

19CSE433 Computer Graphics & Visualization

Professional Elective 1
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2019-22 Batch, BTech CSE

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A solid blue horizontal bar spanning the width of the slide, located at the bottom.

Output Primitives

Points

Lines

- DDA Algorithm
- Bresenham's Algorithm

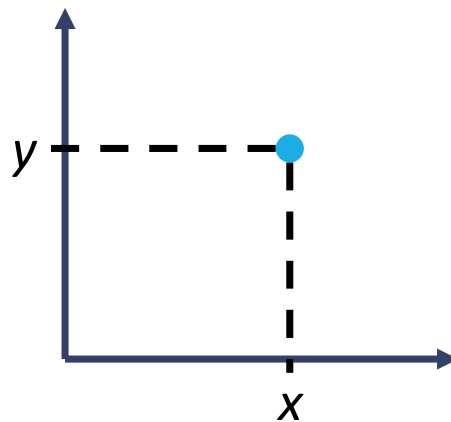
Polygons

- Scan-Line Polygon Fill
- Inside-Outside Tests
- Boundary-Fill Algorithm

Points

Single Coordinate Position

- Set the bit value(color code) corresponding to a specified screen position within the frame buffer

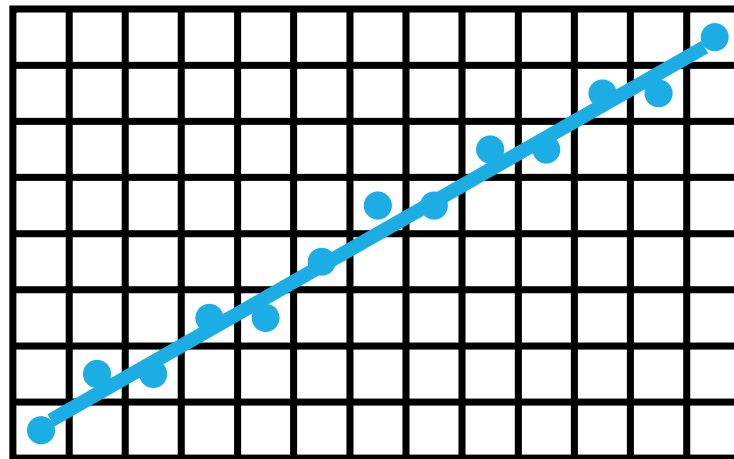


setPixel (x, y)

Lines

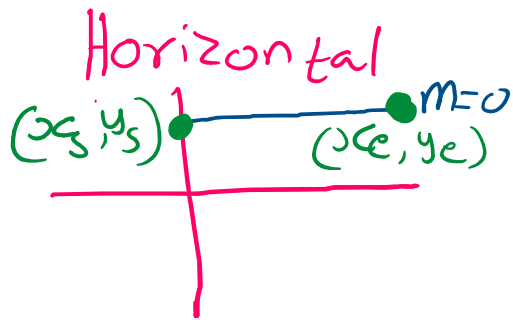
Intermediate Positions between Two Endpoints

