VIKING

PS-IR-E18 Reflected Infrared Proximity Sensor

www.vikingmachinery.co.nz

0.0 Safety Statement

All machinery, especially CNC or automated machinery, has inherent dangers and risks. It is the responsibility of the system designer to ensure that any systems built using any Viking Machinery Ltd. products are safe for use. Any technical information is provided as a reference only, and does not constitute a recommendation as to the fitness of use in any particular application.

Viking Machinery Ltd. strongly urges customers to seek expert advice when dealing with potentially dangerous electrical voltages and sources of mechanical energy. Information contained in this document does not constitute a substitute for expert advice.

Under no circumstances should this product ever be used in a safety critical application.

1.0 Product Specifications

- Supply Voltage – 5-32VDC (Sensing range increases with voltage)
- Operating Current – 10mA
- Current Ripple – 20% peak to peak maximum
- Maximum Output Current – 300mA
- Sensing Distance – Up to 500mm in some circumstances. Stable at 300mm
- NPN Operation, with built in pull up resistor
- Operating temperature – -10°C - 60°C
- Response Frequency – 2Hz
- Sensing media – Opaque objects

2.0 Scope of Document

This document is designed to give an overview of the wiring options for the PS-IR-E18 reflected infrared proximity sensor. This sensor will change state when the sensing element is exposed to an opaque object. Typically, white flat objects will trigger the sensor at the greatest ranges (up to 800mm in our lab tests) but it will detect most opaque objects within 300mm.

Wiring examples are given for typical CNC and microcontroller examples. These are by no means exhaustive, but are a good starting point for beginners.

3.0 Wire Colours & Connection

Your proximity sensor comes with a 1000mm flylead attached. This is unshielded and contains three Ø0.42mm wires. 1 Brown, 1 Blue and 1 Black.

The brown wire is to be connected to a 5-32V DC supply, and the blue is to be connected to the common DC 0V rail. It is important that all 0V terminals are connected in common between all devices used in the system, or else you risk damaging the sensor and equipment. At this point passing an opaque object in front of the sensor will cause a red LED to illuminate on the back end of the sensor, indicating that it has detected an object.

The back wire is our signal wire. We will use this wire to switch our device later. For now we can test the sensor, running on 12V, by connecting our multimeter (on the DC Volts setting) between the blue wire and the black wire. In its normal state the multimeter should read "12V". Placing an opaque object in front of the sensor will illuminate the LED and drop the voltage read on the multimeter to "0V". When the object is removed, the reading should return to "12V"

4.0 Wiring to a CNC B.O.B

The 5 axis CNC breakout board that Viking Machinery supplies can be wired as shown. This breakout board has the correct voltages across all input pins for the voltage that the sensor is supplying. If your BOB has inputs that are at a logic voltage (5V typically) then you will need to protect the inputs from the voltage coming from the sensor. Please refer to section 5.0 for details on interfacing to a logic level micro controller.
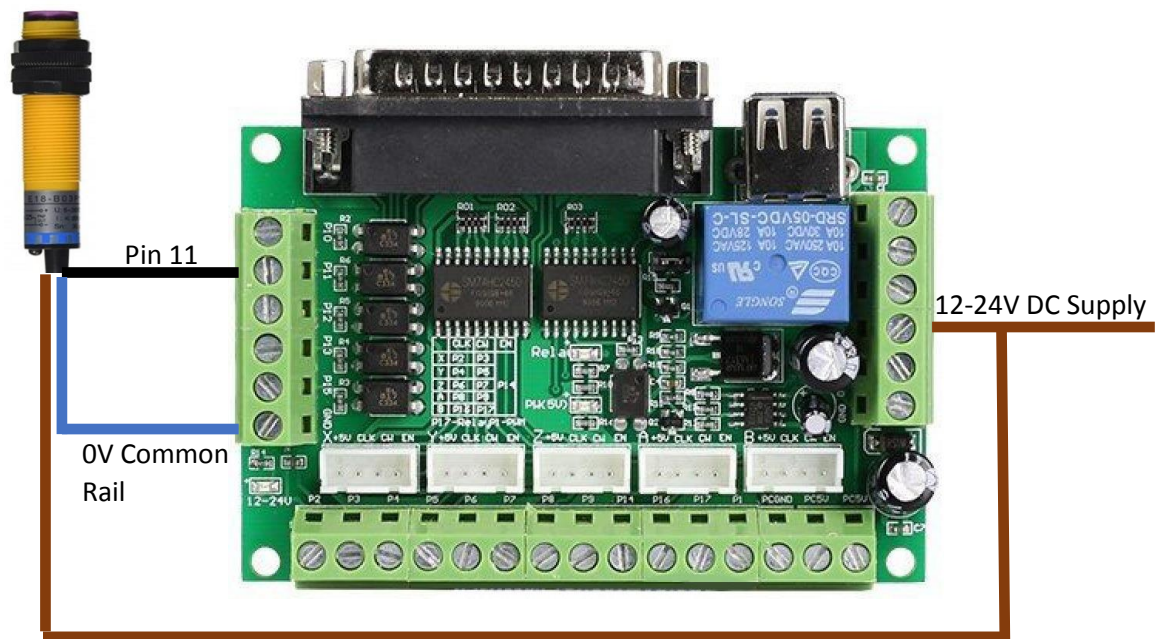
5.0 Wiring to a Microcontroller

