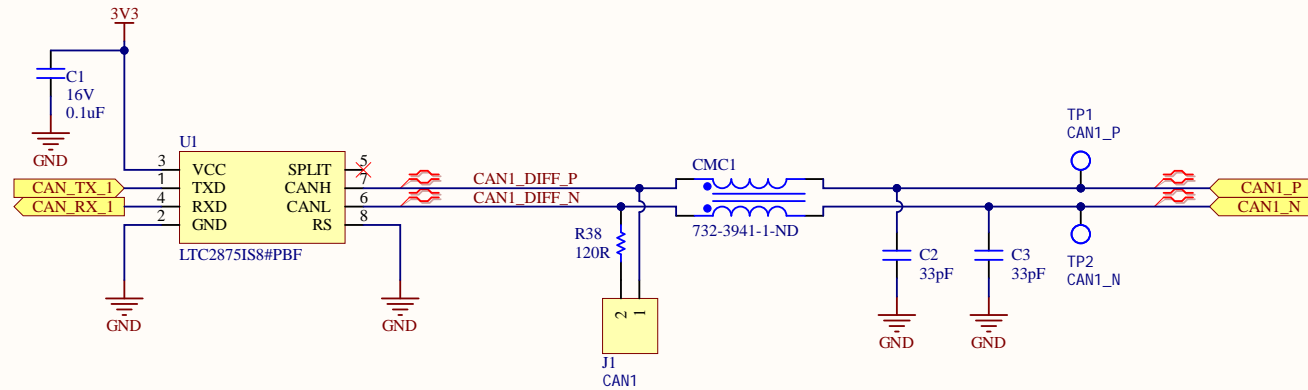
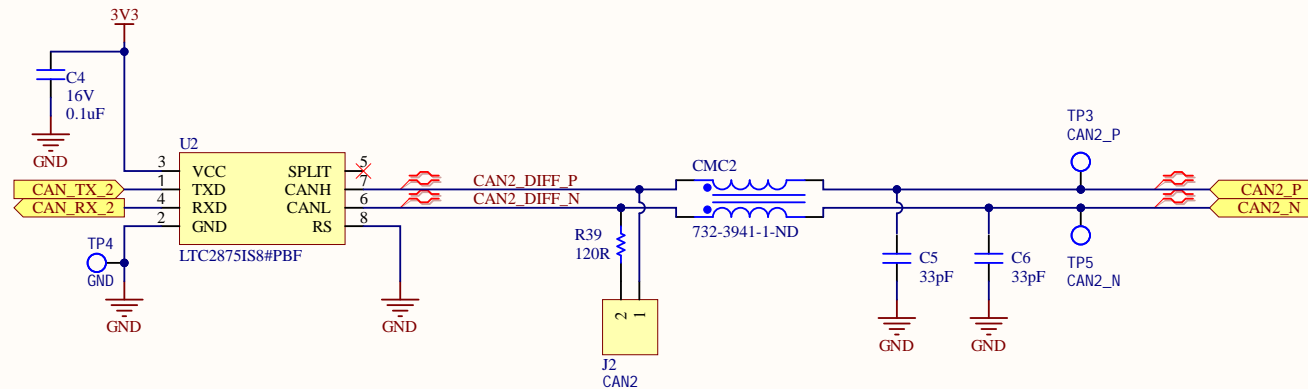


CAN 1



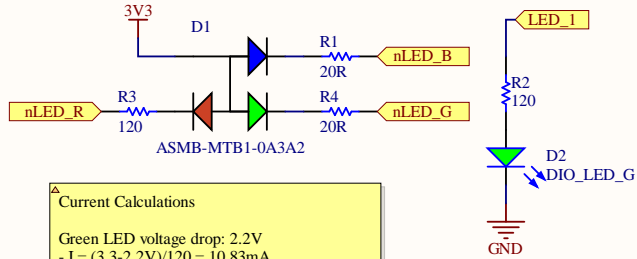
CAN 2



| | | | | |
|---|---|---|---|---|
| | 1 | 2 | 3 | 4 |
| A | | | | |
| B | | | | |
| C | | | | |
| D | | | | |
| | 1 | 2 | 3 | 4 |

