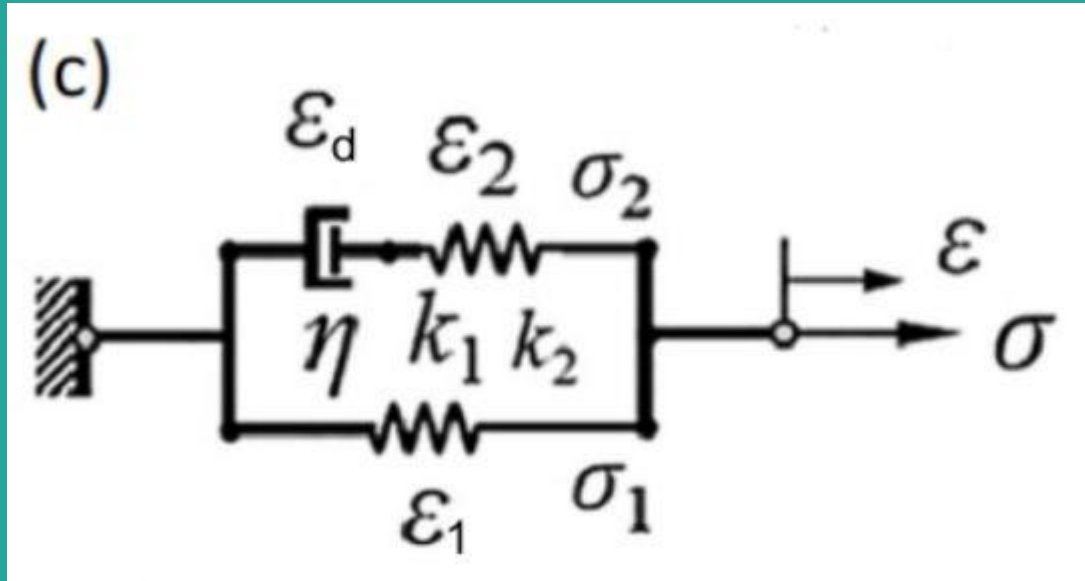


PROJECT-1

CE7620-Rheology of Civil Engineering Materials

ME21S030 - VIJAY HAJARE

Spring and dash-pot arrangement



Question A

Find the relation between the stress, stress rate, strain, and strain rate

$$\sigma_1 = k_1 \varepsilon_1$$

$$\sigma_2 = k_2 \varepsilon_2$$

$$\sigma_d = \eta \dot{\varepsilon}_d$$

$$\varepsilon = \varepsilon_1 = \varepsilon_2 + \varepsilon_d$$

$$\sigma_1 + \sigma_M = \sigma$$

$$\sigma_2 = \sigma_d = \sigma_M$$

where,

σ = stress in spring 1

σ = stress in spring 2

σ = stress in dash-pot

σ = stress in maxwell model

ε = strain in spring 1

ε = strain in spring 2

ε = strain in dash-pot

η = dash-pot constant

k_1 = spring constant in spring 1

k_2 = spring constant in spring 2

Question A

$$\frac{k_1 \varepsilon}{\eta} + \left(\frac{k_1}{k_2} + 1 \right) \dot{\varepsilon} = \frac{\sigma}{\eta} + \frac{\dot{\sigma}}{k_2}$$

Comparing above equation with

$$q_0 \varepsilon + q_1 \dot{\varepsilon} = p_0 \sigma + p_1 \dot{\sigma}$$

$$q_0 = \frac{k_1}{\eta}, \quad q_1 = \left(\frac{k_1}{k_2} + 1 \right), \quad p_0 = \frac{1}{\eta}, \quad p_1 = \frac{1}{k_2}$$

Question B-i)

Jump condition:-

$$p_1 \sigma_0 = q_1 \varepsilon_0$$

$$\sigma_0 = \varepsilon_0 (k_1 + k_2)$$

i) Find the stress response for an applied constant strain:-

$$\varepsilon = \varepsilon_0$$

$$q_0 \varepsilon = p_0 \sigma + p_1 \dot{\sigma}$$

Question B

$$\sigma(t) = \varepsilon_0 \left\{ \frac{q_0}{p_0} + \left(\frac{q_1}{p_1} - \frac{q_0}{p_0} \right) \exp\left(\frac{-p_0 t}{p_1}\right) \right\}$$

$$\sigma(t) = \varepsilon_0 \left\{ k_1 + (k_2) \exp\left(\frac{-k_2 t}{\eta}\right) \right\}$$

