

INTERPOLATING BETWEEN OPTIMAL TRANSPORT & KL REGULARIZED OPTIMAL TRANSPORT WITH RÉNYI DIVERGENCES

joint work with



Jonas Bresch, TU Berlin

University of South Carolina, Columbia, 12.09.2024.

Graduate Colloquium (Alec Helm, Jonah Klein).

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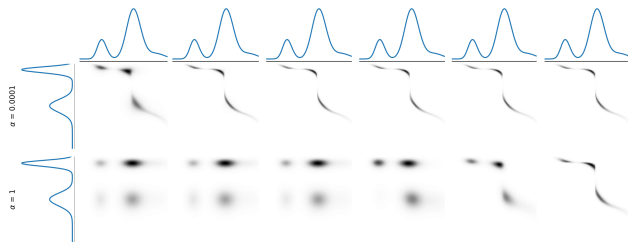
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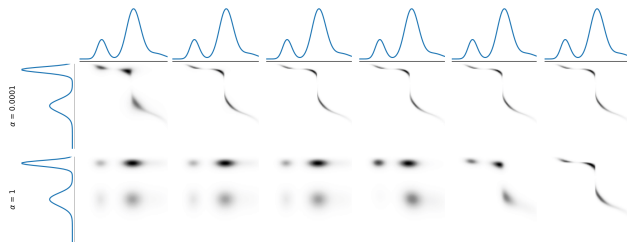
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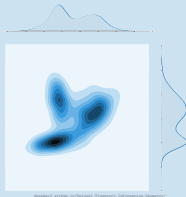
Our solution: Add instead ε times different ($=\alpha$ -Rényi) regularizer and let $\alpha \searrow 0$ instead of $\varepsilon \searrow 0$.

1. Tsallis divergence and α -Rényi divergence



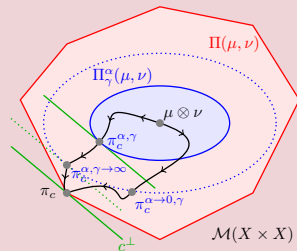
<https://arxiv.org/abs/1405.0487v2>
https://www.wikipedia.org/wiki/Convergence_of_information_theory

2. Optimal transport and its regularization



Source: J. G. L. (2019). Optimal Transport, Information Geometry

3. Rényi-regularized OT



4. Dual formulation

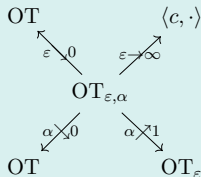


Polyan, Oshin, 2020

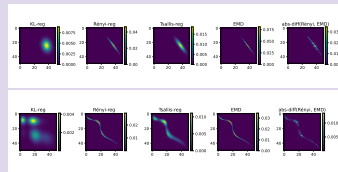
$$\min_{\pi \in \mathcal{P}(X^2)} \langle c, \pi \rangle + \varepsilon R_\alpha(\pi)$$

$$\max_{h \in \mathcal{C}(X^2)} \langle h, \pi \rangle - \varepsilon \ln(\gamma_h^\alpha)$$

5. Interpolation properties



6. Numerical results



DEFINITION (α -RÉNYI DIVERGENCE)

The α -Rényi divergence of *order* $\alpha \in (0, 1)$ is

$$R_\alpha: \mathcal{P}(X) \times \mathcal{P}(X) \rightarrow [0, \infty], \quad (\mu \mid \nu) \mapsto \frac{1}{\alpha - 1} \ln \left(\int_X \left(\frac{\rho_\mu(x)}{\rho_\nu(x)} \right)^\alpha d\nu(x) \right).$$

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$$T_q = \frac{1}{q - 1} [\exp((q - 1)R_q) - 1]: \mathcal{P}(X) \times \mathcal{P}(X) \rightarrow [0, \infty], \quad (\mu \mid \nu) \mapsto \frac{1}{q - 1} \left[\int_X \left(\frac{\rho_\mu(x)}{\rho_\nu(x)} \right)^q d\nu(x) - 1 \right]$$

