# Derivative of Piola mapping

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#### **Abstract**

We present the derivatives of the Piola mapping.

#### 1. First-order derivatives

If we have a mapping  $(\xi, \eta) \to (x, y)$ , then its Jacobian is defined as

$$J = \begin{bmatrix} x_{\xi} & x_{\eta} \\ y_{\xi} & y_{\eta} \end{bmatrix} \qquad , \qquad |J| = x_{\xi} y_{\eta} - x_{\eta} y_{\xi}$$
 (1)

From the general inversion formula, we get

$$J^{-1} = \begin{bmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{bmatrix} = \frac{1}{|J|} \begin{bmatrix} y_\eta & -x_\eta \\ -y_\xi & x_\xi \end{bmatrix}$$
 (2)

From the chain rule, we have an universal formula for the total derivative:

$$f_x = f_\xi \xi_x + f_\eta \eta_x \qquad , \qquad f_y = f_\xi \xi_y + f_\eta \eta_y \tag{3}$$

The Piola mapping is defined as J/|J|. Its first-order derivatives become

$$\frac{\partial}{\partial x} \left[ \frac{1}{|J|} J \right] = -\frac{|J|_x}{|J|^2} J + \frac{1}{|J|} J_x \tag{4a}$$

$$\frac{\partial}{\partial y} \left[ \frac{1}{|J|} J \right] = -\frac{|J|_y}{|J|^2} J + \frac{1}{|J|} J_y \tag{4b}$$

Further computations yield two similar formulas:

$$|J|_{x} = \xi_{x}\widetilde{J}_{1} + \eta_{x}\widetilde{J}_{2} \tag{5a}$$

$$|J|_{v} = \xi_{v}\widetilde{J}_{1} + \eta_{v}\widetilde{J}_{2} \tag{5b}$$

In this setting, the auxiliary functions are

$$\widetilde{J}_1 = x_{\xi\xi}y_{\eta} + x_{\xi}y_{\xi\eta} - x_{\xi\eta}y_{\xi} - x_{\eta}y_{\xi\xi} \tag{6a}$$

$$\widetilde{J}_2 = x_{\xi\eta} y_{\eta} + x_{\xi} y_{\eta\eta} - x_{\eta\eta} y_{\xi} - x_{\eta} y_{\xi\eta}$$
(6b)

Likewise, we get the following matrix derivatives:

$$J_{x} = \xi_{x} \begin{bmatrix} x_{\xi\xi} & x_{\xi\eta} \\ y_{\xi\xi} & y_{\xi\eta} \end{bmatrix} + \eta_{x} \begin{bmatrix} x_{\xi\eta} & x_{\eta\eta} \\ y_{\xi\eta} & y_{\eta\eta} \end{bmatrix}$$
 (7a)

$$J_{y} = \xi_{y} \begin{bmatrix} x_{\xi\xi} & x_{\xi\eta} \\ y_{\xi\xi} & y_{\xi\eta} \end{bmatrix} + \eta_{y} \begin{bmatrix} x_{\xi\eta} & x_{\eta\eta} \\ y_{\xi\eta} & y_{\eta\eta} \end{bmatrix}$$
 (7b)

Imagine now that we have a vector function on the form

$$\begin{bmatrix} u \\ v \end{bmatrix} = \frac{1}{|J|} J \begin{bmatrix} U \\ V \end{bmatrix}$$

By using the product rule, we obtain

$$\begin{bmatrix} u \\ v \end{bmatrix}_x = \left( -\frac{|J|_x}{|J|^2} J + \frac{1}{|J|} J_x \right) \begin{bmatrix} U \\ V \end{bmatrix} + \frac{1}{|J|} J \begin{bmatrix} U_\xi \xi_x + U_\eta \eta_x \\ V_\xi \xi_x + V_\eta \eta_x \end{bmatrix}$$
(8a)

$$\begin{bmatrix} u \\ v \end{bmatrix}_{y} = \left( -\frac{|J|_{y}}{|J|^{2}} J + \frac{1}{|J|} J_{y} \right) \begin{bmatrix} U \\ V \end{bmatrix} + \frac{1}{|J|} J \begin{bmatrix} U_{\xi} \xi_{y} + U_{\eta} \eta_{y} \\ V_{\xi} \xi_{y} + V_{\eta} \eta_{y} \end{bmatrix}$$
(8b)