Question B-ii)

ii) Find the strain response for an applied constant stress

$$\varepsilon(t) = \sigma_0 \left\{ \frac{p_0}{q_0} + \left(\frac{p_1}{q_1} - \frac{p_0}{q_0} \right) \exp\left(\frac{-q_0 t}{q_1}\right) \right\}$$

$$\varepsilon(t) = \sigma_0 \left\{ \frac{1}{k_1} + \left(\frac{1}{k_1 + k_2} - \frac{1}{k_1} \right) \exp\left(\frac{-k_1 k_2 t}{\eta(k_1 + k_2)}\right) \right\}$$

Question C

Find the response for oscillatory loading, $\sigma = \sigma_0 \sin(\omega^c t)$

$$p_0 \sigma_0 \sin(\omega^c t) + p_1 \omega_0^c \cos(\omega^c t) = q_0 \varepsilon + q_1 \dot{\varepsilon}$$

$$\varepsilon(t) = \varepsilon_\alpha \sin(\omega^c t) + \varepsilon_\beta \cos(\omega^c t) + f(t)$$

where,

$$\varepsilon_\alpha = \sigma_0 \left(\frac{p_1 q_1 w^{c^2} + p_0 q_0}{q_0^2 + q_1^2 w^{c^2}} \right) = \sigma_0 \left(\frac{\eta^2 (k_1 + k_2) w^{c^2} + k_1 k_2^2}{k_1^2 k_2^2 + (k_1 + k_2)^2 \eta^2 w^{c^2}} \right)$$

$$\varepsilon_\beta = \sigma_0 w^c \left(\frac{p_1 q_0 - p_0 q_1}{q_0^2 + q_1^2 w^{c^2}} \right) = - \sigma_0 w^c \left(\frac{\eta k_2^2}{k_1^2 k_2^2 + (k_1 + k_2)^2 \eta^2 w^{c^2}} \right)$$

$$f(t) = \left(\frac{p_1}{q_1} \right) \left(\frac{q_0^2 + q_1^2 w^{c^2}}{w^c (p_0 q_1 - p_1 q_0)} \right) \exp\left(\frac{q_0 t}{q_1}\right) = \left(\frac{1}{k_1 + k_2} \right) \left(\frac{\eta^2 (k_1 + k_2)^2 w^{c^2} + k_1 k_2^2}{k_2^2 + \eta^2 w^{c^2}} \right) \exp\left(\frac{k_1 k_2 t}{(k_1 + k_2) \eta}\right)$$

Question D

Find the response for oscillatory displacement, $\varepsilon = \varepsilon_0 \sin(\omega^R t)$

$$p_0 \ddot{x} + p_1 \dot{x} = q_0 \varepsilon_0 \sin(\omega^R t) + q_1 \omega^R \varepsilon_0 \cos(\omega^R t)$$

$$x(t) = \sigma_\alpha \sin(\omega^R t) + \sigma_\beta \cos(\omega^R t) + f(t)$$

where,

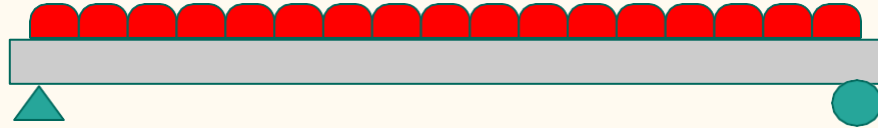
$$\sigma_\alpha = \varepsilon_0 \left(\frac{p_1 q_1 \omega^{R^2} + p_0 q_0}{p_0^2 + p_1^2 \omega^{R^2}} \right) = \varepsilon_0 \left(\frac{\eta^2 (k_1 + k_2) \omega^{R^2} + k_1 k_2}{k_2^2 + \eta^2 \omega^{R^2}} \right)$$

