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Vijaxstark

Summary _

Machine learning engineer with a strong foundation in applied ML, deep learning, and computer vision. Experienced in building models for prediction, image segmentation, and real-time detection across varied problem statements. Currently exploring multi-modal AI, with an interest in developing systems that can interpret and connect information across text, images, and structured data.

Experience _

Science and Humanities Dept, IIITDM Kancheepuram, Research Intern

Dec 2023 - present

- Built regression-based models to predict creep life of nickel-based superalloys using compositional and microstructural features, results published at CICT 2024.
- Currently designing an inverse materials discovery pipeline using conditional GANs, aiming to generate alloy compositions that satisfy specific creep resistance targets.

AUV Society, IIITDM, Team Lead

July 2022 – June 2024

- Led a 22 member team (Team Saaral) in building an autonomous underwater vehicle (AUV) from the ground up, managing integration of mechanical, electrical, and computer vision systems.
- Designed core mechanical components including watertight housings and modular frame layouts; developed realtime object detection pipelines using YOLO for underwater navigation and task automation.
- Participated as finalists in SAUVC 2024, presenting a fully functional AUV at an international robotics competition.

AMTDC, IIT Madras, Research Intern

May 2023 – July 2023

· Developed a time synchronization system using Raspberry Pi and Precision Time Protocol (PTP) to improve coordination in industrial and robotic applications.

Education ____

B.Tech IIITDM Kancheepuram, Mechanical Engineering

Chennai, India

• CGPA 8.78/10

Aug 2021 - May 2025

· Minor in Machine Learning

Publications

Creep Life Prediction for Superalloys using Gradient Boosting Decision Trees

Dec 2024

Vijay Krishna RV, Khushbu Dash, RJ Vikram, Nachiketa Mishra

CICT 2024, IIIT Allahabad

- Built and evaluated multiple regression models for predicting creep life of superalloys; gradient boosting decision trees (GBDT) outperformed other methods in terms of accuracy and generalization

Biomimetic Seasnail Soft Robot for Underwater Exploration (Accepted)

Mar 2025

Vijay Krishna RV, Srikrishnan Srinivasan

International Symposium on Underwater Technology (UT 2025), Taiwan

- Proposed a **soft robotic** platform integrating **YOLOv11**-based object detection for underwater trash identification

Skills

Programming: Python, C++, HTML, Javascript

ML & Deep Learning: PyTorch, TensorFlow, scikit-learn, NumPy, Pandas, OpenCV, MediaPipe, YOLO, U-Net

Tools & Frameworks: Git, SQL, Docker, FastAPI, W&B

Projects

Deepfake Detection using CNN, ViT, and XceptionNet

Built a deep learning pipeline to classify real vs. fake video frames using ResNet-50, Vision Transformer (ViT), and XceptionNet; achieved **97.8%** accuracy with AUC-ROC of **0.9978** using face-centric preprocessing with MTCNN and advanced image augmentation techniques.

Brain Tumor Segmentation using U-Net

Developed a U-Net-based deep learning model for brain tumor segmentation from MRI scans. Implemented custom data generators, augmentation, and Dice loss to handle class imbalance; achieved a Dice coefficient of **0.87** and IoU of **0.80** on the validation set.

News Summarization using BART

Fine-tuned a BART transformer model on the ILSUM dataset to generate abstractive summaries from long-form news articles; achieved ROUGE-1: **50.18**, ROUGE-2: **37.73**, and ROUGE-L: **45.38** on the test set.

Real-Time Pose Classification with MediaPipe

Developed a system that classifies human poses in real time using MediaPipe, enabling gesture-triggered virtual assistant actions.

BMI and Gender Estimation using Swin Transformer V2 and ResNet-50

Built a multi-task prediction system using facial images to estimate BMI and gender, leveraging Swin Transformer V2 and ResNet-50. Achieved an R2 score of **0.91** and Pearson correlation > **0.92** for BMI prediction, with extensive preprocessing including face cropping, augmentation, and normalization.

Document Parsing with LayoutLMv3

Fine-tuned LayoutLMv3 on the FUNSD dataset for token classification in document understanding. Integrated PyTorch Lightning and W&B for training and logging; achieved an F1-score of **84.6**% and validation accuracy of **89.2**% with bounding-box level visualization and structured field tagging.

Relevant Courses

• Pattern Recognition, Artificial Intelligence, Deep Learning, Data Science, Computer Vision, Data Structures and Algorithms

Certifications

- Machine Learning and Deep Learning Specialization Coursera
- Introduction to LLMs NPTEL
- Deep Learning for Computer Vision- NPTEL
- · Advanced Financial Analytics NPTEL

Competitions

- 2nd Place, Push & Router Tracks Unfold 2023 Web3 Hackathon: Built "Coinvo," a decentralized chat app with crypto payments and token-gated group access using the Polygon blockchain.
- Finalists SAUVC 2024 (Team Saaral), Singapore: Designed and deployed an autonomous underwater vehicle (AUV); led vision and systems architecture for international robotics competition.
- Global Finalists (3rd Worldwide) MATE ROV Virtual Challenge: Contributed to simulation design, testing pipelines, and control systems for autonomous underwater robotics.
- Top 100 Finalist Create the Future Design Contest (Tech Briefs, USA): Proposed a hybrid AUV-ROV platform for underwater exploration and aquaculture monitoring.