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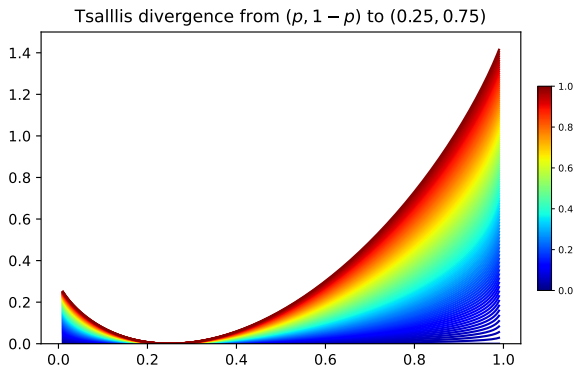
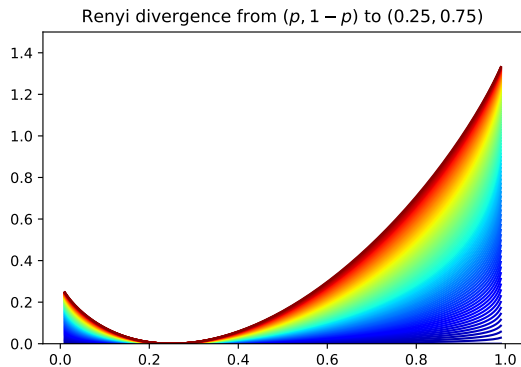
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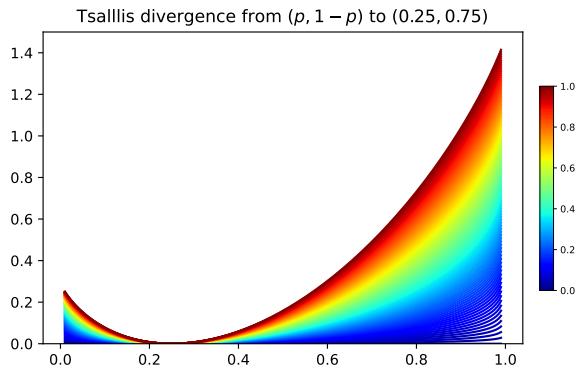
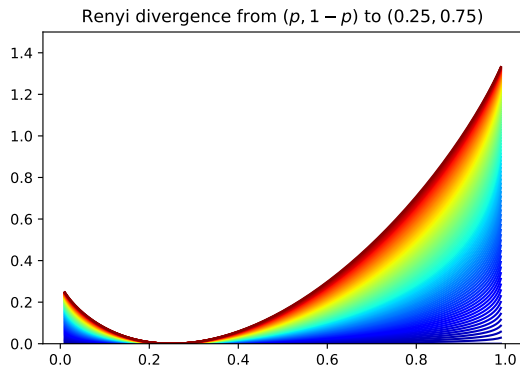
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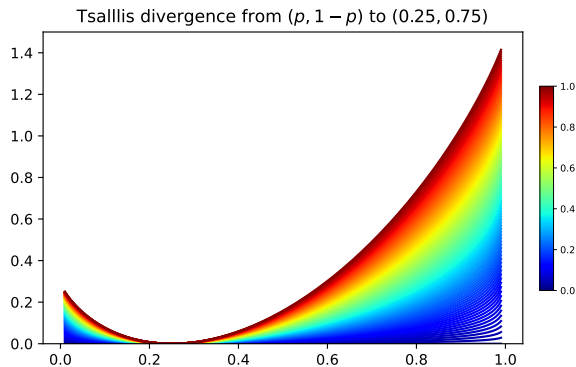
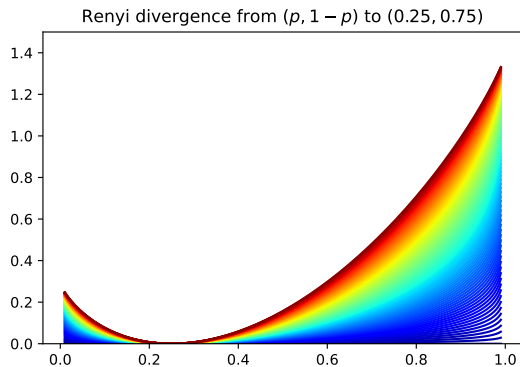
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Tsallis = 1st order approximation of Rényi since $\ln(y) \approx y - 1$ (1st order Taylor).



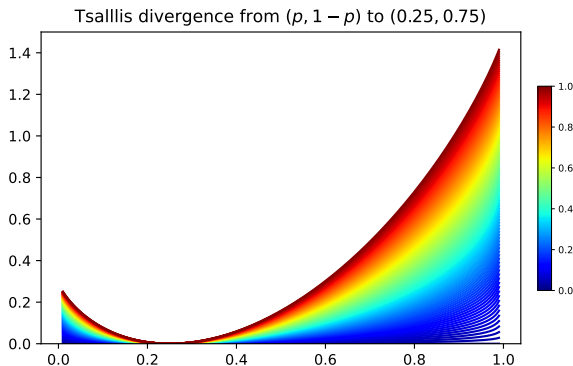
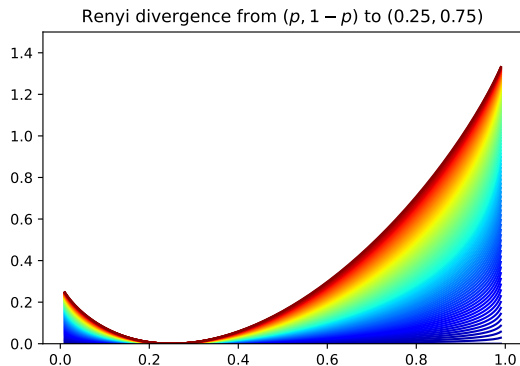


