# COMP 3331/9331: Computer Networks and Applications

Week 8

Network Layer: Control Plane (Routing)

Chapter 5: Section 5.1 - 5.2, 5.6

#### Network layer, control plane: outline

- 5.1 introduction
- 5.2 routing protocols
- link state
- distance vector
- hierarchical routing

5.6 ICMP: The Internet Control Message Protocol

Self study

## Network-layer functions

#### Recall: two network-layer functions:

- \* forwarding: move packets from router's input to appropriate router output
- routing: determine route taken by packets from source Control plane

#### Two approaches to structuring network control plane:

per-router control (traditional)

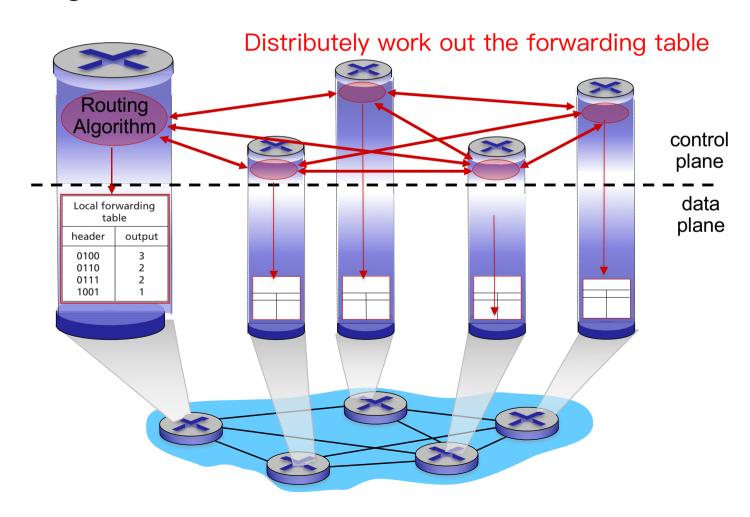
to destination

logically centralized control (software defined networking)

#### Per-router control plane

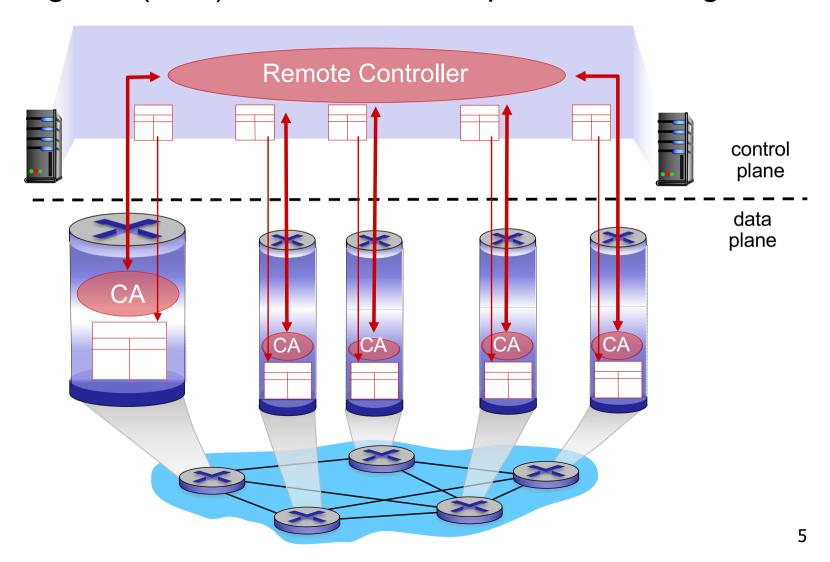
Individual routing algorithm components *in each and every router* interact with each other in control plane to compute forwarding tables

distributed control



## Logically centralized control plane

A distinct (typically remote) controller interacts with local control agents (CAs) in routers to compute forwarding tables

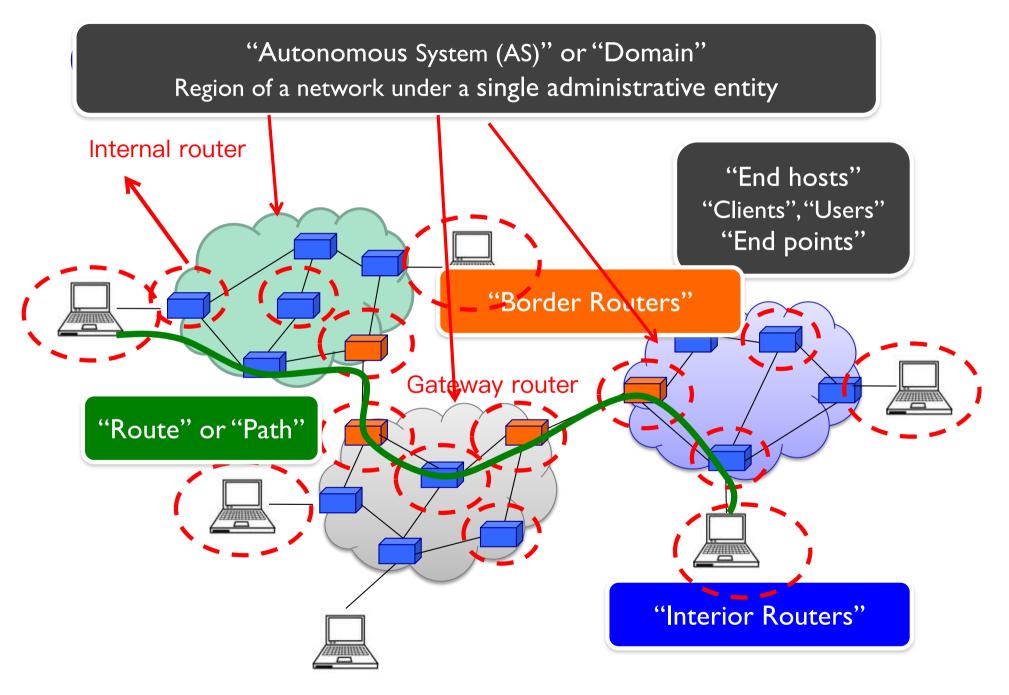


#### Network layer, control plane: outline

- 5.1 introduction
- 5.2 routing protocols
- link state
- distance vector
- Hierarchical routing

5.6 ICMP: The Internet Control Message Protocol

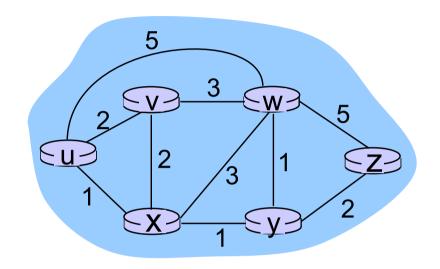
#### Network under the control of a administration



# Internet Routing

- Internet Routing works at two levels
- Each AS runs an intra-domain routing protocol that establishes routes within its domain
  - AS -- region of network under a single administrative entity
  - Link State, e.g., Open Shortest Path First (OSPF)
  - Distance Vector, e.g., Routing Information Protocol (RIP)
- ASes participate in an inter-domain routing protocol that establishes routes between domains
  - Path Vector, e.g., Border Gateway Protocol (BGP)

## Graph abstraction



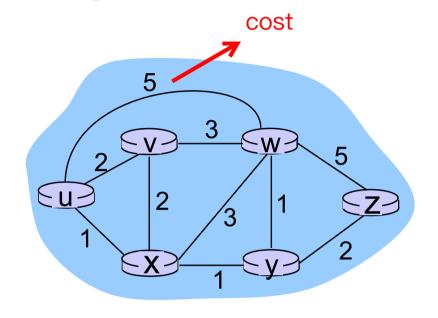
graph: G = (N,E)

 $N = set of routers = \{ u, v, w, x, y, z \}$ 

 $E = \text{set of links} = \{ (u,v), (u,x), (u,w), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) \}$ 

It can be 'point-to-point' link
Or network

## Graph abstraction: costs



$$c(x,x') = cost of link (x,x')$$
  
e.g.,  $c(w,z) = 5$ 

cost of path 
$$(x_1, x_2, x_3, ..., x_p) = c(x_1, x_2) + c(x_2, x_3) + ... + c(x_{p-1}, x_p)$$

key question: what is the least-cost path between u and z? routing algorithm: algorithm that finds that least cost path

