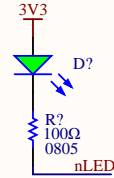
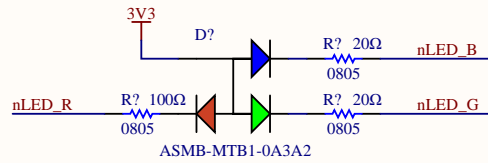


Test LEDs



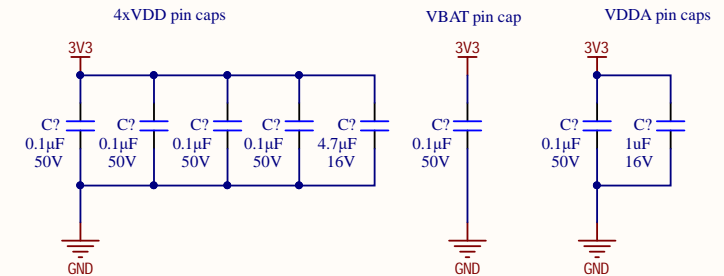
Current Calculations

Green LED voltage drop: 2.2V
- I = (3.3-2.2V)/100 = 11mA

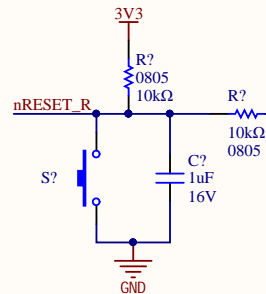
RGB LED voltage drops:

- Red: 2.1V: $I = (3.3-2.1V)/100 = 12mA$
- Blue: 3.1V: $I = (3.3-3.1V)/20 = 10mA$
- Green: 3.1V: $I = (3.3-3.1V)/20 = 10mA$

