[ \lim_{n \rightarrow \infty} \bar{X}_n = \mu \right] = 1$$

4. Central limit theorem: let  $X_1, X_2, \dots, X_n$  be any sequence of i.i.d. random variables with finite expectation  $\mu$  and finite variance  $\sigma^2$ . Let

$$Z_n = \sqrt{n} \cdot \frac{\bar{X}_n - \mu}{\sigma} = \frac{1}{\sigma \sqrt{n}} \left( \sum_{i=1}^n X_i - n\mu \right)$$

Then for any number  $a \in \mathbb{R}$ , it holds that

$$\lim_{n \rightarrow \infty} F_{Z_n}(a) = \Phi(a) = \frac{1}{2\pi} \int_{-\infty}^a e^{-\frac{x^2}{2}} dx$$

where  $\Phi$  is the CDF of the standard normal distribution  $\mathcal{N}(0, 1)$ .

## 4 Applications and Statistics

1. Estimators:

An estimator  $T$  is an unbiased estimator for the parameter  $\theta$  if  $\mathbb{E}[T] = \theta$  irrespective of the value  $\theta$ .

The bias of an estimator  $T$  is defined as  $\mathbb{E}[T] - \theta = \mathbb{E}[T - \theta]$ .

2. Unbiased estimator for the expectation and variance:

Let  $X_1, X_2, \dots, X_n$  be identically distributed samples from a distribution with finite expectation  $\mu$  and finite variance  $\sigma^2$ . Then

- $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$  is an unbiased estimator for  $\mu$ ; and
- $S_n = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}_n)^2$  is an unbiased estimator for  $\sigma^2$ .

3. Bias-variance decomposition of the mean squared error:

$$\text{MSE}[T] = \mathbb{E}[(T - \theta)^2] = \underbrace{(\mathbb{E}[T] - \theta)^2}_{\text{Bias}^2} + \underbrace{\mathbb{V}[T]}_{\text{Variance}}$$

- Estimator  $T_1$  is better than  $T_2$  if  $\text{MSE}[T_1] < \text{MSE}[T_2]$ ;
  - If  $T_1$  and  $T_2$  are both unbiased, then  $T_1$  is better than  $T_2$  iff  $\mathbb{V}[T_1] < \mathbb{V}[T_2]$ .
4. Jensen's inequality: for any random variable  $X$ , and any convex function  $g : \mathbb{R} \rightarrow \mathbb{R}$  (i.e., for all  $\lambda$ ,  $a$  and  $b$ ,  $\lambda g(a) + (1 - \lambda)g(b) \geq g(\lambda a + (1 - \lambda)b)$ ), we have

$$\mathbb{E}[g(X)] \geq g(\mathbb{E}[X])$$

If  $g$  is strictly convex and  $X$  is not constant, then the inequality is strict.

5. Expected number of samples until first collision:  $\sqrt{\frac{\pi N}{2}} - \frac{1}{3} + O(\frac{1}{\sqrt{N}})$

6. The secretary problem (maximise the probability of stopping at the best of  $n$  candidates):

Optimal strategy: reject the first  $x - 1$  candidates, then accept the first candidate  $i \geq x$  that is better than all candidates before

$$\text{Probability of success: } \frac{x-1}{n} \sum_{i=x}^n \frac{1}{i-1} \approx \frac{x}{n} \ln \left( \frac{n}{x} \right)$$

$$\text{Optimal } x = \frac{n}{e} \implies \text{maximum success probability: } \frac{1}{e}$$