

Project 5 - FYS4150

The Schrödinger equation

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Abstract

Supporting material may be found in the following GitHub repository: <https://github.com/Vikenes/FYS4150/tree/main/project5>.

NOMENCLATURE

Basics

$x \in [0, 1]$; $x \rightarrow x_i = ih$ with $i = 0, 1, \dots, M - 1$.

$y \in [0, 1]$; $y \rightarrow y_j = jh$ with $j = 0, 1, \dots, M - 1$.

$\mathbf{x} = (x, y)$; $\mathbf{x} \rightarrow \mathbf{x}_{i,j} = h(i, j)$ with $i, j \in [0, M - 1]$.

$t \in [0, T]$; $t \rightarrow t_n = n\Delta t$ with $n = 0, 1, \dots, N_t - 1$.

$u(t, \mathbf{x}) \rightarrow u(t_n, \mathbf{x}_{i,j}) \equiv u_{i,j}^{(n)}$.

$U^{(n)}$ is a matrix with elements $u_{i,j}^{(n)}$.

$v(\mathbf{x}) \rightarrow v(\mathbf{x}_{i,j}) \equiv v_{i,j}$.

V is a matrix with elements $v_{i,j}$.

NB

M is the number of points along x and y axis.

$M - 1$ is the number of steps.

$M - 2$ is the number of internal points (excluding boundary points).

Dirichlet boundary conditions

$u(t, \mathbf{x}_{0,j}) = u(t, x=0, y) = 0$.

$u(t, \mathbf{x}_{M-1,j}) = u(t, x=1, y) = 0$.

$u(t, \mathbf{x}_{i,0}) = u(t, x, y=0) = 0$.

$u(t, \mathbf{x}_{i,M-1}) = u(t, x, y=1) = 0$.

I. INTRODUCTION

Blah blah

For a single, non-relativistic particle with mass m_P in a two-dimensional potential $\mathcal{V}(t, \mathbf{x})$, the Schrödinger equation reads¹

$$i\hbar \frac{\partial}{\partial t} \Psi(t, \mathbf{x}) = -\frac{\hbar^2}{2m_P} \nabla^2 \Psi(t, \mathbf{x}) + \mathcal{V}(t, \mathbf{x}) \Psi(t, \mathbf{x}). \quad (1)$$

For a set of initial and boundary conditions, the partial differential equation (PDE) describes the temporal and spatial evolution of the complex-valued function $\Psi(t, \mathbf{x})$ related to the quantum state of the aforementioned particle. In such a case, at a time t , the probability density for an experimentalist to locate the particle at \mathbf{x} ("for detecting ..." is better, but I don't want to copy Anders) is large P or small p???

$$P(\mathbf{x}; t) = |\Psi(t, \mathbf{x})|^2 = \Psi^*(t, \mathbf{x}) \Psi(t, \mathbf{x}), \quad (2)$$

originating from the Born rule; fill me

In this paper we will consider a dimensionless time-independent potential, i.e. we let $\mathcal{V}(t, \mathbf{x}) \rightarrow v(\mathbf{x})$. The specifics of the scaling do not concern us in this paper, and we simply rewrite equation (1) to the dimensionless equation

$$i \frac{\partial}{\partial t} u(t, \mathbf{x}) = -\nabla^2 u(t, \mathbf{x}) + v(\mathbf{x}) u(t, \mathbf{x}), \quad (3)$$

where we substituted $\Psi(t, \mathbf{x}) \rightarrow u(t, \mathbf{x})$. In equation (3) all variables are dimensionless. When demanding the proper normalisation on $u(t, \mathbf{x})$, it follows that the Born rule now takes the form of

$$p(\mathbf{x}; t) = |u(t, \mathbf{x})|^2 = u^*(t, \mathbf{x}) u(t, \mathbf{x}). \quad (4)$$

Should maybe rephrase this paragraph.

II. METHODS

We will use the Schrödinger equation to simulate a particle inside a two-dimensional quadratic box of size L^2 . The use of periodic boundary conditions gives rise

¹ In position space, that is. Should we comment on this?

to the confinement of the particle [or something like that](#). We will place two or more walls inside the box to create one or more slits. The specifics of such configurations is elaborated in section [IID](#). A position inside if the box is called $\mathbf{x} = (x, y)$ and a time $t \in$, all unit less. Now $x, y \in [0, L]$ and $t \in [0, T]$ if we let T be the time we simulate for. In this paper, we will use $L = 1$.