Decoupling Caps

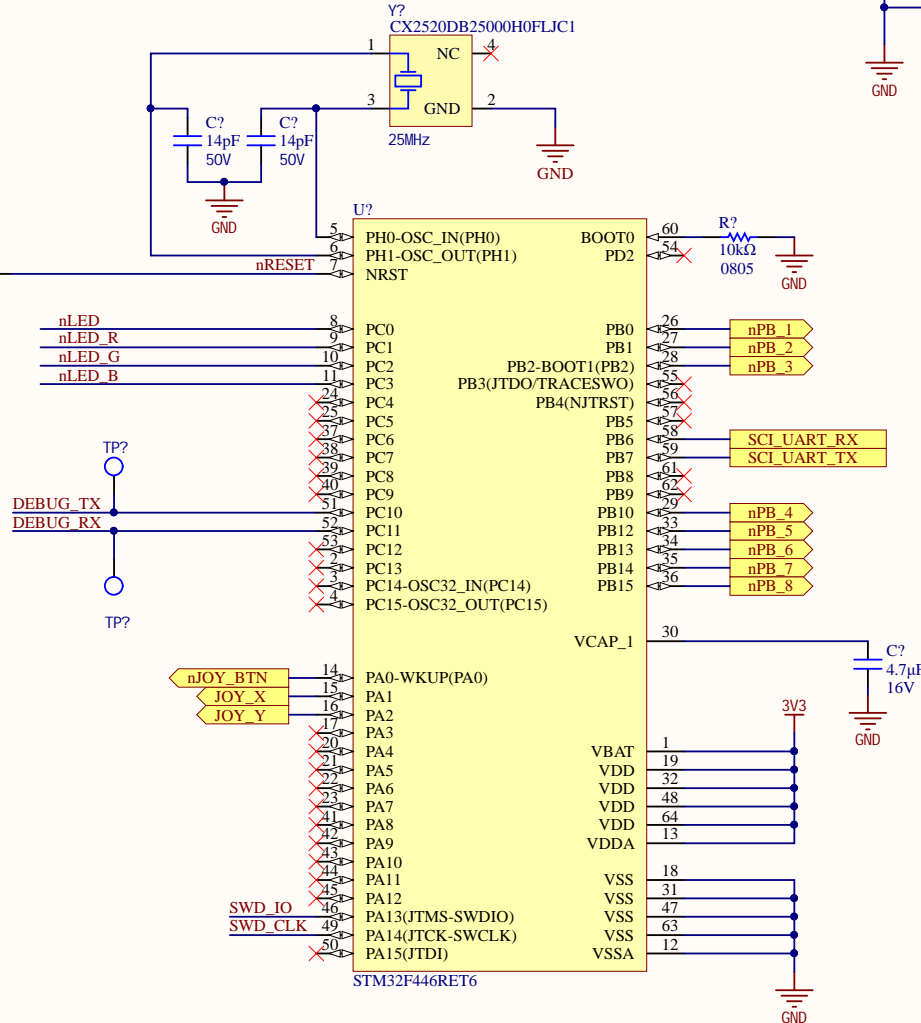


Reset Button

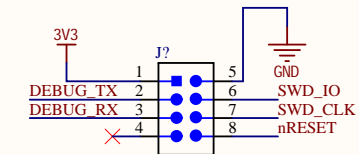



▲ For Debounce Circuit:

$$T = RC \rightarrow C = T/R$$

$$C = 10\text{ms}/10\text{k}\Omega = 1\mu\text{F}$$


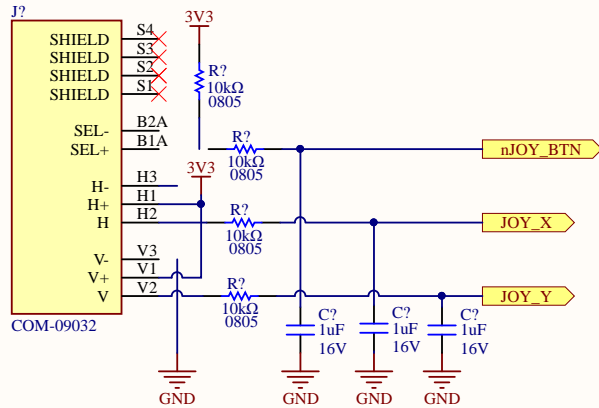
Debug/Programming



Title: SH1_MCU	
Size: Letter Drawn By: Qinyang Bao	
Date: 2020-10-31 Sheet1 of 4	

File: C:\Users\pkmn\Desktop\Document Archive\Other\Electrical Git Repo\MarsRover2020-PCB\Projects\Robot Controller\

2-Axis Joysticks

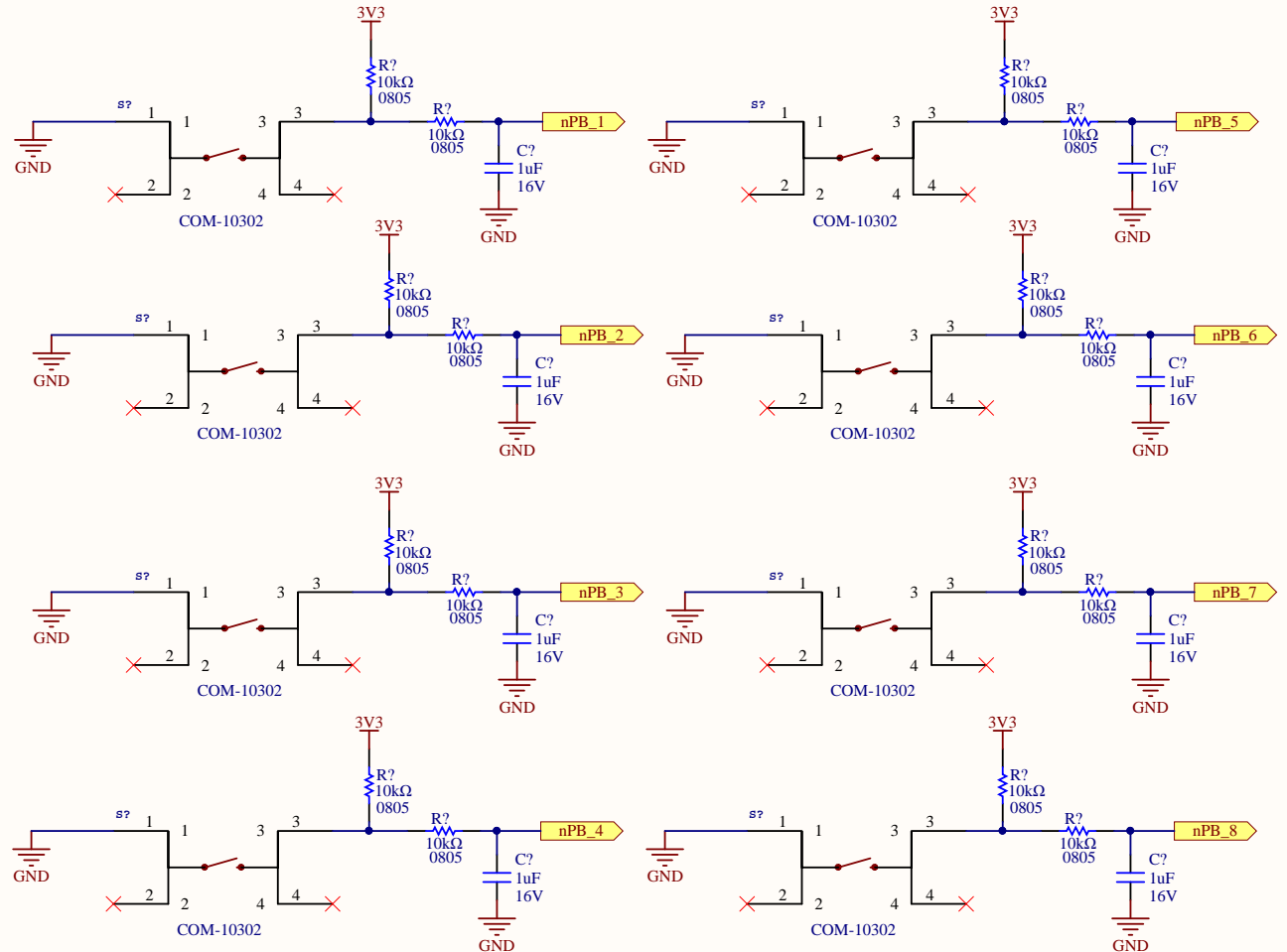


Controls

Joystick:
 - Up/Down is for elevator, Left/Right is for opening/closing shovel
 - Button should be used to choose between L/R and U/D, since the science mechanism may be damaged if too many things are moving at once

Buttons:
 - 1/2: Move left/right 1 index
 - 3/4: Move to leftmost/rightmost index
 - 5/6: Open/close lid
 - 7: Pre-programmed mixing sequence
 - 8: Extra, in case additional functionality is requested later

Pushbuttons



For Debounce Circuits:

$T=RC \rightarrow C= T/R$
 $C= 10ms/10kOhms= 1\mu F$

Title SH2-CONTROLS

Size: Letter Drawn By: Oinyang Bao

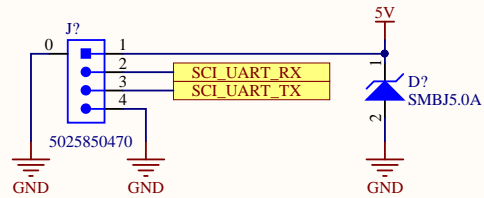
Date: 2020-10-31

Sheet2 of 4

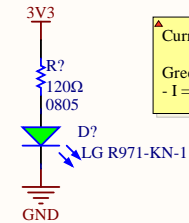
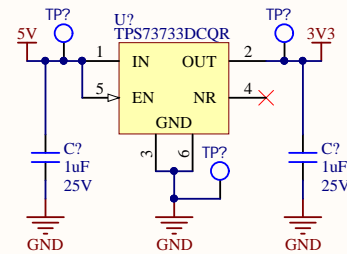
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Power In



5V to 3V3 LDO



Current Calculations
 Green LED voltage drop: 2.2V
 $I = (3.3 - 2.2V) / 120 = 9mA$