For this example, we will use the popular Arduino micro controller. The principle is the same for most 5V TTL input devices.

If we are running the sensor at more than 5V, we need to add a small diode on the input pin if the sensor supply voltage is greater than the supply voltage of the Arduino. Make sure the anode (+) is on the microcontroller side.

If your board does not have an onboard pull-up resistor you will need to wire one between the input pin you are using and the 5V common on the micro controller (example shown in dashed yellow below). 5kΩ or 10kΩ are good pull-up resistor values.
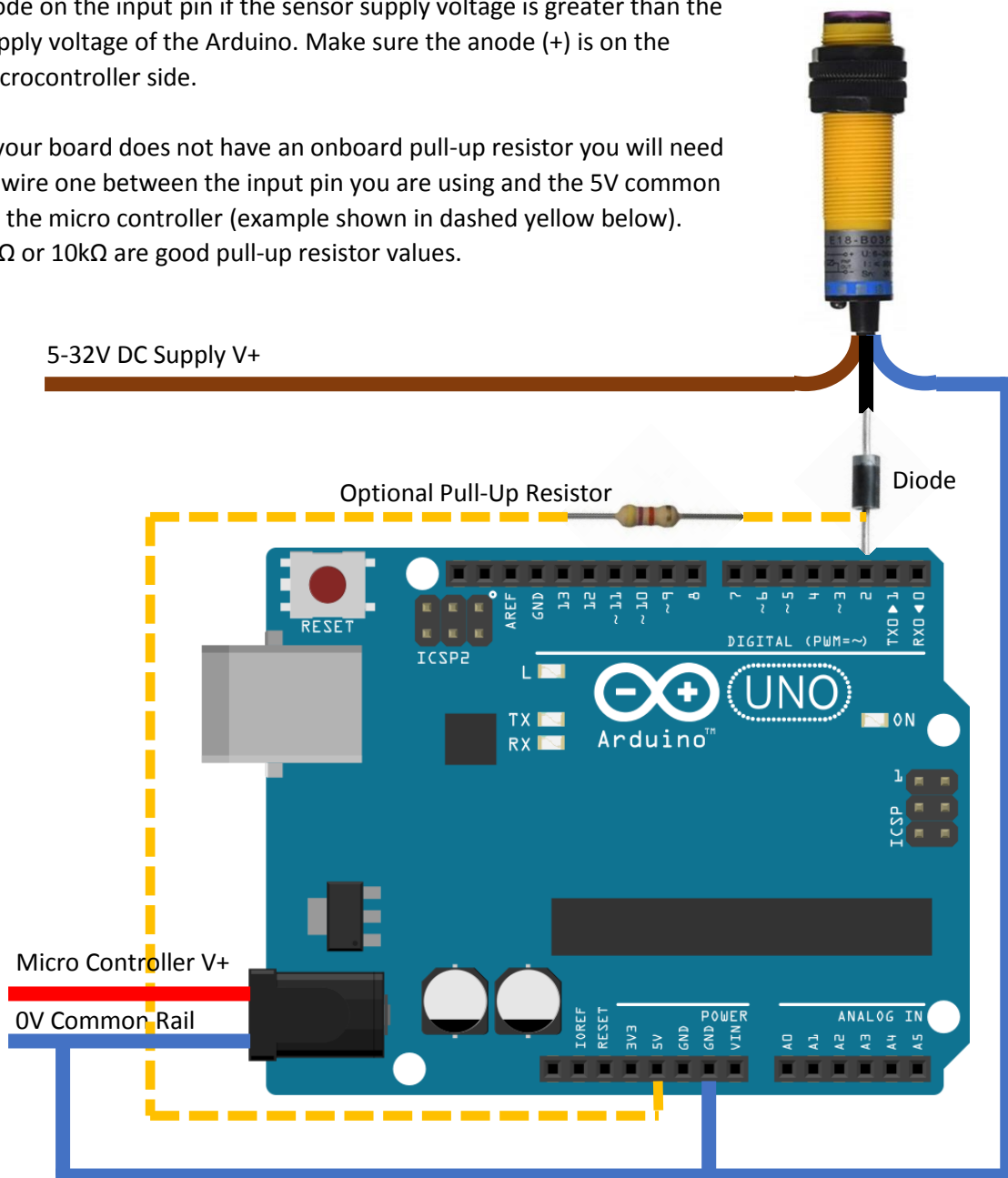

For this example, we would need to set pin 2 to INPUT (with external pull-up resistor wired) or INPUT_PULLUP to use the onboard pullup resistor.