#### Link Cost

- Typically simple: all links are equal
- Least-cost paths => shortest paths (hop count)
- Network operators add policy exceptions
  - Lower operational costs
  - Peering agreements
  - Security concerns

Some of the link maybe very expensive, like those connected to satellite

#### Network layer, control plane: outline

- 5.1 introduction
- 5.2 routing protocols
- link state
- distance vector
- hierarchical routing

5.6 ICMP: The Internet Control Message Protocol

## Routing algorithm classes

Simpler, quickly

Distance Vector (Decentralised)

large network

Can be scaled to very

 Routers maintain cost of each link in the network

Limited size

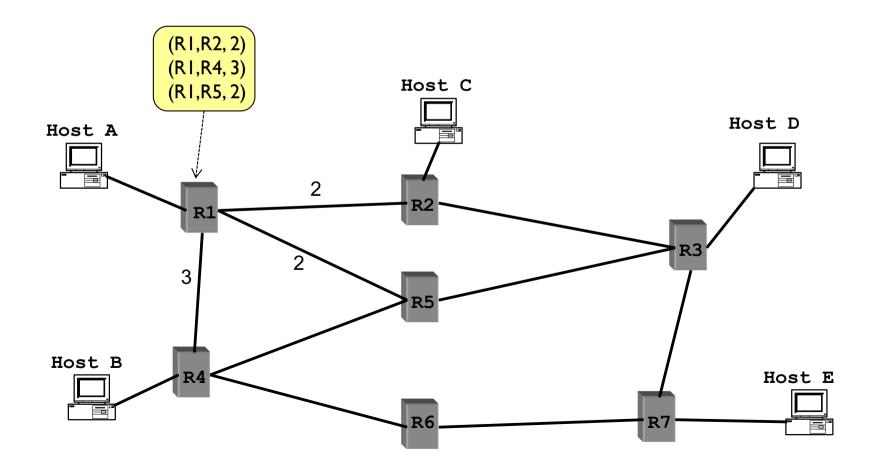
Link State (Global)

- Connectivity/cost changes flooded to all routers
- Converges quickly (less inconsistency, looping, etc.)
- Limited network sizes

- Routers maintain next hop & cost of each destination.
- Connectivity/cost changes iteratively propagate form neighbour to neighbour
- Requires multiple rounds to converge
- Scales to large networks

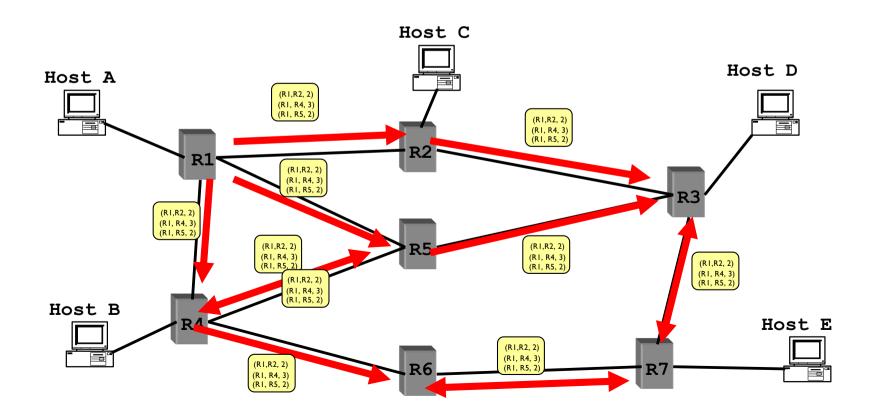
## Link State Routing

- Each node maintains its local "link state" (LS)
  - i.e., a list of its directly attached links and their costs



## Link State Routing

- Each node maintains its local "link state" (LS)
- Each node floods its local link state
  - on receiving a new LS message, a router forwards the message to all its neighbors other than the one it received the message from

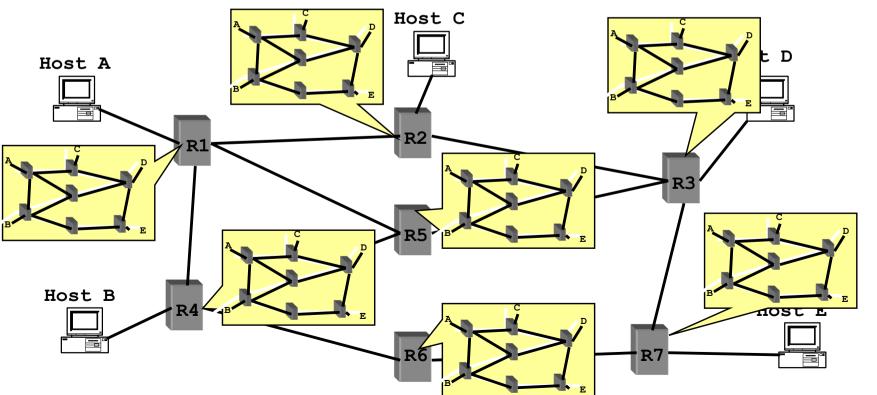


# Flooding LSAs

- Routers transmit Link State Advertisement (LSA) on links
  - A neighbouring router forwards out on all links except incoming
  - Keep a copy locally; don't forward previously-seen LSAs
- Challenges
  - Packet loss
  - Out of order arrival
- Solutions
  - Acknowledgements and retransmissions
  - Sequence numbers
  - Time-to-live for each packet

# Link State Routing

- Each node maintains its local "link state" (LS)
- Each node floods its local link state
- Eventually, each node learns the entire network topology
  - Can use Dijkstra's to compute the shortest paths between nodes



## A Link-State Routing Algorithm

The number of iteration is the number of

## Dijkstra s algorithm

- net topology, link costs known to all nodes
  - accomplished via "link state broadcast"
  - all nodes have same info
- computes least cost paths from one node ('source") to all other nodes
  - gives forwarding table for that node
- iterative: after k iterations, know least cost path to k dest.'s

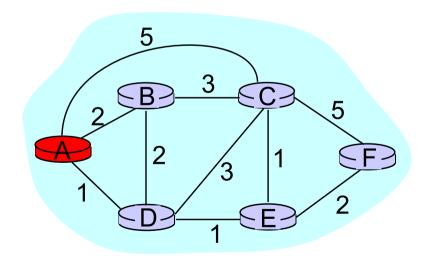
#### notation:

- \* C(X,y): link cost from node x to y; = ∞ if not direct neighbors
- D(V): current value of cost of path from source to dest. v
- D(V): predecessor node along path from source to
- N': set of nodes whose least cost path definitively known

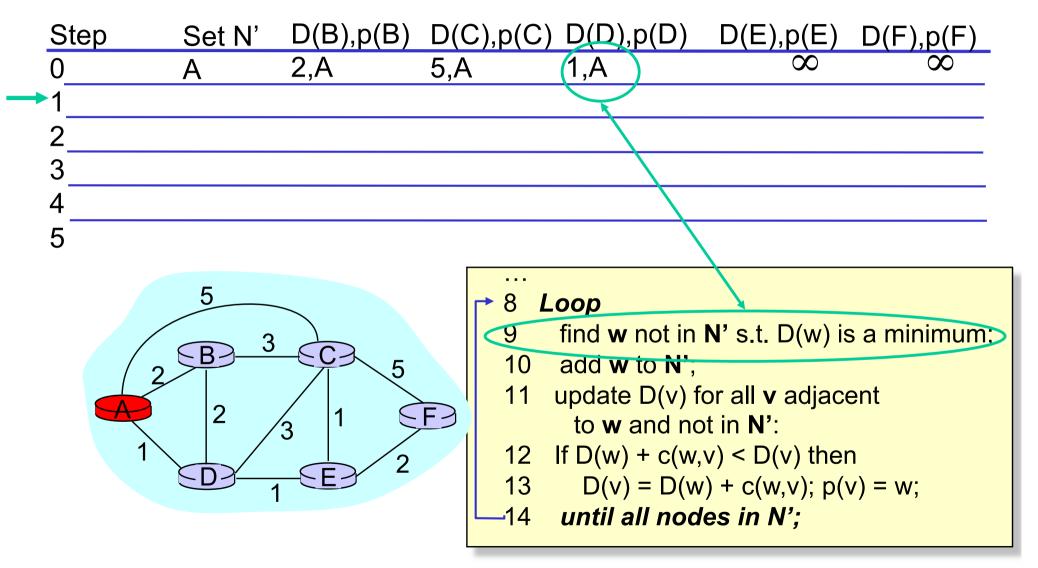
## Dijsktra's Algorithm

```
Initialization:
   N' = \{u\}
   for all nodes v
    if v adjacent to u
       then D(v) = c(u,v)
    else D(v) = \infty
   Loop
    find w not in N' such that D(w) is a minimum
   add w to N'
   update D(v) for all v adjacent to w and not in N':
      D(v) = \min(D(v), D(w) + c(w,v))
13 /* new cost to v is either old cost to v or known
14
     shortest path cost to w plus cost from w to v */
15 until all nodes in N'
```

