





Tree attributes estimation

Viet Nguyen
Faculty of Forest and Environment
University for Sustainable Development
Eberswalde, Germany

These Teaching/Learning materials may be used freely for non-profit purposes with proper recognition of the authors and the project













Content

- 1. Crown delineation
- 2. Tree location, H, and CA estimation
- 3. DBH estimation
- 4. Detected measured tree matching
- 5. Accuracy assessment





Crown delineation by 2D convex hull polygons

Segmentation



Crown delineation

After tree segmentation, tree crowns were delineated by projecting the segmented point cloud on a 2D plane and fitting polygons around the points of each segmented tree.

Reference: Coomes et al., 2017

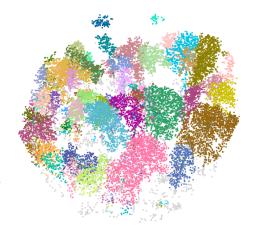


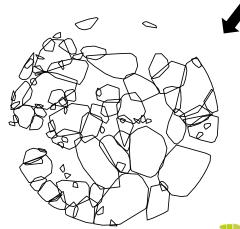


Crown delineation by 2D convex hull polygons

Segmentation Crown delineation

Segmented point cloud





2D polygons



Tree attribute estimation

Segmentation

Crown delineation

Tree location, H, CA, and CBH estimation

- Tree location was defined as the center of the X and Y coordinates of all points in a segmented tree.
- Tree height was derived from the Z
 value of the highest point within each
 segmented tree.
- Crown area was calculated as the area of the 2D crown polygons.





Segmentation

Crown delineation

Tree location, H, CA, and CBH estimation

DBH estimation

Allometry is the study of the relative change in proportion of an attribute compared to another one during growth (*BioMath:Allometry*)

"The study of allometry is extremely important in dealing with measurements and data analysis in the practice of forestry. Allometric relationships often are used to estimate difficult tree measurements, such as volume, from an easily measured attribute such as diameter at breast height (DBH)" ('Tree Allometry', 2022)





Segmentation

Crown delineation

Tree location, H, CA, and CBH estimation

DBH estimation

Source: Nikolai., 2022 Introduction to allometry

Allometric relations in forestry

Tree level

- DBH to height
- DBH to wood volume
- DBH to biomass
- DBH to crown diameter
- DBH to crown length
- DBH to crown volume
- DBH to leaf area
- •

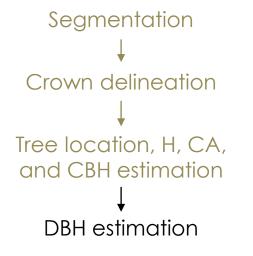
Stand level

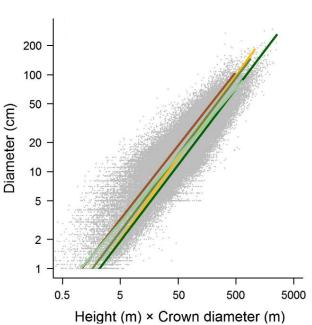
- Height to biomass
- Height to basal area
- Basal area to biomass

• ...









<u>Jucker (2016)</u> developed allometric equations to estimate DBH from tree height and crown diameter, using a global dataset of more than a hundred thousand individual trees



Source: Jucker et al., 2016 https://doi.org/10.1111/gcb.13388

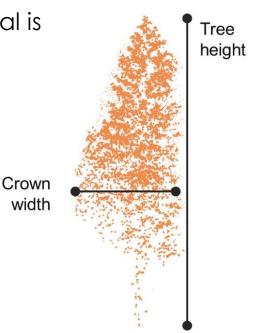




Segmentation Crown delineation Tree location, H, CA, and CBH estimation DBH estimation

The equation used in this tutorial is specific to temperate mixed forests in the Palearctic realm (Jucker et al., 2016)

 $DBH = 0.708 \times (H \times CD)^{0.753}$



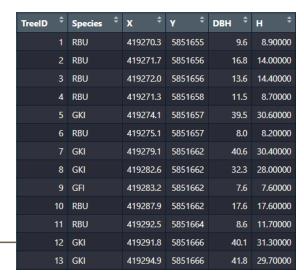
Source: Jucker et al., 2016 https://doi.org/10.1111/gcb.13388



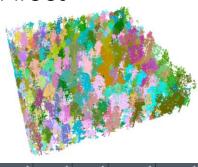
Segmentation Crown delineation Tree location, H. CA. and CBH estimation DBH estimation Measured - Detected tree matching

Which tree in inventory is the tree detected from point cloud?

Measured trees







treeID		хтор ‡	УТОР [‡]	ZTOP ‡	z [‡]	npoints ‡	cnvhll_ ‡
		419347.1	5851575	26.0918	26.0918	1615	49.650
	2	419341.4	5851574	10.2805	10.2805	128	5.056
	4	419339.9	5851574	13.2852	13.2852	275	7.522
		419327.4	5851568	9.2733	9.2733	134	4.938
		419327.7	5851570	16.7855	16.7855	246	7.377





Segmentation Crown delineation Tree location, H, CA, and CBH estimation DBH estimation Measured – Detected tree matching

To evaluate estimated and measured tree attributes at a single tree level, it is necessary to match the ALS-detected trees to field-measured trees. In other words, it is necessary to find which trees in the inventory data are the trees detected from the point cloud. After matching the data, it allows comparing estimated and measured tree attributes tree by tree.





Segmentation Crown delineation Tree location, H, CA, and CBH estimation DBH estimation Measured – Detected tree matching

In this study, matching was performed based on two criteria:

 The distance between measured and detected trees below 4m. For each measured tree, searching for every detected tree within 4m, those trees are then marked as candidate trees for matching.