When the sensor is activated, it will allow current flow out of pin 2, dropping the voltage to near zero and reading as a logic signal. When the sensor is deactivated, the voltage rises on the sensor side of the diode, blocking the current flow. The pull-up resistor now does its magic and gives us a nice clean 5V signal on the pin.

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6.0 Wiring to a Relay Module

Sometimes you will want to switch a power load with a proximity sensor. The easiest way to do this is to use a relay module. The wiring diagram below shows the typical wiring for one channel on our four-channel relay module. Again, we use a small diode to protect the 5V logic circuit from the potentially higher voltage on the sensor if we are using more than 5V to power it. This particular relay board has inbuilt pull-up resistors so you do not need to wire an external one here.
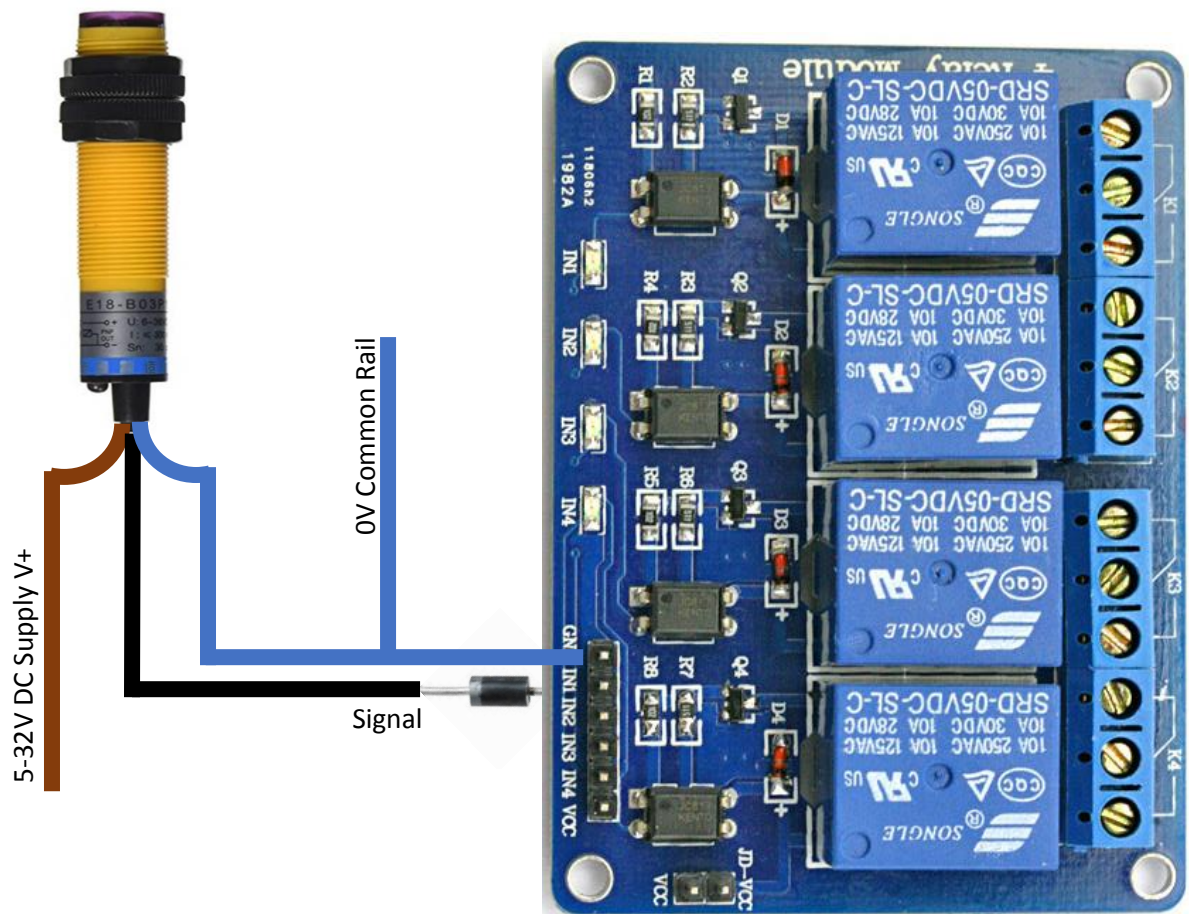
7.0 Wiring to the PLC Shield

Wiring to the PLC shield that Viking Machinery sells is easily accomplished in the manner shown below. The PLC shield will run on 12-24V DC, which makes wiring into the sensor very convenient.

