

**Name:** Vikram Surya R

**Reg No:** 19BCE1490

## Essentials of Data Analytics

### Tasks for Week-9: Gradient Descent

#### **AIM:**

To Understand the gradient descent following operations/functions on 'mtcars' dataset based on given instructions.

#### **Algorithm:**

1. Clear the environmental variables using rm function
2. Create a function named gd for gradient descent with attributes 'x1','x2','y','m1','m2','c','alpha','conv\_ther','iter'.
3. Initialize iterations and Lf values with 0.
4. While iterations less than iter.
5. Calculate y\_predicted as  $m1 * x1 + m2 * x2 + c$
6. New loss function equals  $0.5 * \text{sum of (difference of y and y\_predicted)}^2$ .
7. Calculate gradient descent.
8. Update the values of c and slope using gradient descent function.
9. Check if the value of loss function is less than threshold (Loss function - new loss function) if not break the loop else repeat.
10. Return the optimal, m1 & m2, c, loss.
11. Close the gd function.
12. Retrieve the dataset mtcars.
13. Call the gd function with attributes passed.
14. Compare the results with reg model.

#### **RESULTS:**

```
> gd(data$wt,data$hp,data$mpg,-0.2,-0.2,32,0.0000002,0.0000001,1000000)
[1] "Optimum Slope m1 and m2 : -2.77056594817977 -0.033477391356666 Optimum Intercept : 33.6446952273
715 Loss : 37.3934102824366 Iterations : 1000001"
> reg<-lm(data$mpg~data$wt+data$hp)
> reg
```

```
Call:
lm(formula = data$mpg ~ data$wt + data$hp)
```

```
Coefficients:
(Intercept)      data$wt      data$hp
    37.22727     -3.87783     -0.03177
```

## INFERENCE:

The values of the gradient decent are almost similar to Linear Regression model so the gradient decent can be acceptable.

## CODE:

```
rm(list=ls())

gd<- function(x1,x2,y,m1,m2,c,alpha,conv_thr,iter){
  iterations=0
  Lf<-0
  while(iterations<iter){
    y_p=m1*x1+m2*x2+c
    Lf_new<-0.5*sum(y_p-y)^2
    m1=m1-alpha*sum((y_p-y)*x1)
    m2=m2-alpha*sum((y_p-y)*x2)
    c=c-alpha*sum(y_p-y)
    if(abs(Lf-Lf_new)<=conv_thr){
      break
    }
    Lf=Lf_new
    iterations=iterations+1
  }
  return(paste("Optimal Intercept ",c,"Optimal slope one ",m1,"Optimal slope
two ",m2))
}

data<-mtcars
View(data)

gd(data$wt,data$hp,data$mpg,-0.2,-0.4,32,0.001,0.00001,10000)
```

```
lr<-lm(data$mpg~(data$wt+data$hp))
```

```
lr
```