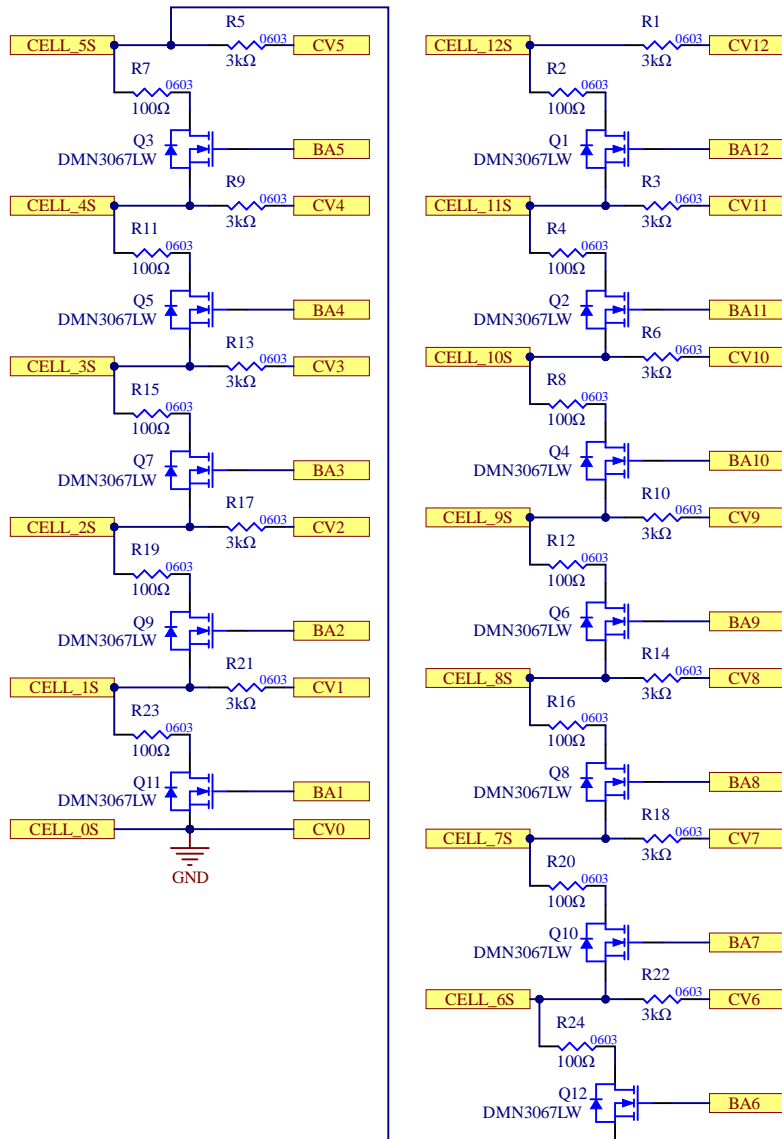


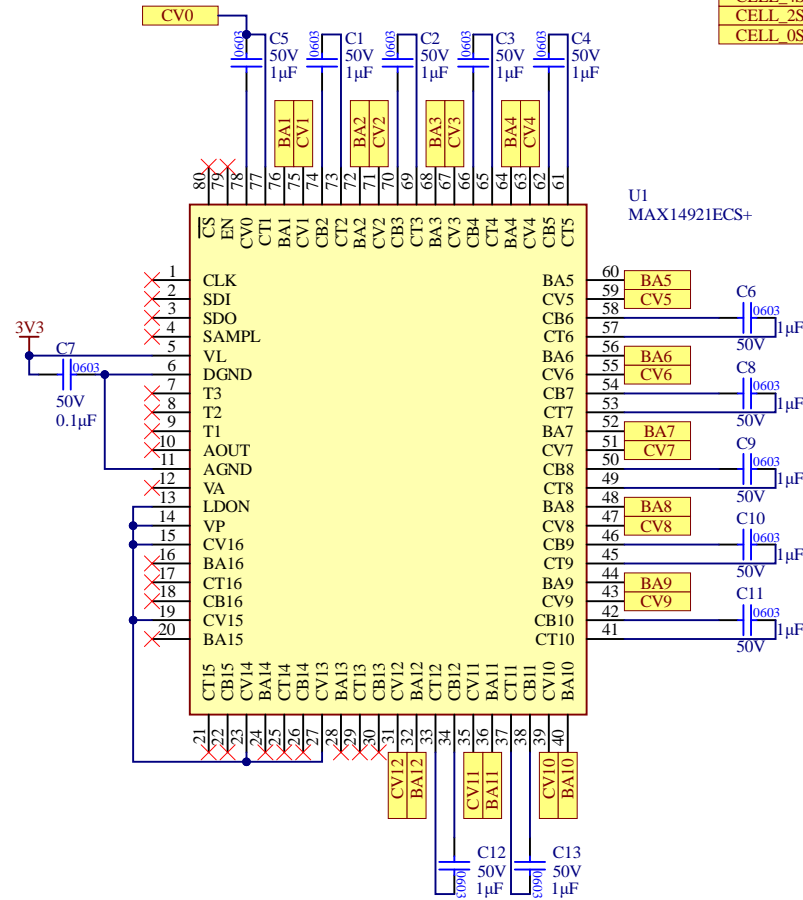
# BMS

## BATTERY CONNECTOR

### CELL BALANCING CIRCUIT



### BMS IC



J1			
8	8	16	16
7	7	15	15
6	6	14	14
5	5	13	13
4	4	12	12
3	3	11	11
2	2	10	10
1	1	9	9
CONN_0430451600			

		University of Waterloo Robotics Team 200 University Ave W Waterloo, Ontario, Canada N2L 3G1	REV *
PROJECT Battery Management System.PrjPcb, [No Variations]			
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		SHEET 1 OF 1	