## 2. Second-order derivatives

From the double product rule, we have

$$\left[\frac{1}{|J|}J\right]_{xx} = \left[\frac{1}{|J|}\right]_{xx}J + 2\left[\frac{1}{|J|}\right]_{x}J_{x} + \frac{1}{|J|}J_{xx}$$
(9a)

$$\left[\frac{1}{|J|}J\right]_{yy} = \left[\frac{1}{|J|}\right]_{yy}J + 2\left[\frac{1}{|J|}\right]_{y}J_{y} + \frac{1}{|J|}J_{yy}$$
(9b)

Applying the same rule on 1/|J| yields

$$\left[\frac{1}{|J|}\right]_{xx} = -\frac{|J|_{xx}}{|J|^2} + \frac{|J|_x^2}{|J|^3}$$
 (10a)

$$\left[\frac{1}{|J|}\right]_{yy} = -\frac{|J|_{yy}}{|J|^2} + \frac{|J|_y^2}{|J|^3}$$
 (10b)

As we see from these formulas, the real objective is finding  $|J|_{xx}$ ,  $|J|_{yy}$ ,  $J_{xx}$  and  $J_{yy}$ . We start with  $J_{xx}$  and use the total derivative rule:

$$J_{xx} = \xi_{xx} \begin{bmatrix} x_{\xi\xi} & x_{\xi\eta} \\ y_{\xi\xi} & y_{\xi\eta} \end{bmatrix}_{x} + \eta_{xx} \begin{bmatrix} x_{\xi\eta} & x_{\eta\eta} \\ y_{\xi\eta} & y_{\eta\eta} \end{bmatrix}_{x}$$

$$= \xi_{xx} \begin{bmatrix} x_{\xi\xi\xi}\xi_{x} + x_{\xi\xi\eta}\eta_{x} & x_{\xi\xi\eta}\xi_{x} + x_{\xi\eta\eta}\eta_{x} \\ y_{\xi\xi\xi}\xi_{x} + y_{\xi\xi\eta}\eta_{x} & y_{\xi\xi\eta}\xi_{x} + y_{\xi\eta\eta}\eta_{x} \end{bmatrix} + \eta_{xx} \begin{bmatrix} x_{\xi\xi\eta}\xi_{x} + x_{\xi\eta\eta}\eta_{x} & x_{\xi\eta\eta}\xi_{x} + x_{\eta\eta\eta}\eta_{x} \\ y_{\xi\xi\xi}\xi_{x} + y_{\xi\xi\eta}\eta_{x} & y_{\xi\xi\eta}\xi_{x} + y_{\xi\eta\eta}\eta_{x} \end{bmatrix}$$

Summarizing, we have arrived at

$$J_{xx} = \xi_{xx} \begin{bmatrix} x_{\xi\xi\xi}\xi_x + x_{\xi\xi\eta}\eta_x & x_{\xi\xi\eta}\xi_x + x_{\xi\eta\eta}\eta_x \\ y_{\xi\xi\xi}\xi_x + y_{\xi\xi\eta}\eta_x & y_{\xi\xi\eta}\xi_x + y_{\xi\eta\eta}\eta_x \end{bmatrix} + \eta_{xx} \begin{bmatrix} x_{\xi\xi\eta}\xi_x + x_{\xi\eta\eta}\eta_x & x_{\xi\eta\eta}\xi_x + x_{\eta\eta\eta}\eta_x \\ y_{\xi\xi\xi}\xi_x + y_{\xi\xi\eta}\eta_x & y_{\xi\eta\eta}\xi_x + y_{\eta\eta\eta}\eta_x \end{bmatrix}$$
(11a)
$$J_{yy} = \xi_{yy} \begin{bmatrix} x_{\xi\xi\xi}\xi_y + x_{\xi\xi\eta}\eta_y & x_{\xi\xi\eta}\xi_y + x_{\xi\eta\eta}\eta_y \\ y_{\xi\xi\xi}\xi_y + y_{\xi\xi\eta}\eta_y & y_{\xi\xi\eta}\xi_y + y_{\xi\eta\eta}\eta_y \end{bmatrix} + \eta_{xx} \begin{bmatrix} x_{\xi\xi\eta}\xi_y + x_{\xi\eta\eta}\eta_y & x_{\xi\eta\eta}\xi_y + x_{\eta\eta\eta}\eta_y \\ y_{\xi\xi\xi}\xi_y + y_{\xi\xi\eta}\eta_y & y_{\xi\eta\eta}\xi_y + y_{\eta\eta\eta}\eta_y \end{bmatrix}$$
(11b)

