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THAPAR INSTITUTE
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Mechanics of Machines

UME 306

Module - 1
Lecture - 5

Instructional objective

- Solved Example
- Practice Exercise

Examples

1. Find the DOF of the system as shown in figure:

Sol:

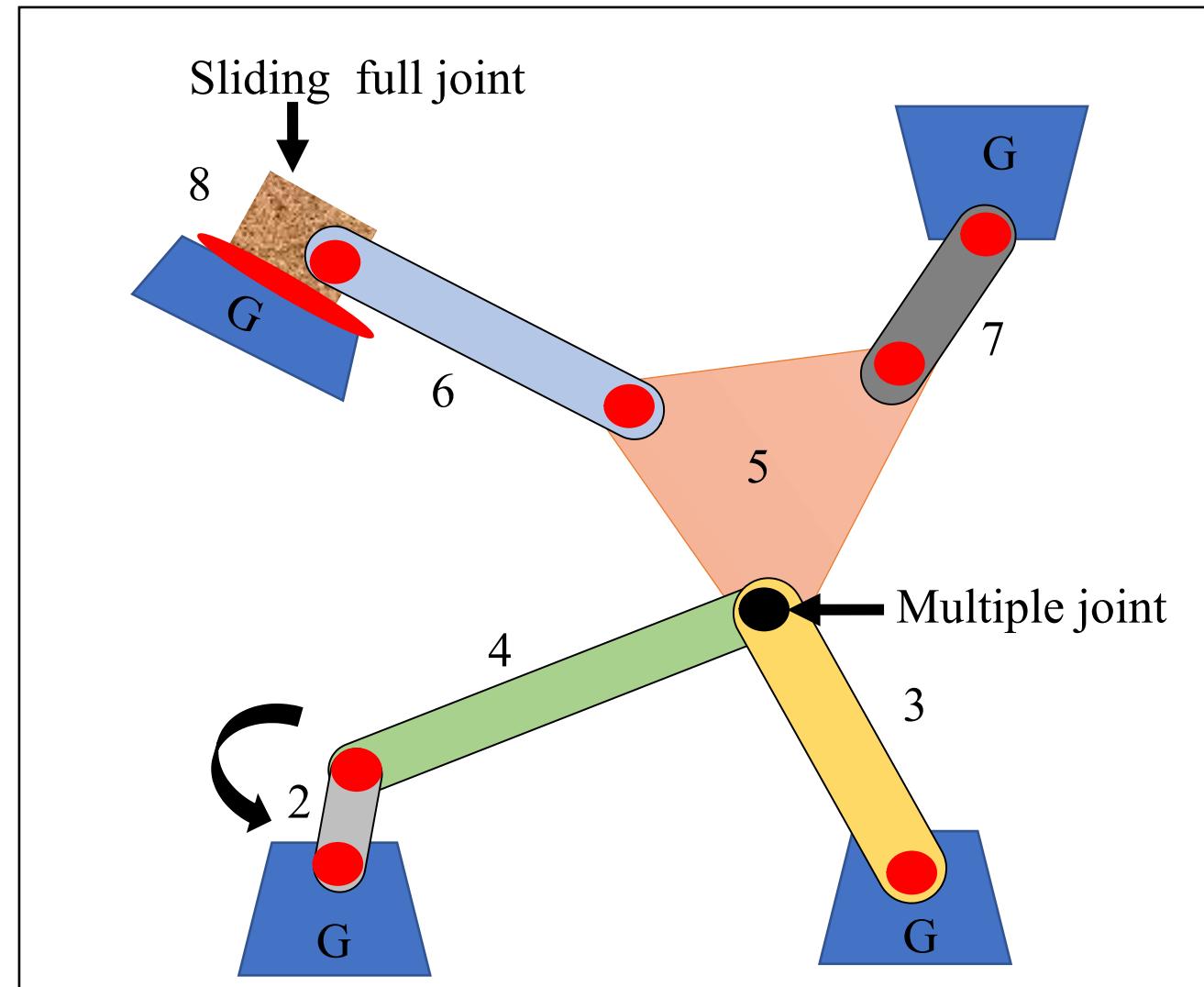
$$M = 3(L - 1) - 2J - h$$

$$L = 8$$

$$J = 10$$

$$h = 0$$

$$\text{DOF} = 1$$



2. Find the DOF of the system as shown in figure:

Sol:

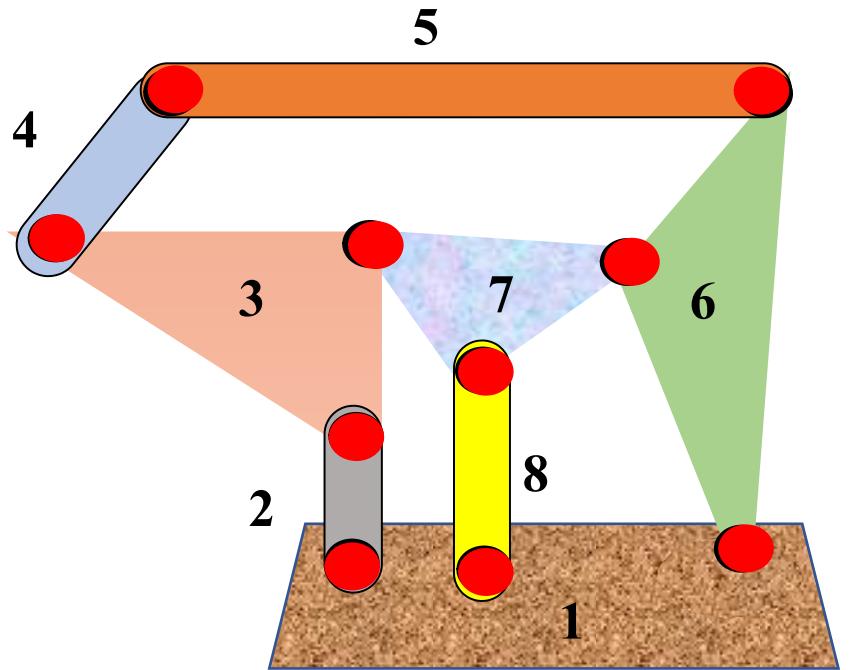
$$M = 3(L - 1) - 2J - h$$

$$L = 8$$

$$J = 10$$

$$h = 0$$

$$\text{DOF} = 1$$



3. Find the DOF of the system as shown in figure:

Sol:

$$M = 3(L - 1) - 2J - h$$

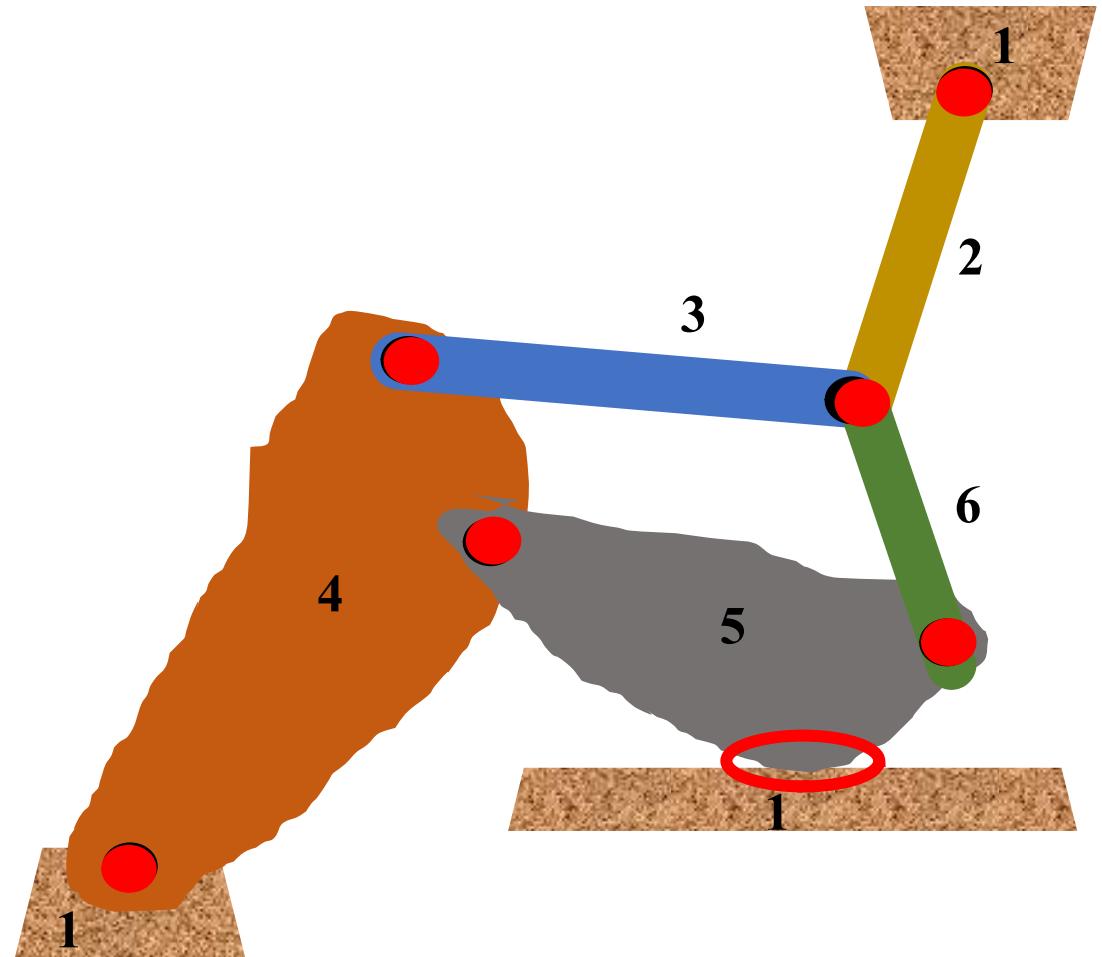
$$L = 6$$

$$J = 7$$

$$h = ?$$

$$h = 1$$

$$\text{DOF} = 0$$



4. Find the DOF of the system as shown in figure:

Sol:

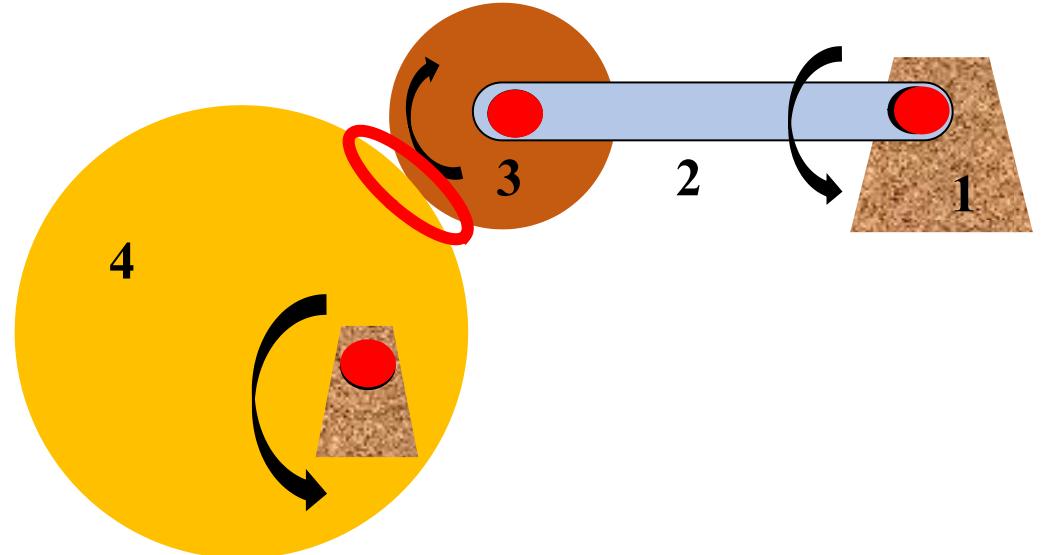
$$M = 3(L - 1) - 2J - h$$

$$L = 4$$

$$J = 3$$

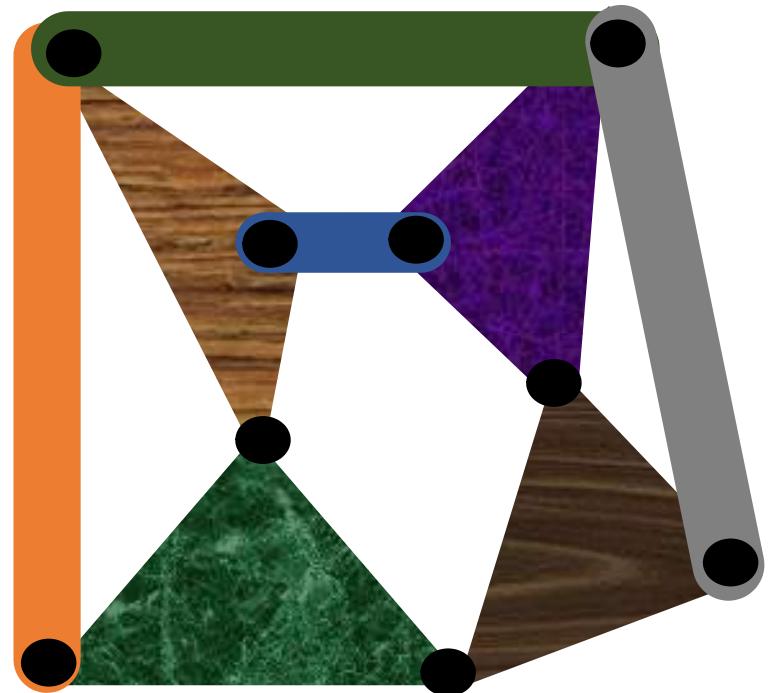
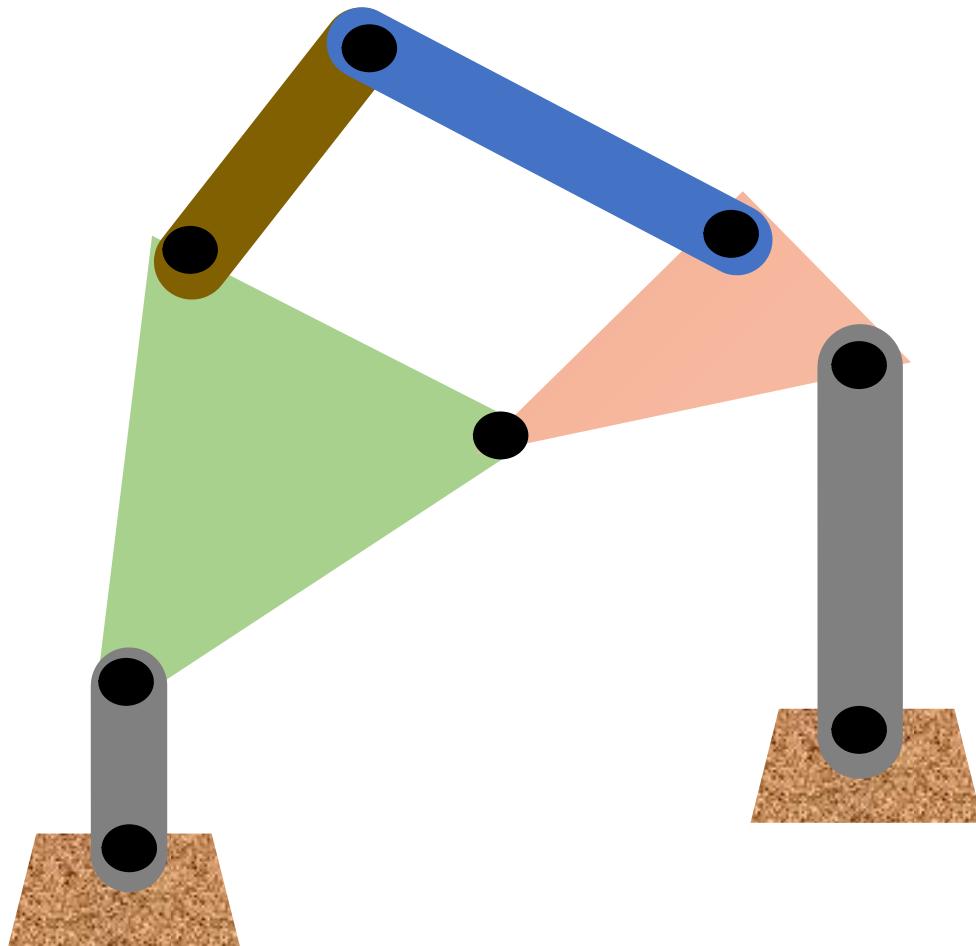
$$h = 1$$

