Learning from User-generated Data Summer Term 2022

Learning from Explicit User Feedback II: Model-based Collaborative Filtering



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Collaborative Filtering: Recap of Last Class

- Exploits users' ratings of items to predict unrated items of target user (knowledge typically represented in a user-item-rating matrix)
 - user-based collaborative filtering
 find similar users based on rated items (vectors over items),
 predict rating as weighted combination of most similar users' ratings
 - item-based collaborative filtering
 find similar items based on user ratings (vectors over users),
 predict rating as weighted combination of most similar items' ratings
- Preprocessing methods can speed up both approaches
- In real-world applications, item-based methods can scale better
- Rating biases should be accounted for

Latent Factor Models

- Try to explain ratings by characterizing both users and items in an *f*-dimensional space of factors derived from the rating patterns
- Instead of the two explicit dimensions user and item, ratings consist of (are influenced by) several (latent!) factors, e.g.,
 - *user characteristics*: gender, age, preference (taste, personality), mood (e.g., serious vs. escapism)
 - item characteristics: genre, mood, usage purpose, ...
 - ▶ in music: instrumentation, era, male vs. female singer, etc.
 - ▶ in movies: comedy vs. drama, amount of action, type of appearing characters, target group, independent movies...
- Computationally derived factors are not necessarily interpretable! (just describe some of the variance in the data)

Matrix Factorization Models

- Purpose: estimate hidden parameters from user ratings ("model-based approach", cf. training of classifier = "learning a model")
- Both users and items are represented as f dimensional column vectors user $u \Rightarrow \text{vector } w_u \in \mathbb{R}^f$, $W = [w_1 \dots w_n]^T$ is thus $n \times f$ matrix item $i \Rightarrow \text{vector } h_i \in \mathbb{R}^f$, $H = [h_1 \dots h_m]$ is $f \times m$ matrix
- Entries in W_u measure interest of u in corresponding dimension, in h_i the extent to which item i is related to dim. (can be negative)
- *f* << *n*,*m* (typically 20<*f*<100)
- Predicted user-item rating is modeled as inner product $r'_{u,i} = w_u^T h_i$ i.e., R' = WH contains all rating predictions for all item-user pairs

Matrix Factorization Models

- Challenge: computing the mapping, i.e., factorizing the matrix
- Matrices W and H found by minimizing the reconstruction error (squared Frobenius norm)

$$err = ||R - WH||_F^2 = \sum_{u,i} (r_{ui} - w_u^T h_i)^2$$

- Minimizing that error is equivalent to finding the *singular value* decomposition (SVD) of R
- SVD: R can be decomposed into a product of 3 matrices: $R = U\Sigma V^T$ (see next slide)
- W and H can then be calculated as $W = U_f \Sigma_f^{1/2}$ cf. [Sarwar et al., 2002] $H = \Sigma_f^{1/2} V_f^T$

Singular Value Decomposition

• The $n \times m$ matrix R can be decomposed into a product of 3 matrices: $R = U \Sigma V^T$.

where

U is an $n \times n$ unitary (orthogonal) matrix (*left singular vectors*), Σ is an $n \times m$ diagonal matrix (diag. entries ... *singular values*), and *V* is an $m \times m$ unitary matrix (*right singular vectors*).

- Calculated iteratively as a numerical approximation
- *Singular values* related to *Eigenvalues*, i.e., features can be ordered according to importance (wrt. describing the data in *R*)
- Truncated SVD: consider only f largest singular triplets \Rightarrow approximation and dimensionality reduction

Singular Value Decomposition – Example

- Ratings as given in R (users and items swapped) (cf. [Jannach et al., 2010])
- User User User R 3 4 Item 1 Item 2 3 6 Item 3 5 3 2 Item 4 5

-0.30

-0.63

0.81

-0.52

-0.22

0.17

User

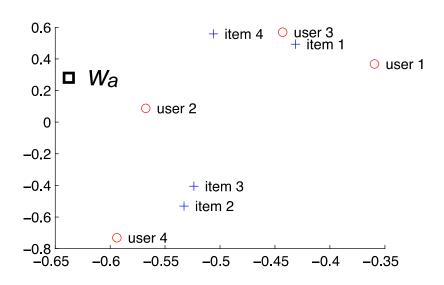
• Calculate SVD using linear algebra package

$$U = \begin{bmatrix} -0.43 & 0.49 & -0.55 & -0.52 \\ -0.53 & -0.53 & 0.42 & -0.51 \\ -0.52 & -0.41 & -0.49 & 0.57 \\ -0.51 & 0.56 & 0.53 & 0.39 \end{bmatrix} \Sigma = \begin{bmatrix} 12.22 & 0 & 0 & 0 \\ 0 & 4.93 & 0 & 0 \\ 0 & 0 & 2.06 & 0 \\ 0 & 0 & 0.30 \end{bmatrix} V = \begin{bmatrix} -0.36 & 0.37 \\ -0.57 & 0.09 \\ -0.44 & 0.57 \\ -0.59 & -0.73 \end{bmatrix}$$

