$$D = \{(0,1,2,3)\}$$

$$\Delta = \{(0,1,2,3)\}$$

$$\Delta = \{(0,1,2,3)\}$$

$$x + 2y - 2z - w = x - y + z + 2w = 0$$
 $3y = 3z + 3w$

$$X = Y - \overline{z} - 2\omega = \cancel{z} + \omega - \cancel{z} - 2\omega = -\omega$$

$$S = \frac{1}{2} \left(-\omega, \frac{1}{2} + \omega, \frac{1}{2}, \omega \right) / \frac{1}{2}, \omega \in \mathbb{R}^{3}$$

Force
$$S = \{(0,1,1,0), (-1,1,0,1)\} = \{v_1,v_2\}$$

Base ortogonal de S

$$\left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{1}=v_{1} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{2} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{3}=v_{3} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{4}=v_{3} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}{c} (0,1,0) \\ \omega_{5}=v_{5} \end{array} \right\} = \frac{1}{2} \left\{ \begin{array}$$

$$\frac{1}{\|V_1\|^2} = V_2 - \frac{\langle V_1, V_2 \rangle}{\|V_1\|^2} V_3 = \frac{\langle V_1, V_2 \rangle}{\|V_1\|^2}$$

$$= (-1, 1/2, -1/2, 1).$$

Projeção ortogonal de (0,1,2,3)=v

$$Lu0!^{2}(a) = \frac{\|m^{2}\|_{S}}{\langle a^{1}m^{7}\rangle} \quad m^{7} + \frac{\|m^{5}\|_{S}}{\langle a^{1}m^{5}\rangle} \quad m^{5}$$

$$=\frac{3}{2}\omega_{1}+\frac{5}{10}\omega_{2}=\frac{3}{2}\omega_{1}+\frac{1}{2}\omega_{2}$$

$$P_{A}(x) \stackrel{\text{def}}{=} 2 1 - x 0$$

$$\Rightarrow 0 2 - x$$

A matriz e' triangular $P_A(x) = (1-x)^2(z-x)$

o determinante e' o produto da diagonal!

Autovalores +1 com multiplicidade alg = 2. +2 4 n alg =1.

Autoespaço assoc. ao autovalor 1:

$$\begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \begin{cases} 2x = 0 = Dx = 0 \\ 3x + 2 = 0 = Dx = 0 \end{cases}$$

Aut (1) = 2 (0, y, 0) / y = 12} [mg(1) =]

A não e' dioigonalizavel pois [mq(1) = 2 > mg(1) = 1]

• Aut
$$(-2) = \frac{1}{2}(2y-2,y,2) / y, z \in \mathbb{R}^{3}$$

Pase $\frac{1}{2}(2y-2,y,2) / y, z \in \mathbb{R}^{3}$
 $y=1 \ z=0$ $y=0 \ z=1$

• Aut
$$(4) = \frac{1}{2}(x,0,x) / 3c \in \mathbb{R}^{2}$$

Base = $\frac{1}{2}(1,0,1)$

Temos que
$$B = \frac{1}{2}(2,1,0), (-1,0,1), (1,0,1)$$

el base de \mathbb{R}^3 e

$$T \int_{B}^{B} = \begin{bmatrix} -2 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 4 \end{bmatrix} = D$$

$$P = \begin{bmatrix} 2 & -1 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix} = I \end{bmatrix} \xrightarrow{B}$$
Base carônia

Assim
$$T \int_{Bc}^{Bc} = P D P^{-1}$$

$$= I \int_{Bc}^{B} T \int_{B}^{B} I \int_{B}^{Bc}$$

$$= I \int_{Bc}^{B} T \int_{Bc}^{B} I \int_{Bc}^{Bc}$$

$$= I \int_{Bc}^{Bc} T \int_{Bc}^{Bc} I \int_{Bc}^{Bc}$$

$$= I \int_{Bc}^{Bc} T \int_{Bc}^{Bc} I \int_{Bc}^{C} I \int_{C}^{C} I \int_{C}^{C$$

(4) Cônica 10x2+10y2+12xy+8 (5x +24/5y-32=0) Dividindo por 2

5x2+5y2 +6xy +4V2 x +12V2y -16=0.

Forma Quadratica $\begin{bmatrix} 5 & 3 \\ 3 & 5 \end{bmatrix} = Q$ $P_{D}(x) = (x-5)^{2} - 9 = x^{2} - 10x + 16$

Autovalorea 8 e 2.

 $\lambda = 8 \qquad \begin{bmatrix} -3 & 3 \\ 3 & -3 \end{bmatrix} \begin{bmatrix} \chi \\ \zeta \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

 $\text{Aut}(8) = \{(x, x) \mid x - y = 0\} = \{(x, x) \mid x \in \mathbb{R}^{2}\}$

Base ortonormal & (1/52, 1/52)}

 $\lambda = 2$ $\begin{cases} 3 & 3 \\ 3 & 3 \end{cases} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Aut (z) = } (-x, -x) / X = 12}

Base ortonormal } (1/1/2, +/1/2) (
de Aut (2)

 $P = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$ Matriz da Rotação $\begin{bmatrix} 4\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$ $\begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} = \begin{bmatrix} 16 & 8 \end{bmatrix}$ 8x'2 + 2y'2 + 16x' + 8y' - 16=0 Dividindo por 2 4x'2 + y'2 + 8x' + 4y' - 8=0 Para simplificar Completando Quadrados:

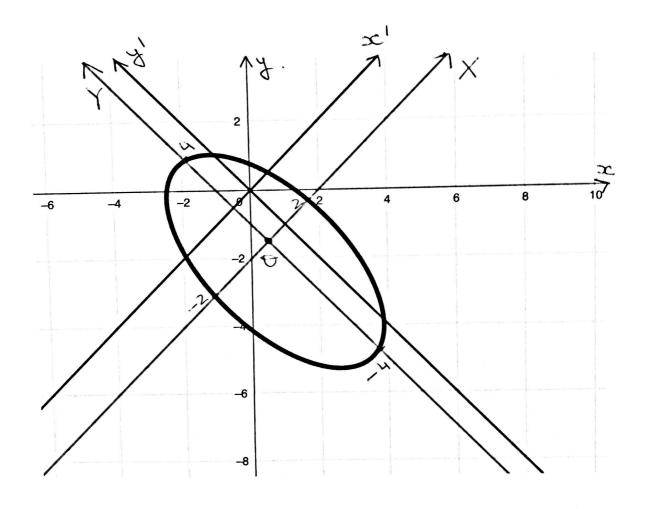
$$\frac{(x'+1)^2}{(x'+1)^2} + (y'+2)^2 = 16.$$

Nova origem (-1, -2).

Equação Reduzida

$$\frac{\chi^2}{2^2} + \frac{\gamma^2}{4^2} = 1.$$

A cônica e' uma Elipse



$$\frac{\chi^2}{2^2} + \frac{\gamma^2}{4^2} = 1.$$