- DDA, Bresenham's line algorithms

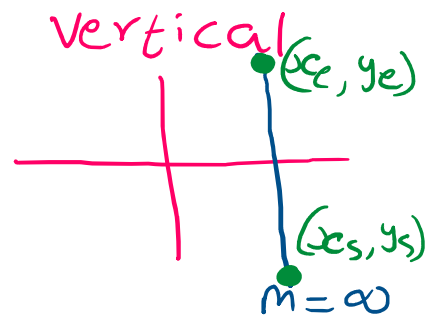


**Jaggies
= Aliasing**

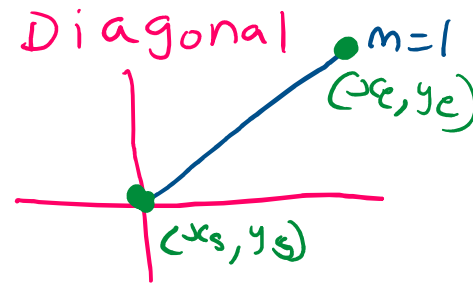
Line drawing- special case



y same
x increment from
 x_s to x_e



x same
y: increment from
 y_s to y_e

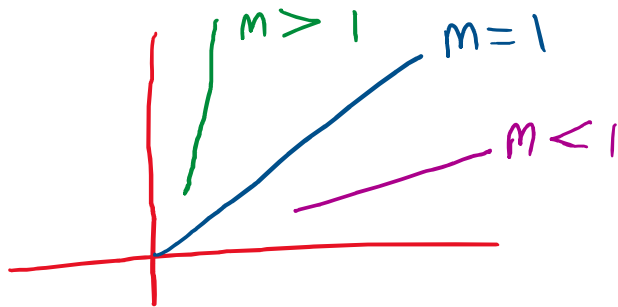


Increment x or y
& calculate other
as $y = x$ or $x = y$

$$m = \frac{\Delta y}{\Delta x} = \frac{y_2 - y_1}{x_2 - x_1}$$

Special case

Rasterization of lines



$$y = mx + c$$

$$x = \frac{y - c}{m}$$

$$m = \frac{\Delta y}{\Delta x} = \frac{y_e - y_s}{x_e - x_s}$$

$m > 1$: nearly vertical $\rightarrow \Delta y > \Delta x$

Increment y & Compute x

$$x = \frac{1}{m} (y - c)$$

$m < 1$: nearly horizontal $\rightarrow \Delta y < \Delta x$

Increment x & compute y

$$y = mx + c$$

DDA Algorithm

Digital Differential Analyzer

- $0 < \text{Slope} \leq 1$
- Unit x interval = 1

$$y = mx + c$$

$$m < 1$$
$$\frac{\Delta y}{\Delta x} < 1$$

$$\Delta y < \Delta x$$

$$k^{\text{th}} \text{ iteration : } y_k = mx_k + c$$

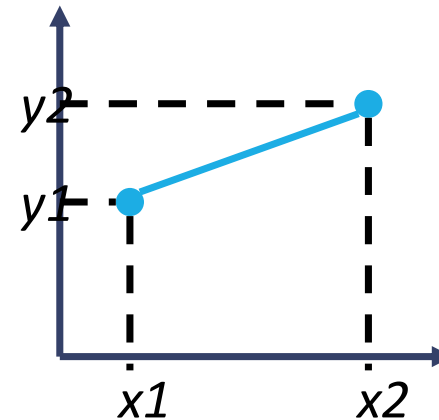
$$k+1^{\text{th}} \text{ iteration : } y_{k+1} = mx_{k+1} + c$$

$$x_{k+1} = x_k + 1$$

$$\therefore y_{k+1} = mx_k + m + c$$
$$= y_k + m$$

Nearly Horizontal

Increment x and compute y



$$y_{k+1} = y_k + m$$

DDA Algorithm

Digital Differential Analyzer

- $0 < \text{Slope} \leq 1$
 - Unit x interval = 1
- $\text{Slope} > 1$
 - Unit y interval = 1

$$x_k = \frac{1}{m} (y_k - c) = \frac{1}{m} y_k - \frac{c}{m}$$

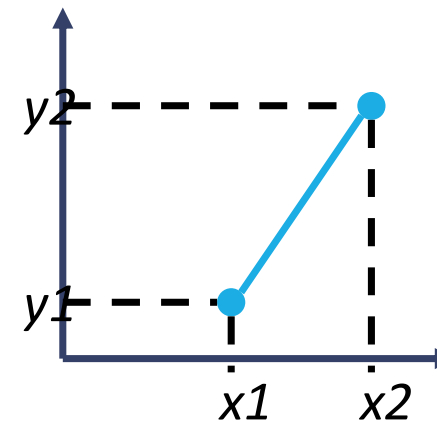
$$x_{k+1} = \frac{1}{m} (y_{k+1} - c)$$

$$y_{k+1} = y_k + 1$$

$$\therefore x_{k+1} = \frac{1}{m} y_k + \frac{1}{m} - \frac{c}{m} = x_k + \frac{1}{m}$$

Nearly Vertical

$$m > 1 \Rightarrow \frac{\Delta y}{\Delta x} > 1 \Rightarrow \Delta y > \Delta x$$



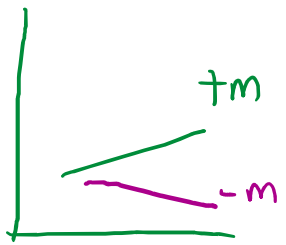
Increment y
Calculate x

$$x_{k+1} = x_k + \frac{1}{m}$$

DDA Algorithm

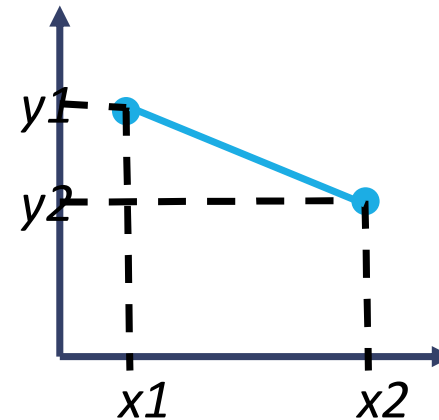
Digital Differential Analyzer

- $0 < \text{Slope} \leq 1$
 - Unit x interval = 1
- Slope > 1
 - Unit y interval = 1
- $-1 \leq \text{Slope} < 0$
 - Unit x interval = -1



y increases from start to end
y decreases

Negative slope, Nearly horizontal
Increment x, compute y

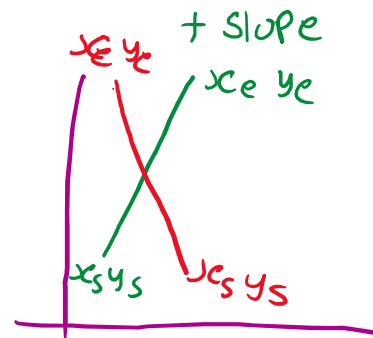


$$y_{k+1} = y_k - m$$

DDA Algorithm

Digital Differential Analyzer

- Slope ≥ 1
 - Unit x interval = 1
- $0 < \text{Slope} < 1$
 - Unit y interval = 1
- $-1 \leq \text{Slope} < 0$
 - Unit x interval = -1
- Slope < -1
 - Unit y interval = -1

