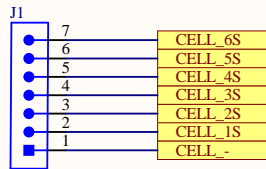
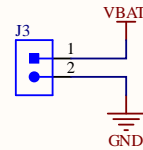


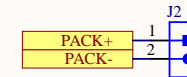
## Battery Balancing



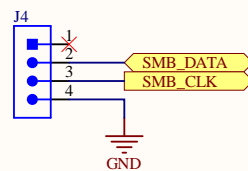
## Battery In



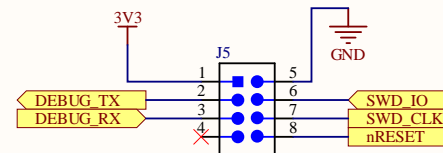
## Pack Out




## EV2400

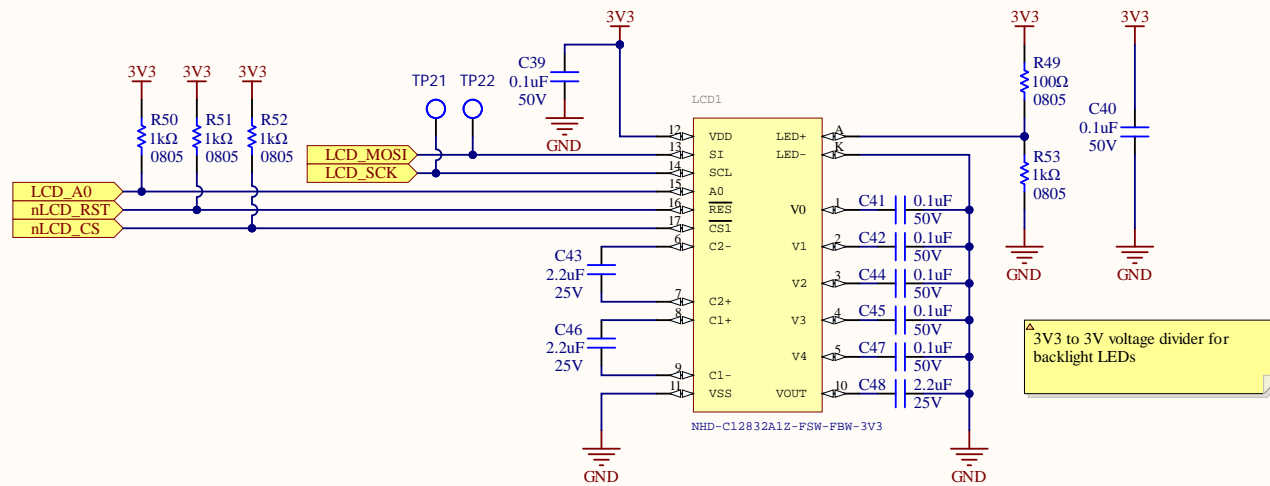


## Debug/Programing

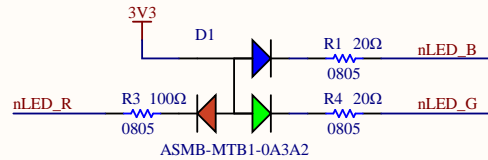


|   |                          |  |   |   |
|---|--------------------------|--|---|---|
| Title Connectors  |                          |  | UW Robotics<br>200 University Avenue<br>Waterloo<br>Ontario<br>Canada N2L 3G6 |  |
| Size: Letter  | Drawn By: Ayesha Ebrahim |  |   |   |
| Date: 2020-05-26  | Sheet of                 |  |   |   |
| File: C:\Users\ayesh\Documents\GitHub\MarsRover2020-PCB\Projects\BMS\Rev1\Connectors.SchDoc |                          |  |   |   |

# LCD



## Test LEDs



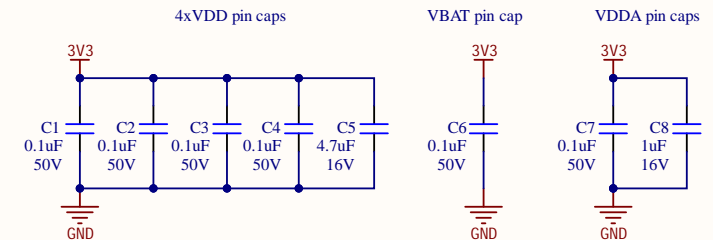
**Current Calculations**

Green LED voltage drop: 2.2V  
 $I = (3.3 - 2.2V) / 100 = 11mA$

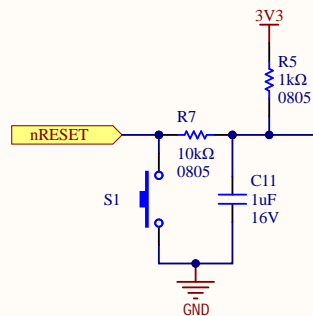
RGB LED voltage drops:  
 - Red: 2.1V:  $I = (3.3 - 2.1V) / 100 = 12mA$   
 - Blue: 3.1V:  $I = (3.3 - 3.1V) / 20 = 10mA$   
 - Green: 3.1V:  $I = (3.3 - 3.1V) / 20 = 10mA$

