PhD

Online Video Object Detection using Association LSTM iccv17

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- First run the SSD detector
- concatenate its bounding box predictions along with the corresponding features after passing the latter through an ROI pooling layer to get 7 x 7 features;
- stacked together these concatenated features for several consecutive frames and pass these the stacked features two an LSTM;
- two different types of losses are used to lawn to perform regression and association simultaneously.
- Regression loss is just a slightly modified version of the SSD loss where a term is added to ensure smooth progression between frames
- association losses performed pairwise trained two consecutive frames though its details are not all that clear