$$\sigma_\beta = \varepsilon_0 \omega^R \left(\frac{p_0 q_1 - p_1 q_0}{p_0^2 + p_1^2 \omega^{R^2}} \right) = \varepsilon_0 \omega^R \left(\frac{k_1 k_2^2 - k_1 k_2 \eta}{k_2^2 + \eta^2 \omega^{R^2}} \right)$$

$$f(t) = \left(\frac{q_1}{p_1} \right) \left(\frac{p_0^2 + p_1^2 \omega^{R^2}}{\omega^R (p_1 q_0 - p_0 q_1)} \right) \exp\left(\frac{-p_0 t}{p_1} \right) = (k_1 + k_2) \left(\frac{k_2^2 + \eta^2 \omega^{R^2}}{\omega^R (k_1 k_2^2 - k_1 k_2 \eta)} \right) \exp\left(\frac{-k_2 t}{\eta} \right)$$

Question E

Find the response for a simply supported beam subjected to constant uniformly distributed load.



$$G(t) = k_1 + k_2 \exp\left(\frac{-k_2 t}{\eta}\right)$$

$$\varepsilon = -\frac{d^2 \Delta}{dx^2} (y - y_0)$$

$$L(\sigma_{xx}) = s L(G) L(\varepsilon) \quad \text{valid for linear model}$$

Question E

$$\begin{aligned} L(\sigma_{xx}) &= s \left(\frac{k_1}{s} + \frac{k_2 \eta}{(s\eta + k_2)} \right) \left(-y L\left(\frac{d^2 \Delta}{dx^2}\right) + L\left(y_0 \frac{d^2 \Delta}{dx^2}\right) \right) \\ &= \left(k_1 + \frac{k_2 \eta s}{(s\eta + k_2)} \right) \left(-y L\left(\frac{d^2 \Delta}{dx^2}\right) + L\left(y_0 \frac{d^2 \Delta}{dx^2}\right) \right) \end{aligned}$$

$$\sum F_x = 0$$

$$P = \int \sigma_{xx} da = 0$$

$$L(P) = \int L(\sigma_{xx}) da = \int \left(k_1 + \frac{k_2 \eta s}{(s\eta + k_2)} \right) \left(-y L\left(\frac{d^2 \Delta}{dx^2}\right) + L\left(y_0 \frac{d^2 \Delta}{dx^2}\right) \right) da$$

$$Ay_c \mathcal{L}\left(\frac{d^2 \Delta}{dx^2}\right) - A \mathcal{L}\left(y_0 \frac{d^2 \Delta}{dx^2}\right) = \frac{k_1 (s\eta + k_2)}{k_2 \eta s} \quad \text{--- (1)}$$

$$\Sigma M_z = 0, \quad M = \int \sigma_{xx} y da$$

$$\mathcal{L}(M) = \int \mathcal{L}(\sigma_{xx}) y da$$

$$= \int \left(k_1 + \frac{k_2 \eta s}{(s\eta + k_2)} \right) \left(-y^2 \mathcal{L}\left(\frac{d^2 \Delta}{dx^2}\right) + y \mathcal{L}\left(y_0 \frac{d^2 \Delta}{dx^2}\right) \right) da$$

$$= k_1 + \frac{k_2 \eta s}{(s\eta + k_2)} \left[\bar{J}_{zz} \mathcal{L}\left(\frac{d^2 \Delta}{dx^2}\right) - Ay_c \mathcal{L}\left(y_0 \frac{d^2 \Delta}{dx^2}\right) \right]$$

$$= \frac{\omega l x}{2s} - \frac{\omega x^2}{2s}$$

Question E

$$\bar{I}_{zz} \mathcal{L} \left(\frac{d^2 \Delta}{dx^2} \right) - A y_c \left(y_0 \frac{d^2 \Delta}{dx^2} \right) = \frac{\left(\frac{\omega l x}{2s} - \frac{\omega x^2}{2s} - K_1 \right) (s\eta + K_1)}{K_1 \eta s}$$

→ (2)

By solving eqⁿs ① and ② solutions for $\frac{d^2 \Delta}{dx^2}$ and $y_0 \frac{d^2 \Delta}{dx^2}$ can be obtained.