$$\text{DOF} = 2$$

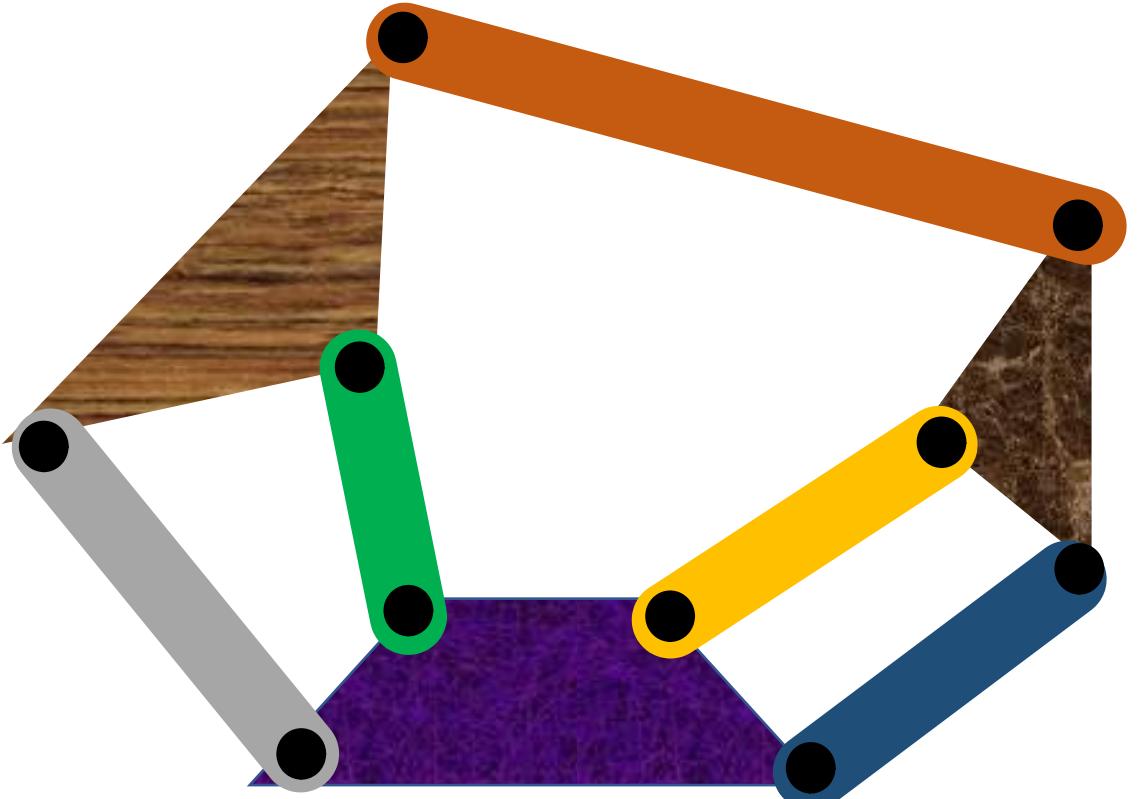


Practice Exercise :

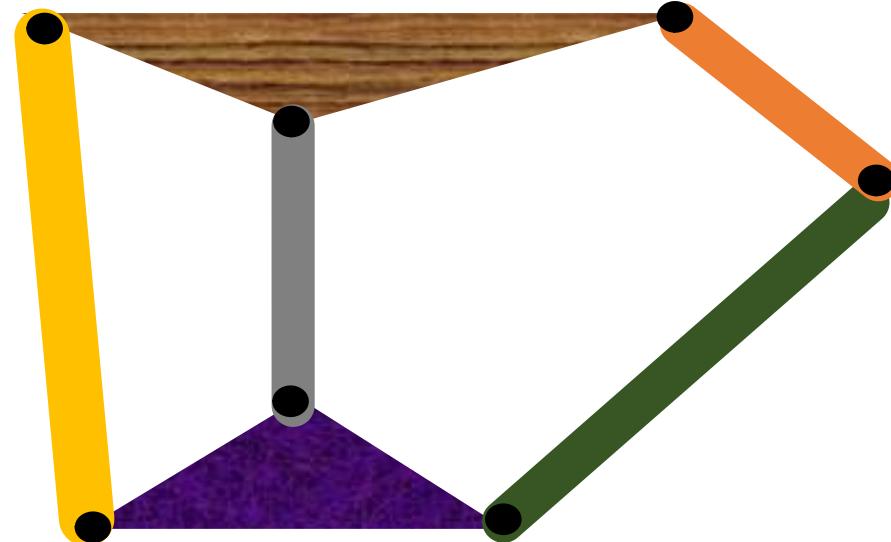
Find the DOF of the system as shown in figures:



Find the DOF of the system as shown in figures:



8 Bar Mechanism



6 Bar Mechanism

Reference Books

1. *Uicker, John Joseph, Gordon R. Pennock, and Joseph Edward Shigley. Theory of machines and mechanisms. Vol. 1. New York: Oxford University Press.*
2. *Norton, Robert L. Design of machinery: an introduction to the synthesis and analysis of mechanisms and machines. Boston: McGraw-Hill Higher Education.*
3. *Rattan, Sarjit S. Theory of machines. Tata McGraw-Hill Education.*
4. *Vinogradov, Oleg. Fundamentals of kinematics and dynamics of machines and mechanisms. CRC press.*
5. *Simón Mata, Antonio, et al. Fundamentals of machine theory and mechanisms. Springer.*

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