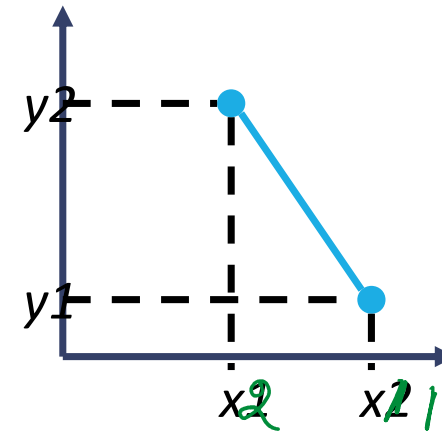


y increases $x \downarrow$

$y \uparrow x \uparrow \Rightarrow +ve \text{ slope}$

Nearly vertical, $\&$ negative slope

Increment y , compute x



$$x_{k+1} = x_k - \frac{1}{m}$$

DDA Algorithm

```
#define ROUND(a) ((int)(a+0.5))

void lineDDA (int xa, int ya, int xb, int yb)
{
    int dx = xb - xa, dy = yb - ya, steps, k;
    float xIncrement, yIncrement, x = xa, y = ya;

    if (abs (dx) > abs (dy)) steps = abs (dx);
    else steps = abs (dy);
    xIncrement = dx / (float) steps;
    yIncrement = dy / (float) steps;

    setPixel (ROUND(x), ROUND(y));
    for (k=0; k<steps; k++) {
        x += xIncrement;
        y += yIncrement;
        setPixel (ROUND(x), ROUND(y));
    }
}
```

Exercise:

Digitize the line from (20,10) to (30,18)

(2,10)to (5,18)

(15,30) to(30,25)

(20,10) to (15,25)

Bresenham's Line Algorithm

Accurate and Efficient

- Use only incremental integer calculations
- Test the sign of an integer parameter

Case) Positive Slope Less Than 1

- After the pixel (x_k, y_k) is displayed, next which pixel is decided to plot in column x_{k+1} ?

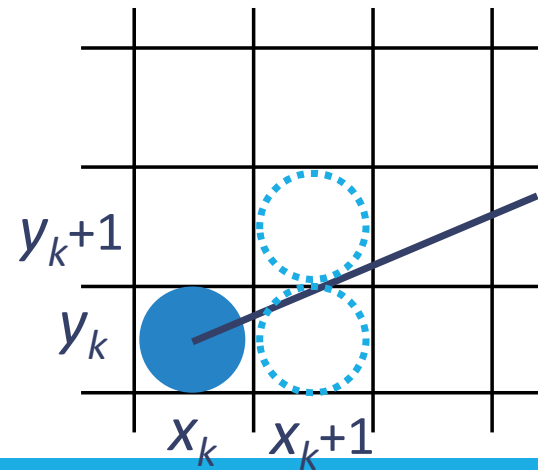
→ (x_k+1, y_k) or (x_k+1, y_k+1)

nearly Horizontal

$m < 1$ $\Delta y < \Delta x$

Increment x

Decide y_k or y_k+1



Bresenham's Algorithm(cont.)

Case) Positive Slope Less Than 1

- y at sampling position x_k

$$y = m(x_k + 1) + b$$

- Difference

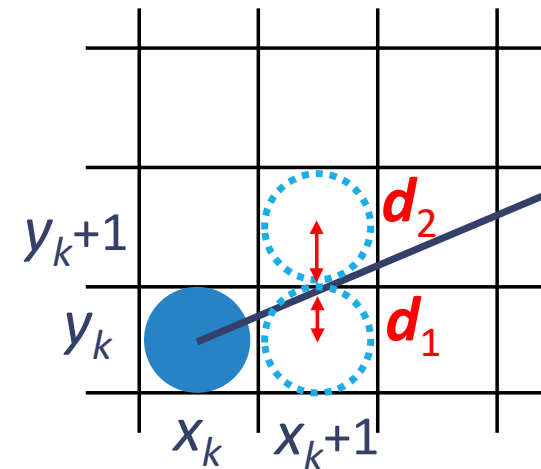
$$d_1 = y - y_k = m(x_k + 1) + b - y_k$$

$$d_2 = y_k + 1 - y = y_k + 1 - m(x_k + 1) - b$$

- Decision parameter

$$d_1 - d_2 < 0 \Rightarrow (x_k + 1, y_k)$$

$$d_1 - d_2 > 0 \Rightarrow (x_k + 1, y_k + 1)$$



$$\begin{aligned} p_k &= \Delta x(d_1 - d_2) \\ &= 2\Delta y \cdot x_k - 2\Delta x \cdot y_k + 2\Delta y + \Delta x(2b - 1) \\ &= 2\Delta y \cdot x_k - 2\Delta x \cdot y_k + c \end{aligned}$$

Bresenham's Algorithm(cont.)

Case) Positive Slope Less Than 1

- Decision parameter

$$\begin{aligned} p_{k+1} - p_k &= (2\Delta y \cdot x_{k+1} - 2\Delta x \cdot y_{k+1} + c) - (2\Delta y \cdot x_k - 2\Delta x \cdot y_k + c) \\ &= 2\Delta y(x_{k+1} - x_k) - 2\Delta x(y_{k+1} - y_k) \end{aligned}$$

- Decision parameter

$$\therefore p_{k+1} = p_k + 2\Delta y - 2\Delta x(y_{k+1} - y_k)$$

$$\begin{aligned} p_0 &= 2\Delta y \cdot x_0 - 2\Delta x \cdot y_0 + 2\Delta y + \Delta x(2b - 1) \\ &= 2\Delta y \cdot x_0 - 2\Delta x \cdot (mx_0 + b) + 2\Delta y + \Delta x(2b - 1) \\ &= 2\Delta y \cdot x_0 - 2\Delta y \cdot x_0 - 2b\Delta x + 2\Delta y + 2b\Delta x - \Delta x \end{aligned}$$

$$\therefore p_0 = 2\Delta y - \Delta x$$

Bresenham's Algorithm(cont.)

Algorithm for $0 < m < 1$

- Input the two line endpoints and store the left end point in (x_0, y_0)
- Load (x_0, y_0) into the frame buffer; that is, plot the first point
- Calculate constants Δx , Δy , $2\Delta y$, and $2\Delta y - 2\Delta x$, and obtain the starting value for the decision parameter as

$$p_0 = 2\Delta y - \Delta x$$

- At each x_k along the line, start at $k=0$, perform the following test:
 - If $p_k < 0$, the next point to plot is (x_k+1, y_k) and

$$p_{k+1} = p_k + 2\Delta y$$

- Otherwise, the next point to plot is (x_k+1, y_k+1) and

- Repeat step 4 Δx times

$$p_{k+1} = p_k + 2\Delta y - 2\Delta x$$

Bresenham's Line-Drawing Algorithm for $|m| < 1$

1. Input the two line endpoints and store the left endpoint in (x_0, y_0) .
2. Load (x_0, y_0) into the frame buffer; that is, plot the first point.
3. Calculate constants Δx , Δy , $2\Delta y$, and $2\Delta y - 2\Delta x$, and obtain the starting value for the decision parameter as

$$p_0 = 2\Delta y - \Delta x$$

4. At each x_k along the line, starting at $k = 0$, perform the following test:
If $p_k < 0$, the next point to plot is $(x_k + 1, y_k)$ and

$$p_{k+1} = p_k + 2\Delta y$$

Otherwise, the next point to plot is $(x_k + 1, y_k + 1)$ and

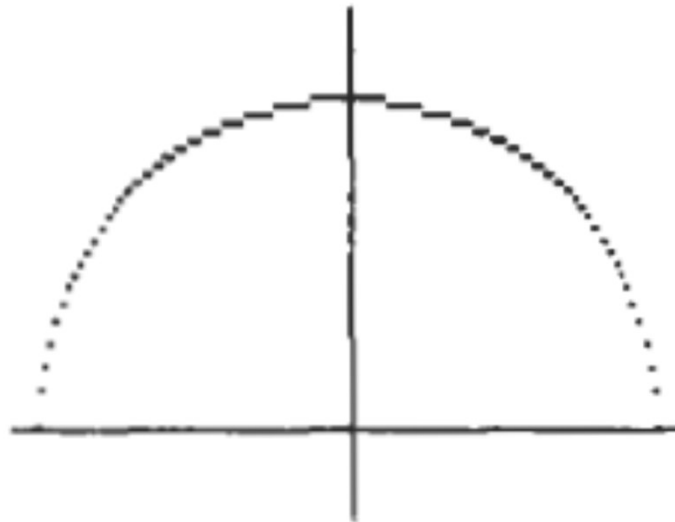
$$p_{k+1} = p_k + 2\Delta y - 2\Delta x$$