Question F-i)

Using the above results find the stress relaxation function, G and creep compliance function, J . Then verify the following:

$$\text{i. } G(0) \times J(0) = 1$$

$$G(t) = k_1 + k_2 \exp\left(\frac{-k_2 t}{\eta}\right)$$

$$J(t) = \frac{1}{k_1} + \left(\frac{1}{k_1 + k_2} - \frac{1}{k_1}\right) \exp\left(\frac{-k_1 k_2 t}{\eta(k_1 + k_2)}\right)$$

$$LHS = G(0) \times J(0)$$

$$LHS = (k_1 + k_2) \times \frac{1}{k_1} + \left(\frac{1}{k_1 + k_2} - \frac{1}{k_1}\right) = 1$$

$$RHS = G(0) \times J(0) = 1$$

Question F-ii)

ii. $G(\infty) \times J(\infty) = 1$

$$G(\infty) \times J(\infty) = k_1 \times \frac{1}{k_1} = 1$$

$$G(\infty) \times J(\infty) = 1$$

Question F-iii)

iii. $1 = J(0) \times G(t) + \int_0^t G(\tau) d\tau$

$$\mathcal{L}(G) = \frac{k_1}{s} + \frac{k_2}{\left(s + \frac{k_2}{\eta}\right)} = \frac{k_1}{s} + \frac{k_2 \eta}{(s\eta + k_2)}$$

$$\mathcal{L}(J) = \frac{1}{sk_1} - \frac{k_2 \eta}{s\eta(k_1 + k_2)k_2 + k_1^2 k_2}$$

$$\left. \frac{dJ}{dt} \right|_{t=s} = \frac{k_1 k_2^2}{k_1 \eta (k_1 + k_2)^2} \exp\left(\frac{-k_1 k_2 s}{\eta (k_1 + k_2)}\right)$$

Question F-iii)

iii. $1 = f(0) \times G(t) + \int_0^t G(t-\tau) \frac{df(\tau)}{d\tau} d\tau$

Applying Laplace transformation to RHS

$$\mathcal{L}(RHS) = \frac{(s\eta + k_2)(k_1 + k_2)}{s(k_1 + k_2)(s\eta + k_2)} = \frac{1}{s}$$

Applying inverse Laplace transformation,

$$\mathcal{L}^{-1}\left(\frac{1}{s}\right) = 1$$

Question G-i)

Also compute the following:

i. Apparent viscosity, $\eta = \int_0^\infty G(t) dt$

$$\eta_a = \int_0^\infty \left\{ k_1 + k_2 \exp\left(\frac{-k_2 t}{\eta}\right) \right\} dt$$

Question G-ii)

ii. Characteristic creep times,

$$\tau_1^c = \left(\frac{J(\infty) - J(0)}{\frac{dJ}{dt}_{(t=0)}} \right) = \frac{\eta(k_1 + k_2)}{k_1 k_2}$$

$$\tau_2^c = \frac{\int_0^{\infty} s[J(\infty) - J(s)] ds}{\int_0^{\infty} [J(\infty) - J(s)] ds} = \frac{\eta(k_1 + k_2)}{k_1 k_2}$$

Question G-iii)

iii. Characteristic relaxation times,

$$\tau_1^R = \left(\frac{G(0) - G(\infty)}{\frac{dG}{dt}_{(t=0)}} \right) = \frac{-\eta}{k_2}$$

$$\tau_2^R = \frac{\int_0^{\infty} s[G(s) - G(\infty)]ds}{\int_0^{\infty} [G(s) - G(\infty)]ds} = \frac{\eta}{k_2}$$

Question H

Comment on the obtained characteristic times and the apparent viscosity.

$$\tau_1^c = \frac{\eta(k_1 + k_2)}{k_1 k_2} \quad \text{and} \quad \tau_1^R = \frac{\eta}{k_2}$$

