

The Tennis Racquet Theorem

MA 203

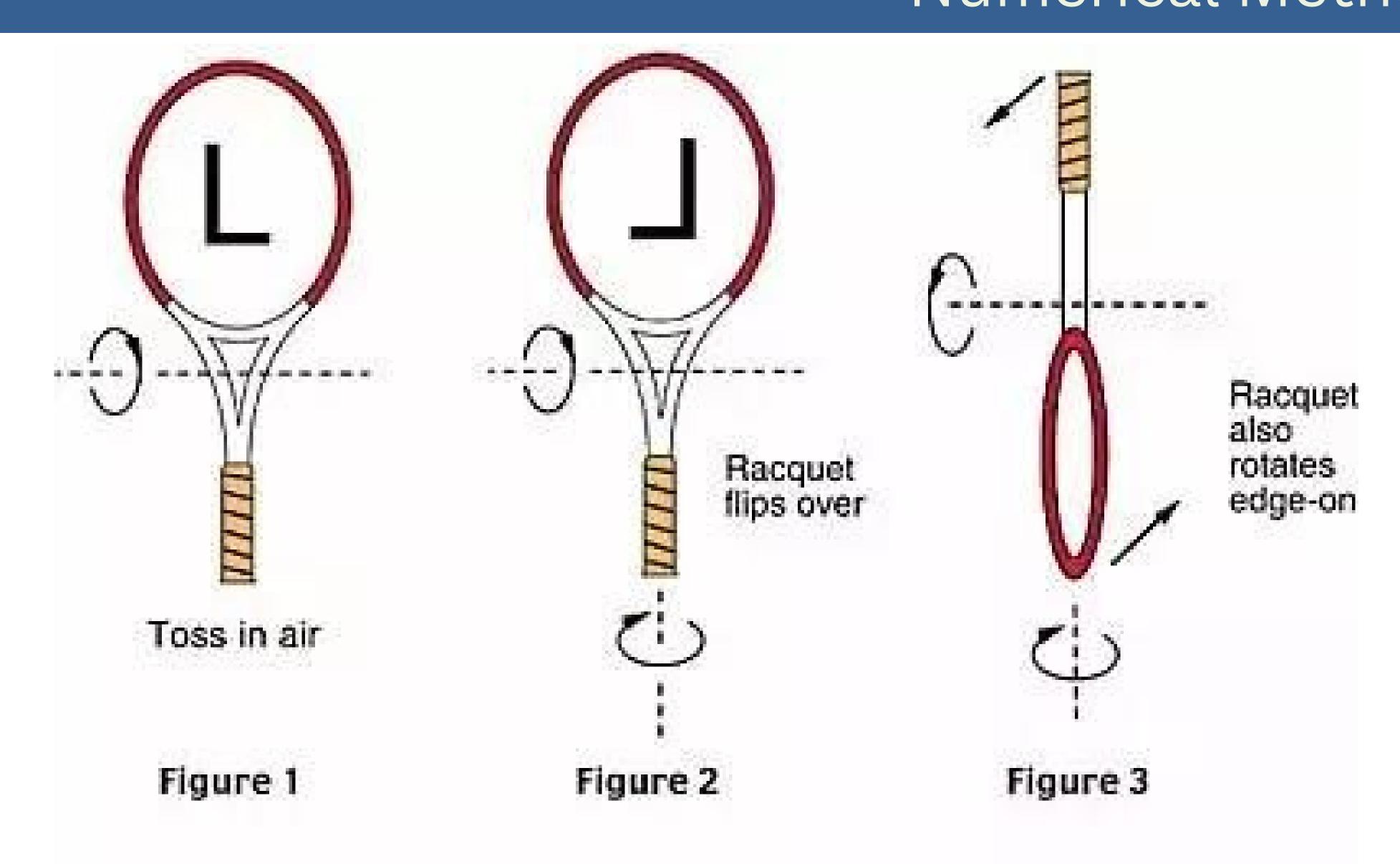
Numerical Methods

Introduction

There lies a mystery, something that defies the most fundamental laws of physics. An object, when rotated in space, *undisturbed*, about a particular axis shows strange behaviour, Whereas, about a different axis, it's normal.

The answer is:

"Tennis Racquet Theorem"



https://www.quora.com/What-is-Tennis-racket-theorem-Djanibekov-effect

Equations

Tennis racquet theorem can be understood using Euler's equations, as listed below.

$$I1 \dot{\omega}1 = -(I3 - I2) \omega 3 \omega 2$$

 $I2 \dot{\omega}2 = -(I1 - I3) \omega 1 \omega 3$
 $I3 \dot{\omega}3 = -(I2 - I1) \omega 2 \omega 1$

*Assume | 11<|2<|3.

Unstable Rotation about 12:

When rotating about 12

$$I1 \dot{\omega}1 = -(I3 - I2) \omega 3 \omega 2$$

 $I3 \dot{\omega}3 = -(I2 - I1) \omega 2 \omega 1$

$\ddot{\omega}$ 21 = (positive quantity) ω 1

This means that $\omega 1$ is not opposed, it will **increase**. Even a small disturbance about the other axis can make the object "flip".

Methods Used

- 1. Euler's Method
- 2. R-k Methods

Results

The following results were obtained when we rotated the object about 13. Rotational Motion of a Tennis Racquet (Runge-Kutta 4) Rotational Motion of a Tennis Racquet (Euler's Method) 1.0 0.8 Angular Velocity Axis 1 Angular Velocity Axis 1 Angular Velocity Axis 2 Angular Velocity Axis 2 Angular Velocity Axis 3 Angular Velocity Axis 3 0.2 0.0 But, what happens when rotated about 12? Rotational Motion of a Tennis Racquet (Euler's Method) Rotational Motion of a Tennis Racquet (Runge-Kutta 4) Angular Velocity Axis 1 Angular Velocity Axis 3 0.5 -0.5Angular Velocity Axis 1 Angular Velocity Axis 2 Angular Velocity Axis 3 -1.0**Object will Flip!**