Nvis 3302ARD RoboCar

Physical Configuration

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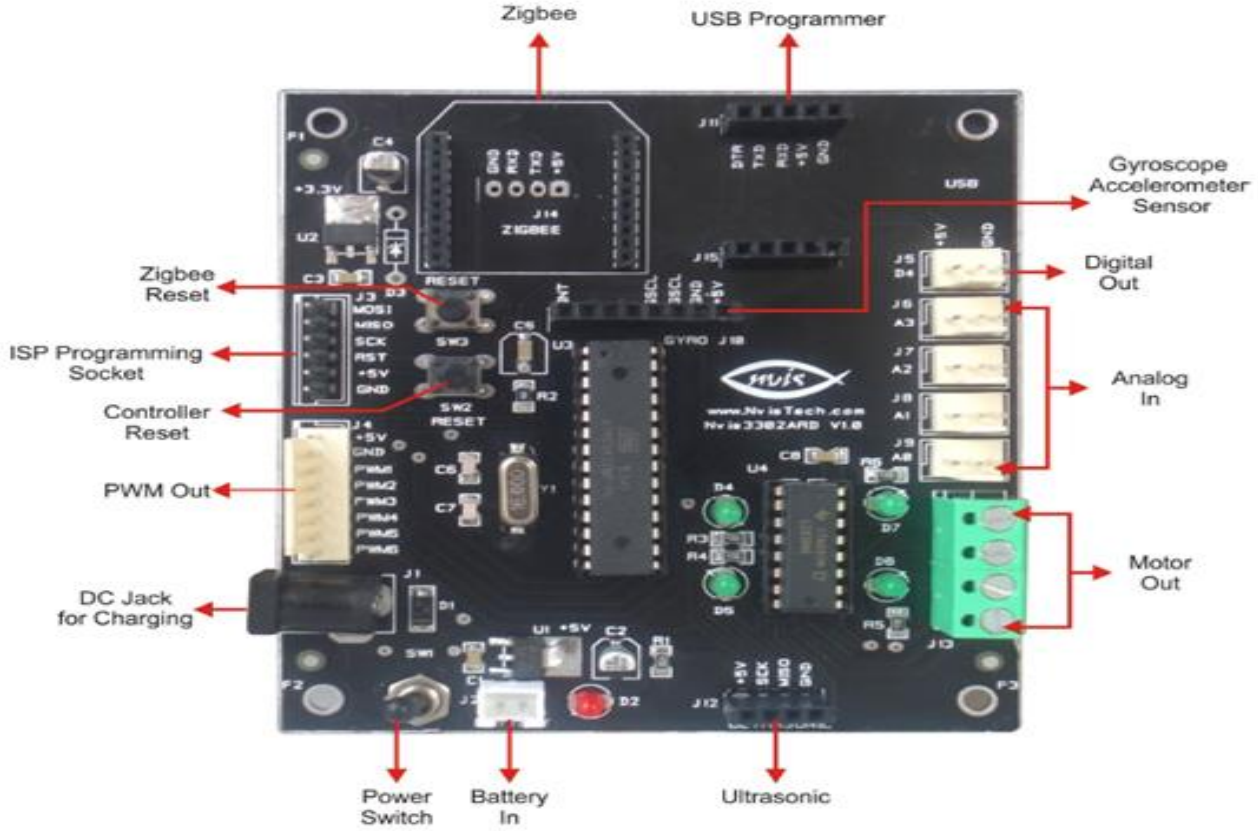
Basic Configuration model

Board configuration and part name



DC Motor

- A motor is a machine that converts electrical energy into mechanical energy(rotation).
- DC motor we have only + and – leads.
- By reversing the polarity, the DC motor will move in the opposite direction.

Configuration Table of Pins:

J13-Phonex Pin Number	Port pin	Arduino Pin	Description
1	PD5	Digital 5	Right Motor Plus
2	PD6	Digital 6	Right Motor Minus
3	PD7	Digital 7	Left Motor Plus
4	PB0	Digital 8	Left Motor Minus

Basic functions of Robocar

- Forward
- Backward
- Right Move
- Left Move
- Clockwise rotation
- Anticlockwise rotation
- Stop

Arduino code for Motor Movement

```
void setup()
{
PinMode(5,OUTPUT);
PinMode(6,OUTPUT);
PinMode(7,OUTPUT);
PinMode(8,OUTPUT);
}
void loop()
{                                          // Forward direction
digitialWrite(5,HIGH);
digitialWrite(6,LOW);
digitialWrite(7,LOW);
digitialWrite(8,HIGH);
}
```

```
//Backward

digitialWrite(5,LOW);
digitialWrite(6,HIGH);
digitialWrite(7,HIGH);
digitialWrite(8, LOW);


// Right Move

digitialWrite(5,LOW);
digitialWrite(6,LOW);
digitialWrite(7,HIGH);
digitialWrite(8, HIGH);
```

```
//  Left

digitalWrite(5,HIGH);
digitalWrite(6,HIGH);
digitalWrite(7,LOW);
digitalWrite(8, LOW);

//Clockwise rotation

digitalWrite(5,HIGH);
digitalWrite(6,LOW);
digitalWrite(7,LOW);
digitalWrite(8, LOW);
```

```
// Anticlock-wise rotation

 digitialWrite(5,LOW);
 digitialWrite(6,LOW);
 digitialWrite(7,LOW);
 digitialWrite(8, HIGH);

 //Stop

  digitialWrite(5,LOW);
  digitialWrite(6,LOW);
  digitialWrite(7,LOW);
  digitialWrite(8, LOW);
```

Thanks