From above expressions it is clear that the characteristic creep time is more than characteristic relaxation time and as

$$G(0) = (k_1 + k_2) \quad \text{and} \quad G(\infty) = k_1$$

We can write relation as

$$\tau_1^c = \frac{G(0)}{G(\infty)} \tau_1^R$$

Question I-i)

Compute the following for the oscillatory loading and oscillatory displacement:

i. Phase lag between the stress and strain

$$\varepsilon_{\alpha} = \sigma_0 \left(\frac{p_1 q_1 w^{c^2} + p_0 q_0}{q_0^2 + q_1^2 w^{c^2}} \right) = \sigma_0 \left(\frac{\eta^2 (k_1 + k_2) w^{c^2} + k_1 k_2^2}{k_1^2 k_2^2 + (k_1 + k_2)^2 \eta^2 w^{c^2}} \right)$$
$$\varepsilon_{\beta} = \sigma_0 w^c \left(\frac{p_1 q_0 - p_0 q_1}{q_0^2 + q_1^2 w^{c^2}} \right) = - \sigma_0 w^c \left(\frac{\eta k_2^2}{k_1^2 k_2^2 + (k_1 + k_2)^2 \eta^2 w^{c^2}} \right)$$

Question I-i)

$$\varepsilon(t) = \overline{\varepsilon}_{\alpha} \cos\Phi \sin(w^c t) + \overline{\varepsilon}_{\beta} \sin\Phi \cos(w^c t) - f(t)$$

substituting $\varepsilon_{\alpha} = \overline{\varepsilon}_{\alpha} \cos\Phi$ and $\varepsilon_{\beta} = \overline{\varepsilon}_{\beta} \sin\Phi$

$$\varepsilon(t) = \overline{\varepsilon}_{\alpha} \sin(w^c t + \Phi) - f(t), \text{ where } \Phi \text{ is phase lag}$$

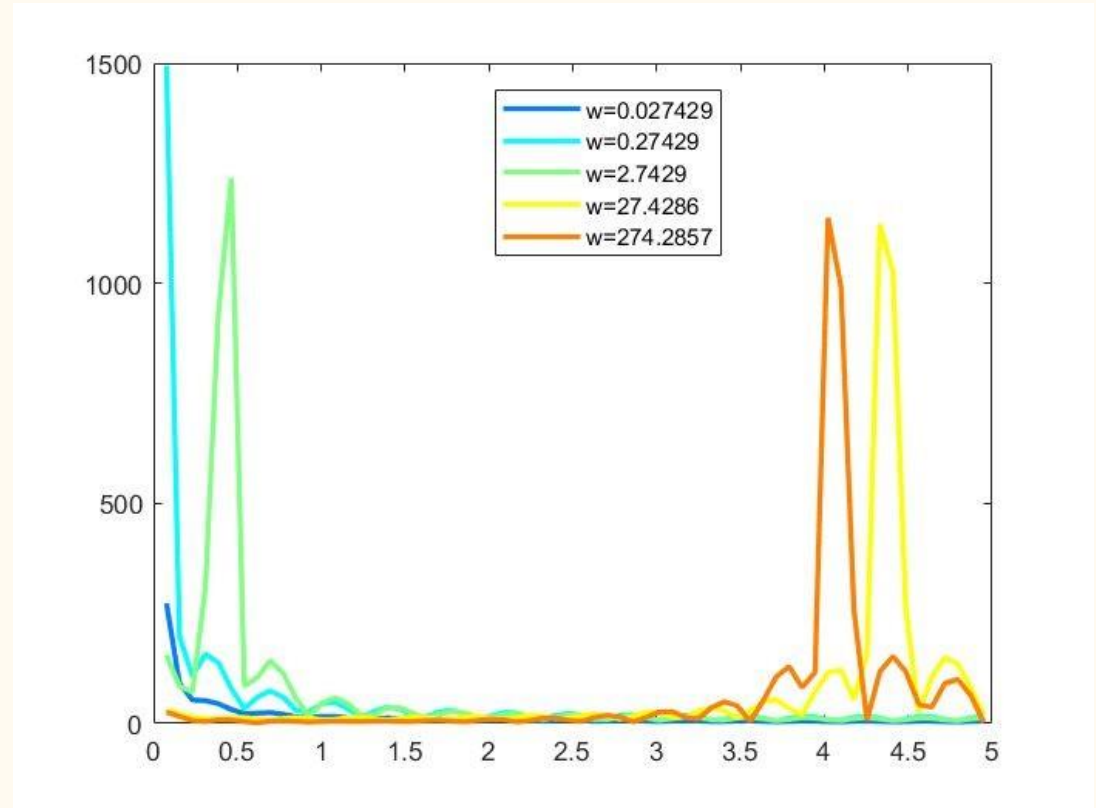
$$\tan\Phi = \frac{\sin\Phi}{\cos\Phi} = -w^c \left(\frac{\eta k_2^2}{k_1 k_2^2 + (k_1 + k_2) \eta^2 w^{c^2}} \right)$$