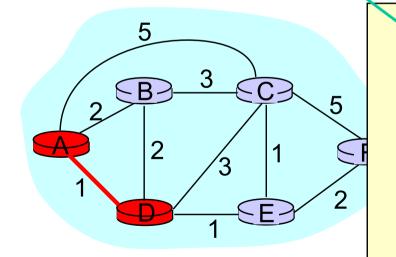
Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	1,A	$\infty$	$\infty$
1						
2						
3						
4						
5						



```
    1 Initialization:
    2 N' = {A};
    3 for all nodes v
    4 if v adjacent to A
    5 then D(v) = c(A,v);
    6 else D(v) = ∞;
    ...
```

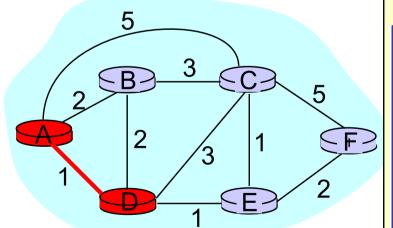


Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	A	2,A	5,A	1,A	$\infty$	$\infty$
<del></del>	AD					
2						
3						
4						
5						



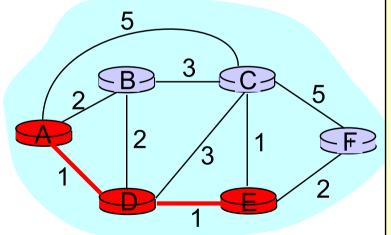
```
8 Loop
9 find w not in N' s.t. D(w) is a minimum;
10 add w to N';
11 update D(v) for all v adjacent to w and not in N':
12 If D(w) + c(w,v) < D(v) then</li>
13 D(v) = D(w) + c(w,v); p(v) = w;
14 until all nodes in N';
```

Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	1,A	$\infty$	$\infty$
<b>→</b> 1	AD <	2, A	4,D		2,D	
2						
3						
4						
5						



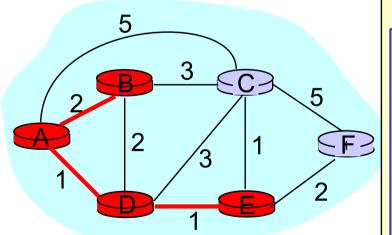
```
9 find w not in N' s.t. D(w) is a minimum;
10 add w to N';
11 update D(v) for all v adjacent
to w and not in N':
12 If D(w) + c(w,v) < D(v) then
13 D(v) = D(w) + c(w,v); p(v) = w;
14 until all nodes in N';
```

Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	1,A	$\infty$	$\infty$
1	AD	2, A	4,D		2,D	
<del>-</del> 2	ADE	2, A	3,E			4,E
3						
4						
5						



```
    Noop
    find w not in N' s.t. D(w) is a minimum;
    add w to N';
    update D(v) for all v adjacent to w and not in N':
    If D(w) + c(w,v) < D(v) then</li>
    D(v) = D(w) + c(w,v); p(v) = w;
    until all nodes in N';
```

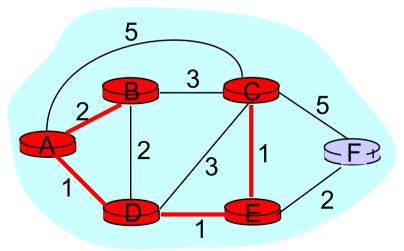
Step	o S	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	\	2,A	5,A	1,A	$\infty$	$\infty$
1	Α	νD	2,A	4,D		2,D	
2	Δ	DE	2,A	3,E			4,E
<b>→</b> 3	Α	DEB		3,E			4,E
4							



5

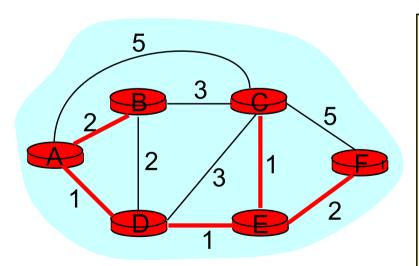
```
    Note: Note
```

Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	1,A	$\infty$	$\infty$
1	AD	2,A	4,D		2,D	
2	ADE	2,A	3,E			4,E
3	ADEB		3,E			4,E
<del>-</del> 4	ADEBC					4,E
5						



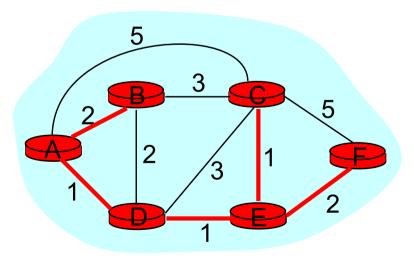
```
    → 8 Loop
    9 find w not in N' s.t. D(w) is a minimum;
    10 add w to N';
    11 update D(v) for all v adjacent to w and not in N':
    12 If D(w) + c(w,v) < D(v) then</li>
    13 D(v) = D(w) + c(w,v); p(v) = w;
    14 until all nodes in N';
```

Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	1,A	$\infty$	$\infty$
1	AD	2,A	4,D		2,D	
2	ADE	2,A	3,E			4,E
3	ADEB		3,E			4,E
4	ADEBC					4,E
<b>→</b> 5	ADEBCF					



```
    8 Loop
    9 find w not in N' s.t. D(w) is a minimum;
    10 add w to N';
    11 update D(v) for all v adjacent to w and not in N':
    12 If D(w) + c(w,v) < D(v) then</li>
    13 D(v) = D(w) + c(w,v); p(v) = w;
    14 until all nodes in N';
```

Step	Set N'	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	Α	2,A	5,A	(1,A)	$\infty$	$\infty$
1	AD		4,D		(2,D)	
2	ADE		(3,E)			4,E
3	ADEB					
4	ADEBC					
5	ADEBCF	Once inclu	ue all of the r	node, then we	e are done	

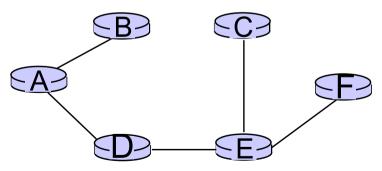


To determine path  $A \rightarrow C$  (say), work backward from C via p(v)

## The Forwarding Table

- Running Dijkstra at node A gives the shortest path from A to all destinations
- We then construct the forwarding table

resulting shortest-path tree from A:



- 1. Flooding to learn the topology of the whole map
- 2. Get the shortest path to each node

Destination	Link
В	(A,B)
С	(A,D)
D	(A,D)
E	(A,D)
F	(A,D)

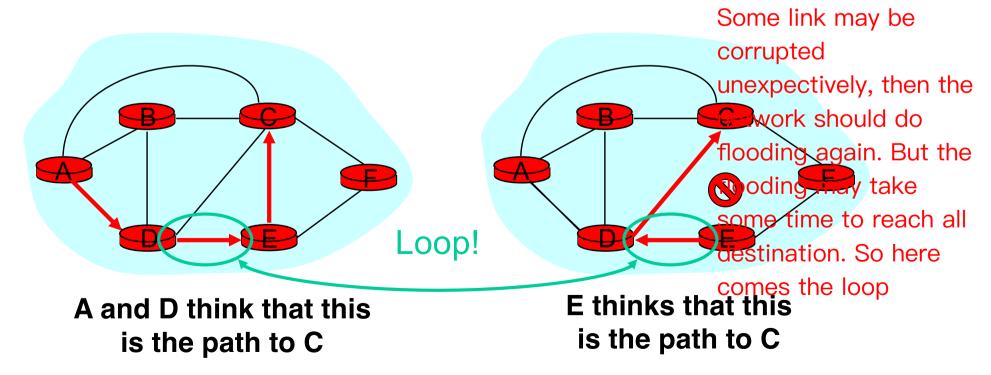
# Issue #1: Scalability

- How many messages needed to flood link state messages?
  - O(N x E), where N is #nodes; E is #edges in graph
- Processing complexity for Dijkstra's algorithm?
  - $O(N^2)$ , because we check all nodes w not in N' at each iteration and we have O(N) iterations
- $\bullet$  How many entries in the LS topology database? O(E)
- $\bullet$  How many entries in the forwarding table? O(N)

