DATA STRUCTURE TEST 03

Algorithmo Vistroot Mode, recorse thro right subtree.

Binary Tree Traversal

- Pre-order · IN OV DED _post order

Lab Section 13 4-5:50pm Sage 3101 TA: Matthew mentors: Aditya & Kajsa & Tyler Н.

= inData.begin();

```
reverse(std::string& str){
   if(str.length()>1){
        reverse(str,0,str.length()-1);
void reverse(std::string& str, int i, int j){
   if(i>j){
        return:
   char c = str[i]:
   str[i] = str[j];
str[j] = c;
   reverse(str,i+1,j-1);
```

Pre-order(NLR) - First node is vout C4,2,4,5,3,6,7)

```
if (root != NULL) {
  cout<<root->data<<" ";
  preorder(root->left);
  preorder(root->right);
```

(4,2,5,1,6,3,7)

Post-order (LRW) (4,5,7,6,7,3,1) Algorithm! At each node first go lett, vight, then Chose that here void postorder (struct node *root)

<u>map <mark>find</mark>()</u> Returns an iterator to the element with key-value 'g' in the map if found, else <u>begin()</u> – Returns an iterator to the first element in the map. $\operatorname{end}()$ – Returns an iterator to the theoretical element that follows the last element in the map. size() - Returns the number of elements in the map. $\underline{\mathsf{max}\ \mathsf{size}()}$ – Returns the maximum number of elements that the map can hold. <u>empty()</u> - Returns whether the map is empty.

pair insert (keyvalue, mapvalue) - Adds a new element to the map. <u>erase (iterator position)</u> - Removes the element at the position pointed by the iterator.

<u>erase(const g)</u> - Removes the key-value 'g' from the map.

ear() – Removes all the elements from the map

single element (1) pair<iterator, bool> insert (const value type& val); iterator insert (iterator position, const value type& val);

```
void findBoxes(const DonutBox& box, DonutBox& current_box, std::vector<DonutBox>& boxes){
   if(box.empty()){
       boxes.push_back(current_box);
   for(unsigned int i=0; i<box.size(); i++){</pre>
        DonutBox tmp_box = box;
        current_box.push_back(box[i]);
        tmp_box.erase(tmp_box.begin()+i);
        findBoxes(tmp_box, current_box, boxes);
        current_box.pop_back();
void findBoxes(const DonutBox& box, std::vector<DonutBox>& boxes){
   DonutBox tmp;
   findBoxes(box, tmp, boxes);
```

```
void RecursiveFor(int i,int max){
  if(i<max){
    x();
    RecursiveFor(i+1,max);
 }
```

Treme, we

```
if (root != NULL) {
           inorder(root->left);
           cout << root -> data << " ";
           inorder(root->right);
Algorithmi. recovse down left tree,
then node, then right
```

```
if (root != NULL) {
   postorder (root->left);
   postorder (root->right);
   cout << root -> data << " ";
```

oid inorder(struct node *root)

```
Solution:
 std::set<int> s3:
 for (std::set<int>::iterator it = s1.begin(); it != s1.end(); ++it) {
    std::set<int>::iterator it2 = s2.find(*it);
    if (it2 != s2.end()) {
     s3.insert(*it);
     s2.erase(it2):
```

If set 1 has k elements and set 2 has n elements, what is the order of your me Solution: O(k (log n + log k))

```
bool insert(int val, TreeNode*& p, TreeNode* first, TreeNode* prev = NULL){
   //we've reached a leaf node
   if(!p){
       //set p to a new node (passed by reference, so parent auto updates)
       p = new TreeNode(val);
        //this means this element is not the first, so we can just use prev's next
       if(prev){
           p->next = prev->next;
           prev->next = p;
       else //otherwise, p's next is the first element
           p->next = first:
       return true:
   else if (val < p->value) //if we go left, prev should not be changed
     return insert(val, p->left, first, prev);
   else if (val > p->value) //if we go right, prev should be p
     return insert(val, p->right, first, p);
     else //element already exists in the set
       return false:
```