$$\Phi = \tan^{-1} \left[-w^c \left(\frac{\eta k_2^2}{k_1 k_2^2 + (k_1 + k_2) \eta^2 w^{c^2}} \right) \right]$$

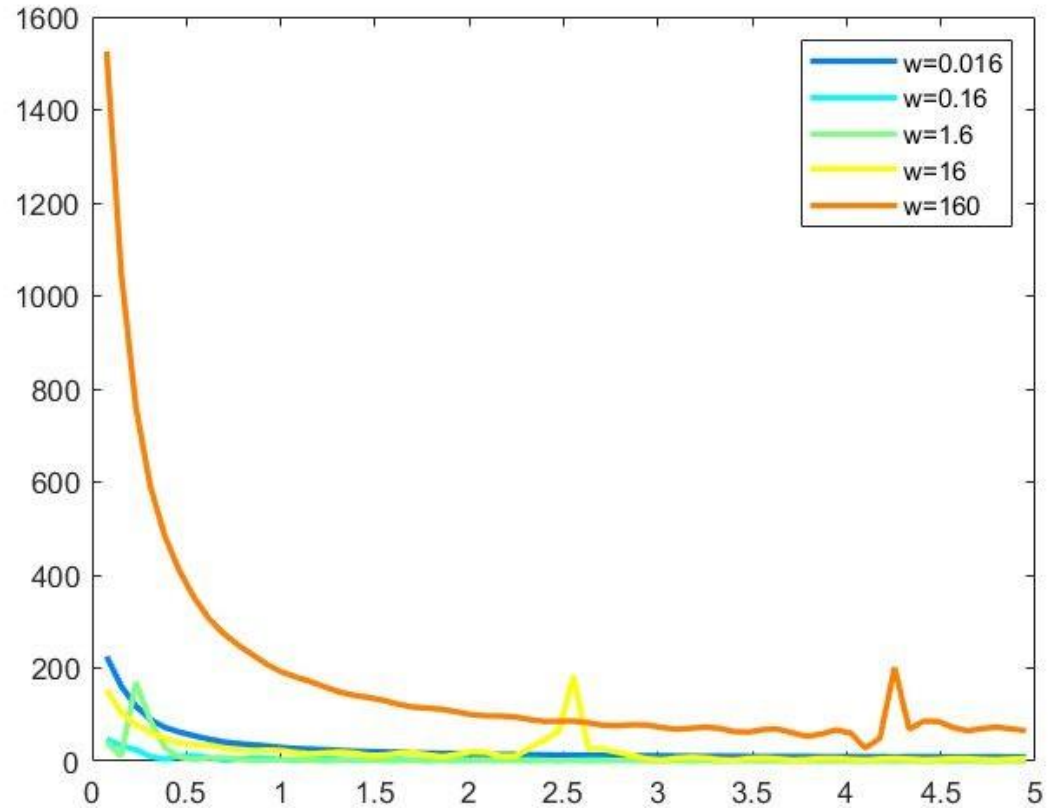
Question I-ii)

ii. Do a Fourier transform of the response and plot the amplitude versus frequency for the following: $\omega_j = \{ 1/100, 1/10, 1, 10, 100 \} \tau_1 j$, where $j = C$ or R

Oscillatory stress input:-



Oscillatory strain input:-



THANK YOU!