The PLC shield supports up to four proximity sensor inputs, four relay outputs and allows logic processing using the plug in Arduino Pro Mini.

12-24V DC +

0V DC -

Signal
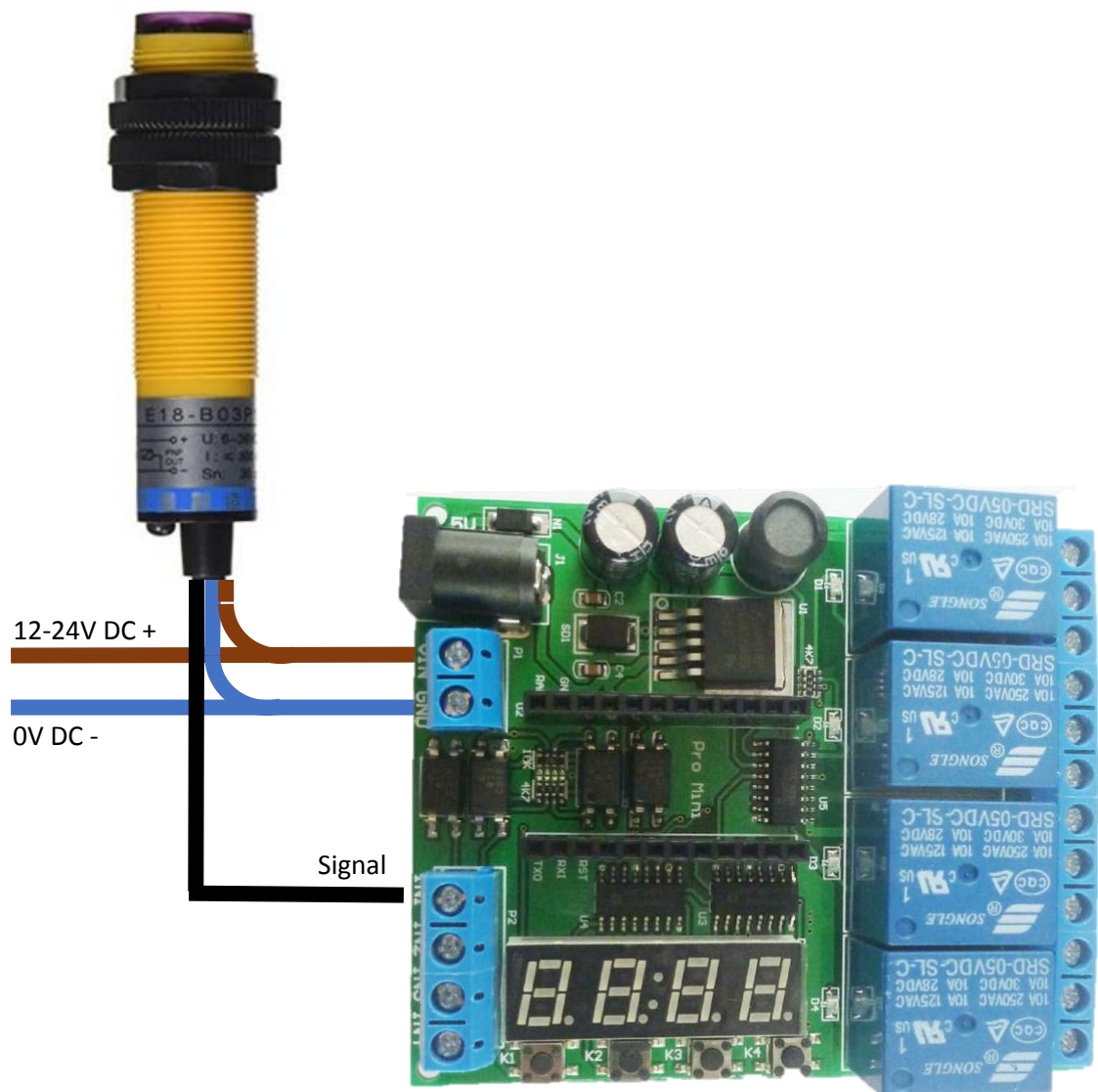
7.0 Reference Links

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