5. Repeat step 4 Δx times.

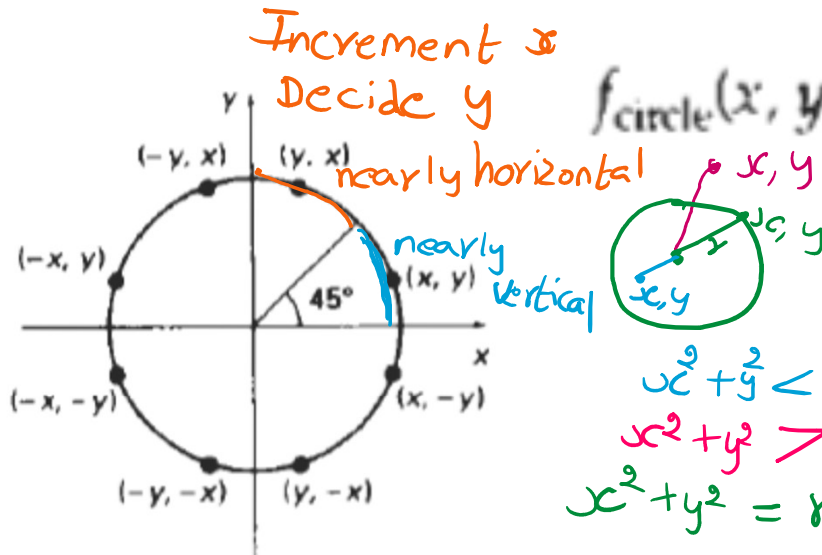
Circle Drawing

$$(x - x_c)^2 + (y - y_c)^2 = r^2$$

$$y = y_c \pm \sqrt{r^2 - (x_c - x)^2}$$



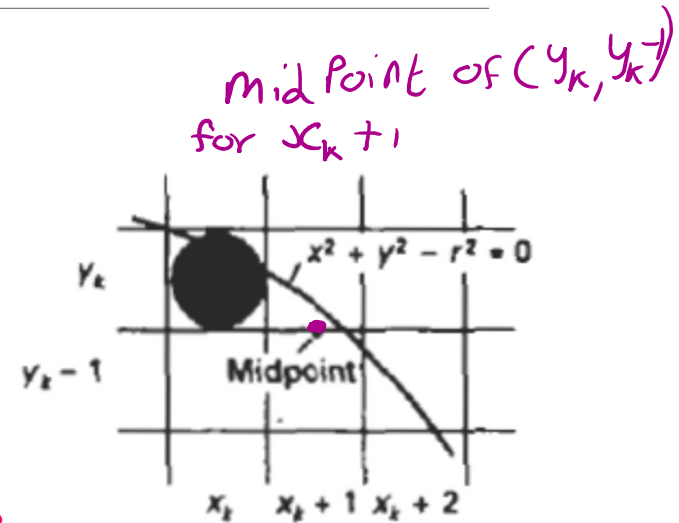
Circle drawing algorithm



$$f_{\text{circle}}(x, y) = x^2 + y^2 - r^2$$

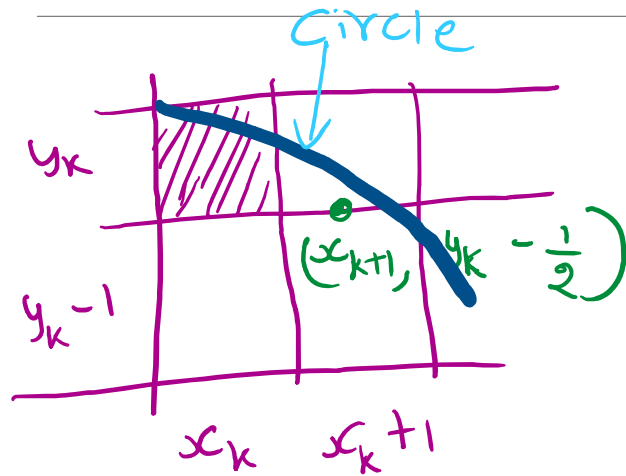
$x^2 + y^2 < r^2 \Rightarrow$ inside circle
 $x^2 + y^2 > r^2 \Rightarrow$ outside circle
 $x^2 + y^2 = r^2 \Rightarrow$ on the circle

$$f_{\text{circle}}(x, y) \begin{cases} < 0, & \text{if } (x, y) \text{ is inside the circle boundary} \\ = 0, & \text{if } (x, y) \text{ is on the circle boundary} \\ > 0, & \text{if } (x, y) \text{ is outside the circle boundary} \end{cases}$$

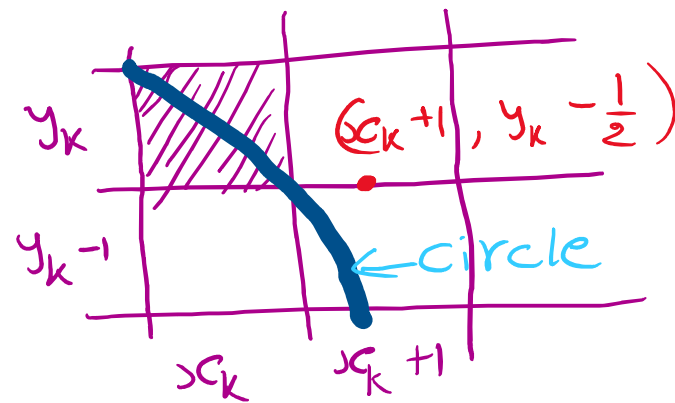


midpoint inside $\Rightarrow y_k$ closer to circle
midpoint outside $\Rightarrow y_k - 1$ closer