A. Numerical scheme

[How to solve etc.](#)

1. Discretisation

We discretise the position $\mathbf{x} \rightarrow \mathbf{x}_{i,j} = (x_i, y_j) = h(i, j)$, where h is the spatial separation between two points on the grid. We consider M points in each direction, giving $i, j \in [0, M)$. The lattice is then made up of $(M - 2) \times (M - 2)$ internal points and boundary points. The time points become $t \rightarrow t_n = n\Delta t$, $n \in [0, N_t)$, where Δt is the time step size and $N_t = T/\Delta t$ is the number of time points. Further, we find the wave function as

$$u(t, \mathbf{x}) \rightarrow u(t_n, \mathbf{x}_{i,j}) \equiv u_{i,j}^{(n)}, \quad (5)$$

and subsequently the probability density,

$$p(\mathbf{x}; t) \rightarrow p(\mathbf{x}_{i,j}; t_n) \equiv p_{i,j}^{(n)}. \quad (6)$$

The potential is discretised as $v(\mathbf{x}) \rightarrow v(\mathbf{x}_{i,j}) \equiv v_{i,j}$.

B. Periodic boundaries

[Dirichlet](#)

C. Initial wave packet

[choose one of these:](#)

$$u(t=0, \mathbf{x}) = \exp\left\{-\frac{(\mathbf{x} - \mathbf{x}_c)^T \Sigma^{-1} (\mathbf{x} - \mathbf{x}_c) + i\mathbf{p}^T (\mathbf{x} - \mathbf{x}_c)}{2}\right\}; \quad (7)$$

$$\Sigma = \text{diag}(\sigma^2)$$

$$u(t=0, \mathbf{x}) = \exp\left\{-\frac{(x - x_c)^2}{2\sigma_x^2} - \frac{(y - y_c)^2}{2\sigma_y^2} + i\mathbf{p} \cdot (\mathbf{x} - \mathbf{x}_c)\right\} \quad (8)$$

D. Slit configuration

To create a single slit, we need *two* objects with the property that the particle cannot propagate through it. Said objects are to have a separation between them, a *slit*,

perpendicular to the dominating motion of the particle [Pls send help, cannot write proper sentences any more:\(](#). A natural choice for the shape is the rectangular with the longer side parallel to the slit, [\(Some theory about interference??\)](#) hence the name "wall". Three such walls give rise to two slits, etcetera. Therefore,

$$\#\text{walls} = \begin{cases} \#\text{slits} + 1 & \text{if } \#\text{slits} \geq 1 \\ 0 & \text{if } \#\text{slits} = 0 \end{cases} \quad (9)$$

To give the Schrödinger equation information about these walls, we simply create a very large potential in the walls. These potential barriers will resemble concrete [\(mener egt ikke betong, men konkrete... hva er ordet??\)](#) walls in the sense that the particle will have to navigate around it in order to get through to the other side.

In particular, we will set up a number of such walls in the middle of our box, the separation between which is the aperture, aligned perpendicular to the initial momentum \mathbf{p} in equation (7). We will make sure that the slit setup is symmetric around the box centre in both directions.

E. Artificial detector screen

To reduce the dimensionality of the problem, we can assume to measure a particle with a detector screen at some horizontal position $x = x_{sc}$ and time $t = t_{sc}$, so that the screen spans of the vertical axis y . With a smart choice of pairing $(t_{sc} \ \& \ x_{sc})$, we can safely assume that the particle is located somewhere along this line. Thus, it makes sense to consider a normalised one-dimensional probability function $p_{x=x_{sc}}(y; t)$ (read: probability of y given $x = x_{sc}$, at t) such that

$$p_{x=x_{sc}}^{\text{tot}}(t) = \sum_{j \in [0, M)} p_{x=x_{sc}}(y_j; t) = 1. \quad (10)$$

[Do we have to explain how we find this?](#)

F. Simulation parameters

III. RESULTS

A. [dunno what to call this section](#)

The first simulation², where there are no slits, is run with parameters according to tables [I](#) and [II](#) (NS). By rights, at any time t , the probabilities $p(\mathbf{x}_{i,j}; t)$ should sum up to one, as the particle is present inside the box. As a sanity check, we plot

$$|1 - p^{\text{tot}}(t)|; \quad p^{\text{tot}}(t) = \sum_{i,j \in [0, M)} p(\mathbf{x}_{i,j}; t) \quad (11)$$

² Animation available here [link to anim.](#)

Simulation parameters ??	
Spatial step size (h)	$5.0 \cdot 10^{-3}$
Temporal step size (Δt)	$2.5 \cdot 10^{-5}$
Total time (T)	*
Slit configuration (following section II D)	
Number of slits (#slits)	*
Number of identical walls	#slits + 1 ≥ 2
Wall dimensions; width \times height	0.02×0.05
Wall centre position	$(0.5, \sim 0.5)^a$
Slit aperture (separation between walls)	0.05
Potential inside barrier (v_0)	$1.0 \cdot 10^{10}$
Initial wave packet (the Gaussian in equation (7))	
Centre position (\mathbf{x}_c)	$(0.25, 0.50)$
Spatial extent (σ)	$(0.05, *)$
Momentum (\mathbf{p})	$(200, 0)$
Vertical screen (following section II E)	
Horizontal position (x_{sc})	0.8
Time point (t_{sc})	0.002

^a Slit setup symmetric around $y = 0.5$.