THEOREM (PROPERTIES OF THE RÉNYI DIVERGENCE)



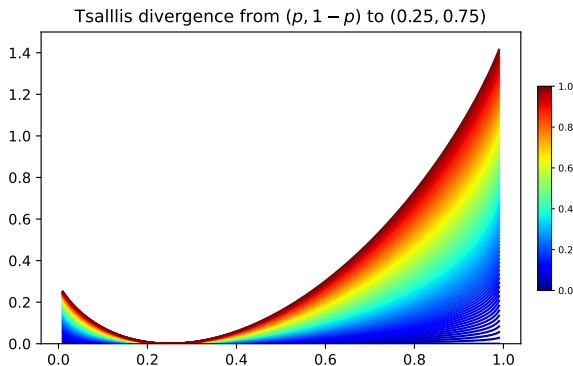
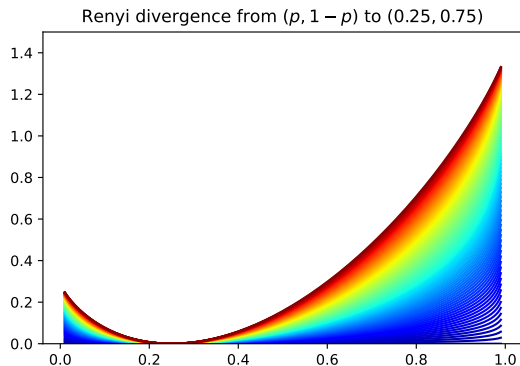
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- R_α **jointly convex**, **jointly weakly lower semicontinuous** for $\alpha \in (0, 1]$.

Let (X, d) metric space, with d lower semicontinuous.

Let $p \in [1, \infty)$, $\mathcal{P}(X)$ the set of probability measures.

$$\mathcal{P}_p(X) := \left\{ \mu \in \mathcal{P}(X) : \int_X d(x, x_0)^p \, d\mu(x) < \infty \right\}, \quad x_0 \in X.$$

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On $\mathcal{P}_p(X)$, the **Wasserstein- p metric** is

$$\text{OT}(\mu, \nu)^p = \min_{\pi \in \Pi(\mu, \nu)} \int_{X \times X} d(x, y)^p d\pi(x, y), \quad \mu, \nu \in \mathcal{P}_p(X),$$

where the **transport polytope** is

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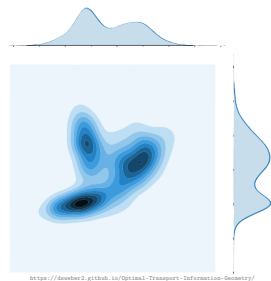
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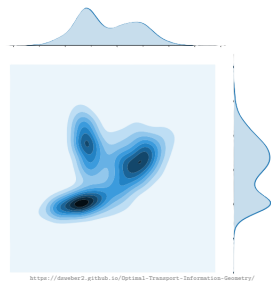
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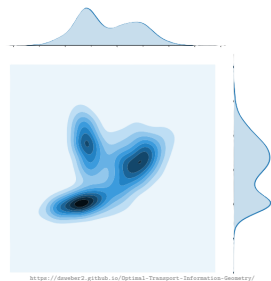
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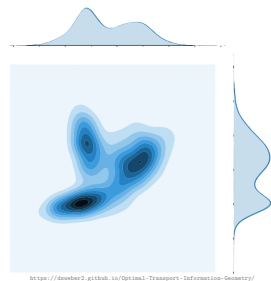
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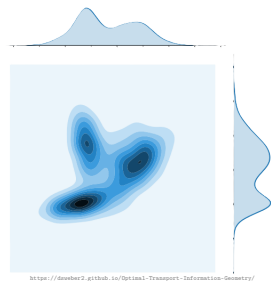
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Notation: $\langle f, \mu \rangle := \int_X f(x) d\mu(x)$, so we can write $\text{OT}(\mu, \nu)^p = \min \{ \langle d^p, \pi \rangle : \pi \in \Pi(\mu, \nu) \}$.



Regularizer: Kullback-Leibler divergence

$$\begin{aligned} & \text{KL}(\cdot \mid \mu \otimes \nu) : \Pi(\mu, \nu) \rightarrow [0, \infty), \\ & \pi \mapsto \int_{X \times X} \ln \left(\frac{d\pi}{d\mu \otimes \nu}(x, y) \right) d\mu(x) d\nu(y) \end{aligned}$$

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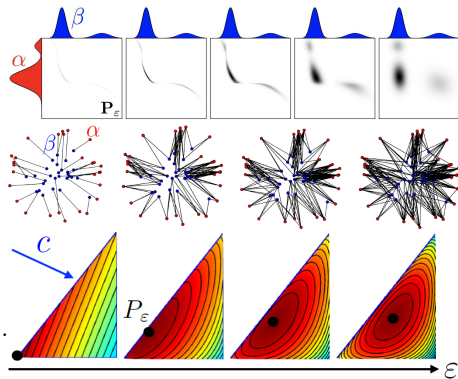
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Here, $c = d^P$. ©G. Péyre, M. Cuturi, 2019

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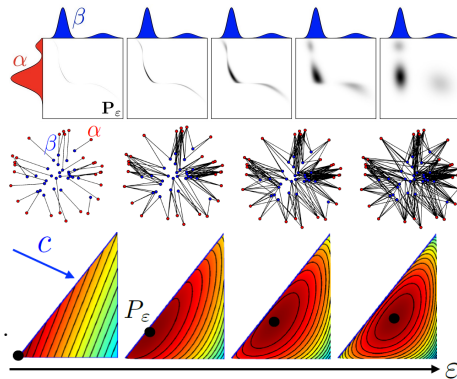
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$$\begin{aligned} \operatorname{argmin} \{ \text{KL}(\pi \mid \mu \otimes \nu) : \langle d^P, \pi \rangle = \text{OT}(\mu, \nu) \} &\xleftarrow{\varepsilon \searrow 0} \hat{\pi}_\varepsilon && \xrightarrow{\varepsilon \rightarrow \infty} \mu \otimes \nu \\ \text{OT}(\mu, \nu) &\xleftarrow{\varepsilon \searrow 0} \text{OT}_\varepsilon(\mu, \nu) && \xrightarrow{\varepsilon \rightarrow \infty} \langle d^P, \mu \otimes \nu \rangle \end{aligned}$$



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Discretize $X \approx (x_i)_{i=1}^N$

Optimal transport plan as KL-projection of Gibbs kernel

$$\hat{P}^\varepsilon = \operatorname{argmin}_{P \in \Pi(\mathbf{r}, \mathbf{c})} \operatorname{KL} \left(P \mid \exp \left(\frac{-M}{\varepsilon} \right) \right)$$

Sinkhorn algorithm finds this projection via matrix scaling.

Discretize $X \approx (x_i)_{i=1}^N$

$\mu, \nu \in \mathcal{P}(X)$ become vectors $\mathbf{r} := (\mu(x_i))_{i=1}^N, \mathbf{c} := (\nu(x_i))_{i=1}^N \in \Sigma_N$,

where

$$\Sigma_N := \{x \in [0, 1]^N : \sum_{i=1}^N x_i = 1\}.$$

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Discretize $X \approx (x_i)_{i=1}^N$

$\mu, \nu \in \mathcal{P}(X)$ become vectors $\mathbf{r} := (\mu(x_i))_{i=1}^N, \mathbf{c} := (\nu(x_i))_{i=1}^N \in \Sigma_N$,

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$$\Sigma_N := \{x \in [0, 1]^N : \sum_{i=1}^N x_i = 1\}.$$

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Optimal transport plan as KL-projection of Gibbs kernel

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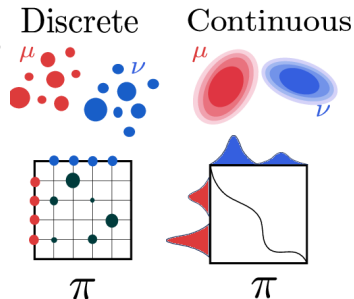
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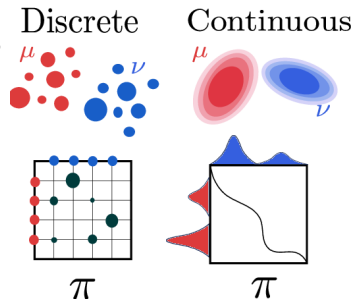
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transport polytope

$$\Pi(\mathbf{r}, \mathbf{c}) := \{\mathbf{P} \in \Sigma_{N \times N} : \mathbf{P} \mathbf{1}_N = \mathbf{r}, \mathbf{P}^T \mathbf{1}_N = \mathbf{c}\}$$



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$$d_{\gamma, \alpha} : \mathcal{P}_p(X) \times \mathcal{P}_p(X) \rightarrow \mathbb{R}, \quad (\mu, \nu) \mapsto \min \left\{ \langle d^p, \pi \rangle^{\frac{1}{p}} : \pi \in \Pi_\gamma^\alpha(\mu, \nu) \right\}. \quad (1)$$

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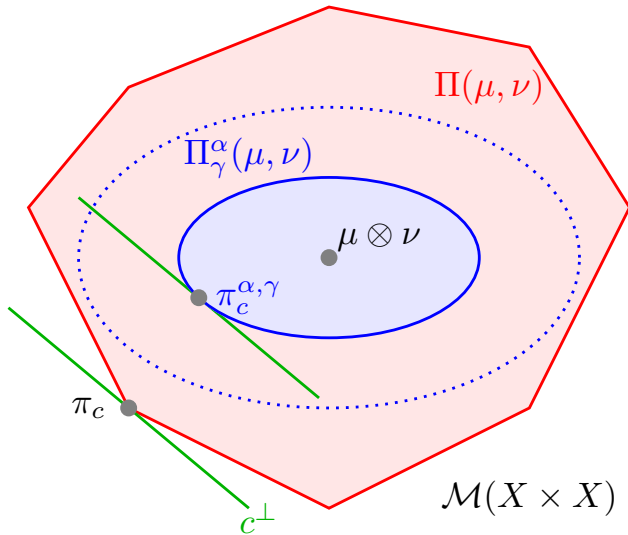
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THEOREM (BRESCH, S. '24)

- For $(\mu, \nu) \in \mathcal{P}_p(X)$, the optimization problem (1) is **convex** and has a **unique** minimizer.
- $\mathcal{P}_p(X)^2 \ni (\mu, \nu) \mapsto \mathbb{1}_{[\mu \neq \nu]}(\mu, \nu) d_{\gamma, \alpha}(\mu, \nu)$ is a **metric** for $\alpha \in (0, 1)$, $\gamma \in [0, \infty]$.



Transport polytope $\Pi(\mu, \nu)$, restricted transport polytope $\Pi_\gamma^\alpha(\mu, \nu)$ for $c = d^p$.
 (Plot inspired by (Cuturi, 2013).)

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$$d^{\alpha, \varepsilon} : \mathcal{P}_p(X) \times \mathcal{P}_p(X) \rightarrow \mathbb{R}, \quad (\mu, \nu) \mapsto \langle d^p, \pi^{\alpha, \varepsilon}(\mu \nu) \rangle^{\frac{1}{p}},$$

where $\pi^{\alpha, \varepsilon}(\mu, \nu) \in \operatorname{argmin} \{ \langle d^p, \pi \rangle + \varepsilon R_\alpha(\pi \mid \mu \otimes \nu) : \pi \in \Pi(\mu, \nu) \}.$ (2)

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THEOREM (LAGRANGIAN POINT OF VIEW AND PRE-METRIC [BRESCH, S. '24])

Let $(\mu, \nu) \in \mathcal{P}_p(X).$

- The optimization problem (2) is **convex** and has a **unique** minimizer.
- Rényi-Sinkhorn $d_{\gamma, \alpha}(\mu, \nu)$ and dual Rényi-Sinkhorn $d^{\alpha, \lambda}(\mu, \nu)$ are **equivalent**:

for $\gamma > 0$, there exists $\varepsilon \in [0, \infty]$, such that $\langle d^p, \pi^{\alpha, \varepsilon}(\mu, \nu) \rangle = d_{\gamma, \alpha}(\mu, \nu)^p.$

DEFINITION (RÉNYI-REGULARIZED OT [BRESCH, S. '24])

The **Rényi-regularized OT** problem is

$$\text{OT}_{\varepsilon, \alpha}: \mathcal{P}_p(X) \times \mathcal{P}_p(X) \rightarrow [0, \infty), (\mu, \nu) \mapsto \min_{\pi \in \Pi(\mu, \nu)} \langle c, \pi \rangle + \varepsilon R_\alpha(\pi \mid \mu \otimes \nu).$$

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LEMMA (MONOTONICITY OF RÉNYI REGULARIZED OT [BRESCH, S. '24])

Let $\mu, \nu \in \mathcal{P}_p(X)$, $\alpha, \alpha' \in (0, 1)$ and $\varepsilon, \varepsilon' \geq 0$ with $\alpha > \alpha'$ and $\varepsilon < \varepsilon'$. Then, we have

$$\text{OT}_{\varepsilon', \alpha}(\mu, \nu) \geq \text{OT}_{\varepsilon, \alpha}(\mu, \nu) \geq \text{OT}_{\varepsilon, \alpha'}(\mu, \nu).$$

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THEOREM (DUAL PROBLEM, DUAL REPRESENTATION [BRESCH, S. '24])

We have the strong duality

$$\text{OT}_{\varepsilon,\alpha}(\mu, \nu) = \max_{\substack{f, g \in \mathcal{C}(X) \\ f \oplus g \leq d}} \langle f \oplus g, \mu \otimes \nu \rangle - \varepsilon \ln \left(\left\langle (d - f \oplus g)^{\frac{\alpha}{\alpha-1}}, \mu \otimes \nu \right\rangle \right) + C_{\alpha,\lambda}. \quad (3)$$

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Proof idea. Use Fenchel-Rockafellar theorem, extend objective to $\mathcal{M}(X) \times \mathcal{M}(X)$ by ∞ .

$$\text{OT}_{\varepsilon, \alpha}(\mu, \nu)$$

THEOREM (INTERPOLATION PROPERTIES).

$$\text{OT}_{\varepsilon, \alpha}(\mu, \nu) \xrightarrow{\varepsilon \rightarrow \infty} \langle d, \mu \otimes \nu \rangle$$

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$$\begin{array}{ccc} & & \langle d, \mu \otimes \nu \rangle \\ & \nearrow^{\varepsilon \rightarrow \infty} & \\ \text{OT}_{\varepsilon, \alpha}(\mu, \nu) & & \\ & \searrow_{\alpha \nearrow 1} & \\ & & \text{OT}_{\varepsilon}(\mu, \nu) \end{array}$$

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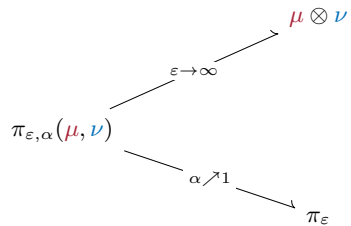
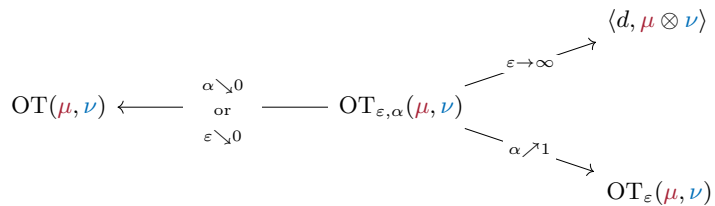
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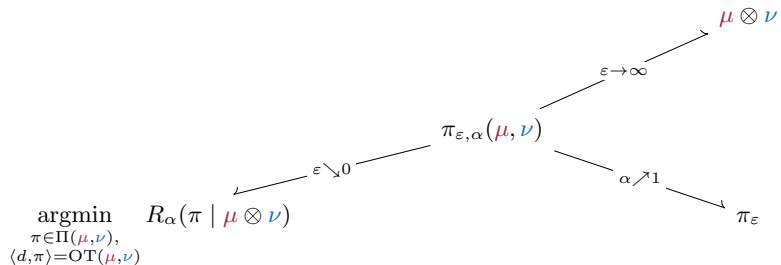
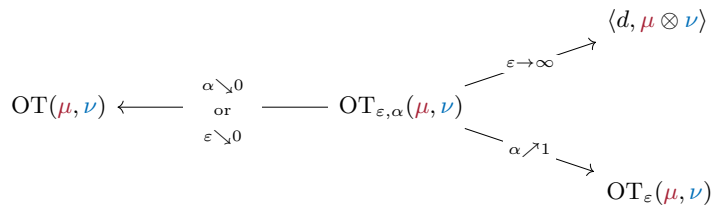
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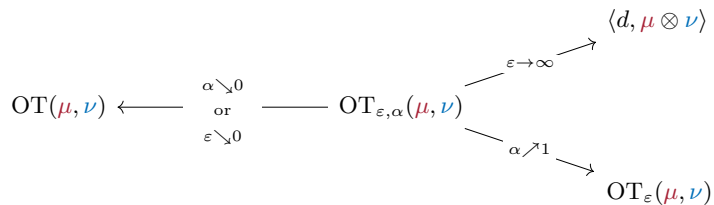
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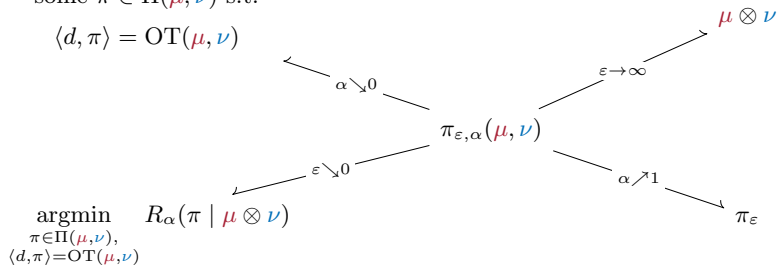