Midpoint inside/outside circle



midpoint inside
 y_k closer to circle
 than $y_k - 1$



midpoint outside circle
 $y_k - 1$ closer to circle
 than y_k

If equal
 any one
 can be
 chosen

Mid point circle drawing algorithm

$$p_k = f_{\text{circle}}\left(x_k + 1, y_k - \frac{1}{2}\right)$$

$$= (x_k + 1)^2 + \left(y_k - \frac{1}{2}\right)^2 - r^2$$

$$p_{k+1} = f_{\text{circle}}\left(x_{k+1} + 1, y_{k+1} - \frac{1}{2}\right)$$

$$= [(x_k + 1) + 1]^2 + \left(y_{k+1} - \frac{1}{2}\right)^2 - r^2$$

$$p_{k+1} = p_k + 2(x_k + 1) + (y_{k+1}^2 - y_k^2) - (y_{k+1} - y_k) + 1$$

$$p_k + 2(x_k + 1) + 1 - 2(y_k - 1)$$

$$P_{k+1} = (x_k + 1)^2 + 1 + 2(x_k + 1) + y_{k+1}^2 + \frac{1}{4} - y_{k+1} - r^2$$

$$P_k = (x_k + 1)^2 + y_k^2 + \frac{1}{4} - y_k - r^2$$

$$P_{k+1} - P_k = 2(x_k + 1) + 1 + (y_{k+1}^2 - y_k^2) - (y_{k+1} - y_k)$$

$$y_{k+1} = y_k \text{ or } y_k - 1$$

$$\therefore P_{k+1} = P_k + 2(x_k + 1) + 1$$

else

$$P_{k+1} = P_k + 2(x_k + 1) + 1 + (y_k^2 + 1 - 2y_k - y_k^2) - (y_k - 1)$$

$$\Leftarrow P_k + 2(x_k + 1) + 1 + (1 - 2y_k) + 1$$

Inside

if $y_{k+1} = y_k$

outside

or

Initial values

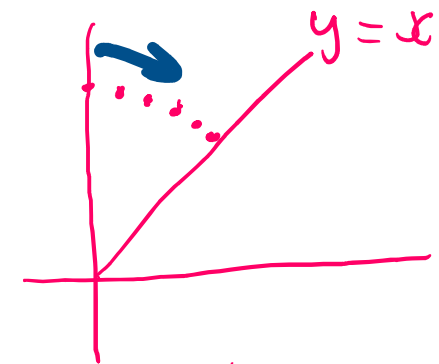
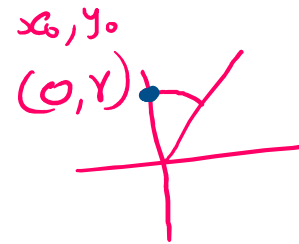
$$2x_{k+1} = 2x_k + 2$$

$$2y_{k+1} = 2y_k - 2$$

$(x_0, y_0) = (0, r)$: Initial value

$$\begin{aligned} p_0 &= f_{\text{circle}}\left(1, r - \frac{1}{2}\right) \\ &= 1 + \left(r - \frac{1}{2}\right)^2 - r^2 \end{aligned}$$

$$p_0 = \frac{5}{4} - r$$



∞ increments
y could be same
or less

Generate pts until $x = y$

Midpoint Circle Algorithm

1. Input radius r and circle center (x_c, y_c) , and obtain the first point on the circumference of a circle centered on the origin as

$$(x_0, y_0) = (0, r)$$

2. Calculate the initial value of the decision parameter as

$$p_0 = \frac{5}{4} - r$$

3. At each x_k position, starting at $k = 0$, perform the following test: If $p_k < 0$, the next point along the circle centered on $(0, 0)$ is (x_{k+1}, y_k) and

$$p_{k+1} = p_k + 2x_{k+1} + 1$$

Otherwise, the next point along the circle is $(x_k + 1, y_{k+1})$ and

$$p_{k+1} = p_k + 2x_{k+1} + 1 - 2y_{k+1}$$

where $2x_{k+1} = 2x_k + 2$ and $2y_{k+1} = 2y_k - 2$.