## Issue#2: Transient Disruptions

That is why we have TTL field

- Inconsistent link-state database
  - Some routers know about failure before others
  - The shortest paths are no longer consistent
  - Can cause transient forwarding loops

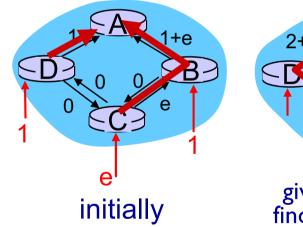


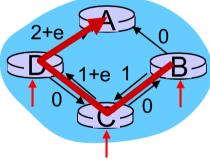
#### Oscillations

#### oscillations possible:

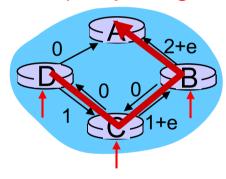
e.g., suppose link cost equals amount of carried traffic:

as the traffic change frequently, the cost also change. As a result, the routers have to keep adjusting forwarding table

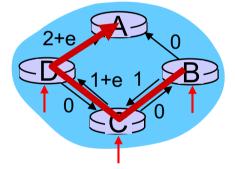




given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs

That is a dynamic process

## Network layer, control plane: outline

- 5.1 introduction
- 5.2 routing protocols
- link state
- distance vector
- hierarchical routing

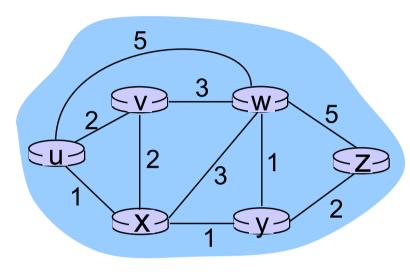
5.6 ICMP: The Internet Control Message Protocol

## Distance vector algorithm

Bellman-Ford equation A kind of distributed protolco

```
let
  d_{x}(y) := cost of least-cost path from x to y
then
  d_{x}(y) = \min_{x} \{c(x,v) + d_{v}(y)\}
                             cost from neighbor v to destination y
                    cost to neighbor v
             min taken over all neighbors v of x
```

## Bellman-Ford example



clearly, 
$$d_v(z) = 5$$
,  $d_x(z) = 3$ ,  $d_w(z) = 3$ 

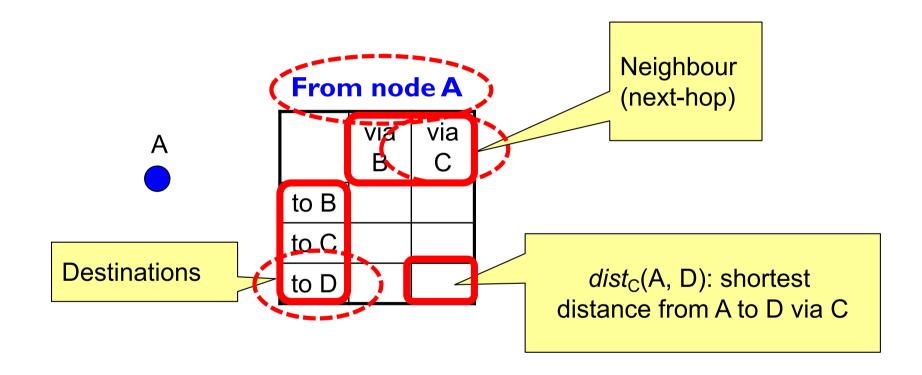
B-F equation says:

$$d_{u}(z) = \min \{ c(u,v) + d_{v}(z), \\ c(u,x) + d_{x}(z), \\ c(u,w) + d_{w}(z) \}$$

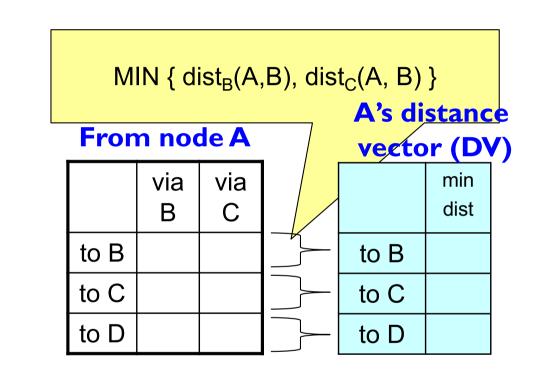
$$= \min \{ 2 + 5, \\ 1 + 3, \\ 5 + 3 \} = 4$$

node achieving minimum is next hop in shortest path, used in forwarding table

# How Distance-Vector (DV) works



Each router maintains its shortest distance to every destination via each of its neighbours



Each router computes its shortest distance to every destination via <u>any</u> of its neighbors

### From node A

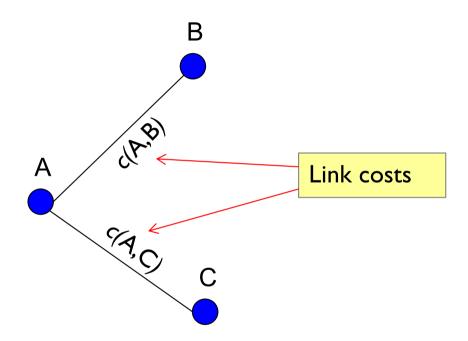
A

	via B	via C
to B	?	?
to C	?	?
to D	?	?

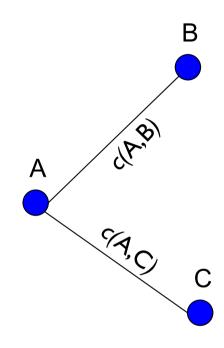
A's DV

	min dist
to B	?
to C	?
to D	?

How does A initialize its dist() table and DV?



How does A initialize its dist() table and DV?



From node A

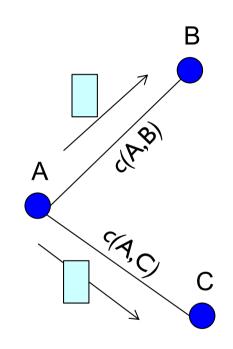
	via B	via C
to B	c(A,B)	∞
to C	8	c(A,C)
to D	8	∞

A's DV

	mindist
to B	c(A,B)
to C	c(A,C)
to D	8

Exchange this table with its neighbors

Each router initializes its dist() table based on its immediate neighbors and link costs