TABLE I: Numerical values for static simulation parameters. Simulation-specific values are denoted “*”.

Simulation name (label ^a)	#slits	T	$\sigma \cdot \hat{\mathbf{e}}_y$
1. No slits (NS)	0	0.008	0.05
2. Double-slit (1) (DS1)	2	0.008	0.10
3. Double-slit (2) (DS2)	2	0.002	0.20
4. ... (SS)	1	0.002	0.20
5. ... (TS)	3	0.002	0.20

^a Prefix to look for in [link to animations etc.](#)

TABLE II: Supplement to table I. Additional information about the simulations considered in this paper.

as a function of time in figure 1, where we see that the deviation ($\sim 10^{-14}$) is close to machine precision.

The next simulation³ we consider has a double-slit barrier and a somewhat broader initial wave packet in the vertical direction (DS1 in II). We perform the same sanity check as above and once again get deviations of order 10^{-14} , also shown in figure 1.

We change the settings of our simulations so that they are only run for a fourth of the duration and with an even larger initial wave packet. Still two slits considered, our third simulation⁴ is run with parameters in accordance with I and II (DS2). Snapshots of the probability distribution $p(\mathbf{x}; t)$ at $t = 0$, $T/2$ and T , $T = 0.002$, are presented in figure 2a. **COMMENT ON NORMALISATION OF COLOURMAP!** In addition, the real and

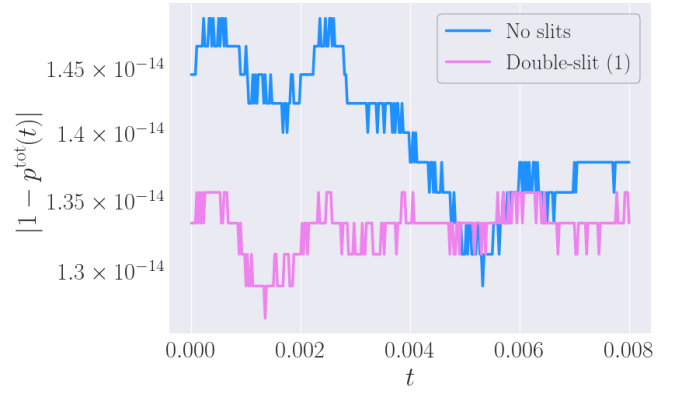


FIG. 1: Some stupid caption. Fix ticks on this plot

imaginary part of $u(t, \mathbf{x})$ at the same time points are presented in figures 2b and 2c, respectively.

B. Screen? idk

Take note of the dotted vertical line in the right panel of figure 2a. Following the method described in section II E, we find the probability density along this screen for detecting the particle. **Is this clear?** The distribution is plotted as a function of y in figure 3.

IV. DISCUSSION

V. CONCLUSION

³ Animation available here [link to anim.](#)

⁴ Animation available here [link to anim.](#)