4. Determine symmetry points in the other seven octants.
5. Move each calculated pixel position (x, y) onto the circular path centered on (x_c, y_c) and plot the coordinate values:

$$x = x + x_c \quad y = y + y_c$$

6. Repeat steps 3 through 5 until $x \geq y$.

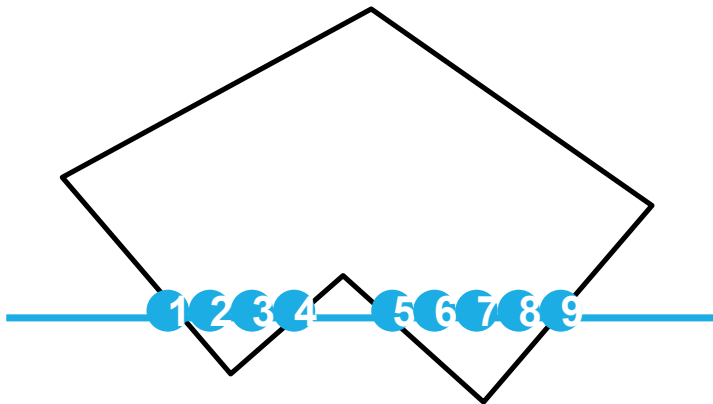
midPoint
Inside circle

$x_{k+1} = x_k + 1$
 $y_{k+1} = y_k - 1$ outside circle

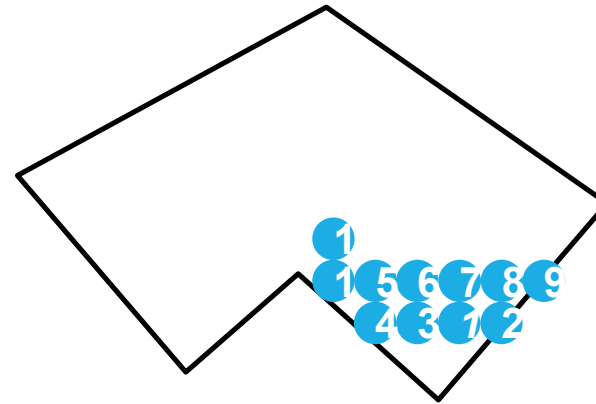
Polygons

Filling Polygons

- Scan-line fill algorithm
 - Inside-Outside tests



