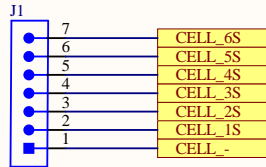
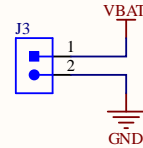


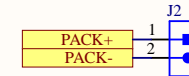
## Battery Balancing



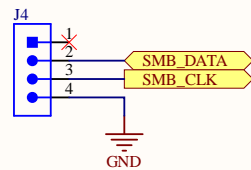
## Battery In



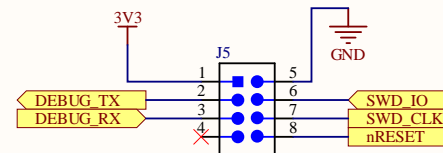
## Pack Out




## EV2400

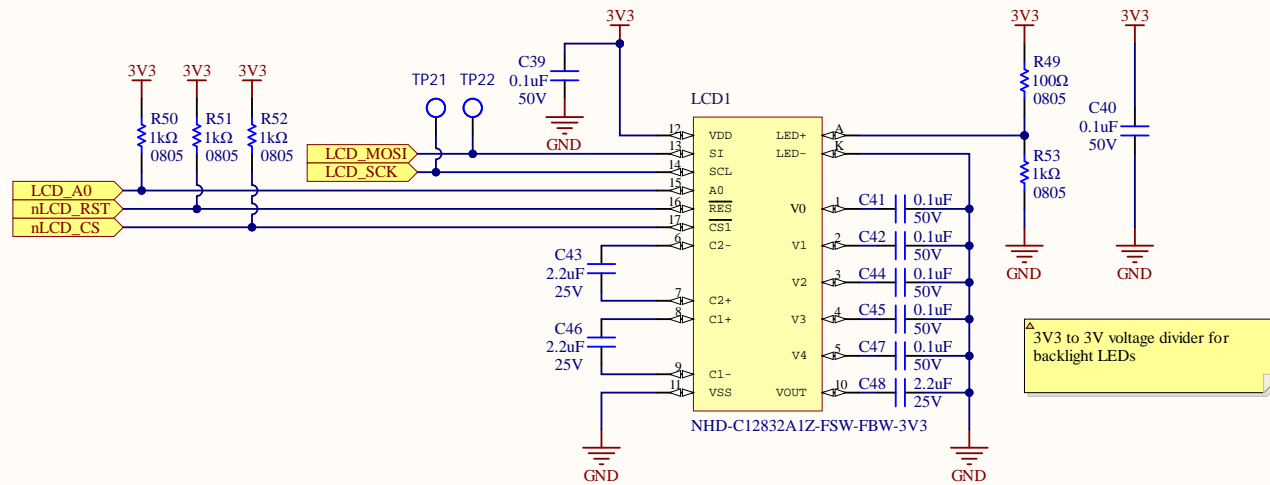


## Debug/Programing

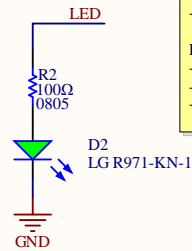
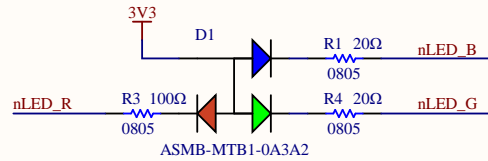


Title Connectors			UW Robotics 200 University Avenue Waterloo Ontario Canada N2L 3G6	
Size: Letter	Drawn By: Ayesha Ebrahim			
Date: 2020-05-23	Sheet of			
File: C:\Users\ayesh\Documents\GitHub\MarsRover2020-PCB\Projects\BMS\Rev1\Connectors.SchDoc				

# LCD



## Test LEDs



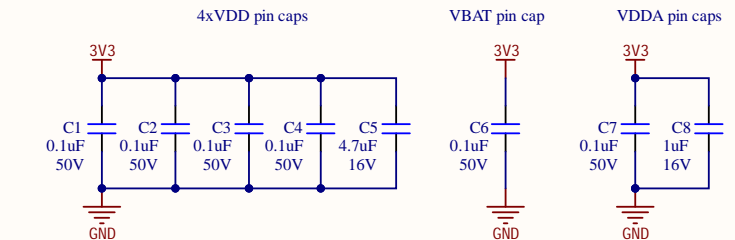
### Current Calculations

Green LED voltage drop: 2.2V  
-  $I = (3.3 - 2.2V) / 100 = 11mA$

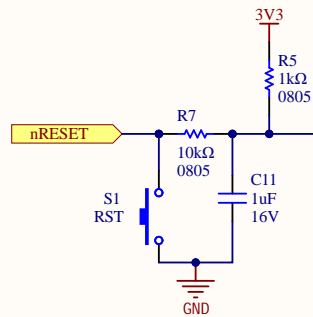
RGB LED voltage drops:

- Red:  $2.1V$ ;  $I = (3.3 - 2.1V) / 100 = 12mA$
- Blue:  $3.1V$ ;  $I = (3.3 - 3.1V) / 20 = 10mA$
- Green:  $3.1V$ ;  $I = (3.3 - 3.1V) / 20 = 10mA$