The product rule implies that

$$\begin{split} |J|_{xx} &= \xi_{xx}\widetilde{J}_1 + \xi_x(\partial_x\widetilde{J}_1) + \eta_{xx}\widetilde{J}_2 + \eta_x(\partial_x\widetilde{J}_2) \\ |J|_{yy} &= \xi_{yy}\widetilde{J}_1 + \xi_y(\partial_y\widetilde{J}_1) + \eta_{yy}\widetilde{J}_2 + \eta_y(\partial_y\widetilde{J}_2) \end{split}$$

The real challenge is differentiating  $\widetilde{J}_1$  and  $\widetilde{J}_2$ . This requires that we must introduce 16 auxiliary functions in total:

$$k_{1x} = (x_{\xi\xi\xi}\xi_x + x_{\xi\xi\eta}\eta_x)y_\eta + x_{\xi\xi}(y_{\xi\eta}\xi_x + y_{\eta\eta}\eta_x)$$

$$k_{2x} = (x_{\xi\xi}\xi_x + x_{\xi\eta}\eta_x)y_{\xi\eta} + x_{\xi}(y_{\xi\xi\eta}\xi_x + y_{\xi\eta\eta}\eta_x)$$

$$k_{3x} = (x_{\xi\xi\eta}\xi_x + x_{\xi\eta\eta}\eta_x)y_{\xi} + x_{\xi\eta}(y_{\xi\xi\xi}\xi_x + y_{\xi\eta\eta}\eta_x)$$

$$k_{4x} = (x_{\xi\eta}\eta_x + x_{\eta\eta}\eta_x)y_{\xi\xi} + x_{\eta}(y_{\xi\xi\xi}\xi_x + y_{\xi\eta\eta}\eta_x)$$

$$k_{5x} = (x_{\xi\xi\eta}\xi_x + x_{\xi\eta\eta}\eta_x)y_{\eta} + x_{\xi\eta}(y_{\xi\eta}\xi_x + y_{\eta\eta\eta}\eta_x)$$

$$k_{6x} = (x_{\xi\xi}\xi_x + x_{\xi\eta\eta}\eta_x)y_{\eta\eta} + x_{\xi}(y_{\xi\eta\eta}\xi_x + y_{\eta\eta\eta}\eta_x)$$

$$k_{7x} = (x_{\xi\eta\eta}\xi_x + x_{\eta\eta\eta}\eta_x)y_{\xi} + x_{\eta\eta}(y_{\xi\xi}\xi_x + y_{\xi\eta\eta}\eta_x)$$

$$k_{8x} = (x_{\xi\eta\eta}\xi_x + x_{\eta\eta\eta}\eta_x)y_{\xi} + x_{\eta\eta}(y_{\xi\xi\eta}\xi_x + y_{\xi\eta\eta}\eta_x)$$

$$k_{1y} = (x_{\xi\xi}\xi_y + x_{\eta\eta\eta}\eta_x)y_{\xi} + x_{\eta\eta}(y_{\xi\xi\eta}\xi_y + y_{\eta\eta\eta}\eta_y)$$

$$k_{2y} = (x_{\xi\xi}\xi_y + x_{\xi\eta\eta}\eta_y)y_{\xi} + x_{\xi}(y_{\xi\xi\eta}\xi_y + y_{\xi\eta\eta}\eta_y)$$

$$k_{3y} = (x_{\xi\xi}\xi_y + x_{\xi\eta\eta}\eta_y)y_{\xi} + x_{\xi\eta}(y_{\xi\xi\xi}\xi_y + y_{\xi\eta\eta}\eta_y)$$

$$k_{4y} = (x_{\xi\eta}\eta_y + x_{\eta\eta\eta}\eta_y)y_{\xi} + x_{\eta}(y_{\xi\xi\xi}\xi_y + y_{\xi\eta\eta}\eta_y)$$

$$k_{5y} = (x_{\xi\xi\eta}\xi_y + x_{\xi\eta\eta}\eta_y)y_{\eta} + x_{\xi}(y_{\xi\eta\eta}\xi_y + y_{\eta\eta\eta}\eta_y)$$

$$k_{6y} = (x_{\xi\xi}\xi_y + x_{\xi\eta\eta}\eta_y)y_{\eta} + x_{\xi}(y_{\xi\eta\eta}\xi_y + y_{\eta\eta\eta}\eta_y)$$

$$k_{7y} = (x_{\xi\eta\eta}\xi_y + x_{\eta\eta\eta}\eta_y)y_{\xi} + x_{\eta\eta}(y_{\xi\xi}\xi_y + y_{\xi\eta\eta}\eta_y)$$

$$k_{8y} = (x_{\xi\eta\eta}\xi_y + x_{\eta\eta\eta}\eta_y)y_{\xi} + x_{\eta\eta}(y_{\xi\xi}\xi_y + y_{\xi\eta\eta}\eta_y)$$