Assume that A's DV is as follows at some later time

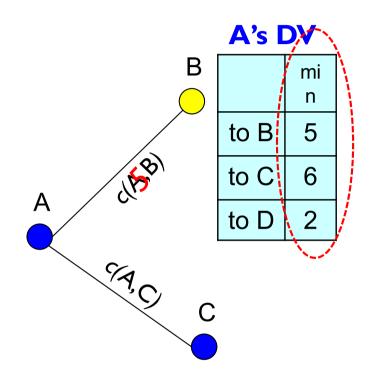
### From node A

	via B	via C
to B	c(A,B)	∞
to C	8	c(A,C)
to D	8	∞

### A's DV

	mindist
to B	5
to C	6
to D	2

Each router sends its DV to its immediate neighbors



From node B		
	via A	via C
to A	5	∞
to C	15	1
to D	00	∞

mindist

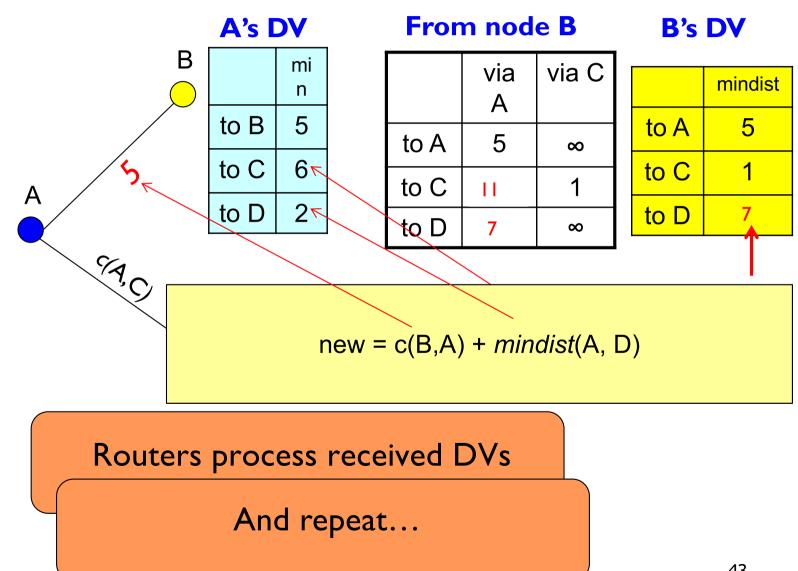
to A 5

to C 1

to D ∞

B's DV

Routers process received DVs



## Distance Vector Routing

- Each router knows the links to its neighbors
- Each router has provisional "shortest path" to every other router -- its distance vector (DV)
- Routers exchange this DV with their neighbors Finally they would converge, which means the router who have the full network of destinations in the table. And they has the shortest path. In a way,
- Routers look over the set of options offered by their neighbors and select the best one

Iterative process converges to set of shortest paths

## Distance vector routing

## iterative, asynchronous:

each local iteration caused by:

- local link cost change
- DV update message from neighbor

### distributed:

- each node notifies neighbors only when its DV changes
  - neighbors then notify their neighbors if necessary

### each node:

wait for (change in local link cost or msg from neighbor) recompute estimates if DV to any dest has changed, *notify* neighbors

### Distance Vector

- c(i,j): link cost from node i to j
- dist<sub>Z</sub>(A,V): shortest dist. from A to V via Z
- mindist(A,V): shortest dist. from A to V

```
0 At node A
1 Initialization:
    for all destinations V do
        if V is neighbor of A
            dist_{V}(A, V) = mindist(A, V) = c(A, V);
5
        else
6
             dist_{V}(A, V) = mindist(A, V) = \infty;
     send mindist(A, *) to all neighbors
loop:
   wait (until A sees a link cost change to neighbor V /* case 1 */
          or until A receives mindist(V,*) from neighbor V) /* case 2 */
     if (c(A, V) changes by \pm d) /* \leftarrow \mathbf{case 1} */
11
        for all destinations Y do
12
                  dist_{\vee}(A, Y) = dist_{\vee}(A, Y) \pm d
     else /* \leftarrow case 2: */
        for all destinations Y do
14
15
                  dist_{V}(A, Y) = c(A, V) + mindist(V, Y);
     update mindist(A, *)
15 if (there is a change in mindist(A, *))
          send mindist(A, *) to all neighbors
16
17 forever
```

### Distance Vector

- c(i,j): link cost from node i to j
- dist<sub>Z</sub>(A,V): shortest dist. from A to V via Z
- mindist(A,V): shortest dist. from A to V

```
0 At node A
1 Initialization:
    for all destinations V do
        if V is neighbor of A
            dist_{V}(A, V) = mindist(A, V) = c(A, V);
5
        else
6
             dist_{V}(A, V) = mindist(A, V) = \infty;
     send mindist(A, *) to all neighbors
loop:
   wait (until A sees a link cost change to neighbor V /* case 1 */
          or until A receives mindist(V,*) from neighbor V) /* case 2 */
     if (c(A, V) changes by \pm d) /* \leftarrow \mathbf{case 1} */
11
        for all destinations Y do
12
                  dist_{\vee}(A, Y) = dist_{\vee}(A, Y) \pm d
     else /* \leftarrow case 2: */
        for all destinations Y do
14
15
                  dist_{V}(A, Y) = c(A, V) + mindist(V, Y);
     update mindist(A, *)
15 if (there is a change in mindist(A, *))
          send mindist(A, *) to all neighbors
16
17 forever
```

## **Example: Initialization**

#### from Node B

	via A	via C	via D	min dist
to A	2	∞	∞	2
to B	-	-	-	0
to C	8	1	8	1
to D	∞	8	3	3

from Node D

	via B	via C
to A	8	8
to B	3	8
to C	8	1
to D	ı	-

min dist	
8	
3	
1	
0	

At this moment, if a packet arrive whose dest is D then it would be dropped A

free Ned A doesn't know the path to

DCO	via B	via C
to A	-	-
to B	2	8
to C	8	7
to D	8	8

know	th	e path to
min		min
dist		dist
0		0
2		2
7	,	7
∞		∞

	via A	via B	via D	mi dis
to A	7	∞	∞	7
to B	∞	1	∞	1
to C	-	-	-	0
to D	∞	∞	1	1

#### from Node B

	via A	via C	via D	min dist
to A	2	∞	∞	2
to B	-	-	-	0
to C	8	1	∞	1
to D	8	∞	3	3

### from Node D

	via B	via C
to A	8	8
to B	3	8
to C	8	1
to D	-	-

min dist
∞
3
1
0

#### from Node A

	via B	via C
to A	-	-
to B	2	8
to C	8	7
to D	8	8

min dist

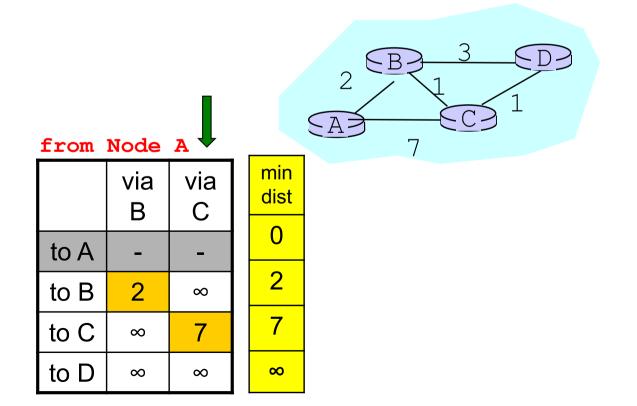
0

2

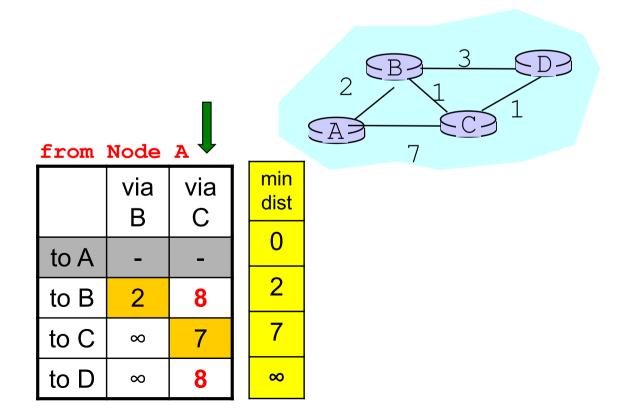
7

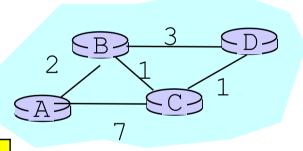
∞

	via A	via B	via D	d d
to A	7	8	8	
to B	∞	1	8	
to C	-	-	-	
to D	∞	8	1	



50





	via B	via C
to A	-	-
to B	2	8
to C	8	7
to D	8	8

min dist	
0	
2	
7	
8	

#### from Node B

	via A	via C	via D	min dist
to A	2	8	∞	2
to B	-	-	-	0
to C	8	1	∞	1
to D	8	8	3	3

#### from Node D

	via B	via C
to A	8	8
to B	3	8
to C	8	1
to D	ı	-

_	
	min dist
	<b>∞</b>
	3
	1
	0

#### from Node A

	via B	via C
to A	-	-
to B	2	8
to C	8	7
to D	8	8

min dist

0
2
7

	via A	via B	via D	min dist
	, ,			7
to A	7	8	8	/
				4
to B	∞	1	∞	1
to C	-	-	-	0
to D	∞	∞	1	1
	- •	- •	1	