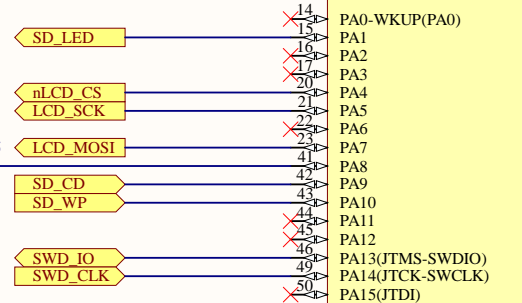
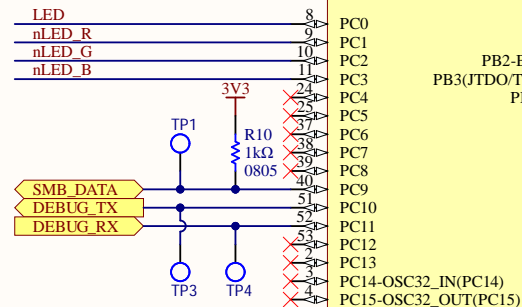
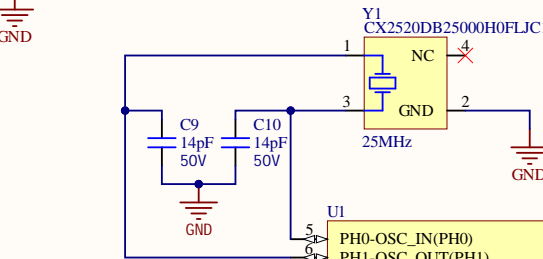
# STM32F446RET6



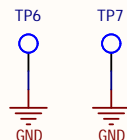
## Reset Button



For Debounce Circuit:  
 $T = RC \rightarrow C = T/R$   
 $C = 10\text{ms}/10\text{k}\Omega = 1\mu\text{F}$

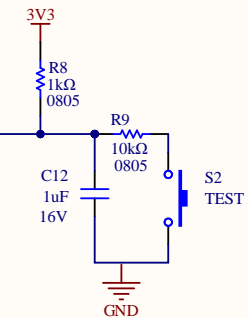


STM32F446RET6

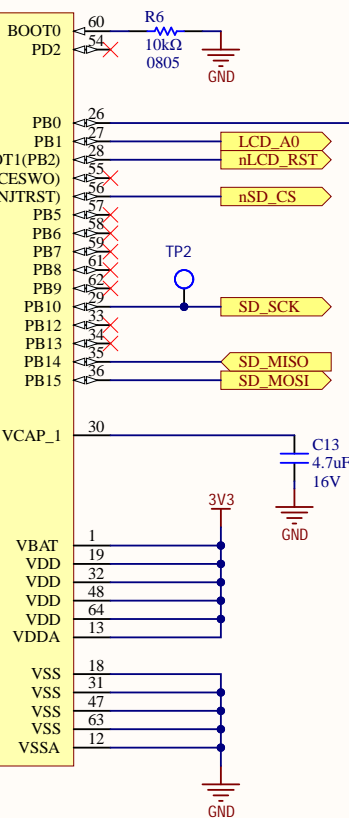


## Decoupling Caps


Test Button



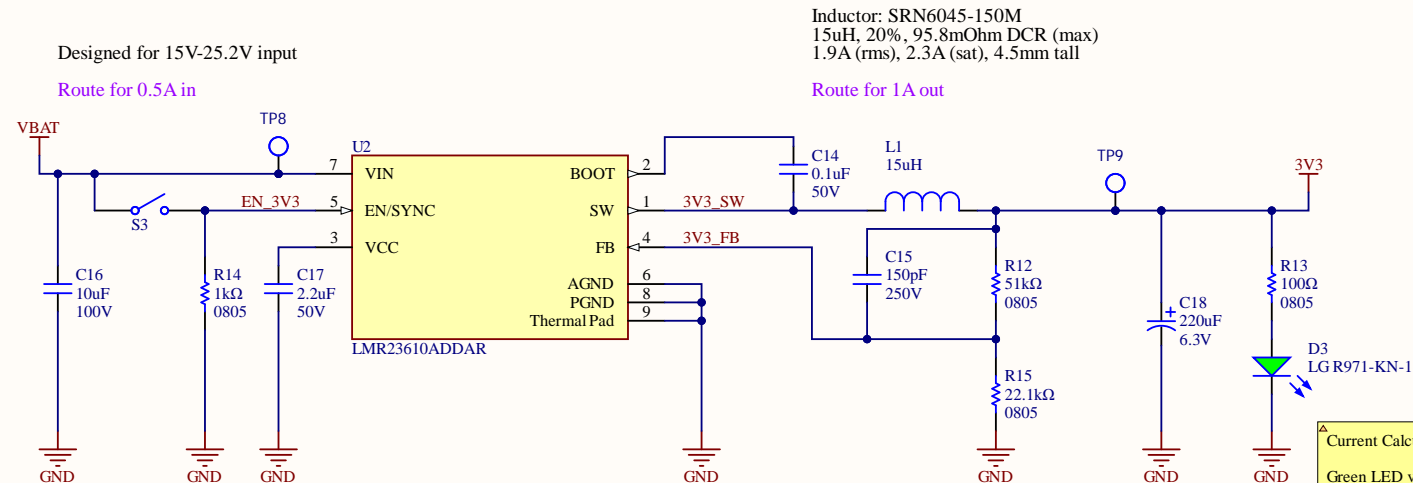
For Debounce Circuit:  
 $T = RC \rightarrow C = T/R$   
 $C = 10\text{ms}/10\text{k}\Omega = 1\mu\text{F}$



MOUNTING\_HOLES

Title MCU		
Size: <b>Letter</b>	Drawn By: Ayesha Ebrahim	
Date: 2020-05-23	Sheet * of *	
File: C:\Users\ayesh\Documents\GitHub\MarsRover2020-PCB\Projects\BMS\Rev1\MCU_SchDoc		

# Battery Voltage to 3V3 Buck @ 1A Max



**Current Calculations**

Green LED voltage drop: 2.2V  
 $I = (3.3 - 2.2V) / 100 = 11mA$

Max expected power on output = 1.65W  
 Max current = 0.5A  
 Expected Efficiency at 1A > 87.7%

# SD Card Connector

