

7/9/25

## 6. Implement gradient descent & backpropagation in deep neural networks

Aim: To implement gradient descent and backpropagation in deep neural networks.

### Objectives:

- \* To understand gradient descent in an optimized method.
- \* To implement backpropagation in deep neural networks to update weights.
- \* To implement a simple neural network for classification task.
- \* To observe how loss decrease with iterations.

## PSEUDOCODE:

BEGIN

Initialize weights and bias randomly

FOR epoch in range (max\_epochs)

FOR each input sample :

#forward pass

compute  $Z = w * x + b$

apply activation to get  $A$

compute output prediction

#compute loss:

loss = cost(y\_true, y\_pred)

#backward pass

compute gradients  $dw, db$  using chain rule

update parameters:

$w = w - \alpha dw$

$b = b - \alpha db$

END for

print after epoch

ENDFOR

END

## OBSERVATION:

- \* Loss decreases as number of iterations increases
- \* weights and bias adjust to minimize error
- \* backpropagation ensures errors are effectively distributed layer by layer
- \* Learning rate ( $\eta$ ) greatly influences convergence speed.

## Result:

Therefore implementation of gradient descent and backpropagation in neural network.

Output:

\* Epoch 1/4:

loss: 0.5954 training: 0.5607

\* Epoch 2/4:

loss: 0.5548 training: 0.5584

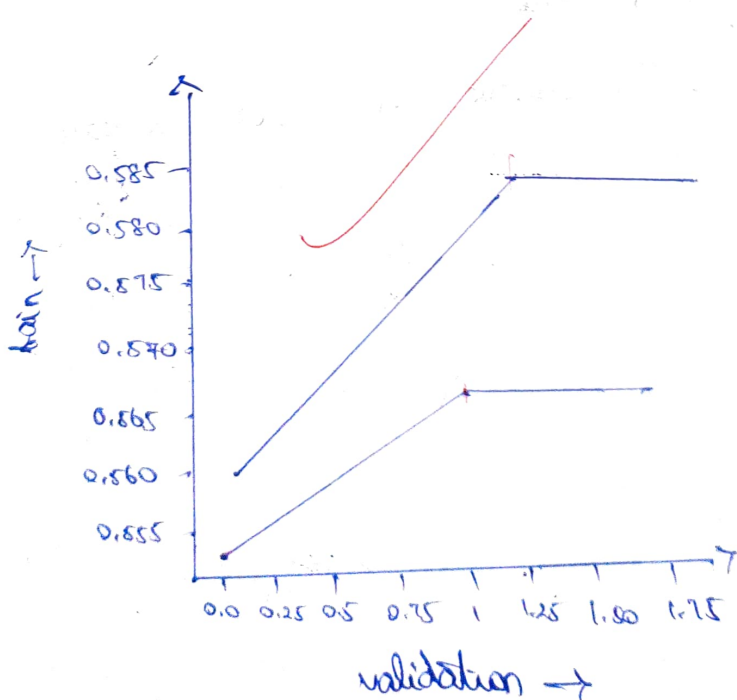
\* Epoch 3/4:

loss: 0.5441 training: 0.5887

\* Epoch 4/4:

loss: 0.5312 training: 0.6012

loss: 0.5312 val-loss: 0.5568



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Code

```
z3 = a2 @ w3 + b3
y_pred = torch.sigmoid(z3)
predicted = (y_pred > 0.5).float()

print("Predictions:\n", predicted)
print("Ground Truth:\n", y)
```

Predictions:  
tensor([[0.],  
[1.],  
[1.],  
[0.]])  
Ground Truth:  
tensor([[0.],  
[1.],  
[1.],  
[0.]])

[ ]:

Simple

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Python 3 (ipykernel) | Idle

Mem: 425.79 MB

Mode: Command

Ln 1, Col 1

L6.ipynb

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The screenshot displays the JupyterLab environment. On the left, a file browser shows a directory named "/ DEEP LEARNING /" containing several files. The file "L6.ipynb" is selected and highlighted in blue. The main area on the right is a code editor showing the content of "L6.ipynb". The code is as follows:

```
[1]: import torch
import torch.nn.functional as F
import matplotlib.pyplot as plt

[4]: X = torch.tensor([[0, 0],
[0, 1],
[1, 0],
[1, 1]], dtype=torch.float32)
y = torch.tensor([0], [1], [1], [0]), dtype=torch.float32)

[5]: torch.manual_seed(42)
input_size = 2
hidden1 = 4
hidden2 = 4
output_size = 1

[6]: W1 = torch.randn(input_size, hidden1, requires_grad=True)
b1 = torch.zeros(hidden1, requires_grad=True)

[7]: W2 = torch.randn(hidden1, hidden2, requires_grad=True)
b2 = torch.zeros(hidden2, requires_grad=True)

[8]: W3 = torch.randn(hidden2, output_size, requires_grad=True)
b3 = torch.zeros(output_size, requires_grad=True)

[9]: lr = 0.1
epochs = 5000
```



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Code

Notebook Python 3 (ipykernel)

```
z3 = a2 @ W3 + b3
y_pred = torch.sigmoid(z3)
loss = F.binary_cross_entropy(y_pred, y)
loss.backward()

with torch.no_grad():
    W1 -= lr * W1.grad
    b1 -= lr * b1.grad

    W2 -= lr * W2.grad
    b2 -= lr * b2.grad

    W3 -= lr * W3.grad
    b3 -= lr * b3.grad

# Zero the gradients
W1.grad.zero_()
b1.grad.zero_()
W2.grad.zero_()
b2.grad.zero_()
W3.grad.zero_()
b3.grad.zero_()

loss_history.append(loss.item())

if epoch % 500 == 0:
    print(f"Epoch {epoch} - Loss: {loss.item():.4f}")
```

Epoch 0 - Loss: 0.0134  
Epoch 500 - Loss: 0.0107

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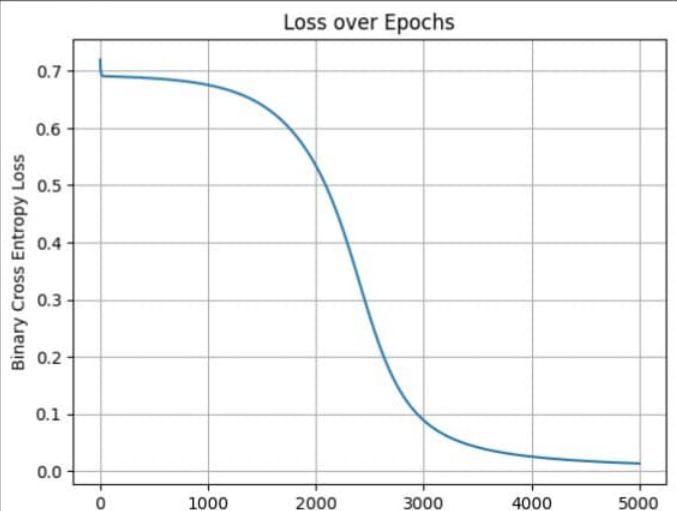
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Logistic reg... L\_3.ipynb L4.ipynb jupyter-ra2... L2.ipynb EX1.ipynb L5.ipynb L6.ipynb jupyter-ra2...

```
plt.title('Loss over epochs')
plt.xlabel('Epoch')
plt.ylabel('Binary Cross Entropy Loss')
plt.grid(True)
plt.show()
```



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