DATA STRUCTURE TEST 03

10	DBFS	DFS
1.	BFS stands for Breadth First Search.	DFS stands for Depth First Search.
2.	BFS(Breadth First Search) uses Queue data	DFS(Depth First Search) uses Stack data
	structure for finding the shortest path.	structure.
3.	BFS can be used to find single source shortest	In DFS, we might traverse through more edges
	path in an unweighted graph, because in BFS,	to reach a destination vertex from a source.
	we reach a vertex with minimum number of	
	edges from a source vertex.	
4.	BFS is more suitable for searching vertices	DFS is more suitable when there are solutions
	which are closer to the given source.	away from source.
5.	BFS considers all neighbors first and therefore	DFS is more suitable for game or puzzle
	not suitable for decision making trees used in	problems. We make a decision, then explore all
	games or puzzles.	paths through this decision. And if this decision
		leads to win situation, we stop.
6.	The Time complexity of BFS is O(V + E) when	The Time complexity of DFS is also O(V + E)
	Adjacency List is used and O(V^2) when	when Adjacency List is used and O(V^2) when
	Adjacency Matrix is used, where V stands for	Adjacency Matrix is used, where V stands for

Here, siblings are visited before the children Here, children are visited before the siblings

vertices and E stands for edges.

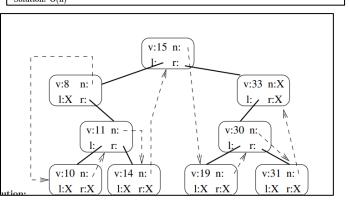
vertices and E stands for edges.

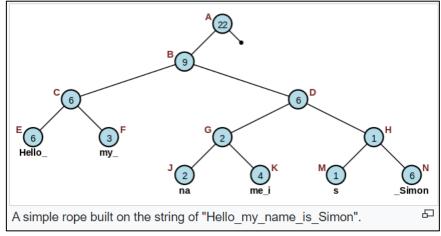
template <class T>

```
//It can point at any Node, not just leaves
prope_iterator& rope_iterator::operator++()
     if (ptr_->right != NULL) { // find the leftmost child of the right node
        ptr_ = ptr_->right;
         while (ptr_->left != NULL) { ptr_ = ptr_->left; }
        while (ptr_->parent != NULL && ptr_->parent->right == ptr_) { ptr_ = ptr_->parent; }
        ptr_ = ptr_->parent;
     return *this;
```

TreeNode <t>* FindSmallestInRange(const T& a, const T& b, TreeNode<t>* root, T& best_value){</t></t>			
Solution:			
if(!root){			
return NULL;			
}			
TreeNode <t>* left_subtree = FindSmallestInRange(a,b,root->left,best_value);</t>			
<pre>TreeNode<t>* right_subtree = FindSmallestInRange(a,b,root->right,best_value);</t></pre>			
if(root->value > a && root->value < best_value){			
<pre>best_value = root->value;</pre>			
return root;			
}			
else if(left_subtree && left_subtree->value == best_value){			
return left_subtree;			
}			
else if (right_subtree){			
return right_subtree;			
}			
return NULL;			
}			
If n is the number of nodes in the tree, what is the worst-case running time of FindSmallestInRange?			
Solution: O(n)			

Operation	Rope	String
Index ^[1]	O(log n)	O(1)
Split ^[1]	O(log n)	O(1)
Concatenate (destructive)	O(log n) without rebalancing / O(n) worst case	O(n)
Concatenate (nondestructive)	O(n)	O(n)
Iterate over each character ^[1]	O(n)	O(n)
Insert ^[2]	O(log n) without rebalancing / O(n) worst case	O(n)
Append ^[2]	O(log n) without rebalancing / O(n) worst case	O(1) amortized, O(n) worst case
Delete	O(log n)	O(n)
Report	O(j + log n)	O(j)
Build	O(n)	O(n)





For reserver about defearding ex. (*kirr) or six