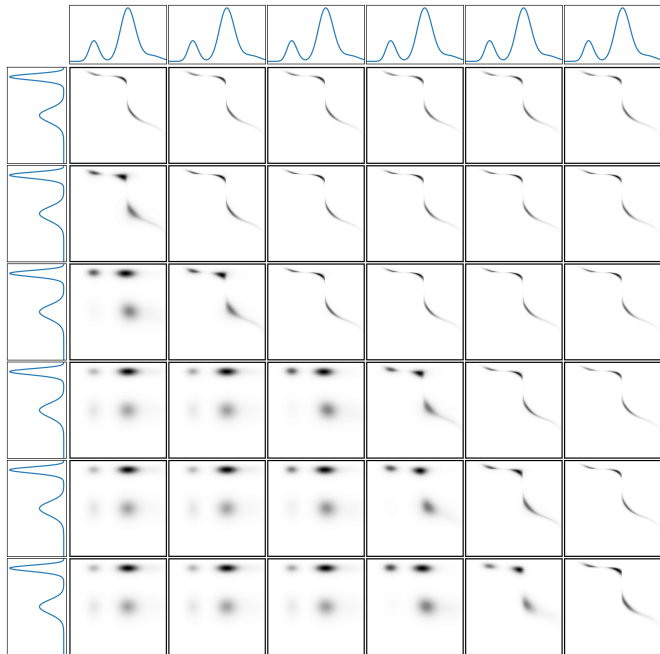
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some $\pi \in \Pi(\mu, \nu)$ s.t.

$$\langle d, \pi \rangle = \text{OT}(\mu, \nu)$$





Solve

$$\min_x f(x),$$

via the updates

$$x^{(k+1)} = x^{(k)} - \eta_k \nabla f(x^{(k)}) \quad , \quad x^{(0)} \in K, \eta_k > 0, \quad (4)$$

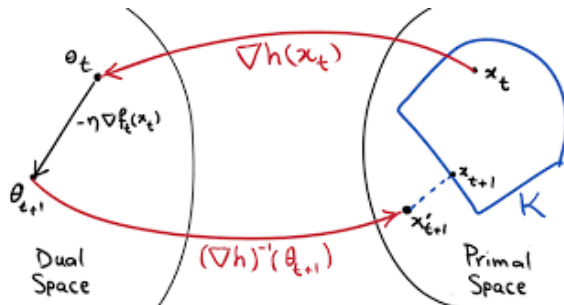
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for a convex function $h: \mathbb{R}^n \rightarrow \mathbb{R}$ with special properties.



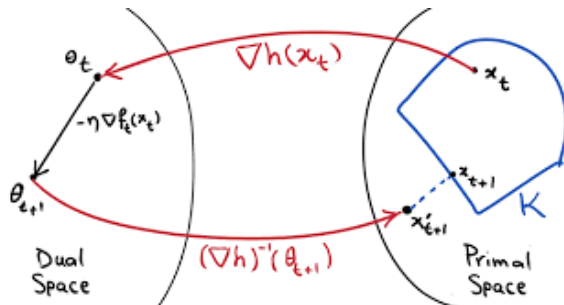
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Choose $K = \Sigma_N$ (probability simplex), $-h = \text{Shannon entropy} \implies D_h = \text{KL}$.

Rényi-regularized OT objective

$$\Pi(\mathbf{r}, \mathbf{c}) \rightarrow [0, \infty), \quad \mathbf{P} \mapsto \langle \mathbf{M}, \mathbf{P} \rangle + \varepsilon R_\alpha(\mathbf{P} \mid \mathbf{r}\mathbf{c}^\text{T}).$$