## STM32F446RET6

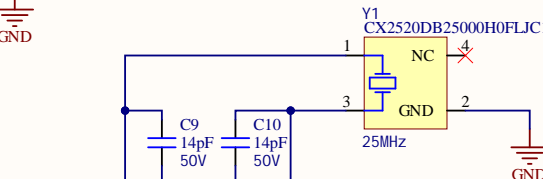
## Decoupling Caps



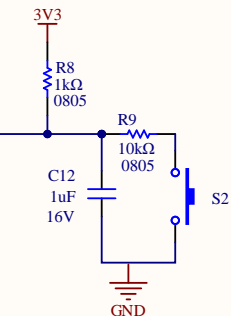
## Reset Button



**For Debounce Circuit:**  
 $T = RC \rightarrow C = T/R$   
 $C = 10ms / 10kOhms = 1\mu F$

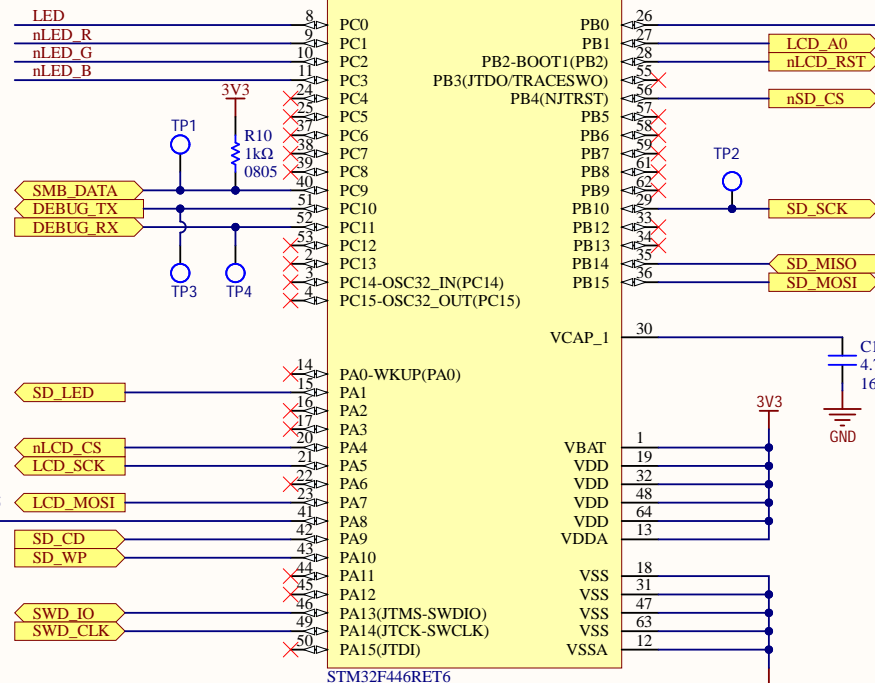
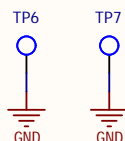


## Test Button



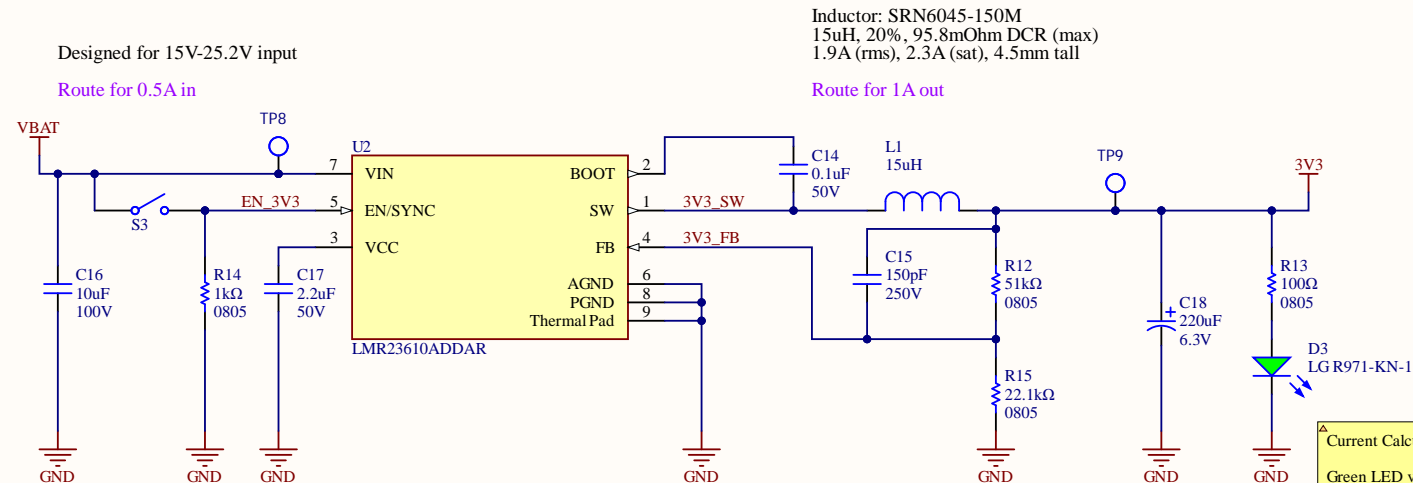
**For Debounce Circuit:**  
 $T = RC \rightarrow C = T/R$   
 $C = 10ms / 10kOhms = 1\mu F$

## GND Test Points



MOUNTING\_HOLES

# Battery Voltage to 3V3 Buck @ 1A Max



Max expected power on output = 1.65W  
Max current = 0.5A  
Expected Efficiency at 1A > 87.7%

# SD Card Connector