Segmentation Crown delineation Tree location, H, CA, and CBH estimation DBH estimation Measured – Detected tree matching

2. The difference in height between measured and detected trees does not exceed 20% of the height of measured trees. After candidate tree searching, the H error is calculated by taking the absolute value of the difference between the detected and measured tree H. The detected tree with the lowest H error was examined to see if this error was below 20% of the measured tree H. If the criterion is fulfilled. the trees get matched. After tree matching, H and DBH can be evaluated further.



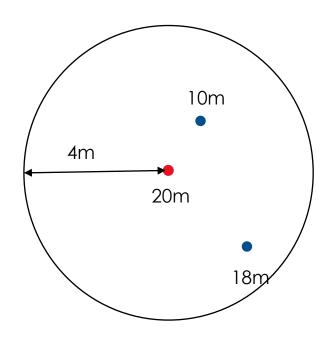


Segmentation Crown delineation Tree location, H, CA, and CBH estimation **DBH** estimation Measured – Detected tree matching

The detected 18m tree gets matched. Because it is within 4m-distance of the measured tree and has the lowest H error



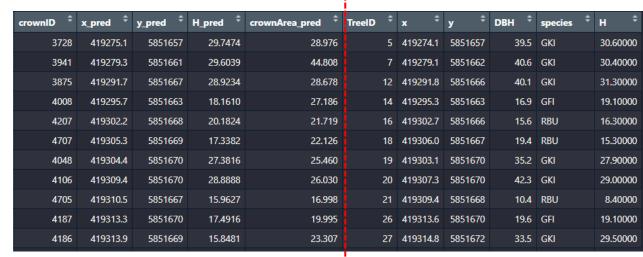
Detected tree





Segmentation Crown delineation Tree location, H, CA, and CBH estimation DBH estimation Measured - Detected tree matching

After matching the data, it is possible to compare predicted and measured tree attributes tree by tree



Predicted attributes

Measured attributes



Accuracy assessment of H and DBH estimation

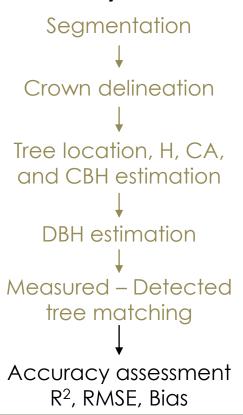
Segmentation Crown delineation Tree location, H, CA, and CBH estimation DBH estimation Measured – Detected tree matching Accuracy assessment R², RMSE, Bias

Some goodness-of-fit measurements can be calculated to assess the accuracy at tree level of the estimated H and DBH for trees matched with the inventory data. These indicators are RMSE, bias, and R² which were calculated as follow:





Accuracy assessment of H and DBH estimation



RMSE =
$$\sqrt{\frac{1}{n_{match}} \sum_{i=1}^{n_{match}} (x_i - y_i)^2}$$

Bias =
$$\frac{1}{n_{match}} \sum_{i=1}^{n_{match}} (x_i - y_i)$$

$$R^{2} = 1 - \frac{\sum_{1}^{n_{match}} (y_{i} - x_{i})^{2}}{\sum_{1}^{n_{match}} (y_{i} - \bar{y})^{2}}$$

Where, n_{match} is the number of matched trees; x_i is the estimated value of tree i; y_i is the measured value of tree i and \overline{y} is the mean of the measured values









¡Thank you for your reading!













References

- BioMath:Allometry.
 http://www.biology.arizona.edu/biomath/tutorials/applications/allometry.html
- Coomes, D. A., Dalponte, M., Jucker, T., Asner, G. P., Banin, L. F., Burslem, D. F. R. P., Lewis, S. L., Nilus, R., Phillips, O. L., Phua, M.-H., & Qie, L. (2017). Area-based vs tree-centric approaches to mapping forest carbon in Southeast Asian forests from airborne laser scanning data.
 Remote Sensing of Environment, 194, 77–88. https://doi.org/10.1016/j.rse.2017.03.017
- Jucker, T., Caspersen, J., Chave, J., Antin, C., Barbier, N., Bongers, F., Dalponte, M., van Ewijk, K. Y., Forrester, D. I., Haeni, M., Higgins, S. I., Holdaway, R. J., Iida, Y., Lorimer, C., Marshall, P. L., Momo, S., Moncrieff, G. R., Ploton, P., Poorter, L., . . . Coomes, D. A. (2017). Allometric equations for integrating remote sensing imagery into forest monitoring programmes. Global Change Biology, 23(1), 177–190. https://doi.org/10.1111/gcb.13388



References

- Nikolai, Knapp. (2020). Match crown projection polygons with tree stem positions.
- https://rdrr.io/github/niknap/MeanShiftR/man/match_CrownsStems.html#heading-4
- Nikolai, Knapp. (2021, October). Introduction to allometry [Paper presentation]. Module:
 Collection & analysis of lidar data, Eberswalde, Brandenburg, Germany.
- Pirotti, F., Kobal, M., & Roussel, J. R. (2017). A COMPARISON OF TREE SEGMENTATION
 METHODS USING VERY HIGH DENSITY AIRBORNE LASER SCANNER DATA. The International
 Archives of the Photogrammetry, Remote Sensing and Spatial Information Sciences, XLII2/W7, 285–290. https://doi.org/10.5194/isprs-archives-XLII-2-W7-285-2017
- Tree allometry. (2022). In Wikipedia.
 https://en.wikipedia.org/w/index.php?title=Tree_allometry&oldid=1066547806