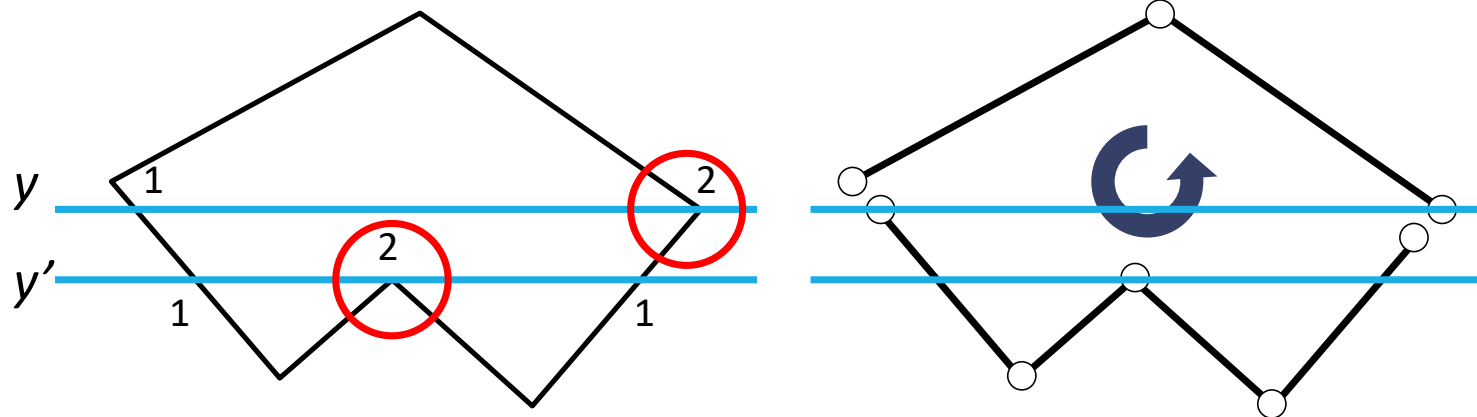
- Boundary fill algorithm



Scan-Line Polygon Fill

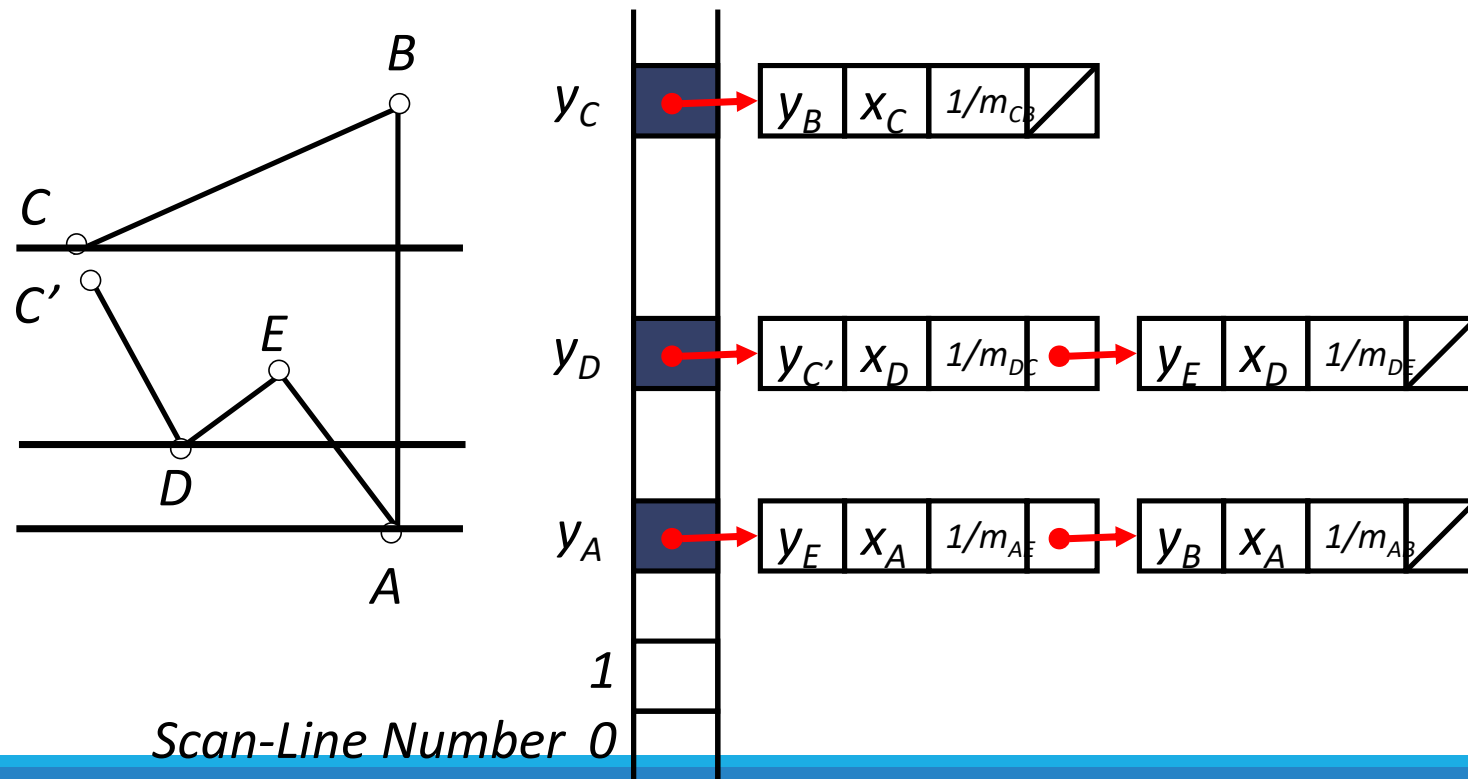
Topological Difference between 2 Scan lines

- y : intersection edges are opposite sides
- y' : intersection edges are same side



Scan-Line Polygon Fill (cont.)

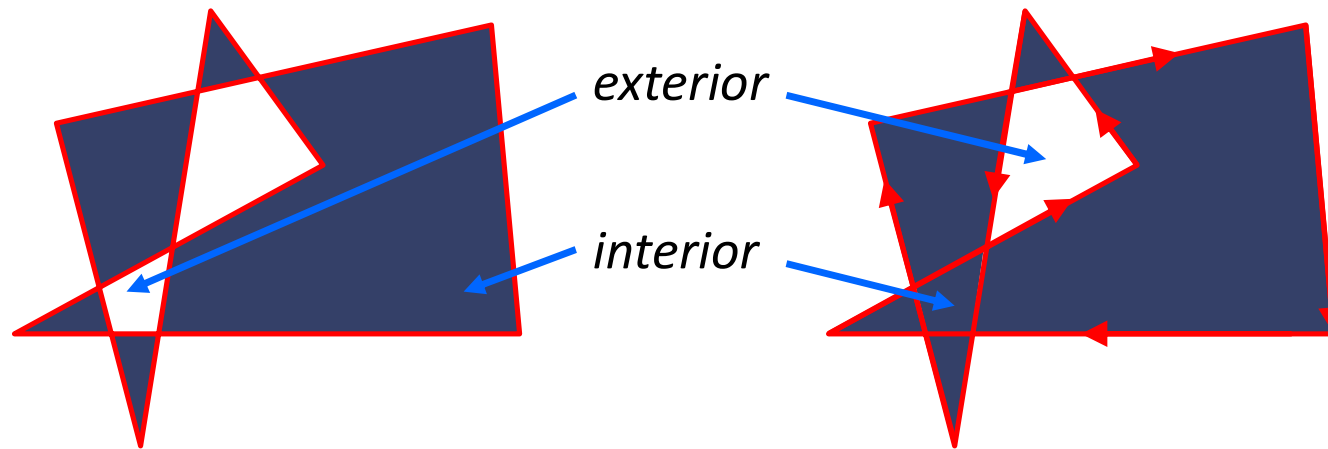
Edge Sorted Table



Inside-Outside Tests

Self-Intersections

- Odd-Even rule
- Nonzero winding number rule



Boundary-Fill Algorithm

Proceed to Neighboring Pixels

- 4-Connected
- 8-Connected