- U corresponds to items, V to users (cf. H, W)
- Taking only *f*=2 most important dimensions allows for graphical representation (both users and items can now be projected in a joint space): row i of U_2 (or V_2) corresponds to first 2 latent features of item *i* (or user *i*, respectively)

Singular Value Decomposition – Example

• 2-dim. graphical representation:



R	User 1	User 2	User 3	User 4
Item 1	3	4	3	1
Item 2	1	3	2	6
Item 3	2	4	1	5
Item 4	3	3	5	2

factorization ... implicit clustering of users and items

• Projecting new user with, e.g., rating vector $a = [5 \ 3 \ 4 \ 4]^T$ into latent space: $w_a = a^T U_2 \Sigma_2^{-1} = [-0.64 \ 0.3]$ (for new item b: $w_b = bV_2 \Sigma_2^{-1}$)

Can again be used to find similar users

• Can also be used to measure similarity between users and items! (make recommendations based on, e.g., cosine similarity)

Back to Matrix Factorization Models

- Problems with SVD as discussed:
 - only makes sense on a fully known user ratings matrix (i.e., no missing values)
 - Why? We can't/don't want to learn missing values.
 - Also: fully known or filled with defaults ⇒ computationally expensive
- Thus we should directly estimate the latent user vectors $w_u \in \mathbb{R}^f$ and item vectors $h_i \in \mathbb{R}^f$ only from known ratings $(u,i) \in L$
- Objective: minimize squared error on L: $\min_{w*,h*} \sum_{(u,i)\in L} (r_{u,i} w_u^T h_i)^2$
- Important: after learning W and H from $(u,i) \in L$, predictions for all $(u,i) \in R$ can be read off R' = WH

Learning Matrix Factorization Models

Two (of many) approaches to iteratively minimizing the squared error:

- 1. Gradient Descent (see next slides)
 - algorithm iterates through all examples in training set L and calculates the difference between modeled rating $w_u^T h_i$ and real rating, modifies latent factors towards predicting the real rating
 - [+] easy implementation, fast running time
- 2. Alternating Least Squares (ALS) (e.g., [Bell & Koren, 2007])
 - both W_U and h_i unknown, equation to minimize not convex (there's more than one optimal solution; local minima)
 - ⇒ however, if one is fixed, the other can be solved optimally
 - ALS alternates between fixing the W_u 's and the h_i 's, solving the other (linear regression) until convergence
 - [+] can be parallelized, in less sparse cases faster than gradient descent

Gradient Descent

• Gradient: calculating the direction of the steepest descent \Rightarrow need partial derivatives of the error function $\sum e_{u,r}$ wrt. each parameter w_{uk}, h_{ik} for all u, i, k

$$e_{ui} = r_{ui} - r'_{ui}$$
 $r'_{ui} = w_u^T h_i = \mathop{a}_{k=1}^f w_{uk} h_{ik}$

• Finding the partial derivative for w_{uk} for fixed i=I, k=K:

$$\frac{\P e_{uI}^2}{\P w_{uK}} = 2e_{uI} \frac{\P e_{uI}}{\P w_{uK}} \qquad | \text{ see def. of } e \Rightarrow r_{uI} \dots \text{ constant}$$

$$= 2(r_{uI} - r'_{uI}) \frac{-\P r'_{uI}}{\P w_{uK}} \qquad | \text{ def. of } r'_{ui} \Rightarrow \mathop{\overset{f}{\underset{k=1}{\otimes}}} w_{uk} h_{Ik} = \underbrace{w_{uK} h_{IK}} + \mathop{\overset{f}{\underset{k=1}{\otimes}}} w_{uk} h_{Ik}$$

$$= -2(r_{uI} - r'_{uI})(h_{IK}) \qquad = h_{IK} \text{ wrt. } \partial w_{uK} \qquad \text{constants wrt. } \partial w_{uK}$$

$$\Rightarrow 2 \parallel 0$$

 \Rightarrow all 0

(Note: for w for one rating; full derivative over all u by U)

Gradient Descent

• Analogous: partial derivative wrt. ∂h_{IK}

$$\frac{\P e_{uI}^2}{\P h_{IK}} = -2(r_{uI} - r'_{uI})(w_{uK})$$

- Usual next step after determining direction of gradient
 ⇒ determine step length
- Alternative: use fixed length parameter as multiplier on the gradient ⇒ learning rate γ
- Update w and h using backpropagation (cf. neural networks)

$$w_{uK} - w_{uK} - g \frac{\P e_{uI}^2}{\P w_{uK}} = w_{uK} + g 2(r_{uI} - r'_{uI})(h_{IK})$$

$$h_{IK} - h_{IK} - g \frac{\P e_{uI}^2}{\P h_{IK}} = h_{IK} + g 2(r_{uI} - r'_{uI})(w_{uK})$$