Add XTAL Connector and
 Battery Balancing Connector,
 CAN Connections, Chip
 Programmer connector, DEBUG
 connector

Test LEDs



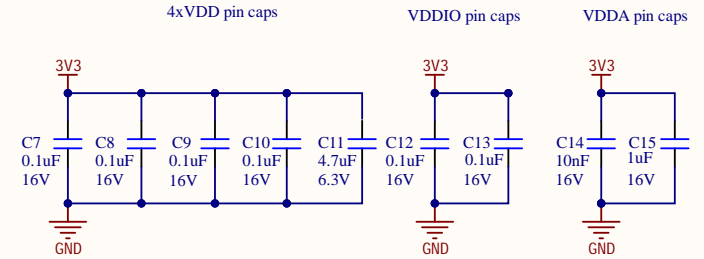
Current Calculations

Green LED voltage drop: 2.2V
 $I = (3.3 - 2.2V) / 120 = 10.83mA$

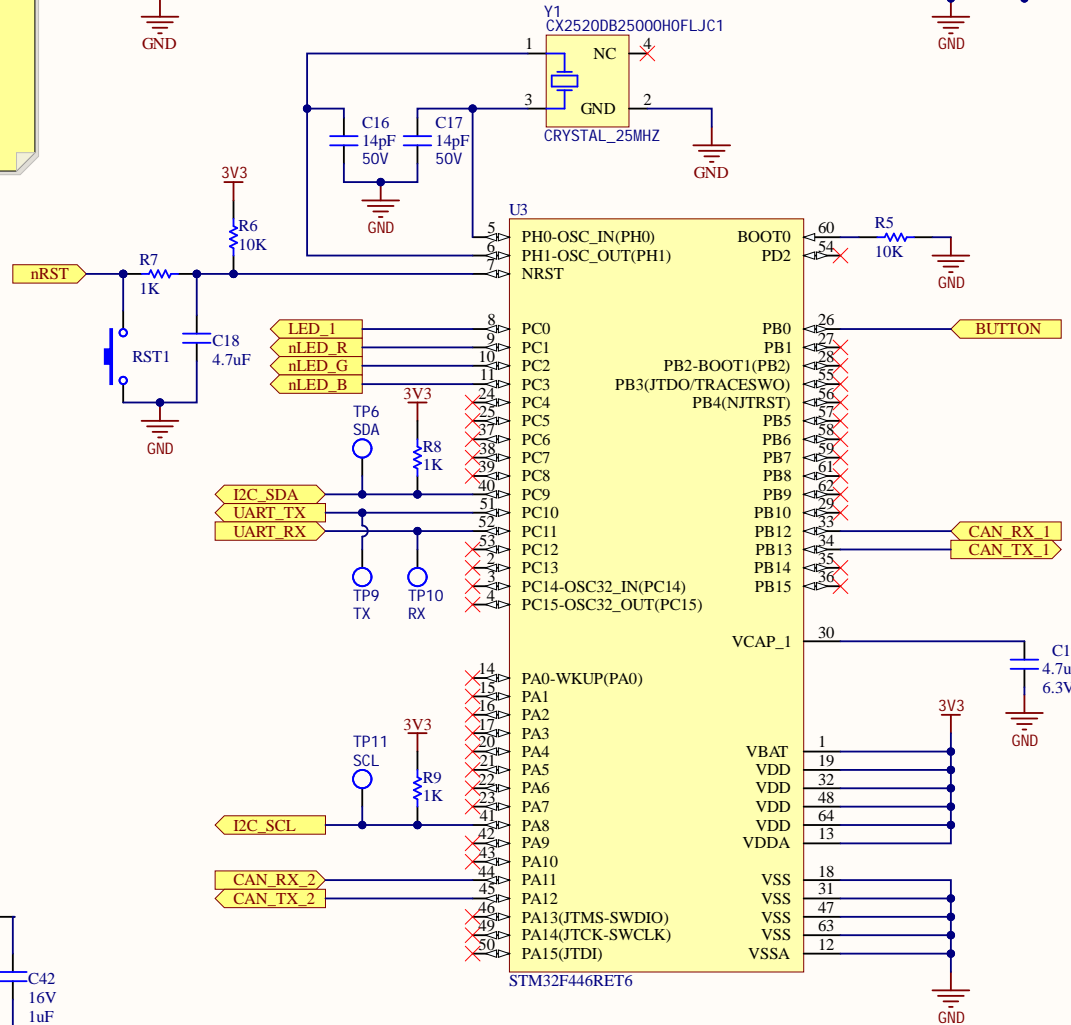
RGB LED voltage drops:

- Red: 2.1V: $I = (3.3 - 2.1V) / 120 = 10mA$
 - Blue: 3.1V: $I = (3.3 - 3.1V) / 20 = 10mA$
 - Green: 3.1V: $I = (3.3 - 3.1V) / 20 = 10mA$

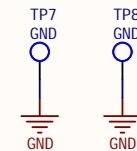
Decoupling Caps



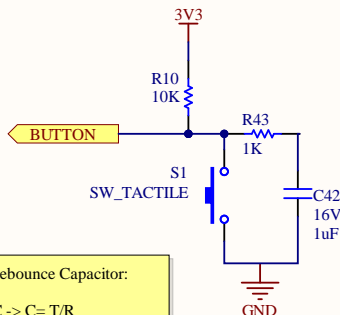
STM32F446RET6



GND Test Points



Test Button



For Debounce Capacitor:

$T = RC \rightarrow C = T/R$
 $C = 0.001ms / 1000Ohms = 1uF$

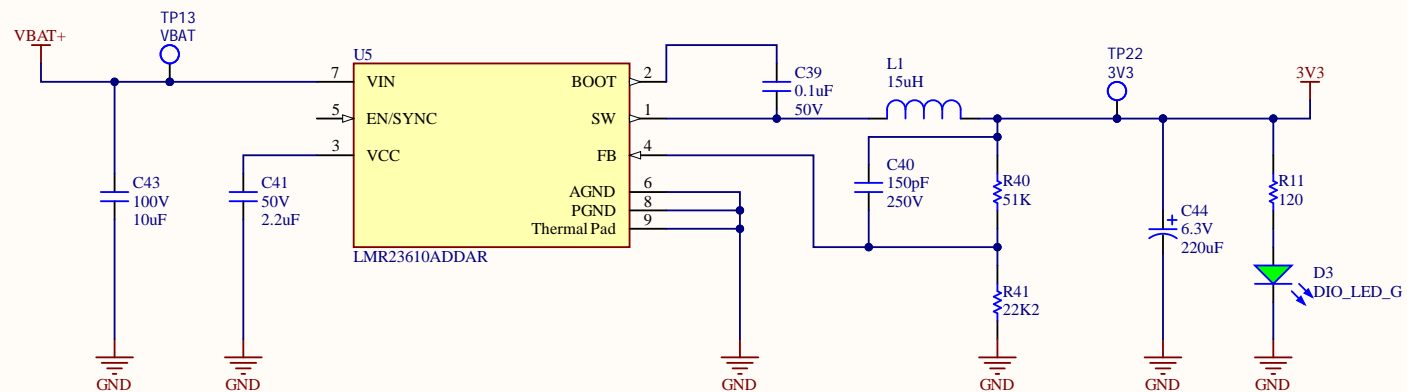
| | | |
|-----------|--|-------------|
| Title | MCU | * |
| Size: | Letter | * |
| Drawn By: | Ayesha Ebrahim | * |
| Date: | 2020-05-04 | Sheet* of * |
| File: | C:\Users\ayesh\Documents\GitHub\MarsRover2020-PCB\Projects\BMS\Rev1\MCU_SchDoc | |



Regulator Characteristics:
Efficiency...

VBAT is the battery voltage not controlled by the battery manager
VBAT max = 25.2V
VBAT min = 18V (assuming no cells fall below 3V)

Battery Voltage to 3V3 Buck @ 1A Max



Current Calculations
Green LED voltage drop: 2.2V
- $I = (3.3 - 2.2V) / 120 = 10.83mA$