is not Lipschitz continuous, but locally Lipschitz on

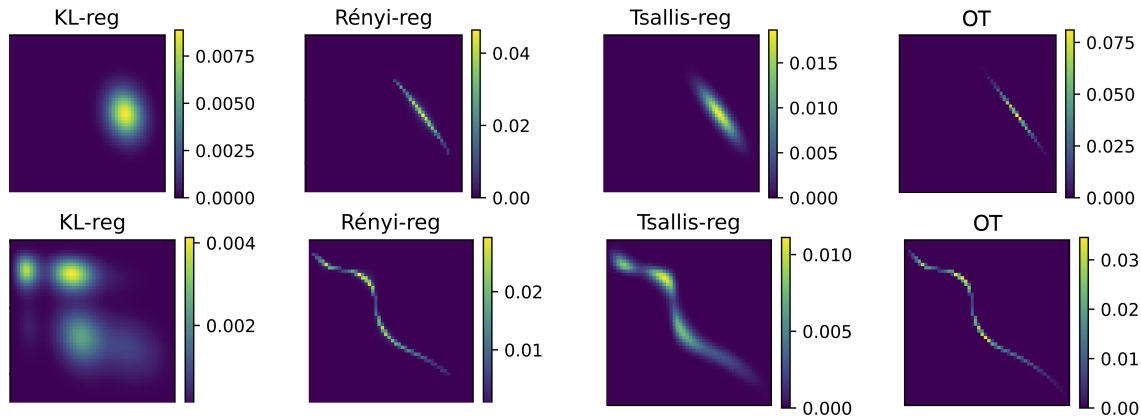
$$\{\mathbf{P} \in \Pi(\mathbf{r}, \mathbf{c}) : \mathbf{P}|_{\text{supp}(\mathbf{r} \otimes \mathbf{c})} > 0\} = \Pi(\mathbf{c}, \mathbf{r}) \cap \mathbb{R}_{>0}^N,$$

which suffices for convergence of a mirror descent with **special step size** $(\eta_k)_{k \in \mathbb{N}}$ (You, Li, 2022).

In each iteration one KL projection onto Σ_N (using Sinkhorn algorithm) is performed:

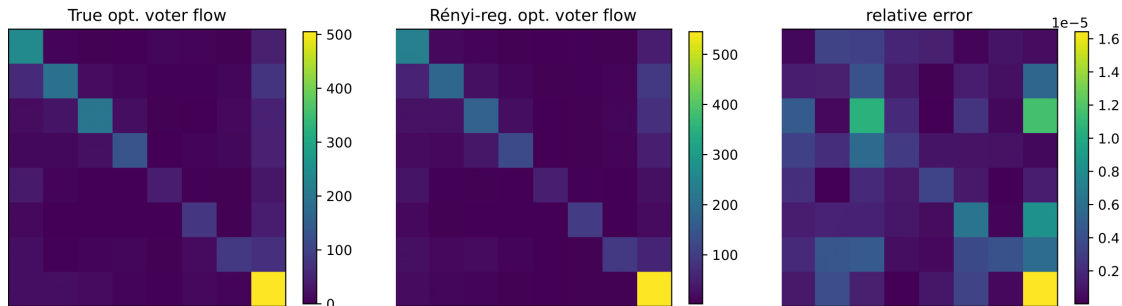
$$\mathbf{P}^{(k)} \leftarrow \text{Sinkhorn} \left(\mathbf{P}^{(k-1)} \odot \exp \left(-\eta_k \mathbf{M} - \frac{\eta_k}{\lambda} \frac{\alpha}{\alpha - 1} \frac{(\mathbf{r}\mathbf{c}^\text{T} \oslash \mathbf{P})^{1-\alpha}}{\langle \mathbf{P}^\alpha, (\mathbf{r}\mathbf{c}^\text{T})^{1-\alpha} \rangle} \right); \mathbf{r}, \mathbf{c} \right), \quad k \in \mathbb{N}.$$

RÉNYI REGULARIZATION YIELDS MORE ACCURATE PLANS



Regularized OT plans for Gaussian (*top*) and Poisson (*bottom*) marginals with regularization parameter $\lambda = 10$, Rényi order $\alpha = 0.01$, Tsallis order: $q = 2$.

NUMERICAL EXPERIMENTS - PREDICTING VOTER MIGRATION



regularizer, $\varepsilon = 1$	abs error \pm std	KL error	mean squared error
KL	$2.4221 \times 10^1 \pm 2.848 \times 10^1$	8.422×10^2	9.008×10^4
Tsallis	$9.409 \pm 1.529 \times 10^1$	3.173×10^2	2.063×10^4
OT	$1.845 \times 10^1 \pm 2.358 \times 10^1$	7.655×10^2	5.738×10^4
$\frac{3}{10}$ -Rényi	6.611 ± 7.868	2.128×10^2	6.759×10^3

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- **Novelty.** $R_\alpha \notin \{f\text{-divergence, Bregman divergence}\}$ and R_α not “separable” due to the logarithm.

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Paper link: <https://arxiv.org/abs/2404.18834>

My website: <https://viktorajstein.github.io>

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$$\text{OT}_{\varepsilon, \alpha}(\mu, \mu) \neq 0$$

To obtain valid, differentiable distance:

$$D_{\varepsilon, \alpha}(\mu, \nu) := \text{OT}_{\varepsilon, \alpha}(\mu, \nu) - \frac{1}{2} \text{OT}_{\varepsilon, \alpha}(\mu, \mu) - \frac{1}{2} \text{OT}_{\varepsilon, \alpha}(\nu, \nu).$$

Can be used for gradient flows.