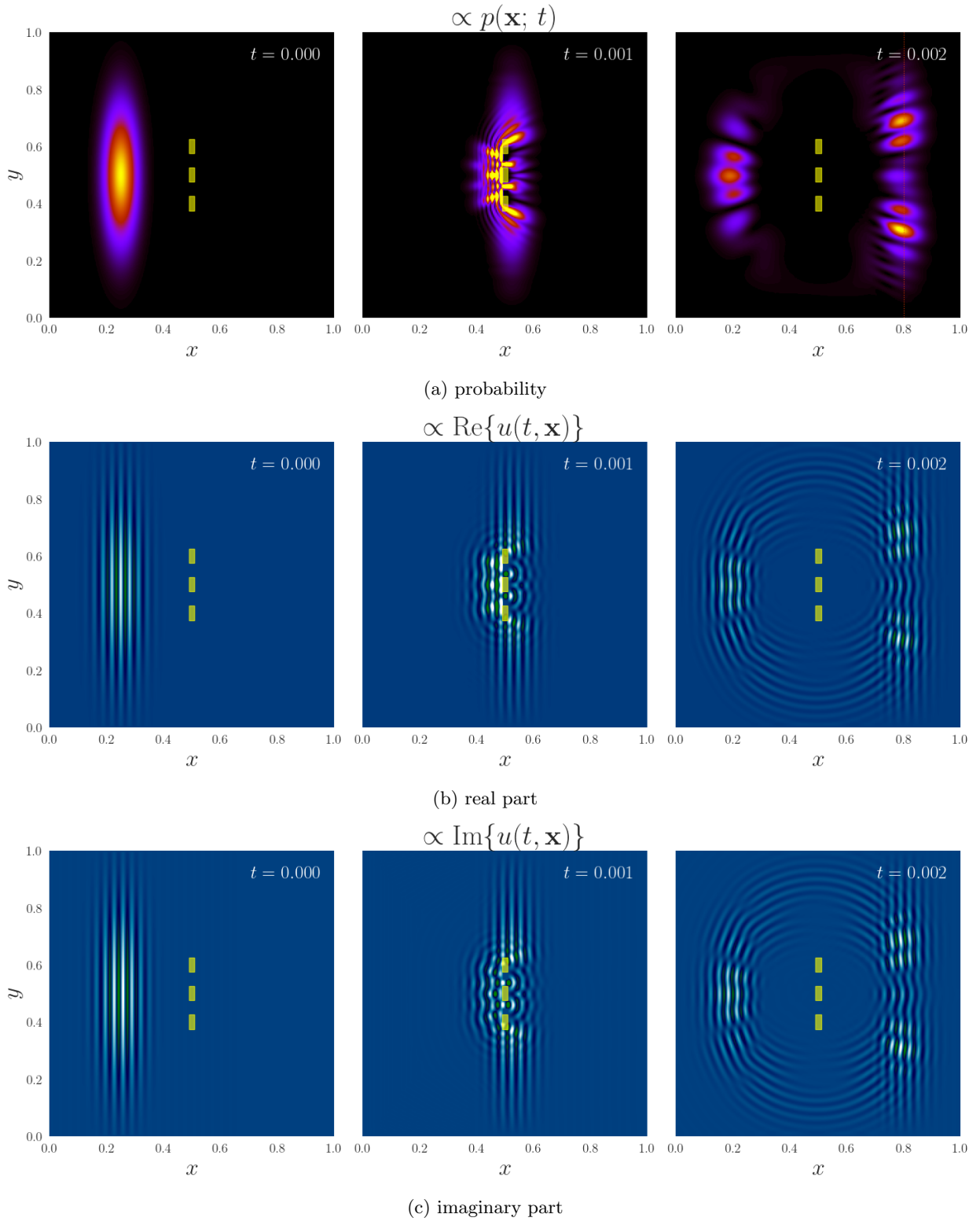


FIG. 2: Colour maps showing blah blah

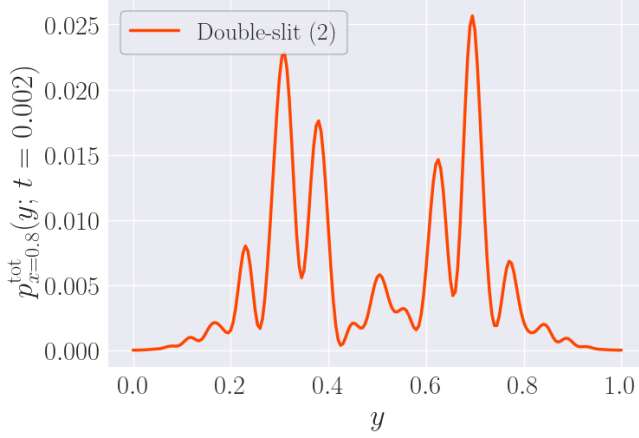


FIG. 3: Some stupid caption

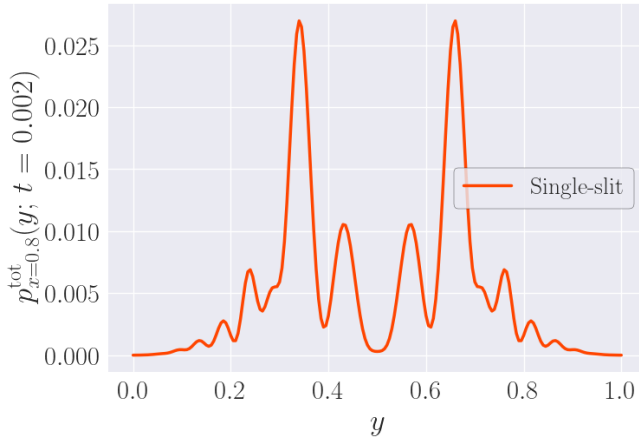


FIG. 4: Some stupid caption

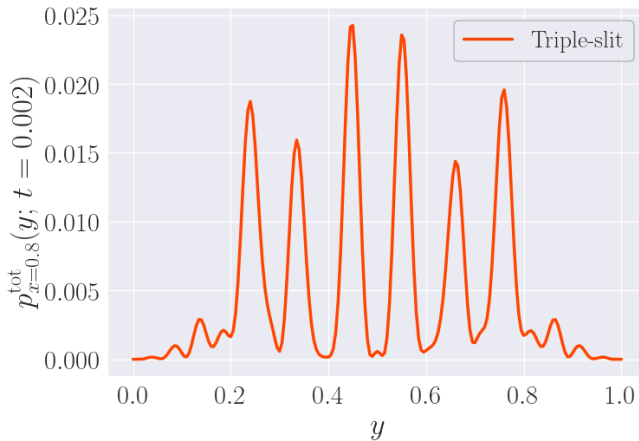


FIG. 5: Some stupid caption

Appendix A: Discretisation

Suppose you have the (1+1)-dimensional PDE $\partial u / \partial t = F$ where $u = u(t, x)$ and

$F = F(t, x, u, \partial u / \partial x, \partial^2 u / \partial x^2)$. The Crank-Nicolson scheme reads [ref](#)

$$\frac{u_i^{(n+1)} - u_i^{(n)}}{\Delta t} = \frac{1}{2} (F_i^{(n+1)} + F_i^{(n)}), \quad (\text{A1})$$

where $u_i^{(n)} = u(n\Delta t, i\Delta x)$ and $F_i^{(n)}$ is F evaluated for i, n and $u_i^{(n)}$. In our (2+1)-dimensional case where $u = u(t, \mathbf{x})$ we have

$$\frac{\partial u}{\partial t} = F(t, \mathbf{x}, u, \nabla^2 u) = i (\nabla^2 u - v(\mathbf{x})u), \quad (\text{A2})$$

and this approach translates to

$$\frac{u_{i,j}^{(n+1)} - u_{i,j}^{(n)}}{\Delta t} = \frac{1}{2} (F_{i,j}^{(n+1)} + F_{i,j}^{(n)}) \quad (\text{A3})$$

where $u_{i,j}^{(n)} = u(n\Delta t, \mathbf{x}_{i,j})$, $\mathbf{x}_{i,j} = h(i, j)$, and $F_{i,j}^{(n)}$ is the right-hand side of equation (A2), explicitly:

$$F_{i,j}^{(n)} = i \left(\left[\frac{\partial^2 u}{\partial x^2} \right]_{i,j}^{(n)} + \left[\frac{\partial^2 u}{\partial y^2} \right]_{i,j}^{(n)} - v_{i,j} u_{i,j}^{(n)} \right); \quad (\text{A4})$$

We can approximate the two spatial double derivatives ([correct way to say?](#)) according to ([Don't know what this approximation is called](#)):

$$\left[\frac{\partial^2 u}{\partial x^2} \right]_{i,j}^{(n)} \approx \frac{1}{h^2} (u_{i+1,j} - 2u_{i,j} + u_{i-1,j})^{(n)}; \quad (\text{A5a})$$

$$\left[\frac{\partial^2 u}{\partial y^2} \right]_{i,j}^{(n)} \approx \frac{1}{h^2} (u_{i,j+1} - 2u_{i,j} + u_{i,j-1})^{(n)}; \quad (\text{A5b})$$

Define $r \equiv \frac{i\Delta t}{2h^2}$. Further, let

$$\begin{aligned} \mathcal{F}_{i,j}^{(n)} = & r (u_{i+1,j} - 2u_{i,j} + u_{i-1,j})^{(n)} \\ & + r (u_{i,j+1} - 2u_{i,j} + u_{i,j-1})^{(n)} \\ & - \frac{i\Delta t}{2} v_{i,j} u_{i,j}^{(n)}. \end{aligned} \quad (\text{A6})$$

Equation (A3) becomes:

$$u_{i,j}^{(n+1)} - \mathcal{F}_{i,j}^{(n+1)} = u_{i,j}^{(n)} + \mathcal{F}_{i,j}^{(n)}; \quad (\text{A7})$$

The final discretisation (A7) is valid for any step in time within the time range ($n \in [0, N_t - 2]$) and all internal points on the grid ($i, j \in [1, M - 2]$).