Thus, we can define the four essential derivatives as

$$\partial_x \widetilde{J}_1 = k_{1x} + k_{2x} - k_{3x} - k_{4x} \tag{12a}$$

$$\partial_{\nu}\widetilde{J}_{1} = k_{1\nu} + k_{2\nu} - k_{3\nu} - k_{4\nu} \tag{12b}$$

$$\partial_x \widetilde{J_2} = k_{5x} + k_{6x} - k_{7x} - k_{8x} \tag{12c}$$

$$\partial_{\nu}\widetilde{J}_{2} = k_{5\nu} + k_{6\nu} - k_{7\nu} - k_{8\nu} \tag{12d}$$

A similar easier derivation is valid for U:

$$\begin{split} U_{xx} &= \begin{bmatrix} (U_{\xi\xi}\xi_x + U_{\xi\eta}\eta_x)\xi_x + U_{\xi}\xi_{xx} + (U_{\xi\eta}\xi_x + U_{\eta\eta}\eta_x)\eta_x + U_{\eta}\eta_{xx} \\ (V_{\xi\xi}\xi_x + V_{\xi\eta}\eta_x)\xi_x + V_{\xi}\xi_{xx} + (V_{\xi\eta}\xi_x + V_{\eta\eta}\eta_x)\eta_x + V_{\eta}\eta_{xx} \end{bmatrix} \\ &= \begin{bmatrix} U_{\xi\xi}\xi_x + U_{\xi\eta}\eta_x & U_{\xi\eta}\xi_x + U_{\eta\eta}\eta_x \\ V_{\xi\xi}\xi_x + V_{\xi\eta}\eta_x & V_{\xi\eta}\xi_x + V_{\eta\eta}\eta_x \end{bmatrix} \begin{bmatrix} \xi_x \\ \eta_x \end{bmatrix} + \begin{bmatrix} U_{\xi} & U_{\eta} \\ V_{\xi} & V_{\eta} \end{bmatrix} \begin{bmatrix} \xi_{xx} \\ \eta_{xx} \end{bmatrix} \end{split}$$

Hence, the double-derivatives of U and V are given by

$$\begin{bmatrix} U \\ V \end{bmatrix}_{xx} = \begin{bmatrix} U_{\xi\xi}\xi_x + U_{\xi\eta}\eta_x & U_{\xi\eta}\xi_x + U_{\eta\eta}\eta_x \\ V_{\xi\xi}\xi_x + V_{\xi\eta}\eta_x & V_{\xi\eta}\xi_x + V_{\eta\eta}\eta_x \end{bmatrix} \begin{bmatrix} \xi_x \\ \eta_x \end{bmatrix} + \begin{bmatrix} U_{\xi} & U_{\eta} \\ V_{\xi} & V_{\eta} \end{bmatrix} \begin{bmatrix} \xi_{xx} \\ \eta_{xx} \end{bmatrix}$$
(13a)

$$\begin{bmatrix} U \\ V \end{bmatrix}_{xx} = \begin{bmatrix} U_{\xi\xi}\xi_x + U_{\xi\eta}\eta_x & U_{\xi\eta}\xi_x + U_{\eta\eta}\eta_x \\ V_{\xi\xi}\xi_x + V_{\xi\eta}\eta_x & V_{\xi\eta}\xi_x + V_{\eta\eta}\eta_x \end{bmatrix} \begin{bmatrix} \xi_x \\ \eta_x \end{bmatrix} + \begin{bmatrix} U_{\xi} & U_{\eta} \\ V_{\xi} & V_{\eta} \end{bmatrix} \begin{bmatrix} \xi_{xx} \\ \eta_{xx} \end{bmatrix}$$
(13a)
$$\begin{bmatrix} U \\ V \end{bmatrix}_{yy} = \begin{bmatrix} U_{\xi\xi}\xi_y + U_{\xi\eta}\eta_y & U_{\xi\eta}\xi_y + U_{\eta\eta}\eta_y \\ V_{\xi\xi}\xi_y + V_{\xi\eta}\eta_y & V_{\xi\eta}\xi_y + V_{\eta\eta}\eta_y \end{bmatrix} \begin{bmatrix} \xi_y \\ \eta_y \end{bmatrix} + \begin{bmatrix} U_{\xi} & U_{\eta} \\ V_{\xi} & V_{\eta} \end{bmatrix} \begin{bmatrix} \xi_{yy} \\ \eta_{yy} \end{bmatrix}$$
(13b)