#### from Node B

	via A	via C	via D	mir dis
to A	2	∞	∞	2
to B	-	-	-	0
to C	8	1	∞	1
to D	8	8	3	3

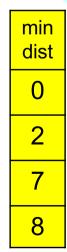
### from Node D

	via B	via C
to A	8	8
to B	3	8
to C	8	1
to D	-	-

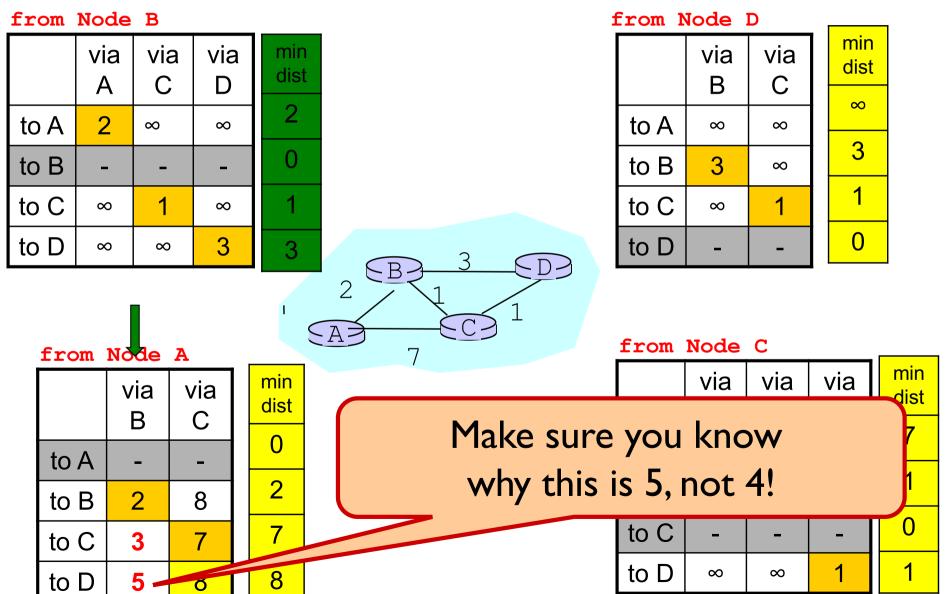
min dist
8
3
1
0

### from Node A

	via B	via C		
to A	-	-		
to B	2	8		
to C	8	7		
to D	8	8		



	via A	via B	via D	m di
to A	7	8	∞	
to B	∞	1	∞	
to C	-	-	-	(
to D	∞	8	1	•



#### from Node B

	via A	via C	via D	min dist
to A	2	<b>∞</b>	∞	2
to B	-	-	-	0
to C	8	1	∞	1
to D	∞	∞	3	3



	via B	via C
to A	8	8
to B	3	8
to C	8	1
to D	ı	-

min dist
∞
3
1
0

#### from Node A

	via B	via C
to A		-
to B	2	8
to C	3	7
to D	5	8

min dist

0

2

3

	via A	via B	via D	mi dis
to A	7	∞	∞	7
to B	∞	1	∞	1
to C	-	-	-	0
to D	8	∞	1	1

### All nodes know the best two-hop paths.

### Make sure you believe this

### from Node B

	via A	via C	via D	min dist
to A	2	8	∞ ∞	2
to B	-	-	-	0
to C	9	1	4	1
to D	∞	2	3	2

### from Node D

	via B	via C
to A	5	8
to B	3	2
to C	4	1
to D	-	-

	min dist
	5
	2
	1
Ī	0

#### from Node A

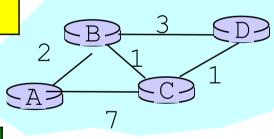
	via B	via C
to A	-	-
to B	2	8
to C	3	7
to D	5	8

min dist
0
2
3
5

<del></del>				
	via A	via B	via D	min dist
	, ,	<b>)</b>		0
to A	7	3	8	3
				4
to B	9	1	4	
				0
to C	\-	-	-	U
to D	<b>≫</b>	1	1	1
to D	8	4		

	via A	via C	via D	mir dist
to A	2	8	∞	2
to B	-	-	-	0
to C	9	1	4	1
to D	8	2	3	2

dist	
2	
0	
	l



#### from Node D

	via B	via C
to A	5	8
to B	3	2
to C	4	1
to D	ı	-

min dist
5
2
1
0

#### from Node A

	via B	via C
to A		-
to B	2	8
to C	3	7
to D	5	8

min dist 0

	via A	via B	via D		
to A	7	3	∞		
ιο / ι		0			
to B	9	1	4		
to C	_	_	_		
				_	
to D	8	4	1		

## Example: Nov

### **Updated**

### from Note B

	via A	via C	via D	min
to A	2	8	∞	
to B	-	-		0
to C	/5	1/	4	1
to D	<sup>1</sup> 7	2	3	2

### from Node D

	via B	via C
to A	5	8
to B	3	2
to C	4	1
to D	-	-

m di	
5	5
2	2
1	
	)

### from Node A

	via B	via C
to A	-	-
to B	2	8
to C	3	7
to D	5	8

min dist

0

2

3

### from Node C

	via A	via B	via D
to A	7	3	8
to B	9	1	4
to C	-	-	-
to D	8	4	1

min dist

3

1

### Check: All nodes know the best three-hop paths.

Check

#### from Node B

	via A	via C	via D	min dist
to A	2	4	8	2
to B	-	-	-	0
to C	5	1	4	1
to D	7	2	3	2

### from Node D

	via B	via C
to A	5	4
to B	3	2
to C	4	1
to D	-	-

min dist	
4	
2	
1	
0	

#### from Node A

	via B	via C
to A	-	-
to B	2	8
to C	3	7
to D	4	8

### from Node C

	via A	via B	via D	
to A	7	3	6	
to B	9	1	3	
to C	-	-	-	
to D	12	3	1	

min dist

3

### Example: End of 3<sup>nd</sup> Full Exchange

### No further change in DVs → Convergence!

#### from Node B

	via A	via C	via D	min dist
to A	2	4	7	2
to B	-	-	-	0
to C	5	1	4	1
to D	6	2	3	2

### from Node D

	via B	via C		
to A	5	4		
to B	3	2		
to C	4	1		
to D	ı	-		

min dist	
4	
2	
1	
0	

#### from Node A

	via B	via C
to A	ı	-
to B	2	8
to C	3	7
to D	4	8

min dist

0
2
3

	via A	via B	via D	mir dis		
	, <b>,</b> ,			3		
to A	7	3	5	3		
_	_		_	1		
to B	9	1	3	<u>'</u>		
1- 0				0		
to C	-	-	-	U		
to D	11	3	1	1		
10 D	' '	<u> </u>		•		

### Intuition

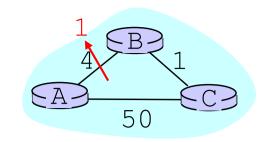
- Initial state: best one-hop paths
- One simultaneous round: best two-hop paths
- Two simultaneous rounds: best three-hop paths
- **\*** ...
- Kth simultaneous round: best (k+1) hop paths
- Must eventually converge
  - as soon as it reaches longest best path
- ....but how does it respond to changes in cost?

