Exercise - 2

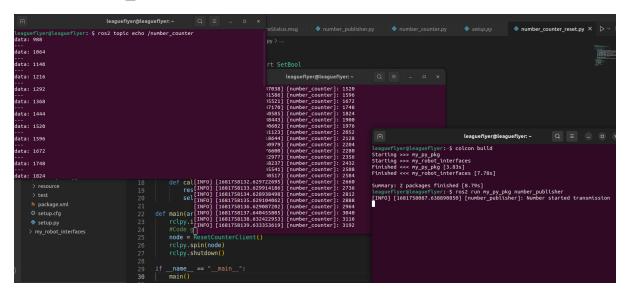
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## Robotics operating System-SEM-IV Professor - Dr. Navneeth

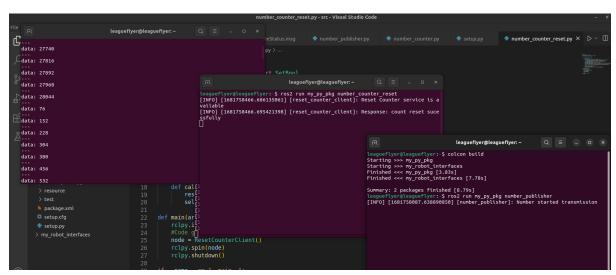
Submitted By: Vikhyat Bansal [CB.EN.U4AIE21076]

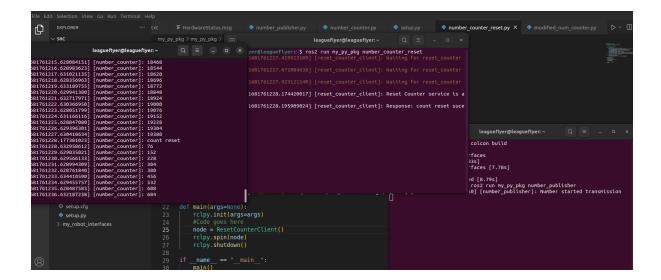


a) The number\_count topic output to the terminal using ros2 topic echo/number\_count without reset.



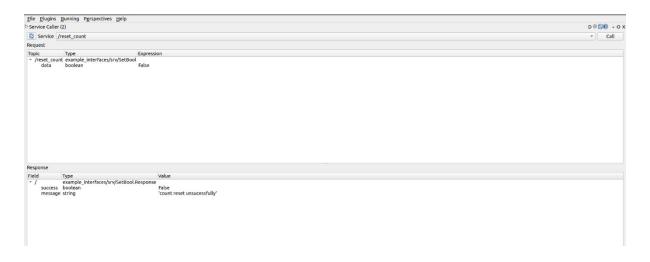
b) The number\_count topic output to the terminal using ros2 topic echo/number count with reset.





c) Request and response for counter value reset through rqt plugin.

## False Condition:



## True Condition:

