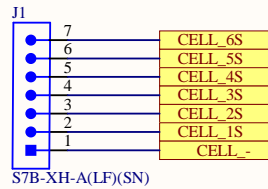
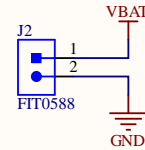


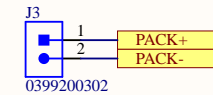
Battery Balancing



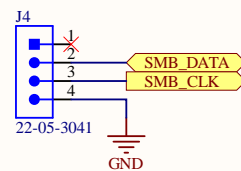
Battery In



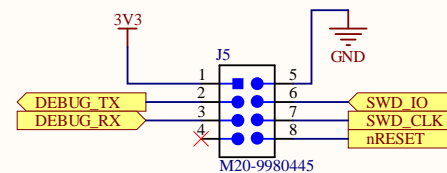
Pack Out




EV2400

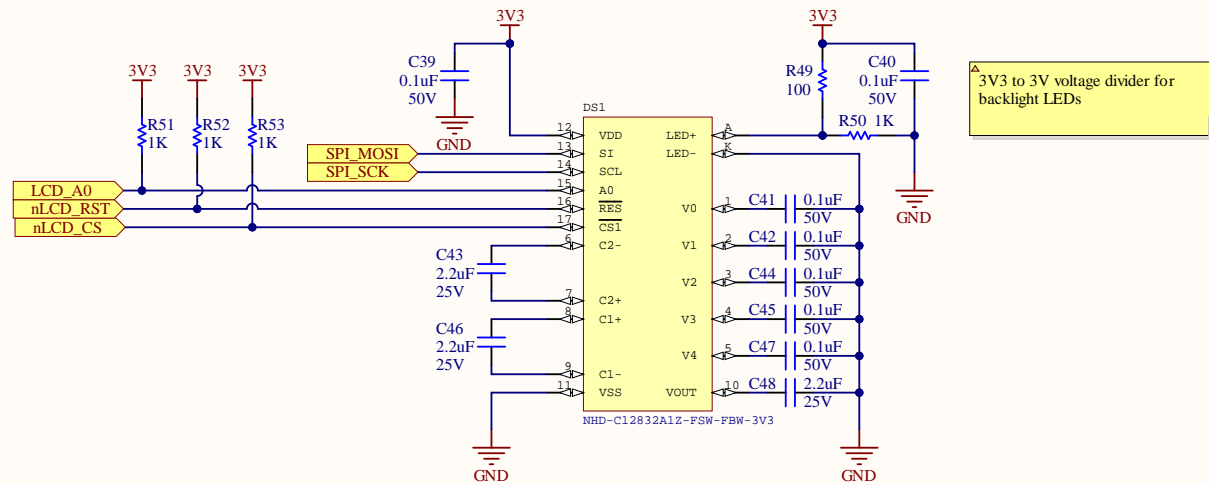


Debug/Programing



Title Connectors		UW Robotics 200 University Avenue Waterloo Ontario Canada N2L 3G6		
Size: Letter	Drawn By: Ayesha Ebrahim			
Date: 2020-05-12	Sheet of			
File: C:\Users\ayesh\Documents\GitHub\MarsRover2020-PCB\Projects\BMS\Rev1\Connectors.SchDoc				

LCD



1



Green LED voltage drop: 2.2V
 $- I = (3.3 - 2.2V) / 120 = 10.83mA$

- Red: $2.1V$: $I = (3.3-2.1V)/120 = 10mA$
- Blue: $3.1V$: $I = (3.3-3.1V)/20 = 10mA$
- Green: $3.1V$: $I = (3.3-3.1V)/20 = 10mA$

$$T=RC \rightarrow C=T/R$$

$$C=0.001\text{ms}/1000\text{Ohms}=1\mu\text{F}$$

C


$$T=RC \rightarrow C=T/R$$
$$C=0.001\text{ms}/1000\text{Ohms}=1\mu\text{F}$$

2



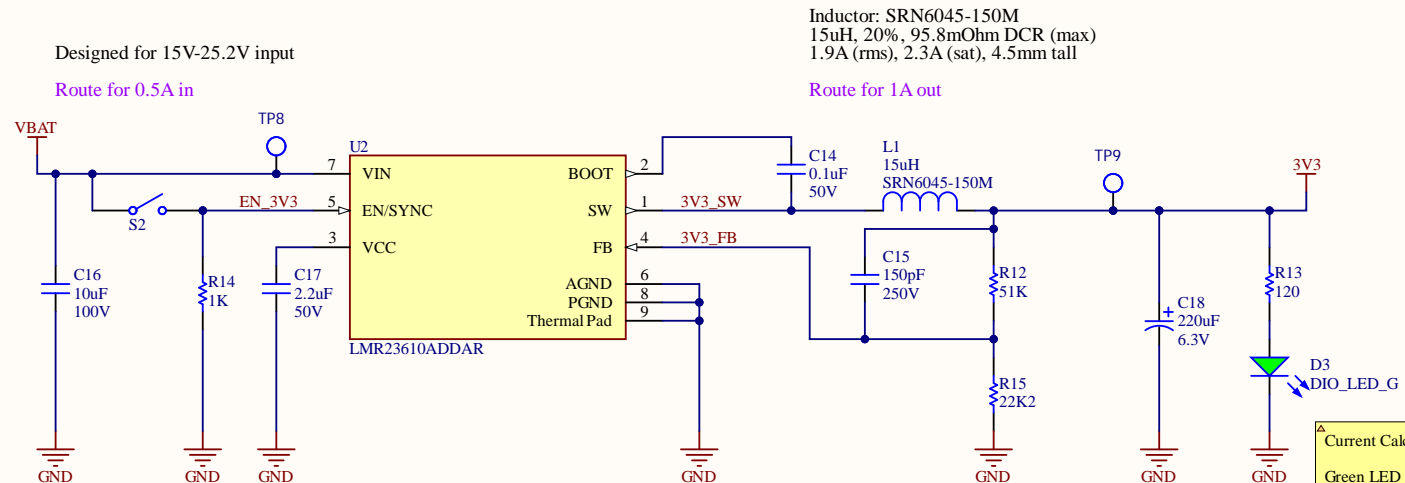
1



MOUNTING_HOLES



Battery Voltage to 3V3 Buck @ 1A Max



Current Calculations

Green LED voltage drop: 2.2V
 $I = (3.3 - 2.2V) / 120 = 10.83mA$

Max expected power on output = 1.65W
 Max current = 0.5A
 Expected Efficiency at 1A > 87.7%

SD Card Connector