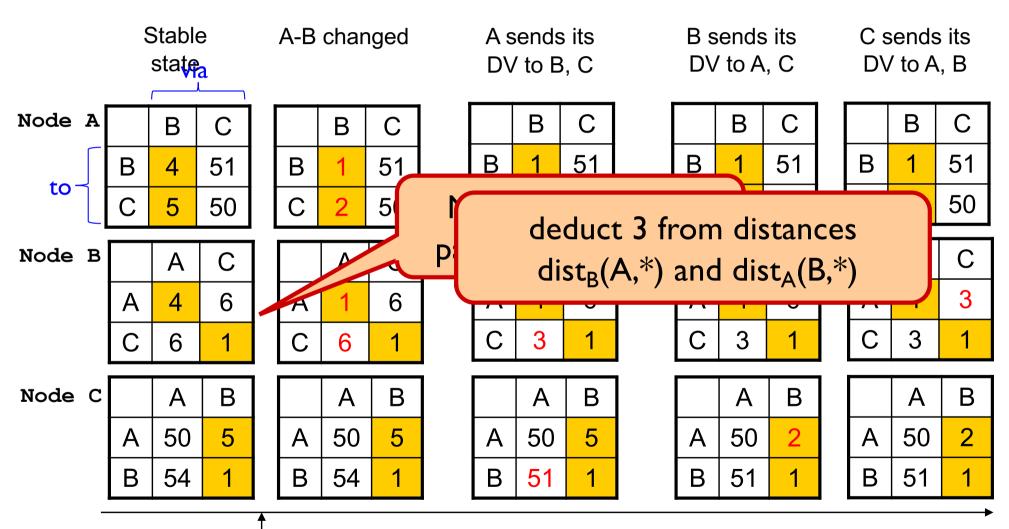
### Problems with Distance Vector

- A number of problems can occur in a network using distance vector algorithm
- Most of these problems are caused by slow convergence or routers converging on incorrect information
- Convergence is the time during which all routers come to an agreement about the best paths through the internetwork
  - whenever topology changes there is a period of instability in the network as the routers converge
- Reacts rapidly to good news, but leisurely to bad news

### **DV: Link Cost Changes**

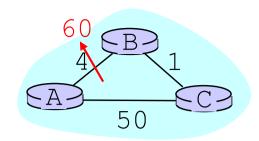
Link cost changes here

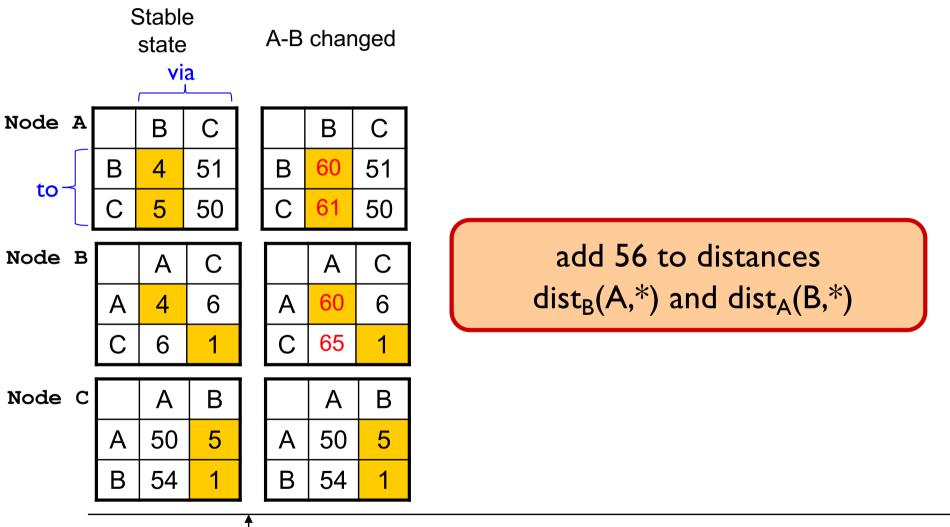




"good news travels fast"

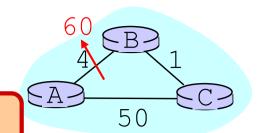
### **DV: Link Cost Changes**



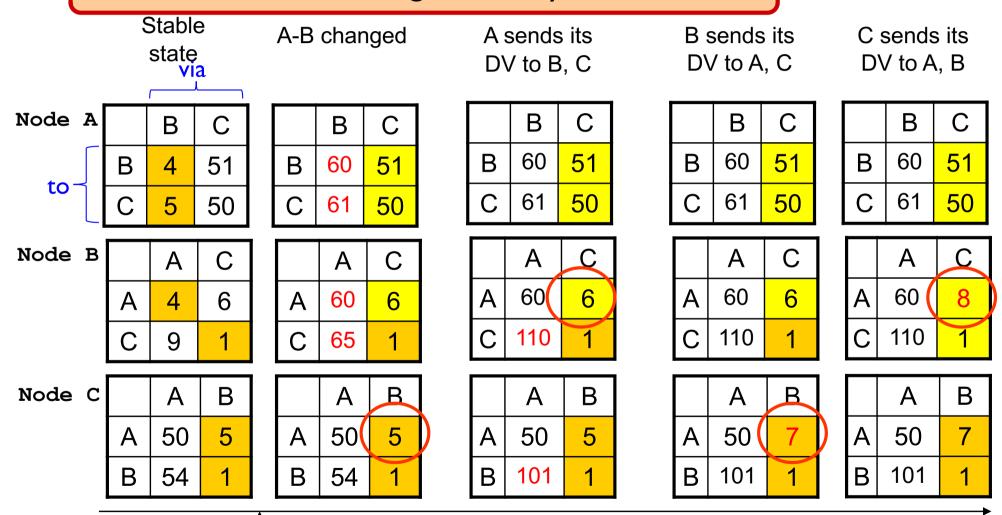


Link cost changes here

## **DV: Link Cost Changes**



### This is the "Counting to Infinity" Problem

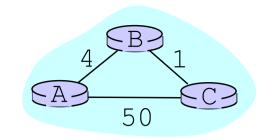


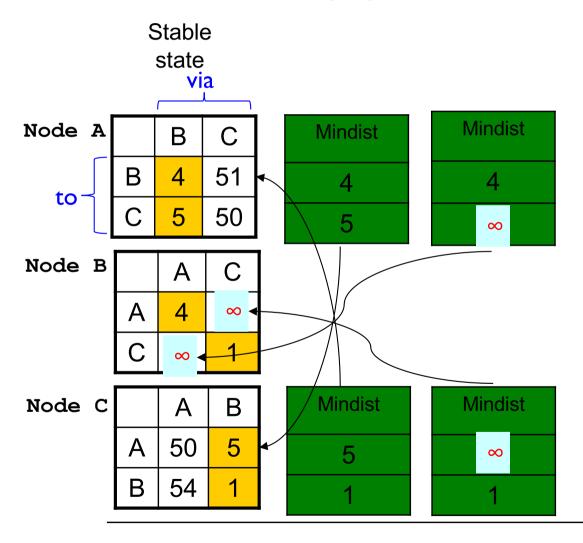
Link cost changes here

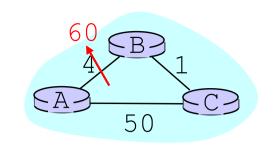
"bad news travels slowly" (not yet converged)

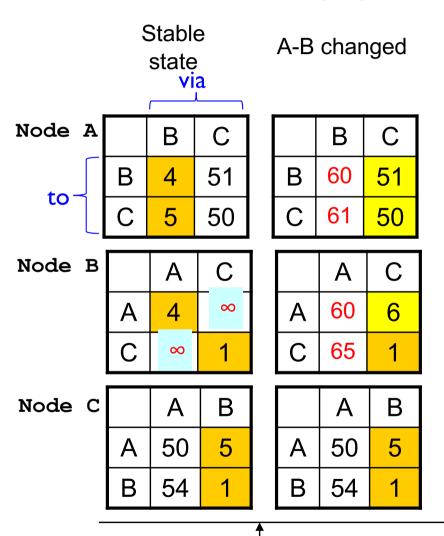
### The "Poisoned Reverse" Rule

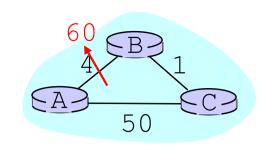
- Heuristic to avoid count-to-infinity
- If B routes via C to get to A:
  - B tells C its (B's) distance to A is infinite (so C won't route to A via B)

