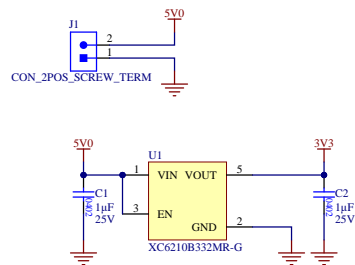

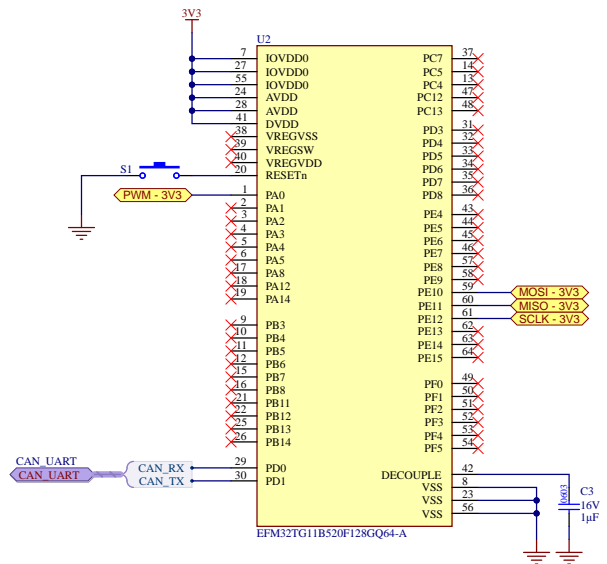


# POWER

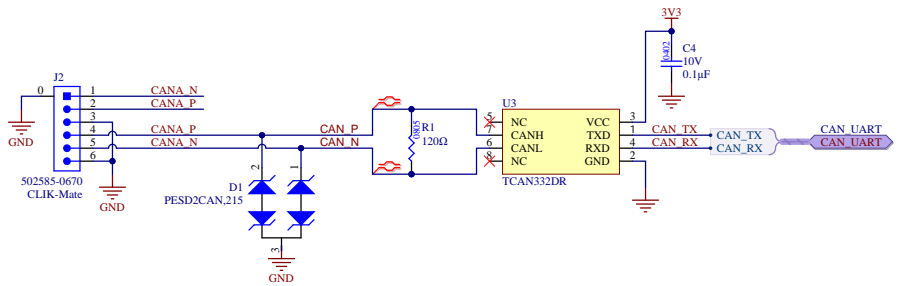


 <b>ROBOTICS</b> TEAM		University of Waterloo Robotics Team 200 University Ave W Waterloo, Ontario, Canada N2L 3G1	REV 1
PROJECT Gimbal.PrjPcb, [No Variations]			
DOCUMENT SH1 - POWER.SchDoc		MODIFIED 2021-11-30	
ENGINEER Taylor McNabb	REVIEWER Lance Bantoto	SHEET 1 OF 3	

# MICROCONTROLLER

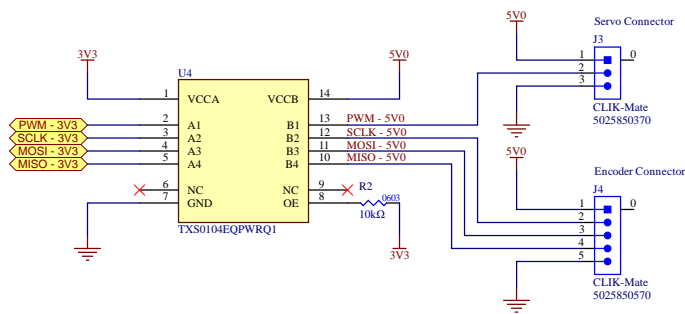



# CAN



<b>UW</b> <b>ROBOTICS</b> TEAM		University of Waterloo Robotics Team 200 University Ave W Waterloo, Ontario, Canada N2L 3G1	REV 1
PROJECT Gimbal.PrjPcb, [No Variations]			
DOCUMENT SH2 - MICROCONTROLLER.SchDoc		MODIFIED 2021-12-01	
ENGINEER Taylor McNabb	REVIEWER Lance Bantoto	SHEET 2 OF 3	

# LEVEL SHIFTER



 <b>ROBOTICS</b> TEAM		University of Waterloo Robotics Team 200 University Ave W Waterloo, Ontario, Canada N2L 3G1	REV •
PROJECT Gimbal.PrjPcb, [No Variations]			
DOCUMENT SH3 - LEVEL SHIFTER.SchDoc		MODIFIED 2021-12-01	
ENGINEER •	REVIEWER •	SHEET 3 OF 3	