A Variant of Gradient Descent in Pseudocode

```
Initialize vectors W_u and h_i (e.g., set all values to 0.1 or estimate priors)
Subtract baseline, such as global average \mu, from all ratings: r_{u,i} \leftarrow r_{u,i} - \mu
Loop over training epochs (e.g., 120) or until error increases:
     For all (u,i) \in L:
           Calculate prediction error: e_{u,i} \leftarrow r_{u,i} - w_u^T h_i
           Iterate over latent factors: k=1...f
                 Update parameters in direction of gradient
                 proportional to learning rate \gamma (e.g., 0.001):
                       W_{uk} \leftarrow W_{uk} + 2v \cdot e_{u,i} \cdot h_{ik}
                       h_{ik} \leftarrow h_{ik} + 2v \cdot e_{u,i} \cdot w_{uk}
           End Iteration
     End For
     Optional: decrease learning rate
End Loop
Add baseline (e.g., \mu) to predicted value and clip predictions to range
```

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cf. [Funk/Webb, 2006]

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Overfitting and Regularization

- The learned model will produce predictions that are optimal for the training data but for unseen data, this might lead to bad predictions ("overfitting")
- E.g., imagine the music genre Jazz is not liked by a user in the training set and so the model predicts values <<0 (far off scale) to be on the safe side (will be clipped to range anyways)
 - \Rightarrow no Jazz track will ever be predicted >0
- *Problem*: fitting of the model is not bound to any value constraints (optimized values can become extreme)
- *Remedy*: penalize magnitude of feature values by introducing **regularization term** (Tikhonov regularization)

avoid overfitting ⇒ improve generalization (= objective of learning!)

Overfitting and Regularization

• Minimize regularized squared error on set of known ratings L

$$\min_{w*,h*} \sum_{(u,i)\in L} (r_{u,i} - w_u^T h_i)^2 + \lambda (\|w_u\|^2 + \|h_i\|^2)$$

- λ ... regularization term (λ either determined by cross-validation or manually set, e.g., to 0.02)
- New optimization objective ⇒ need to re-calculate partial derivatives

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• Updated update steps:

$$w_u \leftarrow w_u + 2\gamma (e_{u,i} \cdot h_i - \lambda \cdot w_u)$$

$$h_i \leftarrow h_i + 2\gamma (e_{u,i} \cdot w_u - \lambda \cdot h_i)$$

Incorporating Biases

- Pure user-item interaction $r'_{u,i} = w_u^T h_i$ can't explain full rating value
- Accounting for biases (e.g., user bias, item bias) is important
- This should be also embedded in the factorization approach, thus

$$r'_{u,i} = \mu + b_i + b_u + w_u^T h_i$$

 μ ... global average rating, b_i ... item bias, b_u ... user bias estimated rating is a linear combination of these + interaction term

• The modified regularized squared error function is:

$$\min_{w*,h*,b*} \sum_{(u,i)\in L} (r_{u,i} - \mu - b_u - b_i - w_u^T h_i)^2 + \lambda (\|w_u\|^2 + \|h_i\|^2 + b_u^2 + b_i^2)$$

• Additional parameter training, cf. [Paterek, 2007]: (e.g., $\lambda_2 = 0.05$)

$$b_u \leftarrow b_u + 2\gamma \left[e_{u,i} - \lambda_2 \cdot (b_u + b_i - \mu) \right]$$

$$b_i \leftarrow b_i + 2\gamma \left[e_{u,i} - \lambda_2 \cdot (b_u + b_i - \mu) \right]$$

Summary: Memory-Based CF Approaches

- Memory-based approaches
 - user-based
 - item-based
- Easily understandable, easy implementation
- Operate directly on full rating matrix (requires large memory)
- Might be too slow for real-time recommendations

Summary: Model-Based CF Approaches

- Model-based approaches
 - item-based with preprocessing (i.e., similarity lookup)
 - (user-based with preprocessing)
 - matrix factorization-based
- Allow real-time recommendations
- Calculate data model (learn from training set)
- Over time, ratings change, items change, users change. Needs strategies for how and when to update the model.
- Training is comparatively expensive, too frequent updates should be avoided.

Summary of Collaborative Filtering

- Collaborative filtering-based recommenders are well-established and researched
- Pros
 - √domain-independent
 - √no knowledge engineering
 - √efficient algorithms exist
 - ✓ potentially serendipitous results
- Cons
 - need users/community
 - need rating data (sparsity is a severe issue)
 - cold-start problems
 - models might be complex and not interpretable

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