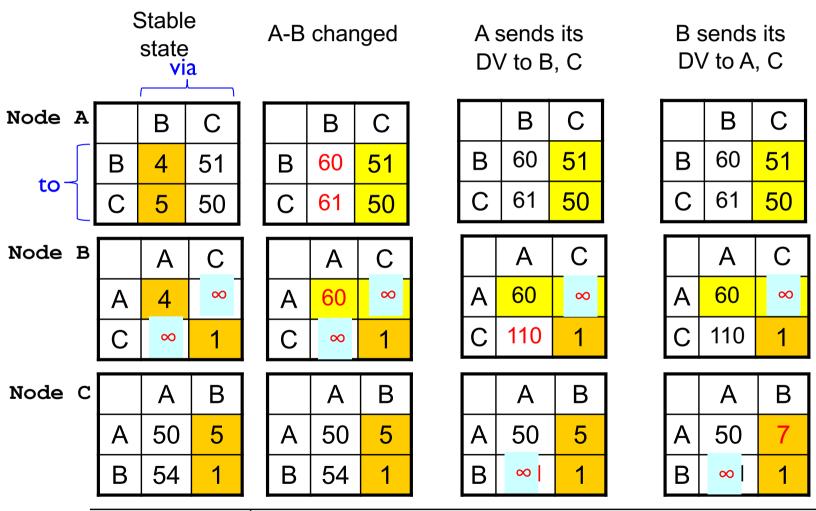


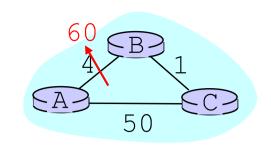


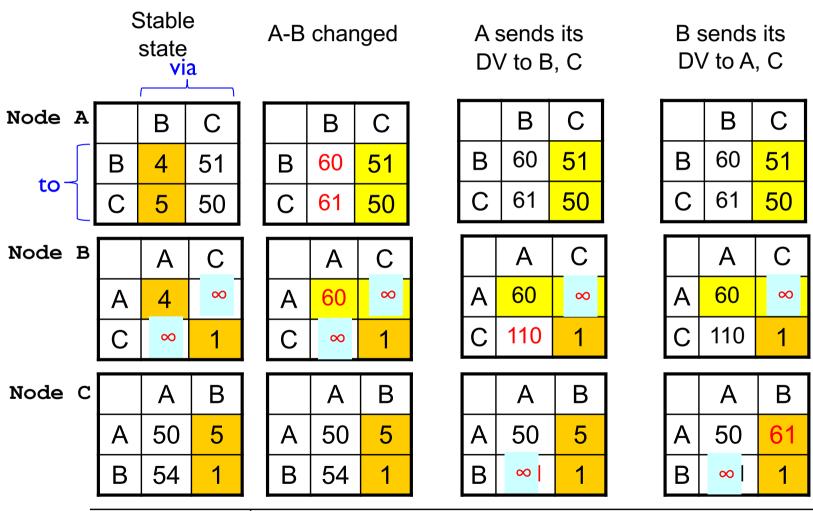




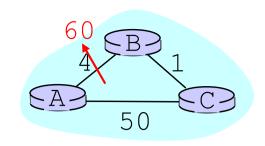


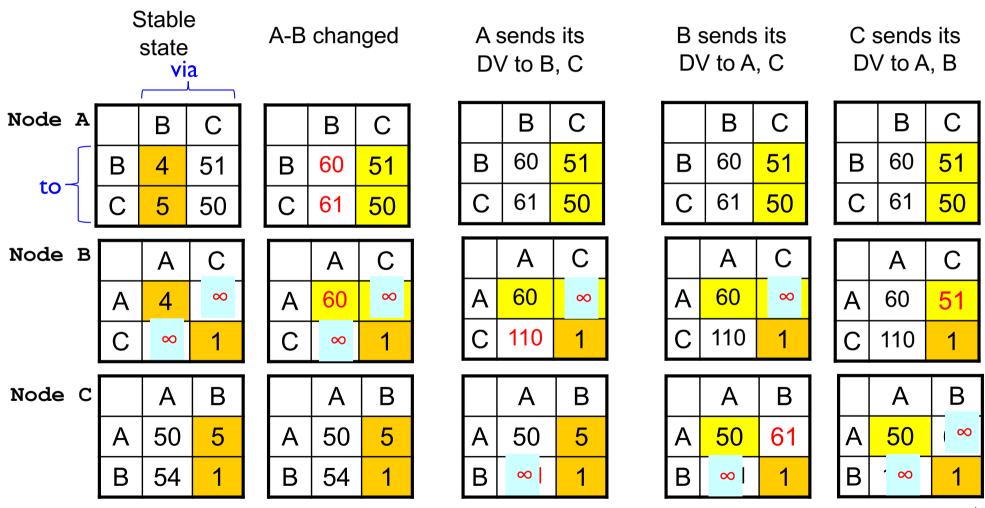






If B routes through C to get to A:
B tells C its (B's) distance to A is infinite

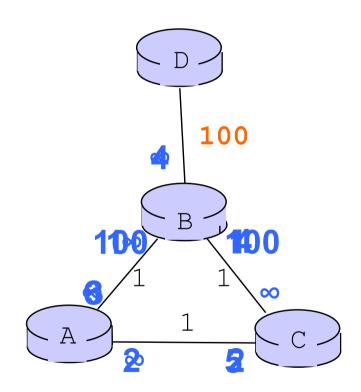




Link cost changes here

Converges after C receives another update from B 7

# Will Poison-Reverse Completely Solve the Count-to-Infinity Problem?



Numbers in blue denote the best cost to destination D advertised along the link

## Quiz: Link-state routing

- In link state routing, each node sends information of its direct links (i.e., link state) to \_\_\_\_\_?
- A. Immediate neighbours
- B. All nodes in the network
- C. Any one neighbor
- D. No one

## Quiz: Distance-vector routing

- In distance vector routing, each node shares its distance table with
- A. Immediate neighbours
- B. All nodes in the network
- C. Any one neighbor
- D. No one

## Quiz: Distance-vector routing

- Which of the following is true of distance vector routing?
- A. Convergence delay depends on the topology (nodes and links) and link weights
- B. Convergence delay depends on the number of nodes and links
- C. Each node knows the entire topology
- D. A and C
- E. B and C

Each link does't know the entire topology. For instead, they just know the ssp to each node

### Comparison of LS and DV algorithms

### message complexity

- LS: with n nodes, E links, O(nE) msgs sent
- DV: exchange between neighbors only
  - convergence time varies

### speed of convergence

- LS: O(n²) algorithm requires
   O(nE) msgs
  - may have oscillations
- DV: convergence time varies
  - may be routing loops
  - count-to-infinity problem

## robustness: what happens if router malfunctions?

### LS:

- node can advertise incorrect link cost
- each node computes only its own table

### DV:

- DV node can advertise incorrect path cost
- each node's table used by others
  - error propagate thru network

### Real Protocols

### Link State

Open Shortest Path First (OSPF)

Intermediate system to intermediate system (IS-IS)

### Distance Vector

Routing Information Protocol (RIP)

Interior Gateway Routing Protocol (IGRP-Cisco)

Border Gateway Protocol (BGP)

### Network layer, control plane: outline

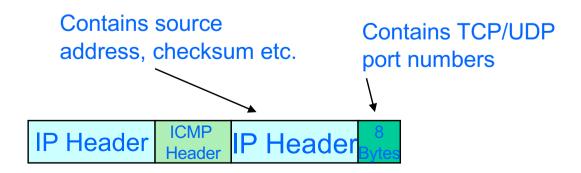
- 5.1 introduction
- 5.2 routing protocols
- link state
- distance vector
- hierarchical routing

5.6 ICMP: The Internet Control Message Protocol

Self study

### ICMP: Internet Control Message Protocol

- Used by hosts & routers to communicate network level infromation
  - Error reporting: unreachable host, network, port
  - Echo request/reply (used by ping)
- Works above IP layer
  - ICMP messages carried in IP datagrams
- ICMP message: type, code plus IP header and first
   8 bytes of IP datagram payload causing error



### ICMP: Internet Control Message Protocol

<ul><li>Type</li></ul>	Code	Description
0	0	echo reply(ping)
3	0	dest. network unreachable
3	I	dest host unreachable
3	3	dest port unreachable
3	4	frag needed; DF set
8	0	echo request(ping)
11	0	TTL expired
11	I	frag reassembly time exceeded
12	0	bad IP header

## Traceroute and ICMP

- Source sends series of UDP segments to dest
  - first set has TTL = I
  - second set has TTL=2, etc.
  - unlikely port number
- When nth set of datagrams arrives to nth router:
  - router discards datagrams
  - and sends source ICMP messages (type II, code 0)
  - ICMP messages includes IP address of router

when ICMP messages arrives, source records RTTs

### stopping criteria:

- UDP segment eventually arrives at destination host
- destination returns ICMP "port unreachable" message (type 3, code 3)
- source stops

