$W_1 = (transition matrix)$ Neural Networks: 1 Wil di Wil di  $W_{I}^{T} = (5 \times 4)$ [ W1, W2, W3, W4]  $\begin{array}{c|c} & & & & \\ & &$ W12 W2 W32 W42 W13 W23 W33 W45 W14 W24 W39 W44 [ W15 W25 W35 W45] Wij is the weight in input layer and in input layer and 1 (d) the node j in the Hidden-layer. input layer batch size = 32 # of samples (imputs) How do we define the shape of input? -> [botch\_size, do, di] -> [batch\_size, (do,)]

Activation Function  $h_i = g(a_i) = g(W_i X + b_i)$ Could be Rely, tanh, Sigmoid and linear. Why do ne need activation? Ans: convert linear > nonlinear Recall:

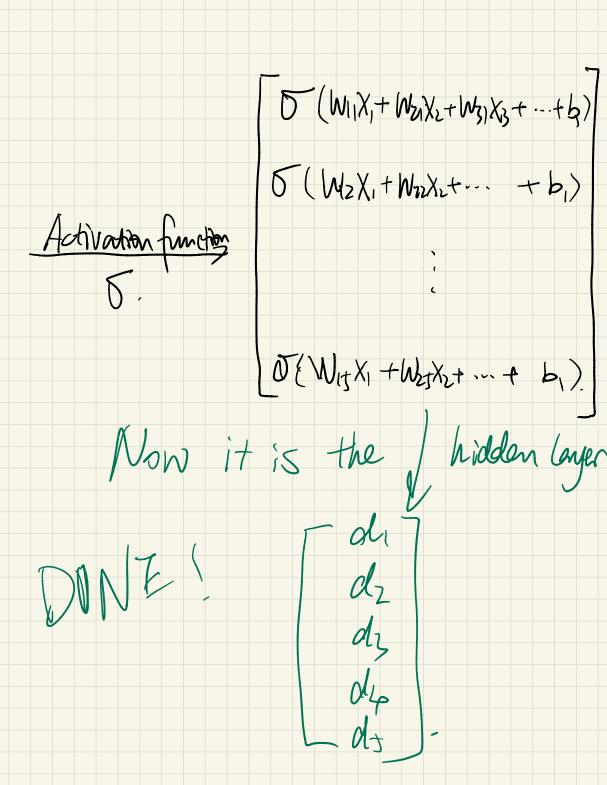
Input layer

[X]

WIIXI+WZIXI+WXIXS+W4X4+b] (4x1) | X2 | W X / b3 W12X1 + W22X2 + W2X3 + W42X4+61 Linear W13X1 + W23X2+ W33A37

Transform W14X1 + W24X2+ W34X3+ ...+61

- arison W15X1 + ... + 61 X X4



Model = Sequential (L 1) Sequential is the function we borrow from tf-keras to build our model 2) Dense -> build a layer \* input\_shape=(1,) 7) (Why?) Summery: look at the parameters: