

## Chapter 1

# Homework #2. Rakhmatulin Viktor

### 1.1 Task#1

Find minimum of function with respect to parameters  $a, b, c$  :  $f(x) = ax^2 + bx + c$

Solution:

Minimum could lie at the point where  $f'(x) = 0$ , so  $2ax + b = 0$  thus  $x^* = -\frac{b}{2a}$

If  $a > 0$ :  $f'(x) > 0$  when  $x > x^*$  and  $f'(x) < 0$  when  $x < x^*$ . Thus,  $x^*$  is the minimum point and

$$f(x^*) = \frac{a}{4a^2} - \frac{b}{2a} + c = \frac{1}{4a} - \frac{b}{2a} + c$$

Answer:  $a > 0, x^* = -\frac{b}{2a}, f(x^*) = \frac{1}{4a} - \frac{b}{2a} + c$

### 1.2 Task#2

What are dimensions of gradient of a function  $h(x) = f(Ax)$ , constructed of function  $f : R^m \rightarrow R$  and matrix  $A \in R^{m \times k}$ . Find the dimensions of  $\nabla_x h(x)$

Solution:

$$\nabla h(x) = A^T \nabla_y f(y) \text{ where } y = Ax$$

Answer:  $\nabla h_{k \times 1}(x)$

### 1.3 Task#3

Prove that for a strongly convex function with parameter  $\mu$  holds,

$$\frac{\mu}{2} \|x - x^*\|^2 \leq f(x) - f(x^*)$$

Solution: For strong convex functions stands:  $f(y) \geq f(x) + (\nabla f(x), y - x) + \frac{\mu}{2} \|x - y\|^2$   
 $\forall x, y \in \text{dom} f$ . For extremal point also stands that  $\nabla f(x^*) = 0$ . From substitution  $x = x^*$  we get:  
 $f(x) \geq f(x^*) + \frac{\mu}{2} \|x^* - x\|^2$  or  $f(x) - f(x^*) \geq \frac{\mu}{2} \|x^* - x\|^2$  Q.E.D.

## 1.4 Task#4

Derive a) gradient  $\nabla f(x)$  and b) Hessian matrix  $\nabla^2 f(x)$  (both in vector form) for the function  $f(x) = (x, c)^2; x \in \mathbb{R}^n$

Solution:

Lets assign  $y = (x, c)$

Handwritten solution for Task #4:

$$\nabla f(x) = 2 \begin{pmatrix} y \cdot \frac{\partial y}{\partial x_1} \\ \vdots \\ y \cdot \frac{\partial y}{\partial x_n} \end{pmatrix} = 2 \begin{pmatrix} y \cdot c_1 \\ \vdots \\ y \cdot c_n \end{pmatrix} \quad \frac{dy}{dx_i} = c_i$$

$$\frac{dy}{dx} = \left( \sum_{i=1}^n x_i \cdot c_i \right) \frac{1}{dx} = [c_1 \ c_2 \ \dots \ c_n] = C^T$$

$$\Delta^2 f(x) = \frac{d(\nabla^T f(x))}{dx} = \frac{d}{dx} (y c_1 \ y c_2 \ \dots \ y c_n) \equiv$$

$$\equiv 2 \cdot \begin{pmatrix} \frac{dy}{dx_1} \cdot c_1 & \frac{dy}{dx_1} \cdot c_2 & \dots & \frac{dy}{dx_1} \cdot c_n \\ \frac{dy}{dx_2} \cdot c_1 & \frac{dy}{dx_2} \cdot c_2 & \dots & \frac{dy}{dx_2} \cdot c_n \\ \vdots & \vdots & \ddots & \vdots \\ \frac{dy}{dx_n} \cdot c_1 & \frac{dy}{dx_n} \cdot c_2 & \dots & \frac{dy}{dx_n} \cdot c_n \end{pmatrix} = 2 \begin{pmatrix} c_1^2 & c_1 c_2 & \dots & c_1 c_n \\ c_1 c_2 & c_2^2 & \dots & c_2 c_n \\ \vdots & \vdots & \ddots & \vdots \\ c_n c_1 & c_n c_2 & \dots & c_n^2 \end{pmatrix}$$

Figure 1.1: Task #4: Solution

## 1.5 Task#5

Derive Hessian matrix  $\nabla^2 f(x)$  for the function  $f(x) = g(Ax + b)$ , assuming differentiable  $g : \mathbb{R}^m \rightarrow \mathbb{R}$ , with dimensions  $A \in \mathbb{R}^{(m \times n)}$ ;  $b \in \mathbb{R}^m$ ;  $x \in \mathbb{R}^n$ .

$$\nabla f(x) = A^T \nabla_y g(Ax+b); \text{ where } y = Ax+b$$

Let  $V = \nabla_y g(y)$  then  $\nabla_x f(x) = (V^T a_1, V^T a_2, \dots, V^T a_n)$   
 $a_i$  - column of  $A$

$$\nabla^2 f(x) = \begin{pmatrix} \frac{d}{dx_1} (\nabla_y^T g \cdot a_1) & \frac{d}{dx_1} (\nabla_y^T g \cdot a_2) & \dots & \frac{d}{dx_1} (\nabla_y^T g \cdot a_n) \\ \frac{d}{dx_m} (\nabla_y^T g \cdot a_1) & \dots & \dots & \frac{d}{dx_m} (\nabla_y^T g \cdot a_n) \end{pmatrix}$$

Figure 1.2: Task #5: Solution

## 1.6 Task#6

Solve optimal step-size problem for the quadratic function, with symmetric positive definite matrix  $A \in R^{n \times n}$ , and  $x, b, d \in R^n$ . Your goal is to find optimal  $\gamma$  for given  $A, b, d, x$ . The resulting expression must be written in terms of inner products(....)

$$f(\gamma) = (A(x + \gamma d), x + \gamma d) + (b, x + \gamma d) \rightarrow \min_{\gamma \in R}$$

$$\begin{aligned} f(\gamma) &= (Ax + A\gamma d, x + \gamma d) + (b, x + \gamma d) \equiv \\ &\equiv (Ax, x) + (Ax, \gamma d) + (A\gamma d, x) + (A\gamma d, \gamma d) + (b, x) + \\ &\quad + (b, \gamma d) \\ \frac{df}{d\gamma} &= 0 + (Ax, d) + (Ad, x) + 2\gamma (Ad, d) + 0 + (b, d) \\ f'(\gamma) = 0 &\Rightarrow \boxed{\gamma = - \frac{(Ax, d) + (Ad, x) + (b, d)}{2(Ad, d)}} \end{aligned}$$

Figure 1.3: Task #6: Solution

## 1.7 Task#7

Derive subgradient (subdifferential) for the function  $f(x) = [x^2 - 1]^+, x \in \mathbb{R}$ .

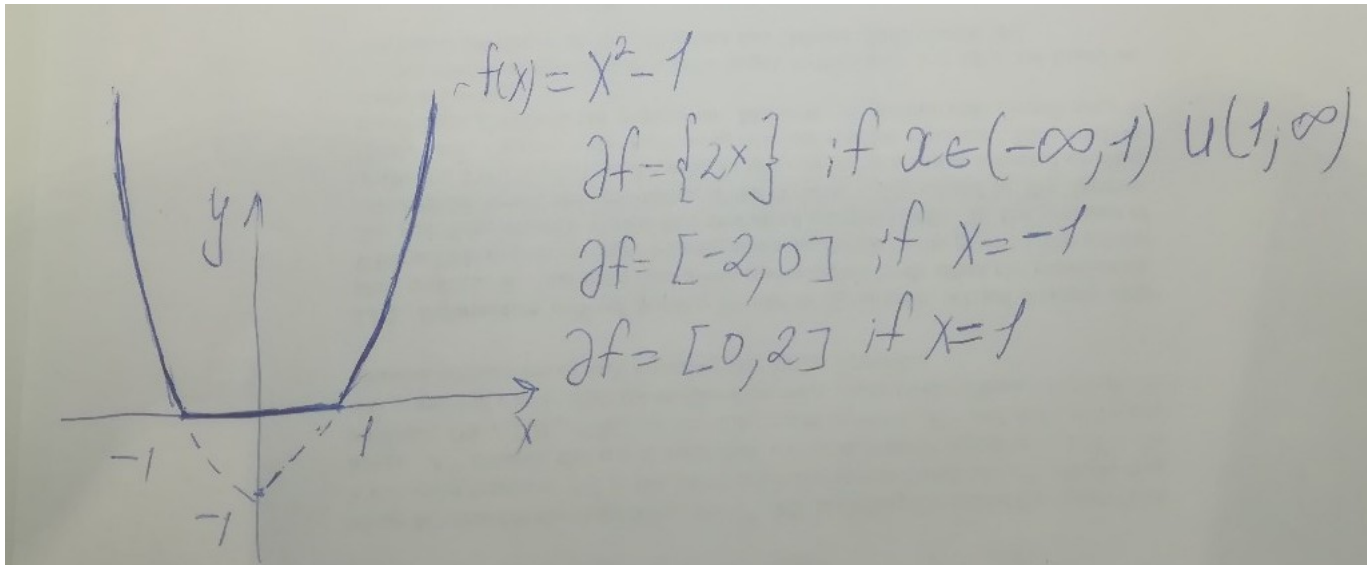


Figure 1.4: Task #7: Solution

## 1.8 Task#8

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be given by  $f(x) = 12x > Qx - x > b$ , where  $b \in \mathbb{R}^n$  and  $Q$  is a real symmetric matrix positive definite  $n \times n$  matrix. Suppose that we apply steepest descent (or gradient descent) method to this function with  $x^0 \neq Q^{-1}b$ . Show that method converges in one step that is  $x^1 = Q^{-1}b$ , if and only if  $x^0$  is chosen such that  $g^0 = Qx^0 - b$  is an eigenvector of  $Q$ .

## 1.9 Task#9

Find the minimizer of  $f(x, y) = x^2 + xy + 10y^2 - 22y - 5x$  numerically by steepest descent

1. For each iteration, record the values of  $x, y$  and  $f$  and include in a table.
2. Plot the values on a contour plot.
3. Explore different starting values, such as  $(1, 10), (10, 10), (10, 1)$ . Does the number of steps depend significantly on the starting guess?

Solution: The code is in the repository.

3. Amount of steps depends significantly on the starting point:

$x_0 = ([1.0, 10.0]) = 5$  iterations

$x_0 = ([10.0, 10.0]) = 8$  iterations

| step | x           | y            | f(x,y)       |
|------|-------------|--------------|--------------|
| 0    | 15          | -10          | 1220         |
| 1    | 14.24095917 | 0.4747634888 | 130.1704166  |
| 2    | 3.537601665 | -0.300948240 | 1.288541941  |
| 3    | 3.447819527 | 0.937875377  | -13.95516917 |
| 4    | 2.181837049 | 0.8461375452 | -15.75817663 |
| 5    | 2.171220009 | 0.9926532766 | -15.97140187 |
| 6    | 2.02150715  | 0.9818029918 | -15.9966175  |
| 7    | 2.020251327 | 0.9991310345 | -15.99959993 |
| 8    | 2.002543409 | 0.9978478474 | -15.99995269 |
| 9    | 2.002394907 | 0.9998972396 | -15.9999944  |
| 10   | 2.000300838 | 0.9997454699 | -15.99999934 |
| 11   | 2.000283271 | 0.9999878523 | -15.99999992 |
|      |             |              |              |
|      |             |              |              |

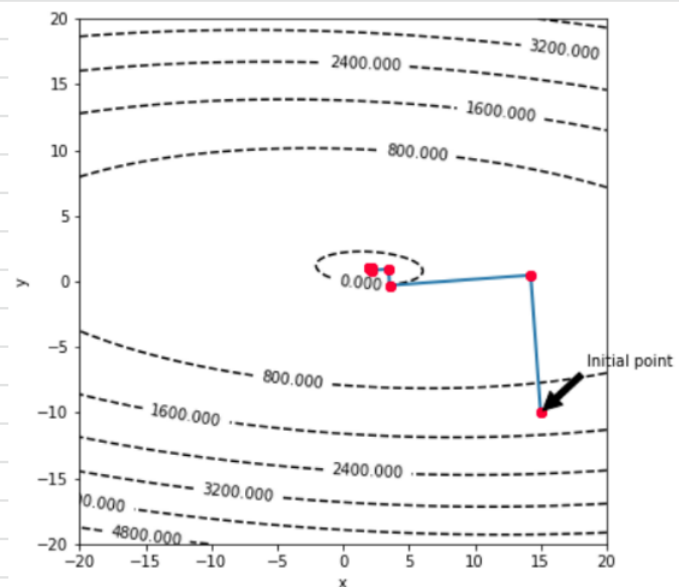


Figure 1.5: Task #9: Solution to point 1 and 2

$x_0 = ([10.0, 1.0]) = 36$  iterations

On the picture "Task #9: comments on point 3" demonstrated the case when  $x_0 = ([10.0, 1.0])$ . The steepest descent moves very slowly when the function values become flat

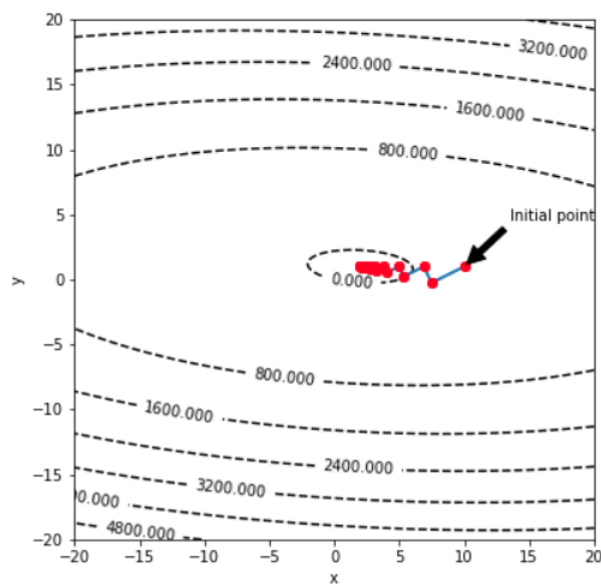


Figure 1.6: Task #9: comments on point 3

## 1.10 Task#10

Let the cost function of the unconstrained optimization problem of interest be

$$f(x) = \frac{1}{4}(x_1-1)^2 + \sum_{i=2}^n (2 * x_{i-1} - x_i - 1)^2$$

Consider two different scenarios, first  $n=3$ , and then  $n=10$ . Using  $x^0 = [-1.5, 1, \dots, 1]^T$  write out the first iteration of the steepest descent algorithm and obtain the optimum value for  $\alpha^0$ . What is the value of  $x^1$  if you implement  $\alpha^0$ ? Verify that  $f(x^1) < f(x^0)$

2. Write a code to find the minimizer of  $f(x)$  using steepest descent algorithm with starting point of  $x^0 = [-1.5, 1, \dots, 1]$  and using 1)  $x^1 = \operatorname{argmin}_f(x^k - \alpha \nabla f(x^k))$ .

2) constant  $\alpha = 0.1$ .

3) constant  $\alpha = 0.5$ .

4) constant  $\alpha = 1.0$ .

(Use  $\|x^{k+1} - x^k\| \leq 10^{-6}$  the stopping condition for your algorithm)

3. How many steps it takes for the algorithm to converge for each choices of the step sizes above?

4. Use `fminbnd` from Matlab or an equivalent function from the programming language of your-choice to solve the problem. How many steps this algorithm takes to converge?

Solution:

|    | $f(x_0) = 7.8125$ |  |             |                   |
|----|-------------------|--|-------------|-------------------|
| n  | step              | x1   | f(x1)       | $f(x_1) < f(x_0)$ |
| 3  | 0.01588745        | [-1.00351715<br>1.07943726 1. ]                        | 1.1169341   | TRUE              |
| 10 | 0.01588745        | [-1.00351715<br>1.07943726 1. 1.1. 1. 1.<br>1. 1. 1. ] | 1.116934129 | TRUE              |

Figure 1.7: Task #10: point 1 solution

| n  | alpha  | iterations       | f(xn)        |
|----|--------|------------------|--------------|
| 3  | argmin | 43836            | 7.24E-08     |
| 3  | 0.1    | doesn't converge | undefined    |
| 3  | 0.5    | doesn't converge | undefined    |
| 3  | 1      | doesn't converge | undefined    |
| 10 | argmin | 15               | 0.9830311985 |
| 10 | 0.1    | doesn't converge | undefined    |
| 10 | 0.5    | doesn't converge | undefined    |
| 10 | 1      | doesn't converge | undefined    |

Figure 1.8: Task #10: point 2 and 3 solution

4. Comment: Gradient norm in  $n = 10$  faster converges to eps.

In python only conjugate gradient is available as a part of scipy library.

Output from the library solver n = 3:

Optimization terminated successfully.  
Current function value: 0.000000  
Iterations: 132  
Function evaluations: 1275  
Gradient evaluations: 255  
x: [0.9998953 0.99957355 0.99829311]

Output from the library solver n = 10:

Optimization terminated successfully.  
Current function value: 0.983031  
Iterations: 13  
Function evaluations: 336  
Gradient evaluations: 28  
x: [0.9998953 0.99957355 0.99829311]

Conclusion: conjugate gradient method from the library requires less iterations compare to steepest gradient descent